



PicoScope 9000 Series PC Sampling Oscilloscopes

User's Guide



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1 Welcome

Thank you for buying a Pico Technology product!

The PicoScope 9000A Series of PC Sampling Oscilloscopes from Pico Technology is a range of wide-bandwidth compact units designed to replace traditional bench-top electrical and optical sampling oscilloscopes costing many times the price.



PicoScope 9201A PicoScope 9211A PicoScope 9221A PicoScope 9231A

Here are some of the benefits provided by your new PicoScope 9000A Series PC Sampling Oscilloscope:

- **Portability:** Take the unit with you and plug it into any Windows PC.
- **Performance:**
 - Two electrical channels with user-selectable bandwidth of 12 GHz or 8 GHz
 - Optical channel with typical unfiltered optical bandwidth of 8 GHz
 - 10 ps/div to 50 ms/div time base
 - 5 TS/s maximum equivalent sampling rate (200 fs shortest sampling interval)
 - Up to 1 GHz direct trigger, up to 2.7 GB/s clock recovery trigger, and up to 10 GHz prescaled trigger
 - Up to 10 GHz Pattern Sync Trigger with Eye Line mode for eye diagram averaging
 - Multi-functional dual-channel pulse/pattern generators with typical 100 ps @ 20%-80% rise/fall time
 - Dual-channel TDR/TDT with 100 ps system corrected fall time
 - USB 2.0 (FS) and LAN interfaces
- **Powerful built-in measurement capabilities:** High-resolution cursors and automatic Pulse, NRZ- and RZ-eye pattern measurements with statistics, histograms, automated mask test with predefined standard and custom masks, waveform processing including FFT, TDR/TDT measurements with normalization.
- **Applications:** Telecom Service and Manufacturing, Digital System Design, Semiconductor Characterization and Testing, High-Speed digital (pulse) measurements, TDR characterization of circuit boards, IC packages and cables.
- **Flexibility:** Use it as a sampling oscilloscope, spectrum analyzer, communications signal analyzer or time domain reflectometer.
- **Long-term support:** Software upgrades are available to download from our [website](#). You can also call our technical specialists for support. You can continue to use both of these services free of charge for the lifetime of the product.
- **Value for money:** You don't have to pay twice for all the features that you already have in your PC, as the PicoScope 9000A Series sampling scope contains the special hardware you need and nothing more.
- **Convenience:** The software makes full use of the large display, storage, user interface and networking built in to your PC.

2 Introduction

2.1 Overview

The PicoScope 9000A Series PC Sampling Oscilloscopes are wide-bandwidth sampling oscilloscopes for use with personal computers. They are fully USB 2.0-capable and backwards-compatible with USB 1.1. The PicoScope 9211A and 9231A models also have a built-in LAN interface.

With the PicoScope 9000A software, the PicoScope 9000A Series scopes can be used as PC Sampling Oscilloscopes, PC Spectrum Analyzers, PC Communications Signal Analyzers and Time Domain Reflectometers.

For basic instructions on installing and using your oscilloscope, please refer to the printed Quick Start Guide supplied with the instrument.

2.2 Minimum PC requirements

For the PicoScope 9000A Series PC Sampling Oscilloscope to operate correctly, you must connect it to a computer with the minimum requirements to run Windows or the following (whichever is the higher specification):

Processor	Pentium-class processor or equivalent.
Memory	256 MB.
Disk space	Software occupies about 40 MB.
Operating system	Microsoft Windows XP SP2, Vista or 7.
Ports	USB 1.1 compliant port minimum. USB 2.0 compliant port recommended. LAN (PicoScope 9211A/9231A only).

2.3 Safety information

We strongly recommend that you read the general safety information below before using your oscilloscope for the first time. If you use the oscilloscope in a manner contrary to these instructions, safety protection built in to the equipment may cease to function. This could cause damage to your computer or other equipment, or lead to injury to yourself and others.

Maximum input range

The PicoScope 9000A PC Sampling Oscilloscopes are designed to measure voltages in the range stated in the [Specifications](#) ^[10] table. The oscilloscope can withstand the maximum voltage range stated in the [Specifications](#) ^[10] table, and operation with voltages exceeding this range may cause physical damage.

Mains voltages

The PicoScope 9000A Series PC Sampling Oscilloscopes are designed for performing measurements on circuits that are not directly connected to the mains (line power). Any attempt to connect the oscilloscope to mains (line) voltages will cause irreparable damage to the instrument, possible damage to other equipment, and a likelihood of personal injury or death.



The PicoScope 9000A Series PC Sampling Oscilloscopes must not be directly connected to the mains (line power).

Failure to heed this warning may lead to injury or death.

Safety grounding

The PicoScope 9000A Series PC Sampling Oscilloscopes connect directly to the ground of your computer through the USB cable provided. This connection is intended only to minimize interference, and therefore you must not rely on it as a protective safety ground.

Do not connect the grounded connectors on the front panel to any source other than ground. If in doubt, use a meter to check that there is no significant AC or DC voltage between the oscilloscope's ground socket and point to which you intend to connect it. Failure to check may cause damage to your computer, or injury to yourself and others.

Repairs

The oscilloscope contains no user-serviceable parts. Repair or calibration of the oscilloscope requires specialized test equipment and must only be performed by Pico Technology.

Cooling fan

The unit contains a low-noise cooling fan that expels air through the holes in the back of the unit (shown in the [Connections](#) ^[9] section). Do not block these holes, as this might cause the unit to overheat. Do not insert anything in the holes, as this could damage the unit or cause injury.

Cleaning and decontamination

- Remove all connections from the unit
- Clean the external surfaces of the oscilloscope with a soft damp cloth. Do not use chemical cleaners.
- Make sure that the instrument is completely dry before using again.

2.4 Safety symbols

The following symbols appear on the front panel of the PicoScope 9000A Series PC Sampling Oscilloscope.

Symbol 1: Caution: risk of electric shock



This symbol indicates that a safety hazard exists on the indicated connections if you do not take correct precautions. Ensure that you read in detail all safety documentation associated with the product before using it.

Symbol 2: Equipotentiality



This symbol indicates that the indicated connectors are all at the same potential (i.e. are shorted together). You must therefore take necessary precautions to avoid applying a potential across the indicated terminals as this may result in a large current, causing damage to the product and connected equipment.

2.5 FCC notice

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his or her own expense.

For safety and maintenance information see the [safety warning](#)³.

2.6 CE notice

The PicoScope 9000A Series PC Sampling Oscilloscopes meet the intent of the EMC directive 89/336/EEC and are designed to the EN61326-1 (1997) Class B Emissions and Immunity standard.

The oscilloscopes also meet the intent of the Low Voltage Directive and are designed to the BS EN 61010-1:2001 / IEC 61010-1:2001 (safety requirements for electrical equipment for measurement, control, and laboratory use) standard.

2.7 Legal information

The material contained in this release is licensed, not sold. Pico Technology grants a licence to the person who installs this software, subject to the conditions listed below.

Access. The licensee agrees to allow access to this software only to persons who have been informed of these conditions and agree to abide by them.

Usage. The software in this release is for use only with Pico products or with data collected using Pico products.

Copyright. Pico Technology claims the copyright of, and retains the rights to, all material (software, documents etc) contained in this release. You may copy and distribute the entire release in its original state, but must not copy individual items within the release other than for backup purposes.

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Fitness for purpose. As no two applications are the same, Pico Technology cannot guarantee that its equipment or software is suitable for a given application. It is your responsibility, therefore, to ensure that the product is suitable for your application.

Mission-critical applications. This software is intended for use on a computer that may be running other software products. For this reason, one of the conditions of the licence is that it excludes use in mission-critical applications, for example life support systems.

Viruses. This software was continuously monitored for viruses during production, but you are responsible for virus-checking the software once it is installed.

Support. If you are dissatisfied with the performance of this software, please contact our technical support staff, who will try to fix the problem within a reasonable time. If you are still dissatisfied, please return the product and software to your supplier within 28 days of purchase for a full refund.

Upgrades. We provide upgrades, free of charge, from our web site at www.picotech.com. We reserve the right to charge for updates or replacements sent out on physical media.

Trademarks. *Windows* is a trademark or registered trademark of Microsoft Corporation. *Pico Technology* and *PicoScope* are internationally registered trademarks of Pico Technology.

2.8 Contact details

You can obtain technical assistance from Pico Technology at the following address:

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Email:

Technical Support: support@picotech.com

Sales: sales@picotech.com

Web site: www.picotech.com

3 Product Information

3.1 What's in the box?

Your PicoScope 9000A Series PC Oscilloscope kit contains the following items:

Order No.	Quantity	Description
-	1	PicoScope 9201A Sampling Oscilloscope
-	1	PicoScope 9211A Sampling Oscilloscope
-	1	PicoScope 9221A Sampling Oscilloscope
-	1	PicoScope 9231A Sampling Oscilloscope
-	2	SMA connector saver (attached to electrical channels)
		<u>Standard Accessories</u>
DI053	1	CD: PicoScope 9000A series software
DO134	1	Quick Start Guide: PS9000A r2
PS007	1	Power Supply: 6V 2.5A earthed output, IEC connector
MI106	1	Cable: USB2 1.8 m
MI144	1	Carry case: PicoScope
MI193	1	IEC lead for PS007 UK
MI194	1	IEC lead for PS007 EU
MI195	1	US power cord (North American customers only)
		<u>For PicoScope 9201A only</u>
MI197	4	Dust Cap 6mm PVC
		<u>For PicoScope 9211A only</u>
MI197	7	Dust Cap 6 mm PVC
TA075	1	1 m crossover LAN cable
TA076	1	1 m patch LAN cable
DO153	1	Leaflet: 9211A LAN configuration r1
DO154	1	Leaflet: 9211A clock recovery connections r1
		<u>TDR/TDT Accessories Kit</u>
	1	SMA(m)-SMA(m) cable, 30 cm length
	1	SMA(m)-SMA(m) cable, 80 cm length
	1	Resistive Power Divider
	1	SMA(m)-SMA(m) Adaptor
	1	SMA(f) Short
	1	SMA(f) 50-ohm Termination
		<u>For PicoScope 9221A only</u>
MI197	6	Dust Cap 6 mm PVC
	1	SMA connector saver (attached to O/E output)
	1	SMA(m)-SMA(m) cable, 30 cm length

		<u>For PicoScope 9231 only</u>
MI197	8	Dust Cap 6 mm PVC
	1	SMA connector saver (attached to O/E output)
		<u>TDR/TDT Accessories Kit</u>
	1	SMA(m)-SMA(m) cable, 30 cm length
	1	SMA(m)-SMA(m) cable, 80 cm length
	1	Resistive Power Divider
	1	SMA(m)-SMA(m) Adaptor
	1	SMA(f) Short
	1	SMA(f) 50-ohm Termination
		<u>Optional Accessories for Optical Measurements</u>
		51.8 Mb/s Reference Receiver Filter
		155 Mb/s Reference Receiver Filter
		622 Mb/s Reference Receiver Filter
		1.250 Gb/s Reference Receiver Filter
		2.488 Gb/s and 2.500 Gb/s Reference Receiver Filter
		SMA(m)-SMA(m) cable, 30 cm length
		Resistive Power Divider

Some product packs may contain additional items.

3.2 Connections

Standard oscilloscope connectors

The PicoScope 9000A Series PC Sampling Oscilloscopes have SMA oscilloscope connectors. The inputs and outputs have an impedance of 50 Ω , so they are compatible with low-impedance oscilloscope probes having different attenuations. If your probe has a BNC connector, use an SMA(m)-BNC(f) adaptor.

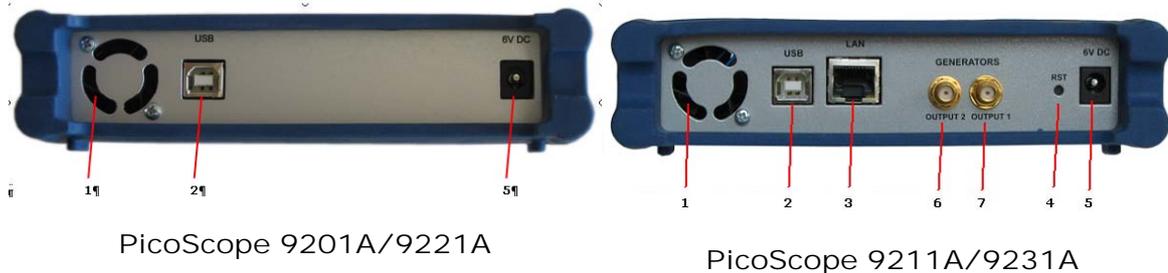
Connector diagrams

Front Panel



1. Channel 1 Electrical Input
2. Channel 2 Electrical Input
3. External Direct Trigger Input
4. External Clock Recovery Trigger Input
5. External Prescaled Trigger Input
6. Optical Input
7. O/E Output

Rear Panel



1. Cooling holes. There is a low-noise fan inside the unit that blows air through these holes. Do not block the cooling holes or insert any objects through them, as this could damage the unit or cause injury.
2. USB 2.0 port
3. LAN port
4. LAN Reset Switch
5. Power socket: for use with the AC adaptor supplied with the unit
6. Generator. Output 2
7. Generator. Output 1

4 Specifications & Characteristics

The distinction between specifications, characteristics, typical performance, and nominal values is as follows.

Specifications describe guaranteed performance over the temperature range +15°C to +25°C (unless otherwise noted) from the firmware calibration temperature. All specifications apply after the instrument's temperature has been stabilized after 1 hour of continuous operation. Unless otherwise noted, corrected limits are given when specifications are achieved using software processing.

Many performance parameters are enhanced through frequent, simple calibrations.

All specifications are subject to change without notice. Specifications are valid after a 1 hour warm-up period, and $\pm 5^\circ\text{C}$ from the firmware calibration temperature.

Characteristics provide useful, but not guaranteed, information about the functions and performance of the instrument.

Typical Performance, where listed, is not guaranteed, but indicates the performance that most units will exhibit.

Nominal Value indicates the expected, but not guaranteed, value of the parameter.

Factory Calibration Cycle. For optimum performance, the instrument should have a complete verification of specifications once every 12 months.

4.1 Family Specifications

Specifications	PicoScope 9201A	PicoScope 9211A	PicoScope 9221A	PicoScope 9231A
Electrical Channels	2			
Optical Channels	-		1	
Electrical Bandwidth	12 GHz or 8 GHz			
Unfiltered Optical Bandwidth	-		8 GHz typical	
Time Base Scale	10 ps/div to 50 ms/div			
Trigger	Direct: DC to 1 GHz Prescaler: 1 to 10 GHz	Direct: DC to 1 GHz Prescaler: 1 to 10 GHz Clock Recovery: 12.3 Mbps to 2.7 Gbps		
Pattern Sync Trigger	-	Up to 10 Gbps		
Generators	-	Step, Pulse, NRZ, RZ. 100 ps typ 20%-80% rise/fall time	-	Step, Pulse, NRZ, RZ. 100 ps typ 20%-80% rise/fall time.
PC Interface	USB	USB, LAN	USB	USB, LAN
Kit	-	TDR/TDT Accessories Kit	Optional Accessories for Optical Measurements	1. TDR/TDT Accessories Kit. 2. Optional Accessories for Optical Measurements

4.2 Electrical Channels

Number of Channels	2 (simultaneous acquisition)
Bandwidth, 3dB Flatness	
Full	DC to 12 GHz
Narrow	DC to 8 GHz
Rise Time, 10% to 90% calculated from $T_r = 0.35/BW$	
Full Bandwidth	= 29.2 ps
Narrow Bandwidth	= 43.7 ps
RMS Noise, maximum	
Full Bandwidth	< 2 mV
Narrow Bandwidth	< 1.5 mV
	Note: Averaging reduces noise, until a system limitation of approximately 100 μ V RMS is reached
Scale Factors (Sensitivity)	2 mV/div to 500 mV/div (full scale is 8 divisions). Adjustable in a 1-2-5-10 sequence. Also adjustable in 0.5% fine increments.
DC Voltage Accuracy	$\pm 2\%$ of full vertical scale ± 2 mV at a temperature within $\pm 3^\circ\text{C}$ of vertical calibration temperature
DC Offset Range	Adjustable from -1 V to 1 V in 25 mV increments (coarse). Also adjustable in fine increments of 1 mV.
ADC	16 bits
Vertical Resolution	125 μ V/LSB or less without averaging. Up to 16 bits with averaging
Operating input voltage	With Digital Feedback (Single-valued signal acquisition): 1 V p-p at ± 1 V range. Without Digital Feedback (Multi-valued signal acquisition): ± 300 mV relative to channel offset. ± 400 mV relative to channel offset, typical.
Maximum Safe Input Voltage	16 dBm, or ± 2 V (DC + peak AC)
Nominal Input Impedance	(50 \pm 1)
Input connectors	SMA (F)
Deskew (The difference in delay between channels)	Can be nulled out with 1-ps resolution to compensate for differences in input cables or probe length. Up to 100 ns of skew can be nulled out.
Attenuation	Attenuation factors may be entered to scale the oscilloscope for external attenuators connected to the channel inputs
Range	0.00001:1 to 1,000,000:1
Units	Ratio or dB
Scale	Volt, Watt, Ampere, or Unknown

Channel-to-channel isolation =45 dB for input frequency DC to 8.5 GHz, =35 dB for input frequency >8.5 GHz to 12 GHz.

4.3 Optical Channel (PicoScope 9221A/9231A)

Unfiltered Optical Bandwidth	DC to 8 GHz typical. <i>DC to 7 GHz guaranteed @ Full Electrical Bandwidth.</i>
Effective Wavelength Range	750 nm to 1650 nm
Calibrated wavelengths	850 nm (MM), 1310 nm (MM/SM), 1550 nm (SM)
Transition time (10% to 90% calculated from $T_r = 0.48/BW$ optical)	60 ps, max
RMS noise, maximum	4 μW (1310 & 1550 nm), 6 μW (850 nm)
Scale Factors (Sensitivity)	1 $\mu V/div$ to 400 $\mu V/div$ (full scale is 8 divisions)
DC Accuracy, typical	$\pm 25 \mu W \pm 10%$ of full vertical scale
Maximum input peak power	+7 dBm (1310 nm)
Fiber Input	Single-mode (SM) or Multi-mode (MM)
Fiber input connector	FC/PC
Input Return Loss	SM: -24 dB, typical MM: -16 dB, typical, -14 dB, maximum
Optional Filter Data Rates	51.8 Mb/s (OC1/STM0) 155 Mb/s (OC3/STM1) 622 Mb/s (OC,12/STM4) 1.250 Gb/s (GBE) 2.488 Gb/s (OC48/STM16) 2.500 Gb/s (Infiniband 2.5G)

4.4 Time Base (Horizontal)

Time Bases	Main, Intensified, Delayed, or Dual Delayed
Scale Factors	Full scale is 10 divisions
Main Time Base	10 ps/div to 50 ms/div. Adjustable in a 1-2-5-10 sequence. Also adjustable in 0,1% fine increment.
Delayed Time bases	10 ps/div to current Main Time Base setting. Adjustable in a 1-2-5-10 sequence. Also adjustable in 0.1% fine increments.
Sampling Methods	
Sequential Equivalent Time Sampling	Acquires one sample per trigger. Time base from 10 ps/div to <1 $\mu s/div$.
Combine Equivalent Time Sampling	Acquires a packet of samples per one trigger. Time Base from =1 $\mu s/div$ to <10 $\mu s/point$.
Sequential Real Time Sampling	Acquires full acquisition per one trigger. Time Base from =10 $\mu s/point$ to 50 ms/div.

Delta Time Interval Accuracy	<p><i>For > 450 ps/div: $\pm 0,2\%$ of of Delta Time Interval ± 15 ps.</i></p> <p><i>For = 450 ps/div: ± 15 ps or $\pm 5\%$ of of Delta Time Interval ± 5 ps, whichever is smaller.</i></p> <p>Note: at a temperature within $\pm 3^{\circ}\text{C}$ of horizontal calibration temperature.</p>
Typical Timing Accuracy	The time base uses a series of near 4.7-ns blocks. Time base linearity and small discontinuities across these blocks contribute to the 15-ps accuracy specification.
Variable Delay (Time offset relative to trigger)	Up to 10000 screen widths of Delayed Time Base or 499.95 ms, whichever is smaller.
Minimum Delay (Minimum time offset relative to trigger)	< 40 ns
Display Units	Time or Bit Period
Time Interval Resolution	<p>$= (\text{screen width}) / (\text{record length})$ or 200 fs, whichever is larger.</p> <p>Note: The time interval resolution is the smallest time you can resolve between two points.</p>

4.5 Trigger

4.5.1 Trigger

Trigger Sources	External Direct Trigger, External Prescaled Trigger, Internal Clock Trigger (internally connected to direct trigger), Clock Recovery Trigger (for PicoScope 9211/9221/9231)
Trigger Modes	Triggered: causes the scope to trigger synchronously with the trigger input signal. Freerun: causes the scope to generate its own triggers.
Trigger Holdoff	Adjustable from 5 μs to 1 s in a 1-2-5-10 sequence, or in 8 ns increments.
Internal Clock Repetition Rate	16 ns to 2 ms in a 1-2-5-10 sequence, or in 8 ns increments.

4.5.2 Direct Trigger

Direct Trigger Bandwidth and Sensitivity	
Normal Hysteresis	<i>100 mV p-p DC to 100 MHz. Increasing linearly from 100 mV p-p at 100 MHz to 200 mV p-p at 1 GHz. Pulse Width: 500 ps @ 200 mV p-p</i>
High Sensitivity Hysteresis, typical	<i>50 mV p-p at 100 MHz. Increasing linearly from 50 mV p-p at 100 MHz to 100 mV p-p at 1 GHz.</i>
RMS Direct Trigger Jitter	<p><i>3.5 ps + 20 ppm of delay setting, typical.</i></p> <p><i>4 ps + 20 ppm of delay setting, maximum.</i></p> <p>Note: Measured at 1 GHz with the triggering level adjusted for optimum trigger</p>

Trigger Slope	Positive: triggers on rising edge. Negative: triggers on falling edge.
Direct Trigger Level Range	-1 V to 1 V
Direct Trigger Level Resolution	1 mV
Direct Trigger Level Accuracy	$\pm (50 \text{ mV} + 0.1 \text{ of trigger level})$
Direct Trigger Hysteresis	Normal: the trigger hysteresis is set so the instrument meets the trigger sensitivity specification. High Sensitivity: hysteresis is turned off to allow a best sensitivity to high-frequency signals. This mode should not be used for noisy lower-frequency signals that may mistrigger without hysteresis.
Maximum Safe Direct Trigger Input Voltage	16 dBm, or $\pm 2 \text{ V}$ (DC + peak AC)
Direct Trigger Nominal Input Impedance	(50 ± 1)
Direct Trigger Coupling	DC coupled
Direct Trigger Input Connector	SMA (F)

4.5.3 Prescaled Trigger

Prescaled Trigger Bandwidth and Sensitivity (Sine Wave Input)	200 mV p-p to 2 V p-p from 1 GHz to 7 GHz, 300 mV p-p to 1 V p-p from 7 GHz to 8 GHz. 400 mV p-p to 1 V p-p from 8 GHz to 10 GHz, typical.
Prescaled Trigger RMS Jitter	3.5 ps + 20 ppm of delay setting, typical. 4 ps + 20 ppm of delay setting, maximum.
Prescaled Trigger input characteristics	50 Ω , AC coupled, divide-by-32 prescaler ratio, fixed level zero volts.
Prescaled Trigger Maximum Safe Input Voltage	$\pm 2 \text{ V}$ (DC+peak AC)
Prescaled Trigger Input Connector	SMA (F)

4.5.4 Clock Recovery Trigger (PicoScope 9211A & 9221A)

Clock Recovery Trigger Data Rate and Sensitivity	50 mV p-p from 12.3 Mb/s to 1 Gb/s. 100 mV p-p from 1 Gb/s to 2.7 Gb/s. Continuous Rate.
Recovered Clock RMS Trigger Jitter, maximum	1 ps + 1.0% of Unit Interval
Clock Recovery Trigger input characteristics	50 Ω , AC coupled.

Clock Recovery Trigger Maximum Safe Input Voltage	±2 V (DC+peak AC)
Clock Recovery Trigger Input Connector	SMA (F)

4.5.5 Pattern Sync Trigger (Picoscope 9211A/9221A/9231A)

Pattern Sync Trigger Clock Frequency	External Direct Trigger: 10 MHz to 1 GHz. External Prescaled Trigger: 1 GHz to 8 GHz (1 GHz to 10 GHz, typical). Clock Recovery Trigger: 12.3 GHz to 2.7 GHz.
Divider Ratio	External Direct Trigger: <250 MHz: 1; 250 MHz to <500 MHz: 2; 500 MHz to <1 GHz: 4. External Prescaled Trigger: 1 GHz to <8 GHz: 32; 8 GHz to 10 GHz (typical): 64. Clock Recovery Trigger: 12.3 MHz to <1 GHz: 4; 1 GHz to <2 GHz: 8; 2 GHz to <2.7 GHz: 16.
Programmable Pattern Length	Minimum: 7. Maximum: 65535 ($2^{16}-1$).
Eye Line mode	Displays averaged eye diagrams
Start bit	0 to (Pattern Length - 7) bits
Scan bits	1 to (65535 - Start bit)

4.6 Acquisition

Digital feedback	Multi-valued signal: Digital feedback is off. Single-valued signal: Digital feedback is on.
Number of Acquisition Channels	2 (simultaneous acquisition)
ADC Resolution	16 bits
Digitizing Rate	DC to 200 kHz maximum. The signal is sampled and digitized at a rate dictated by the trigger repetition rate and the time base range.
Acquisition Modes	Sample (normal), Average, Envelope
Average Modes	Stable or Multiple
Number of averages	From 2 to 4096 in x2 sequence
Envelope Modes	Min, Max or both Min-Max values acquired over one or more acquisitions.
Number of envelopes	From 2 to 4096 in x2 sequence, and continuously.
Data Record Length	32 to 4096 points maximum per channel in x2 sequence

4.7 Display

Display Resolution	Variable. Default resolution:
--------------------	----------------------------------

Display Style	<p>Full: 800 points horizontally x 600 points vertically. Data: 501 points horizontally x 257 points vertically.</p> <p>Dots. Vectors. Variable Persistence: time that each data point is retained on the display. Persistence time can be varied from 100 ms to 20 s. Infinite Persistence. Variable Gray Scaling: five levels of a single color that is varied in saturation and luminosity. Refresh time can be varied from 1 s to 200 s. Infinite Gray Scaling. Variable color Grading: with color Grading selected, historical timing information is represented by a temperature or spectral color scheme providing "z-axis" information about rapidly changing waveforms. Refresh time can be varied from 1 to 200 s. Infinite color Grading.</p>
Graticule	Full Grid, Axes with tick marks, Frame with tick marks, Off (no graticule).
Screen	<p>Single: all waveforms are superimposed and are eight divisions high. Dual: with two graticules, all waveforms can be four divisions high, displayed separately or superimposed. Quad: with four graticules, all waveforms can be two divisions high, displayed separately or superimposed. When you select dual or quad screen display, every waveform channel, memory and function can be placed on a specified graticule.</p>
Display Format	YT only, XY only, or both YT & XY.
Colors	You may choose a default color selection, or select your own color set. Different colors are used for displaying selected items: background, channels, functions, waveform memories, FFTs, TDR/TDTs, and histograms.

4.8 Save/Recall

Management

Store and recall setups, waveforms, and screen images to any drive on your PC. Storage capacity is limited only by disk space.

File extensions

Waveform files:
 .wfm for binary format
 .txt for text format
 Data base files: .cgs.
 Setup files: .set.

Operating System	Microsoft Windows® XP or Vista.
Waveform Save/Recall	Up to four waveforms may be stored into the waveform memories (M1-M4), and then recalled for display.
Save/Recall to Disk	You can save or recall your acquired waveforms to or from any drive on the PC. To save a waveform, use the standard Windows "Save as" dialog box. From this dialog box you can create subdirectories and waveform files, or overwrite existing waveform files. You can load, into one of Waveform Memories, a file with a waveform you have previously saved and then recall it for display.
Save/Recall Setups	The instrument can store complete setups in the memory and then recall them.
Autoscale	Pressing the Autoscale key automatically adjusts the vertical channels, the horizontal scale factors, and the trigger level for a display appropriate to the signals applied to the inputs. The Autoscale feature requires a repetitive signal with a frequency greater than 1 kHz, duty cycle greater than 1%, amplitudes greater than 50 mV p-p (vertical) and 200 mV p-p (trigger). Autoscale is operative only for relatively stable input signals.

4.9 Marker

Marker Type	X-Marker: vertical bars (measure time). Y-Marker: horizontal bars (measure volts). XY-Markers: waveform markers (x and +).
Marker Measurements	Absolute, Delta, Volt, Watt, Rho, Time, Frequency, Distance, Phase, Slope.
Marker Modes	Independent: both markers can be adjusted independently. Paired: both markers can be adjusted together.
Ratiometric measurements	Provide ratiometric measurements between measured and reference values. These measurements give results in such ratiometric units as %, dB, and degrees.

4.10 Measure

Automated Measurements	Up to ten simultaneous measurements, or four statistics measurements, are supported at the same time.
Automatic Parametric	53 automatic measurements available
Amplitude Measurements	Maximum, Minimum, Peak-Peak, Top, Base, Amplitude, Middle, Mean, DC RMS, AC RMS, Area, Cycle Mean, Cycle DC RMS, Cycle AC RMS, Cycle Area, Positive Overshoot, Negative Overshoot.

Timing Measurements	Period, Frequency, Positive Width, Negative Width, Rise Time, Fall Time, Positive Duty Cycle, Negative Duty Cycle, Positive Crossing, Negative Crossing, Burst Width, Cycles, Time at Maximum, Time at Minimum, Positive Jitter p-p, Positive Jitter RMS, Negative Jitter p-p, Negative Jitter RMS.
Dual-Channel Measurements	Delay (8 options), Phase Deg, Phase Rad, Phase %, Gain, Gain dB.
FFT Measurements	FFT Magnitude, FFT Delta Magnitude, THD, FFT Frequency, FFT Delta Frequency.
Measurement Statistics	Display minimum, maximum, mean and standard deviation on any displayed waveform measurements.
Method of Top-Base Definition	Histogram, Min/Max, or User-Defined (in absolute voltage).
Thresholds	Settable in percentage, voltage or divisions. Standard thresholds are 10-50-90 % or 20-50-80 %.
Margins	Any region of the waveform may be isolated for measurement using vertical bars
Measurement Mode	Repetitive or Single-shot

4.11 Limit Test

Limit Test	Signals can be tested by up to four automatic parametric measurements and compared to user-defined test boundaries. Failure tolerances can be selected independently for each of the parametric tests. Limit test can be set to run continuously for a user-selected number of waveforms, or for a defined number of failures.
On failure actions	Beep, Save failed waveform to disk or Stop acquisition

4.12 Mathematics

Waveform Math	Up to four math waveforms can be defined and displayed using math functions F1-F4
Math Operators	Add, Subtract, Multiply, Divide, Invert, Absolute, Exponentiation (e), Exponentiation (10), Logarithm (e), Logarithm (10), Differentiate, Integrate, Inverse FFT, Linear Interpolation, Sin (x)/x Interpolation, Smoothing, Trend.
Operands	Any channel, waveform memory, math function, spectrum, or constant can be selected as a source for one of two operands.

4.13 FFT

FFT	Up to two fast Fourier transforms can be run simultaneously
Frequency Span	$\text{Frequency Span} = \text{Sample Rate} / 2 = \text{Record Length} / (2 \times \text{Time Base Range})$
Frequency Resolution	$\text{Frequency Resolution} = \text{Sample Rate} / \text{Record Length}$
FFT Windows	The built-in filters (Rectangular, Nicolson, Hanning, Flattop, Blackman- Harris and Kaiser-Bessel) allow optimization of frequency resolution, transients, and amplitude accuracy.
FFT Measurements	Marker measurements can be made on frequency, delta frequency, magnitude, and delta magnitude. Automated FFT Measurements include: FFT Magnitude, FFT Delta Magnitude, THD, FFT Frequency, and FFT Delta Frequency.

4.14 Zoom

Zoom feature	The zoom feature allows waveforms (memories, functions, and spectrums) to be expanded and positioned in both vertical and horizontal axes. Allows precise comparison and study of fine waveform detail without affecting ongoing acquisitions.
Complex Scale	You can select different Complex Scale: Magnitude, Phase, Magnitude + Phase, Real, Imaginary, and Real + Imaginary.
Vertical expanding and positioning	Zoom provides a vertical dynamic range of 10 million divisions or 1 million screens
Horizontal expanding and positioning	Zoom provides a horizontal dynamic range of 640 divisions or 64 screens

4.15 Histogram

Histogram Axis	Vertical, or Horizontal. Both vertical and horizontal histograms, with periodically updated measurements, allow statistical distributions to be analysed over any region of the signal.
Histogram Measurement Set	Scale, Offset, Hits in Box, Peak Hits, Pk-Pk, Median, Mean, Standard Deviation, Mean \pm 1 Std Dev, Mean \pm 2 Std Dev, Mean \pm 3 Std Dev.
Histogram Window	The histogram window determines which part of the database is used to plot the histogram. You can set the size of the histogram window to be any size that you want within the horizontal and vertical scaling limits of the scope.

4.16 Eye-Diagram

Eye Diagram

The PicoScope 9000 can automatically characterise an NRZ and RZ eye pattern. Measurements are based upon statistical analysis of the waveform.

NRZ Measurement Set

AC RMS, Area, Bit Rate, Bit Time, Crossing %, Crossing Level, Crossing Time, Cycle Area, Duty Cycle Distortion (%), Extinction Ratio (dB, %, ratio), Eye Amplitude, Eye High, Eye High dB, Eye Width (%), Fall Time, Frequency, Jitter (p-p, RMS), Max, Mean, Mid, Min, Negative Overshoot, Noise p-p (One, Zero), Noise RMS (One, Zero), One Level, Peak-Peak, Period, Positive Overshoot, Rise Time, RMS, Signal-to-Noise Ratio, Signal-to-Noise Ratio dB, Zero Level.

RZ Measurement Set

AC RMS, Area, Bit Rate, Bit Time, Contrast Ratio (dB, %, ratio), Cycle Area, Extinction Ratio (dB, %, ratio), Eye Amplitude, Eye High, Eye High dB, Eye Opening Factor, Eye Width (%), Fall Time, Jitter P-p (Fall, Rise), Jitter RMS (Fall, Rise), Max, Mean, Mid, Min, Negative Crossing, Noise P-p (One, Zero), Noise RMS (One, Zero), One Level, Peak-Peak, Positive Crossing, Positive Duty Cycle, Pulse Symmetry, Pulse Width, Rise Time, RMS, Signal-to-Noise, Zero Level.

4.17 Mask Test

Mask Test

Acquired signals are tested for fit outside areas defined by up to eight polygons. Any samples that fall within the polygon boundaries result in test failures. Masks can be loaded from disk, or created automatically or manually.

Mask Creation

You can create the following Mask: Standard predefined Mask, Automask, Mask saved on disk, Create new mask, Edit any mask.

Standard Mask

Standard predefined optical or standard electrical masks can be created.

SONET/SDH

OC1/STMO (51.84 Mb/s)
 OC3/STM1 (155.52 Mb/s)
 OC9/STM3 (466.56 Mb/s)
 OC12/STM4 (622.08 Mb/s)
 OC18/STM6 (933.12 Mb/s)
 OC24/STM8 (1.2442 Gb/s)
 OC48/STM16 (2.48832 Gb/s)
 FEC2666 (2.6666 Gb/s)

Fiber Channel

FC133 Electrical (132.8 Mb/s)
 FC133 Optical (132.8 Mb/s)
 FC266 Electrical (265.6 Mb/s)
 FC266 Optical (265.6 Mb/s)
 FC531 Electrical (531.35 Mb/s)
 FC531 Optical (531.35 Mb/s)

	FC1063 Electrical (1.0625 Gb/s) FC1063 Optical (1.0625 Gb/s) FC1063 Optical PI Rev13 (1.0625 Gb/s) FC1063E Abs Beta Rx.mask (1.0625 Gb/s) FC1063E Abs Beta Tx.mask (1.0625 Gb/s) FC1063E Abs Delta Rx.mask (1.0625 Gb/s) FC1063E Abs Delta Tx.mask (1.0625 Gb/s) FC1063E Abs Gamma Rx.mask (1.0625 Gb/s) FC1063E Abs Gamma Tx.mask (1.0625 Gb/s) FC2125 Optical (2.1231 Gb/s) FC2125 Optical PI Rev13 (2.1231 Gb/s) FC2125E Abs Beta Rx.mask (2.125 Gb/s) FC2125E Abs Beta Tx.mask (2.125 Gb/s) FC2125E Abs Delta Rx.mask (2.125 Gb/s) FC2125E Abs Delta Tx.mask (2.125 Gb/s) FC2125E Abs Gamma Rx.mask (2.125 Gb/s) FC2125E Abs Gamma Tx.mask (2.125 Gb/s) FC4250 Optical PI Rev13 (4.25 Gb/s) FC4250E Abs Beta Rx.mask (4.25 Gb/s) FC4250E Abs Beta Tx.mask (4.25 Gb/s) FC4250E Abs Delta Rx.mask (4.25 Gb/s) FC4250E Abs Delta Tx.mask (4.25 Gb/s) FC4250E Abs Gamma Rx.mask (4.25 Gb/s) FC4250E Abs Gamma Tx.mask (4.25 Gb/s)
Ethernet	1.25 Gb/s 1000Base-CX Absolute TP2 (1.25 Gb/s) 1.25 Gb/s 1000Base-CX Absolute TP3 (1.25 Gb/s) GB Ethernet (1.25 Gb/s) 2XGB Ethernet (2.5 Gb/s) 3.125 Gb/s 10GBase-CX4 Absolute TP2 (3.125 Gb/s)
Infiniband	2.5G InfiniBand Cable mask (2.5 Gb/s) 2.5G InfiniBand Driver Test Point 1 (2.5 Gb/s) 2.5G InfiniBand Driver Test Point 10 (2.5 Gb/s) 2.5G InfiniBand Driver Test Point 2 (2.5 Gb/s) 2.5G InfiniBand Driver Test Point 3 (2.5 Gb/s) 2.5G InfiniBand Driver Test Point 4 (2.5 Gb/s) 2.5G InfiniBand Driver Test Point 5 (2.5 Gb/s) 2.5G InfiniBand Driver Test Point 6 (2.5 Gb/s) 2.5G InfiniBand Driver Test Point 7 (2.5 Gb/s) 2.5G InfiniBand Driver Test Point 8 (2.5 Gb/s) 2.5G InfiniBand Driver Test Point 9 (2.5 Gb/s) 2.5G InfiniBand Receiver mask (2.5 Gb/s) InfiniBand (2.5 Gb/s) 5.0G InfiniBand Driver Test Point 1 (5 Gb/s) 5.0G InfiniBand Driver Test Point 6 (5 Gb/s) 5.0G InfiniBand Transmitter Pins (5 Gb/s)
XAUI	3.125 Gb/s XAUI Far End (3.125 Gb/s) 3.125 Gb/s XAUI Far End (3.125 Gb/s) XAUI-E Far (3.125 Gb/s) XAUI-E Near (3.125 Gb/s)
ITU G.703	DS1, 100 Ohm twisted pair, (1.544 Mb/s) 2 Mb 120, 120 Ohm twisted pair, (2.048 Mb/s)

	2 Mb 75, 75 Ohm coax, (2.048 Mb/s)
	DS2 110, 110 Ohm twisted pair, (6.312 Mb/s)
	DS2 75, 75 Ohm coax, (6.312 Mb/s)
	8 Mb, 75 Ohm coax, (8.448 Mb/s)
	34 Mb, 75 Ohm coax, (34.368 Mb/s)
	DS3, 75 Ohm coax, (44.736 Mb/s)
	140 Mb 0, 75 Ohm coax, (139.264 Mb/s)
	140 Mb 1, 75 Ohm coax, (139.264 Mb/s)
	140 Mb 1 Inv, 75 Ohm coax, (139.264 Mb/s)
	155 Mb 0, 75 Ohm coax, (155.520 Mb/s)
	155 Mb 1, 75 Ohm coax, (155.520 Mb/s)
	155 Mb 1 Inv, 75 Ohm coax, (155.520 Mb/s)
ANSI T1/102	DS1, 100 Ohm twisted pair, (1.544 Mb/s)
	DS1C, 100 Ohm twisted pair, (3.152 Mb/s)
	DS2, 110 Ohm twisted pair, (6.312 Mb/s)
	DS3, 75 Ohm coax, (44.736 Mb/s)
	STS1 Eye, 75 Ohm coax, (51.84 Mb/s)
	STS1 Pulse, 75 Ohm coax, (51.84 Mb/s)
	STS3, 75 Ohm coax, (155.520 Mb/s)
Rapid IO	RapidIO Serial Level 1, 1.25G Rx (1.25 Gb/s)
	RapidIO Serial Level 1, 1.25G Tx LR (1.25 Gb/s)
	RapidIO Serial Level 1, 1.25G Tx SR (1.25 Gb/s)
	RapidIO Serial Level 1, 2.5G Rx (2.5 Gb/s)
	RapidIO Serial Level 1, 2.5G Tx LR (2.5 Gb/s)
	RapidIO Serial Level 1, 2.5G Tx SR (2.5 Gb/s)
	RapidIO Serial Level 1, 3.125G Rx (3.125 Gb/s)
	RapidIO Serial Level 1, 3.125G Tx LR (3.125 Gb/s)
	RapidIO Serial Level 1, 3.125G Tx SR (3.125 Gb/s)
G.984.2	XAUI-E Far (3.125 Gb/s)
PCI Express	R1.0a 2.5G Add-in Card Transmitter Non-Transition bit mask (2.5 Gb/s)
	R1.0a 2.5G Add-in Card Transmitter Transition bit mask (2.5 Gb/s)
	R1.0a 2.5G Exp.Card Host Non-Transition bit mask (2.5 Gb/s)
	R1.0a 2.5G Exp.Card Host Transition bit mask (2.5 Gb/s)
	R1.0a 2.5G Exp.Card Module Non-Transition bit mask (2.5 Gb/s)
	R1.0a 2.5G Exp.Card Module Transition bit mask (2.5 Gb/s)
	R1.0a 2.5G Exp.Card Transmitter Non-Transition bit mask (2.5 Gb/s)
	R1.0a 2.5G Exp.Card Transmitter Transition bit mask (2.5 Gb/s)
	R1.0a 2.5G Mobile Transmitter bit mask (2.5 Gb/s)
	R1.0a 2.5G Receiver mask (2.5 Gb/s)
	R1.0a 2.5G System Board Transmitter Non-Transition bit mask (2.5 Gb/s)
	R1.0a 2.5G System Board Transmitter Transition bit mask (2.5 Gb/s)

R1.0a 2.5G Transmitter Non-Transition bit mask (2.5 Gb/s)
R1.0a 2.5G Transmitter Transition bit mask (2.5 Gb/s)
R1.1 2.5G Add-in Card Transmitter Non-Transition bit mask (2.5 Gb/s)
R1.1 2.5G Add-in Card Transmitter Transition bit mask (2.5 Gb/s)
R1.1 2.5G Cable Receiver End Non-Transition bit mask (2.5 Gb/s)
R1.1 2.5G Cable Receiver End Transition bit mask (2.5 Gb/s)
R1.1 2.5G Cable Transmitter End Non-Transition bit mask (2.5 Gb/s)
R1.1 2.5G Cable Transmitter End Transition bit mask (2.5 Gb/s)
R1.1 2.5G Express Module System Non-Transition bit mask (2.5 Gb/s)
R1.1 2.5G Express Module System Transition bit mask (2.5 Gb/s)
R1.1 2.5G Express Module Transmitter Path Non-Transition bit mask (2.5 Gb/s)
R1.1 2.5G Express Module Transmitter Path Transition bit mask (2.5 Gb/s)
R1.1 2.5G Receiver mask (2.5 Gb/s)
R1.1 2.5G System Board Transmitter Non-Transition bit mask (2.5 Gb/s)
R1.1 2.5G System Board Transmitter Transition bit mask (2.5 Gb/s)
R1.1 2.5G Transmitter Non-Transition bit mask (2.5 Gb/s)
R1.1 2.5G Transmitter Transition bit mask (2.5 Gb/s)
R2.0 5.0G Add-in Card 35 dB Transmitter Non-Transition bit mask (5 Gb/s)
R2.0 5.0G Add-in Card 60 dB Transmitter Non-Transition bit mask (5 Gb/s)
R2.0 5.0G Add-in Card 35 dB Transmitter Transition bit mask (5 Gb/s)
R2.0 5.0G Add-in Card 60 dB Transmitter Transition bit mask (5 Gb/s)
R2.0 5.0G Mobile Transmitter mask (5 Gb/s)
R2.0 5.0G Receiver mask (5 Gb/s)
R2.0 5.0G System Board Transmitter Non-Transition bit mask (5 Gb/s)
R2.0 5.0G System Board Transmitter Transition bit mask (5 Gb/s)
R2.0 5.0G Transmitter Non-Transition bit mask (5 Gb/s)
R2.0 5.0G Transmitter Transition bit mask (5 Gb/s)
R2.1 5.0G Transmitter Non-Transition bit mask (5 Gb/s)
R2.1 5.0G Transmitter Transition bit mask (5 Gb/s)

Serial ATA	<p>Ext Length, 1.5G 250 Cycle, Rx Mask (1.5 Gb/s)</p> <p>Ext Length, 1.5G 250 Cycle, Tx Mask (1.5 Gb/s)</p> <p>Ext Length, 1.5G 5 Cycle, Rx Mask (1.5 Gb/s)</p> <p>Ext Length, 1.5G 5 Cycle, Tx Mask (1.5 Gb/s)</p> <p>Gen1, 1.5G 250 Cycle, Rx Mask (1.5 Gb/s)</p> <p>Gen1, 1.5G 250 Cycle, Tx Mask (1.5 Gb/s)</p> <p>Gen1, 1.5G 5 Cycle, Rx Mask (1.5 Gb/s)</p> <p>Gen1, 1.5G 5 Cycle, Tx Mask (1.5 Gb/s)</p> <p>Gen1m, 1.5G 250 Cycle, Rx Mask (1.5 Gb/s)</p> <p>Gen1m, 1.5G 250 Cycle, Tx Mask (1.5 Gb/s)</p> <p>Gen1m, 1.5G 5 Cycle, Rx Mask (1.5 Gb/s)</p> <p>Gen1m, 1.5G 5 Cycle, Tx Mask (1.5 Gb/s)</p> <p>Ext Length, 3.0G 250 Cycle, Rx Mask (3 Gb/s)</p> <p>Ext Length, 3.0G 250 Cycle, Tx Mask (3 Gb/s)</p> <p>Ext Length, 3.0G 5 Cycle, Rx Mask (3 Gb/s)</p> <p>Ext Length, 3.0G 5 Cycle, Tx Mask (3 Gb/s)</p> <p>Gen1, 3.0G 250 Cycle, Rx Mask (3 Gb/s)</p> <p>Gen1, 3.0G 250 Cycle, Tx Mask (3 Gb/s)</p> <p>Gen1, 3.0G 5 Cycle, Rx Mask (3 Gb/s)</p> <p>Gen1, 3.0G 5 Cycle, Tx Mask (3 Gb/s)</p> <p>Gen1m, 3.0G 250 Cycle, Rx Mask (3 Gb/s)</p> <p>Gen1m, 3.0G 250 Cycle, Tx Mask (3 Gb/s)</p> <p>Gen1m, 3.0G 5 Cycle, Rx Mask (3 Gb/s)</p> <p>Gen1m, 3.0G 5 Cycle, Tx Mask (3 Gb/s)</p>
Mask Margin	Available for industry standard mask testing
Automask Creation	Masks are created automatically for single-valued voltage signals. Automask specifies both delta X and delta Y tolerances. The failure actions are identical to those of limit testing.
Data collected during test	Total number of waveforms examined, number of failed samples, number of hits within each polygon boundary

4.18 Generators (PicoScope 9211A/9231A)

Output Channels	Two channels: Output 1 and Output 2.
Trigger	Via Internal Clock Trigger (internally connected to direct trigger).
Modes	<p>Step: Generates a pulse having one leading step per acquisition cycle with a fixed pulse width.</p> <p>Coarse TB: Generates an oscillation synchronous with coarse timebase generator and having frequency near 210 MHz.</p> <p>Pulse: Generates pulses with selectable period, width, and delay. Slope and deskew can be selected for each channel independently.</p> <p>NRZ: Outputs a selectable PRBS (pseudorandom binary sequence) polynomial of NRZ format. Clock, period and pattern length are selectable. Internal trigger is selectable between clock and pattern. Slope and deskew between channels can be selected for each channel independently.</p>

	RZ: Outputs a selectable PRBS polynomial of RZ format. Clock, period and pattern length are selectable. Internal trigger is selectable between clock and pattern. Slope and deskew between channels can be selected for each channel independently.
Step Mode	
Width	Fixed value between 580 ns and 640 ns.
Delay	Range: 0 to 15 steps. Step: near 4.7 ns.
Rise/Fall Time (20% to 80%)	<i>130 ps or less @ 50 external termination.</i> 100 ps typ.
Aberrations	<i>± 4% or less over the zone 2 ns before leading step transition.</i> <i>+ 2%, -15% or less for the first 3 ns following leading step transition.</i> <i>+ 2%, -5% or less over the zone 3 ns to 20 ns following leading step transition.</i> <i>± 2% or less over the zone 20 ns to 500 ns following leading step transition.</i>
Output High Level	<i>0 V to -50 mV @ 50 external termination.</i>
Output Low Level	<i>-330 mV to -470 mV @ 50 external termination.</i>
RMS Jitter	4.5 ps + 20 ppm of delay setting, typical. <i>5 ps + 20 ppm of delay setting, maximum @ 50% DESKEW control.</i>
Coarse TB Mode	Frequency between 200 MHz and 220 MHz
Pulse Mode	
Period	Range: 8 ns to 524 μ s. Resolution: 4 digits or 8 ns, whichever is larger. <i>Accuracy: 100 ppm.</i>
Width	Range (for =40 ns period): 18 ns to (Period - 14 ns). Resolution: 4 digits or 8 ns, whichever is larger. <i>Accuracy: ±(1 ns + 100 ppm*Width).</i>
Delay	Range: 0 ns to (Period - 16 ns). Resolution: 4 digits or 8 ns, whichever is larger. <i>Accuracy: ±(1 ns + 100 ppm*Delay).</i>
RMS Jitter	30 ps, typical
NRZ Mode	
Clock	Range: 8 ns to 524 μ s. Resolution: 4 digits or 8 ns, whichever is larger. <i>Accuracy: 100 ppm.</i>
Delay	Range: 0 ns to (Clock - 16 ns) for Clock =32 ns. Resolution: 4 digits or 8 ns, whichever is larger. <i>Accuracy: ±(1 ns + 100 ppm*Delay).</i>
Pattern Length	2^7-1 (127 bits), $2^{10}-1$ (1023 bits), $2^{11}-1$ (2047 bits), $2^{15}-1$ (32767 bits).

Internal Trigger Source	Clock or Pattern.
RZ Mode	
Clock	Range: 16 ns to 524 μ s. Resolution: 4 digits or 16 ns, whichever is larger. Accuracy: 100 ppm.
Delay	Range: 0 ns to (Clock - 16 ns) for Clock = 32 ns. Resolution: 4 digits or 8 ns, whichever is larger. Accuracy: $\pm(1 \text{ ns} + 100 \text{ ppm} * \text{Delay})$.
Pattern Length	2^7-1 (127 bits), $2^{10}-1$ (1023 bits), $2^{11}-1$ (2047 bits), $2^{15}-1$ (32767 bits).
Internal Trigger Source	Clock or Pattern.
Slope	Positive or Negative. Can be selected for each channel independently.
Deskew between channels	Range: ± 250 ps typ. Resolution: 1 ps typ. Can be selected for each channel independently.

4.19 TDR/TDT (PicoScope 9211A/9231A)

TDR/TDT channels	2
TDR Stimulus	Internal generators (Output 1 or Output 2), or External
Step Transition	Internal generator: negative only. External generator: positive or negative.
TDR Incident Step Amplitude	
Output High Level	0 V to -25 mV @ 50 Ω external termination.
Output Low Level	-165 mV to -235 mV @ 50 Ω external termination
TDR Reflected Step Amplitude	(188 \pm 34) mV. (94 \pm 17) mV on the screen.
TDT Step Amplitude	
Output High Level	0 V to -50 mV @ 50 Ω external termination.
Output Low Level	-330 mV to -470 mV @ 50 Ω external termination
TDR Incident System Rise Time (Combined Oscilloscope, Step Generator and TDR, 20% to 80%)	100 ps or less @ 50 Ω external termination, typical
TDR Reflected System Rise Time (Combined Oscilloscope, Step Generator and TDR, 20% to 80%)	100 ps or less @ 50 Ω external termination, typical

TDR Aberrations	<p>$\pm 10\%$ or less over the zone 2 ns before leading step transition.</p> <p>+5%, -15% or less for the first 3 ns following leading step transition.</p> <p>+3%, -5% or less over the zone 3 ns to 20 ns following leading step transition.</p> <p>$\pm 2\%$ or less over the zone 20 ns to 500 ns following leading step transition.</p>
TDT Incident System Rise Time (Combined Oscilloscope and Step Generator, 20% to 80%)	100 ps or less @ 50 external termination, typical
TDT Aberrations	<p>$\pm 4\%$ or less over the zone 2 ns before leading step transition.</p> <p>+2%, -15% or less for the first 3 ns following leading step transition.</p> <p>+2%, -5% or less over the zone 3 ns to 20 ns following leading step transition.</p> <p>$\pm 2\%$ or less over the zone 20 ns to 500 ns following leading step transition.</p>
Corrected Characteristic for internal generators	<p>Minimum Rise Time: 100 ps or 0.1 x time/div, whichever is greater, typical.</p> <p>Maximum: 3 x time/div, typical.</p>
TDR Normalized Aberration for internal generators	=3% typical
TDT Normalized Aberration for internal generators	=0.5% typical
Vertical Scale	Volts, Rho (10 mrho/div to 2 rho/div), Ohm (1 ohm/div to 100 ohm/div).
Horizontal Scale	Time or Distance (Meter, Foot, Inch)
Distance Preset Units	Propagation Velocity (0.1 to 1.0) or Dielectric Constant (1 to 100)

4.20 Power Requirements

Power supply voltage	+6 V \pm 5%
Power supply current	<p>PicoScope 9201A: 1.9 A max.</p> <p>PicoScope 9211A: 2.6 A max.</p> <p>PicoScope 9221A: 2.3 A max.</p> <p>PicoScope 9231A: 2.9 A max.</p>
Protection	Auto shutdown on excess or reverse voltage
AC adaptor	Universal adaptor supplied

4.21 PC connection

PC connection

USB 2.0 (FS). Compatible with USB 1.1.
LAN (PicoScope 9211A/9231A only).

4.22 Physical Characteristics

Dimensions

Width: 170 mm
Height: 40 mm
Depth: 260 mm

Net Weight

1.1 kg

4.23 Environmental Conditions

Temperature

Operating: +5°C to +35°C for normal operation,
+15°C to +25°C for quoted accuracy.
Storage: -20°C to +50°C

Humidity

Operating: Up to 85 % relative humidity (non-
condensing) at +25°C.
Storage: Up to 95 % relative humidity (non-
condensing).

5 Menu

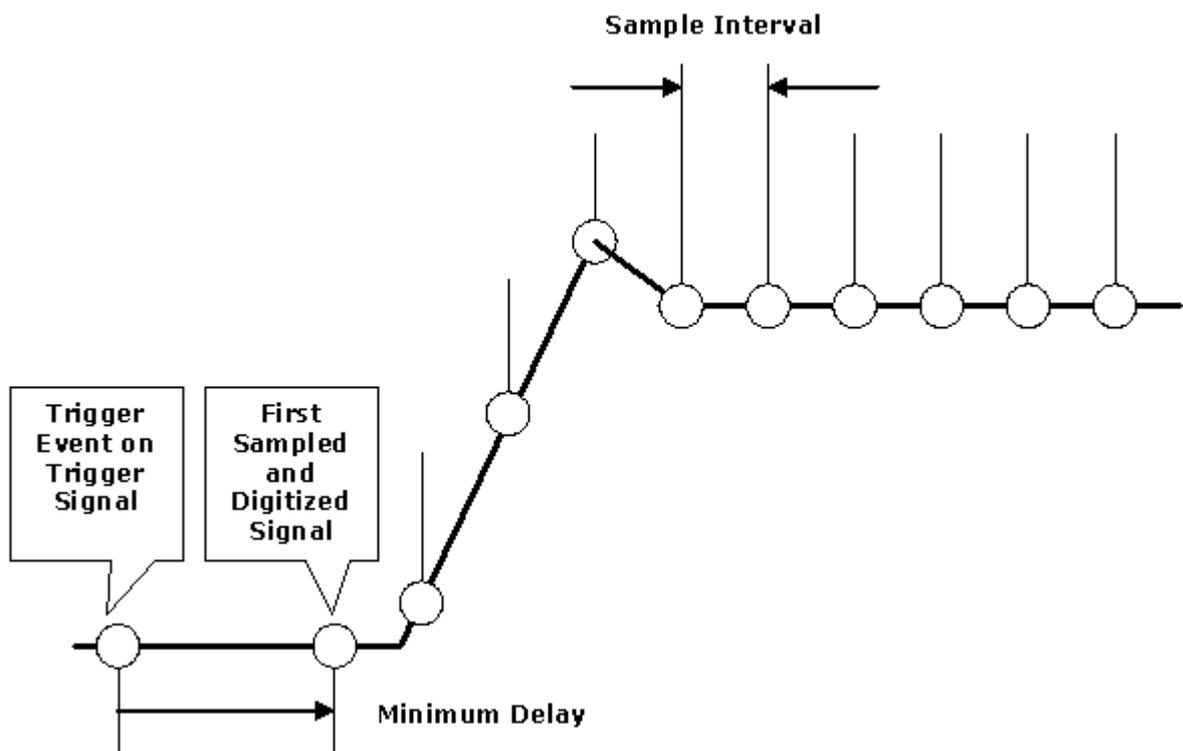
5.1 Acquisition Menu

Acquisition

Acquisition is a process of digitizing data points from a signal and assembling them into a trace record that is shown on the display. Once you have created a trace, acquisition of the signal is continuous and you see a live trace on the display.

How traces are acquired

The PicoScope 9000A uses a sequential sampling technique for acquiring waveforms. When the oscilloscope acquires trace records, it bases the sampling process on a trigger event that occurs on the trigger signal. The trigger signal is independent of the signal being acquired.



Acquisition of a Trace

When the trigger event is detected, the PicoScope 9000 waits a specified period of time before sampling and digitizing the first trace point. The time period is the horizontal position of the trace, which is set using the variables. After the first point is digitized, the PicoScope 9000 waits for another trigger event before sampling and digitizing the second point of the trace record. For the second point, the waiting time between the trigger event and the sampling and digitizing of the point is increased by the sample interval. The acquisition process continues until all the points in the trace are sampled and digitized. Points are acquired in order from left to right, and each point is sampled from a separate trigger event. When all the points in the trace record have been sampled and digitized, the trace is displayed.



For very slow trigger rates with traces that do not involve math functions or operations, a partial trace will be displayed even before all data points are accumulated.

A trace remains on the display until it is replaced by a more recent acquisition or until you clear the trace.

Determining the sample interval

The sample interval is the time difference represented between successive points on the trace record. This is different from the sampling rate, which is the actual time that it takes to sample and digitize the successive points in the trace record. Since only one point is sampled and digitized after a trigger event, the sampling rate is much slower than the sample interval.

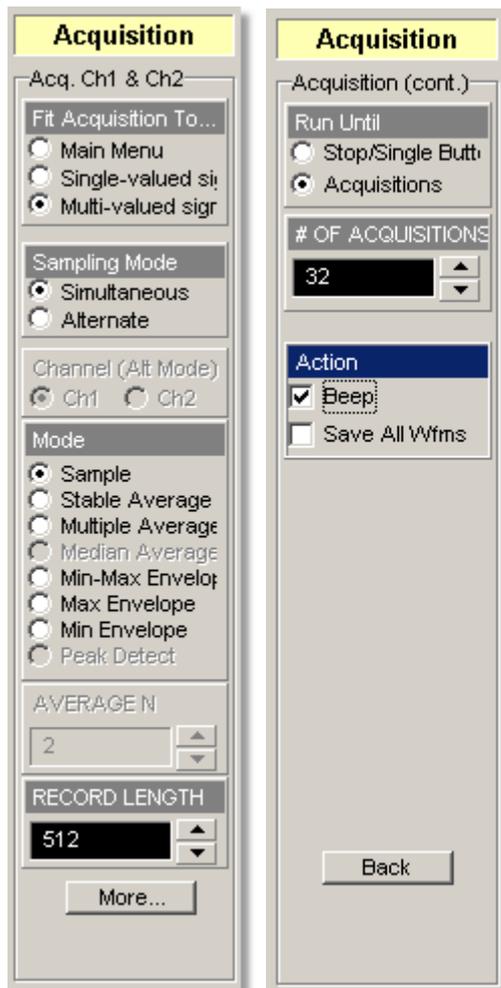
To compute the sample interval, divide the time period that the trace record displays by the number of points in the trace record. For example, if you are display a trace at 10 ns per division, and if the trace has 500 points (record length is equal to 512 points), the sample interval is 10 ns multiplied by 10 (divisions) and divided by 500 (points), or 200 ps.

All traces on the main or intensified time bases have the same record length and horizontal size. Similarly, all traces on delayed or dual delayed time bases share the same record length and horizontal size. This means that the PicoScope 9000 uses one sample interval for main or intensified traces and a different sample interval for delayed or dual delayed traces.

Equivalent sample rate

The sample interval is 1 divided by the equivalent sample rate. The time duration of the data in a channel memory is the time between the sample points times the number of points. For example, if the equivalent sample rate is 100 GSa/s and the memory depth is 500 points/10 divisions, the time between the sample points is 10 ps. 10 ps times 500 points is 5 ns of waveform data stored in the channel memory. Because there are ten horizontal divisions on the display, set the time base to 500 ps/div to show the whole channel memory on the display.

$$\text{Time duration of the record} = \text{record length} / \text{equivalent sampling rate}$$



Acquisition menu

The acquisition system of the PicoScope 9000 has several options for converting analogue data into digital form. The acquisition menu allows you to modify the way the instrument acquires the data from the input waveform by selecting the number of averages or envelopes, detection interval, and record length. Two types of waveforms can be selected for acquiring - single-valued waveforms or multi-valued waveforms.

Acquisition readout and icons

The Acquisition readout at the top-left of the display shows the state of the acquisition system.



Acquisition readout

It shows the following data:

- Equivalent sample rate for each of the channels
- If the Average mode is selected it shows the number of averages (Avg N = XXX)
- If the Envelope mode is selected it shows the number of acquisitions (Env = XXX)

The Acquisition icon at the top right of the display shows the type of waveform that is selected for acquiring:

- The  icon shows acquisition for single-valued waveforms when digital feedback is used
- The  icon shows acquisition for multi-valued waveforms when digital feedback is not used

System controls

You can control the acquisition process at any time by clicking on of the System Controls buttons Run, Stop/Single or Clear Display. For more details see [System Controls](#)^[34].

Using the System Controls, you control whether the oscilloscope is running or stopped.

The Run button  causes the instrument to resume acquiring data. If the instrument is stopped, it starts acquiring data on the next trigger event. If the instrument is already in the run mode, it continues to acquire data on successive trigger events.

The Stop/Single button  causes the instrument to stop acquiring data or to acquire a single waveform. You can stop acquisition if you want to freeze the displayed waveform(s) for closer analysis or measurement.

5.1.1 Fit Acquisition To...



The Fit Acquisition To... menu selects a mode of digital feedback.

Main Menu

The Main Menu mode selects digital feedback mode for all main menus excluding the following cases:

- NRZ or RZ measurement in the Eye Diagram menu is selected
- One of the standard masks for eye-diagram waveforms is selected in the Mask Test menu

When digital feedback mode is selected the  icon appears at the top right of the display. When digital feedback sampling loop mode is not selected the  icon appears at the top right of the display.

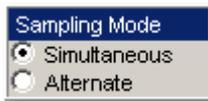
Single-valued signal

The Single-valued signal mode uses a digital feedback architecture that is the best choice for waveforms such as sine waves and pulses. When Single-valued signal mode is selected, the  icon appears at the top right of the display.

Multi-valued signal

The Multi-valued signal mode does not use the digital feedback architecture. This mode is the best choice for waveforms such as eye diagrams. When Multi-valued mode is selected, the  icon appears at the top right of the display.

5.1.2 Sampling Mode



The Sampling Mode menu selects how the signals will be acquired if more than one channel is selected. You can specify Simultaneous or Alternate mode.

Simultaneous

When more than one channel is selected, vertical acquisition is done simultaneously for both channels from a common strobe pulse. The Simultaneous Sampling Mode provides synchronous dual-channel acquisition with insignificant delay between channels. You can specify all functions for both channels equally from the Acquisition menu. Also, you cannot use the DESKEW variable from the Channel menu.

Alternate

When more than one channel is selected, the vertical acquisition switches sequentially through the selected channels. You can specify all functions for the selected channel from the Acquisition menu independently. For example, you can select the Stable Average mode for channel 1 and Min-Max Envelope mode for channel 2. Also, you can use the DESKEW variable from the Channel menu.

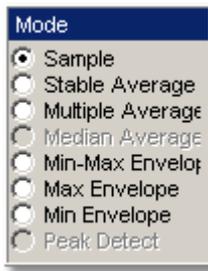
5.1.3 Channel (Alt Mode)



The Channel (Alt Mode) menu selects the waveform from one of the channels: Ch1 or Ch2.

You can specify all functions for this selected channel from the Acquisition menu. The Channel menu can be active only when the Alternate mode is selected in the [Sampling Mode](#) ³⁵ menu.

5.1.4 Mode



The Mode option lets you choose how the oscilloscope will create points in the waveform record.

The PicoScope 9000 supports three basic acquisition modes. These are:

- Sample mode (default mode) - acquires one sample point per trigger and displays results without further processing
- Average mode - calculates the average values for each record point over many waveform records
- Envelope mode - uses the highest and lowest samples across several waveform records

When you select the Average mode you can enter the number of averages with the AVERAGE N variable. When you select the Envelope mode you can enter the number of acquisitions with the ENVELOPE N variable.

Acquisition modes do not affect the data sampling itself. However, they do affect the analysis of the sampling, and therefore the way the oscilloscope combines the samples into a data point value.

Envelope and Average modes operate after the oscilloscope has taken two or more acquisitions. For example, each Average mode averages the corresponding data points from two or more waveforms, not the waveform as a whole. Envelope mode builds an envelope from the peak minimum and maximum values of each point on a succession of waveforms.

Side effect of averaging and enveloping

Averaging improves the accuracy of some software measurements, because the measurements are taken from averaged data. However, some measurements can be adversely affected by averaging or enveloping. For example, if you take a rise time measurement of a signal with horizontal jitter, the averaged trace will indicate an inaccurately slow reading. Be cautious when taking software measurements of averaged or enveloped traces. Use statistical measurements on the unaveraged signal to take an accurate rise time measurement on a signal with jitter.

Sample acquisition mode

With the Sample radio button pressed, the oscilloscope saves one sample during each acquisition interval. Samples are accurately acquired at precisely and uniformly programmed intervals. When the record is full, the oscilloscope acquires new samples that overwrite the previously acquired waveforms. In the Sample mode, the sample interval varies with the time base settings.

At slower sweep speeds, the sample interval is often so large that the oscilloscope misses information between samples (for example, repetitive glitches). In the above waveform, the Sample mode misses a glitch in the first peak but happens to capture it in the second.

One drawback of the Sample mode is that it can be fooled by aliasing because the bandwidth of the data is proportional to the timebase scale settings. As the Nyquist Theorem predicts, the bandwidth of the data drops as you slow the timebase.

The default mode is Sample, which is useful for acquiring fast signals.

Average mode

Pressing one of two Average radio buttons (Stable Average or Multiple Average) lets you acquire and display a waveform that is the combined result of several acquisitions. The oscilloscope acquires data as in the Sample mode and then averages it according to the number of averages that you specify. Each point in a record is numerically averaged with the same point in all other records. This reduces the random noise of a displayed waveform and provides a cleaner display, improves resolution of the displayed waveform, and increases measurement repeatability, all due to a more stable, displayed waveform. The noise sources can average to zero over time while the underlying waveform is preserved. The effective resolution of the displayed waveform increases as more acquisitions are averaged together, provided that the input waveform is repetitive and has a stable trigger point. However, averaging reduces the throughput of the instrument. Also, the waveform is less responsive to changes, especially when you select a high number of averages. The vertical resolution can be improved to 16 bits by using averages.



Use the Clear Display button to reset the averaging process.



Note that averaging is particularly useful for single-valued waveforms, such as pulses. Multi-valued waveforms, such as eye-diagrams, are not improved with averaging because the eye "collapses" to the average value between logic level one and logic level zero.

Two Average modes are available in the PicoScope 9000:

- Stable Average mode.
- Multiple Average mode.

Stable Average

Stable averaging lets you use the following algorithm:

$$A_n = A_{n-1} + \frac{x_n - A_{n-1}}{2^k}$$

where:

- n - is the current acquisition's number
- A_n - is the current acquisition's cumulative average
- A_{n-1} - is the previous acquisition's cumulative average
- x_n - is the newly acquired sample's value
- k - is the number of averages

As the number of acquisitions increases, the number of averages k increases and the size of the correction term (2^{-k}) decreases. Although the display becomes less noisy after each acquisition, the first acquisition has the greatest effect, and succeeding acquisitions have less effect as the correction term becomes smaller. For example, a change that occurs during the second acquisition shows up on the screen much sooner than one that occurs during the sixteenth. Whenever you adjust a control that affects the display, the scope starts a new averaging sequence to ensure that you will see the change immediately.

Stable averaging produces slightly less improvement—that is, a smaller signal-to-noise improvement ratio—than conventional averaging.

Signal-to-Noise Improvement Ratio with Stable and Multiple Averaging

Selected Number of Averages	Signal-to-Noise Improvement Ratio			
	Stable Average		Multiply sampling	
	Numeric	dB	Numeric	dB
2	1.41	3.0	1.41	3.0
4	1.98	5.9	2.00	6.0
8	2.75	8.8	2.82	9.0
16	3.84	11.7	4.00	12.0
32	5.24	14.6	5.64	15.0
64	7.51	17.5	8.00	18.0
128	10.60	20.5	11.28	21.0
256	14.90	23.4	16.00	24.0
512			22.56	27.0

Multiple Average

Multiple averaging lets you use the following algorithm:

$$A_i = \frac{\sum_{m=1}^N A_m}{N}$$

where:

- N - is the number of averages in every point
- A_m - is the acquired value of the waveform at point i during acquisition cycle m
- A_i - is the averaged value of the waveform at point i

When Multiple averaging is selected the oscilloscope works during the acquisition cycle as follows:

1. Operator selects the number of averages
2. The oscilloscope samples and digitizes N times the i th point of the waveform
3. Processor calculates new averaged value at point i
4. This procedure repeats for every point of the waveform

Unlike the stable average mode, the multiple average mode is N times slower. However, every point of the waveform is displayed filtered from noise. The Multiple Average mode has the most effective Signal-to-Noise Improvement Ratio.

Envelope Modes

Three Envelope modes are available in the PicoScope 9000:

- Min-Max Envelope mode
- Max Envelope mode
- Min Envelope mode

Clicking one of the envelope radio buttons (Min-Max Envelope, Max Envelope or Min Envelope) lets you acquire and display a waveform showing the extreme values of several acquisitions over a period of time. Thus, the oscilloscope detects peaks. You can specify a number of acquisitions over which to accumulate and display the min/max data. The oscilloscope compares the min/max values from the current acquisition with those stored from previous acquisitions up to the specified number of acquisitions. An enveloped waveform then shows the maximum excursions of the individual waveform records. This often results in a thicker waveform trace that shows the variations of the signal. Use this mode to reveal the noise band around the signal.

Because it degrades the timing information in the data by a factor of 2, Envelope mode is typically not suitable for FFT analysis. In addition, this mode can obscure the statistical distribution of the samples that occurred between the minimum and maximum values. However, you can create a display of this distribution by using the persistence display modes to view only peak values sampled over a period of time.



The Envelope mode requires a stable trigger for time correlation.

Min-Max Envelope. This radio button tells the oscilloscope to acquire and display the variation of both extremes - maximum and minimum.

Max Envelope. This radio button tells the oscilloscope to acquire and display the variation of maximum values.

Min Envelope. This radio button tells the oscilloscope to acquire and display the variation of minimum values.

5.1.5 AVERAGE N / ENVELOPE N



Number of Averages

The AVERAGE N variable changes the number of averages (records) when you select one of the two average radio buttons (Stable Average or Multiple Average). The number of averages can be specified from 2 to 4096 in multiples of two by one of these methods:

- By using the AVERAGE N spin box
- By using the [Pop-up Keypad](#) ⁴²⁷ for some specific settings

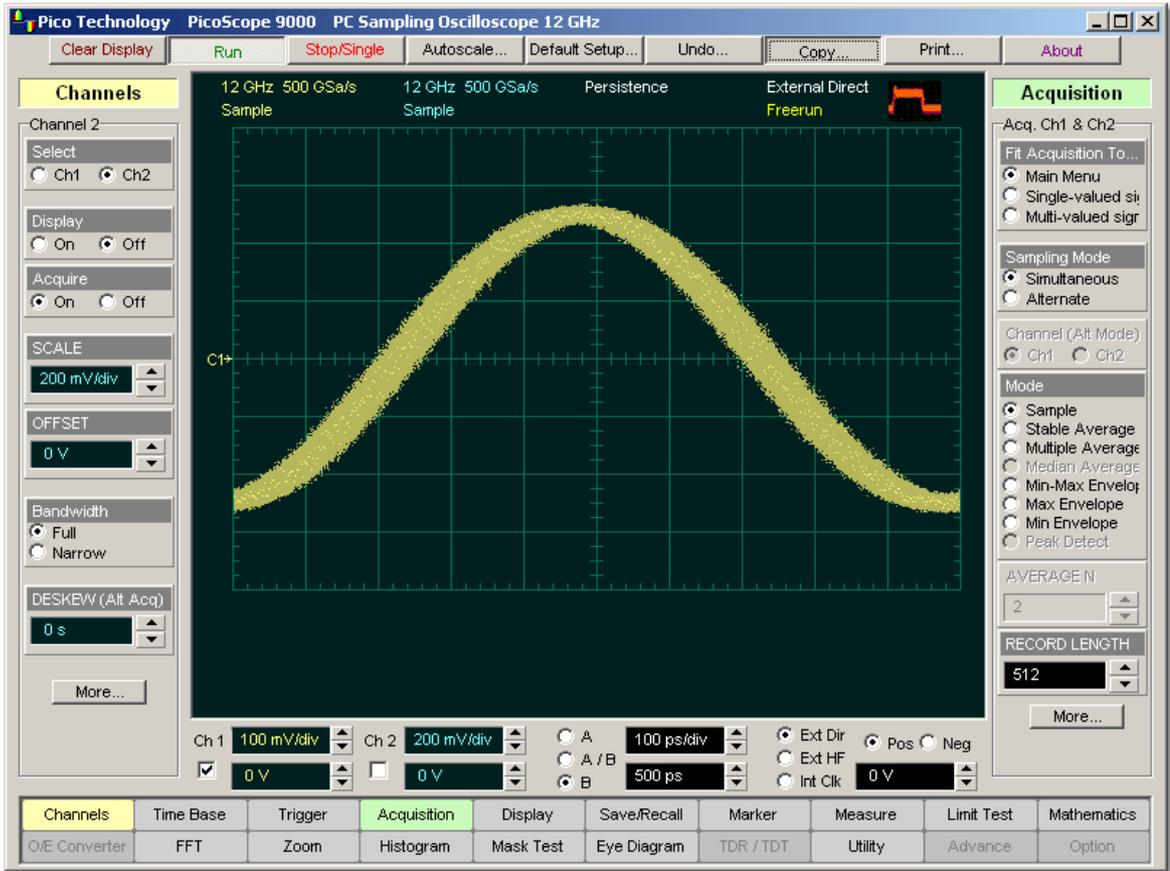


The waveform is less responsive to changes if a large number of averages is specified.

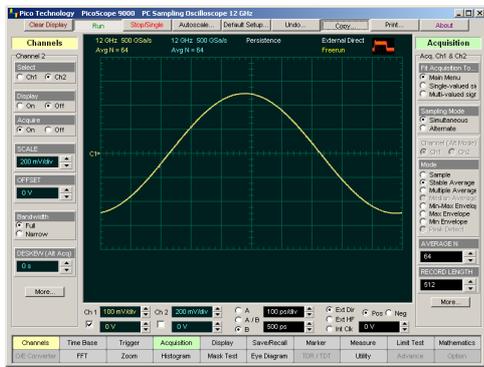
Number of Envelopes

The ENVELOPE N variable changes the number of acquisitions when you select one of the three envelope radio buttons (Min-Max Envelope, Max Envelope or Min Envelope). The number of acquisitions can be specified from 2 to 4096 in multiples of two or continuously using one of these methods:

- By using the ENVELOPE N spin box
- By using the [Pop-up Keypad](#) ⁴²⁷ to enter specific settings



Sample Acquisition Mode



Average Acquisition Mode



Min-Max Envelope Acquisition Mode

5.1.6 RECORD LENGTH



The number of samples that form a trace is called the record length (in points per waveform). For example, if the horizontal (timebase) scale is set up as 10 ns/div, the total displayed sweep time is 100 ns. The greater the amount of sampled data that is available for analysis or measurements, the greater the record length.

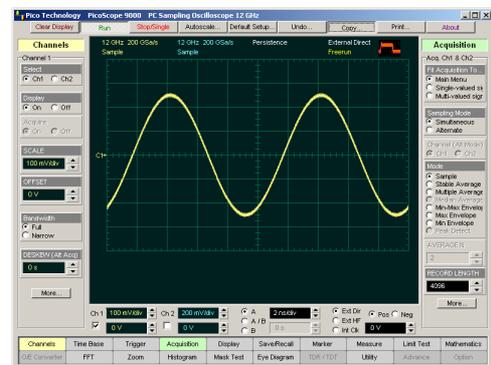
You can select record length with one of these methods:

- By using the RECORD LENGTH spin box
- By using the [Pop-up Keypad](#)⁴²⁷ to enter specific settings

Record length can be selected from 32 to 4096 samples in multiples of two.



Record length with 32 samples



Record length with 4096 samples

Fast Fourier Transform algorithms require a record length that is a power of two. The 4096-point record length is provided as a convenience, and the visual truncation is a natural result.

When Alternate Sampling Mode is selected, the record length is set independently for each channel. Remember that equivalent sample rate and record length work together. If you combine a small record length memory depth with a high equivalent sample rate, you will have a very fast throughput (display update rate) but very little data in the channel memory. Because more data points need to be acquired, a waveform with a long record length takes longer to construct than one with a short record length. However, a long record length produces a waveform with higher horizontal resolution, and so a trade off exists between throughput and resolution.

You can set both the main record length and the delayed record length using the variables. All traces on the main timebase have the same record length. Delayed traces similarly share identical record lengths.

5.1.7 Run Until



The Run Until menu allows you to determine when the acquisition of data stops.

Stop/Single Button. You must press the Stop/Single key to stop the acquisition of data.

Acquisitions. After the number of acquisitions are met the acquisition is stopped. The number of acquisitions can be specified in the # OF ACQUISITIONS menu.

5.1.8 # OF ACQUISITIONS



Sets the number of acquisitions. After the selected number of acquisitions is met, the acquisition is stopped.

5.1.9 Action



The Action menu allows you to specify what the instrument does after acquisition is stopped. Two actions can be selected.

Beep

The Beep provides an audio tone.

Save All Wfms

Clicking Save All Wfms opens the Windows Acquisition Limit Files dialog box, which allows you to select the type of format you want to save the waveform as, and also to enter a key file name. You can select one of three types of waveform formats:

- Binary format with .wfm extension
- Text format with .txt extension
- Both formats with .wfm, and .txt extensions

After the Run key is pressed, the oscilloscope acquires the specified number of acquisitions. All of them will be saved into the memory.

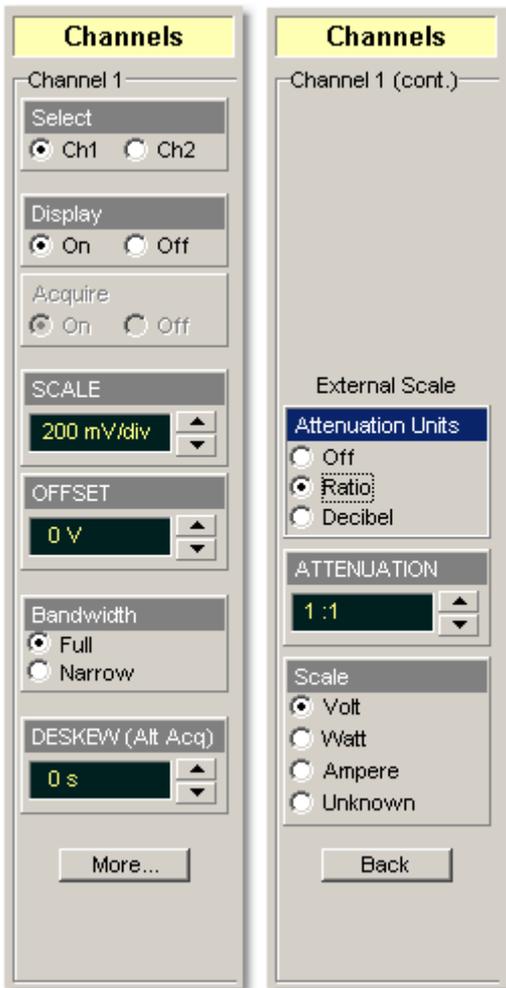
5.2 Channels Menu



WARNING!

The input circuits can be damaged by electrostatic discharge. Therefore, avoid applying static discharges to the front panel input connectors. Before connecting any coaxial cable to the connectors, momentarily short the centre and outer conductors of the cable together. Avoid touching the front panel input connectors without first touching the case of the instrument. Personnel should be properly grounded, and should touch the case of the instrument before touching any connector. Be sure that the instrument and PC are properly earth-grounded to prevent build-up of static charge.

Repair of damage due to misuse is not covered under the warranty!



The Channels menu allows you to set all controls for vertical setups of all live (channel) waveforms.

To display the Channels menu, click the button of the main menu.

The controls for each channel are independent. When you select the Channels menu either the SCALE, OFFSET, DESKEW, or ATTENUATION control is highlighted in the same color as the selected channel, indicating that the function is active.

5.2.1 Channel Select



Many of the controls of the PicoScope 9000A, especially the channel controls, operate on the selected channel. The instrument applies all actions that only affect one channel at a time, such as applying changes to the vertical control settings, to the selected channel.

Clicking the Ch1 or the Ch2 radio buttons:

- Toggles it between channels 1 and 2.
- Assigns the function keys to the selected channel.

5.2.2 Channel Display



There are two ways to add selected channels to the display and remove them again:

- Use the On or Off radio buttons on the Channels/Display menu
- Use the Ch1 and Ch2 check boxes in the Permanent Controls Area

Clicking the On/Off buttons:

- Turns the display for the selection on or off
- Changes the label from on to off or vice versa

Turning the Display off does not turn off acquisition of the selected channels. To turn off acquisition of the selected channel, use the Acquire menu.

The Display turns on or off the display of the waveform for the chosen channel. When the channel display is on, a waveform is displayed for that channel, unless the offset is adjusted so the waveform is clipped off of the display.

When the channel display is off, the waveform display for that channel is turned off, but acquisition on that channel is not stopped. Turning a channel's display off also turns off the XY-markers while X- or Y-markers are available. Measurements, functions, FFTs, and histograms also are available to that channel.

Turning a channel off increases the display update rate for the remaining channel that is on.

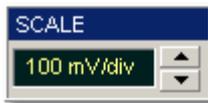
5.2.3 Channel Acquire



On. Turns on acquisition of the selected channel.

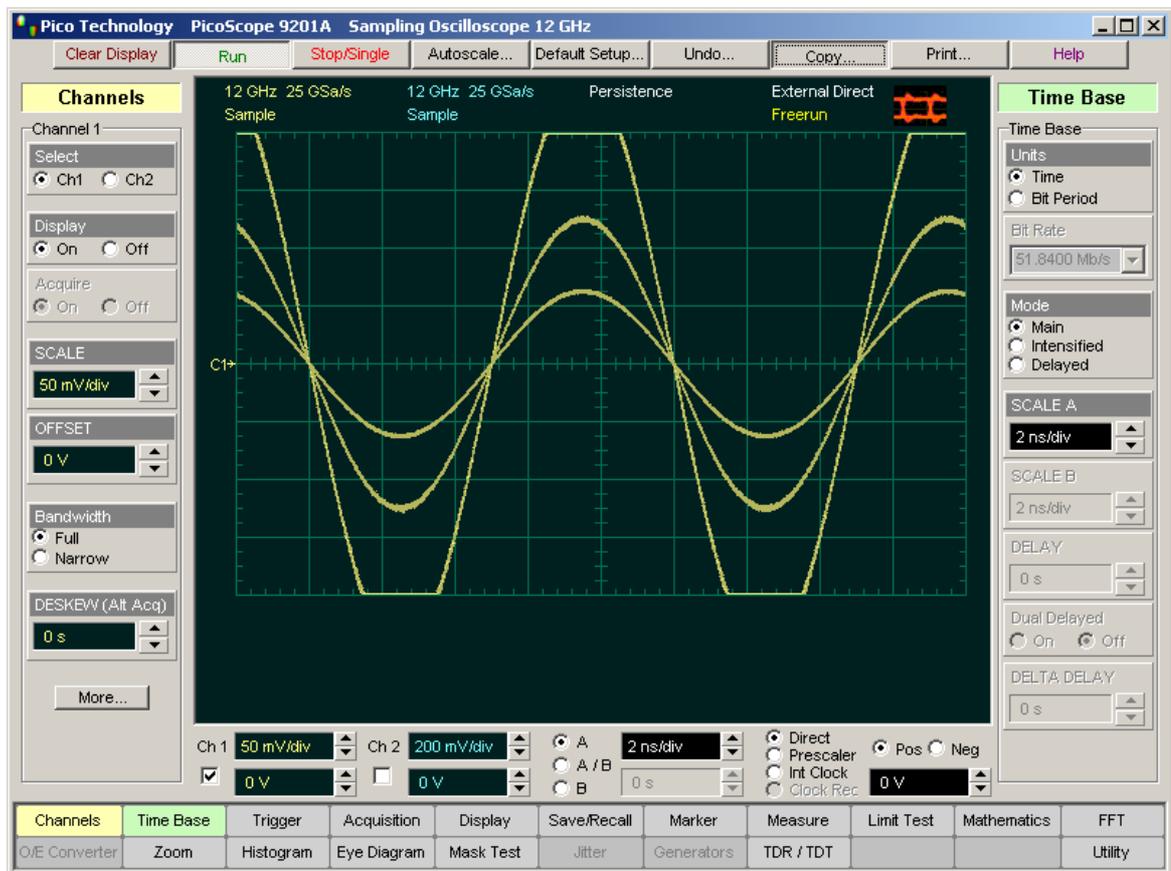
Off. Turns off acquisition of the selected channel.

5.2.4 Channel SCALE



The SCALE controls vertical scaling of the waveform. It determines the portion of the input signal presented to the acquisition system. Adjust the SCALE to control the portion of the vertical window displayed on screen. The vertical window is always centered around the offset value that is set.

As the numeric value of the scale is increased the displayed waveform decreases in size, and as numeric value of the scale is decreased, the waveform increases in size.



Vertical scaling of a waveform



The channel SCALE does not affect the vertical acquisition window.



Only waveform traces from input channels can be vertically adjusted with the SCALE control. It does not affect waveforms saved in memories, or waveform functions.

You can set the vertical sensitivity of the selected channel in one of three ways:

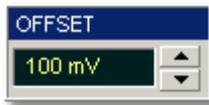
- Use the SCALE spin box
- Use the Ch1 and Ch2 spin boxes in the Permanent Controls area
- Use the [Pop-up Keypad](#)⁴²⁷ to enter specific settings

You can change the vertical scaling from 2 mV/div to 500 mV/div. If fine mode is off, the vertical scaling is in a 1-2-5-10 sequence. When fine mode is on, you can change the vertical scaling with a 0.5% increment or better.

The SCALE changes automatically if the attenuation factor is changed. The units the scale is displayed in depend on the unit of measure selected with the Scale menu. The choices for units are volts, watts, amperes, or unknown.

The SCALE changes automatically if the display graticule mode (single, dual or quad) or the attenuation factor is changed.

5.2.5 Channel OFFSET



The OFFSET variable changes the vertical position of a particular channel's waveform on the display screen without modifying the waveform itself. It determines the portion of the input signal presented to the acquisition system.

The advantage of digital offset is that it is calibrated. The offset voltage is the voltage at the centre of the graticule area, and the range of offset is ± 1 V. As you vary the offset, the middle voltage level moves relative to zero. This moves the vertical acquisition window up and down on the waveform. With input signals that are smaller than the window, the waveform appears to move in the window. Applying a negative offset moves the vertical range down relative to the DC level of the input signal, moving the waveform up on the display. Likewise, applying a positive offset moves the vertical range up, moving the waveform down on the display.

Set the vertical offset to display the features of interest on your waveform and avoid clipping.



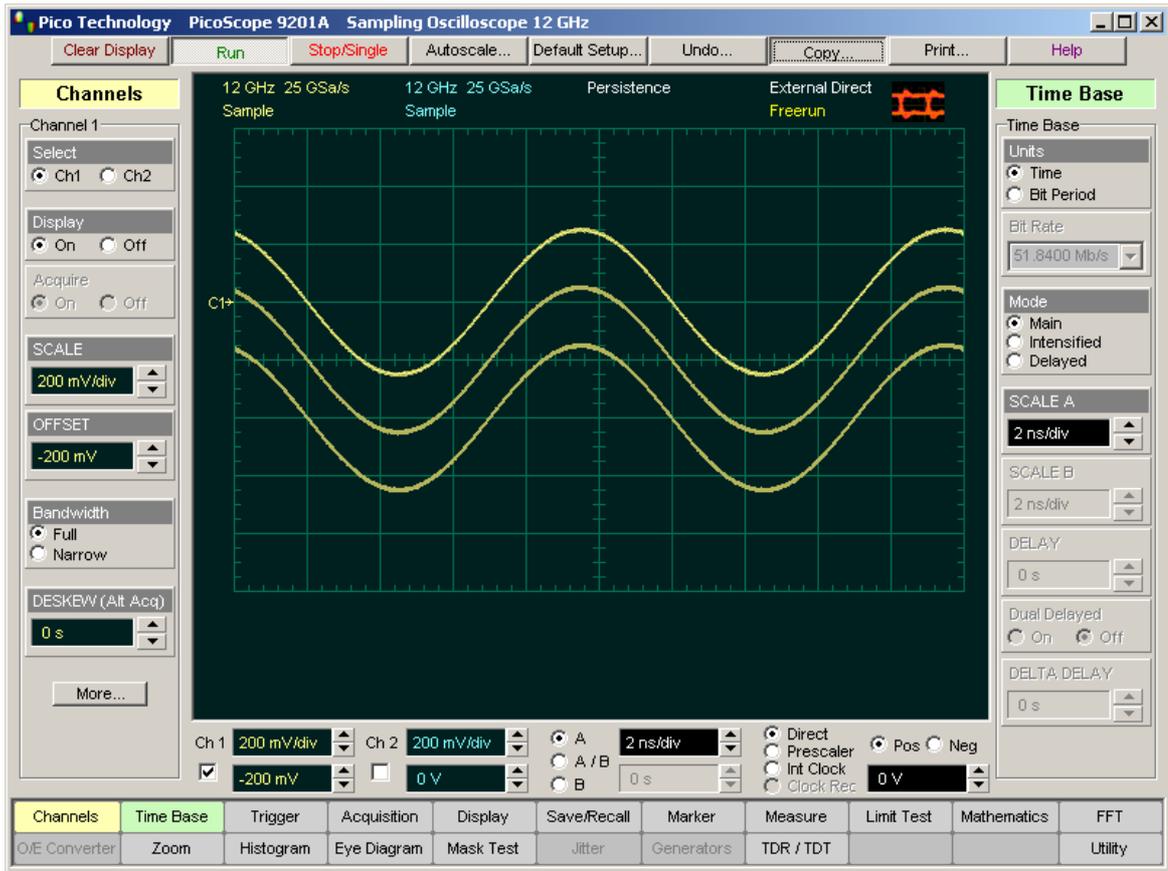
Waveform data outside the vertical acquisition window is clipped: that is the data is limited to the minimum and/or maximum boundaries of the vertical acquisition window. This limiting can cause inaccuracies in amplitude-related measurements.



The OFFSET control affects the vertical acquisition window for selected input channel. It does not affect waveforms saved in memories, or waveform functions.

You can move the trace of the selected channel up or down in one of four ways:

- Use the OFFSET spin box
- Use the Ch1 and Ch2 offset spin boxes of the Permanent Controls Area
- Use the [Pop-up Keypad](#)⁴²⁷ for some specific settings
- Use a channel Ground Reference Indicator



Sine-wave signal with different offsets

If fine mode is off, the offset can be changed in 25-mV steps. When fine mode is on, you can change the offset in 1-mV steps.

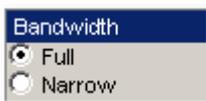
The OFFSET changes automatically if the attenuation factor is changed. The units the offset voltage is displayed in depend on the unit of measure selected with the Scale menu. The choices for units are volts, watts, amperes, or unknown.

The OFFSET changes automatically if the display graticule mode (single, dual or quad) or the attenuation factor is changed.



Each channel has a channel Ground Reference Indicator located to the left of the graticule area. The Ground Reference Indicator shows you where zero volts is for each channel.

5.2.6 Channel Bandwidth



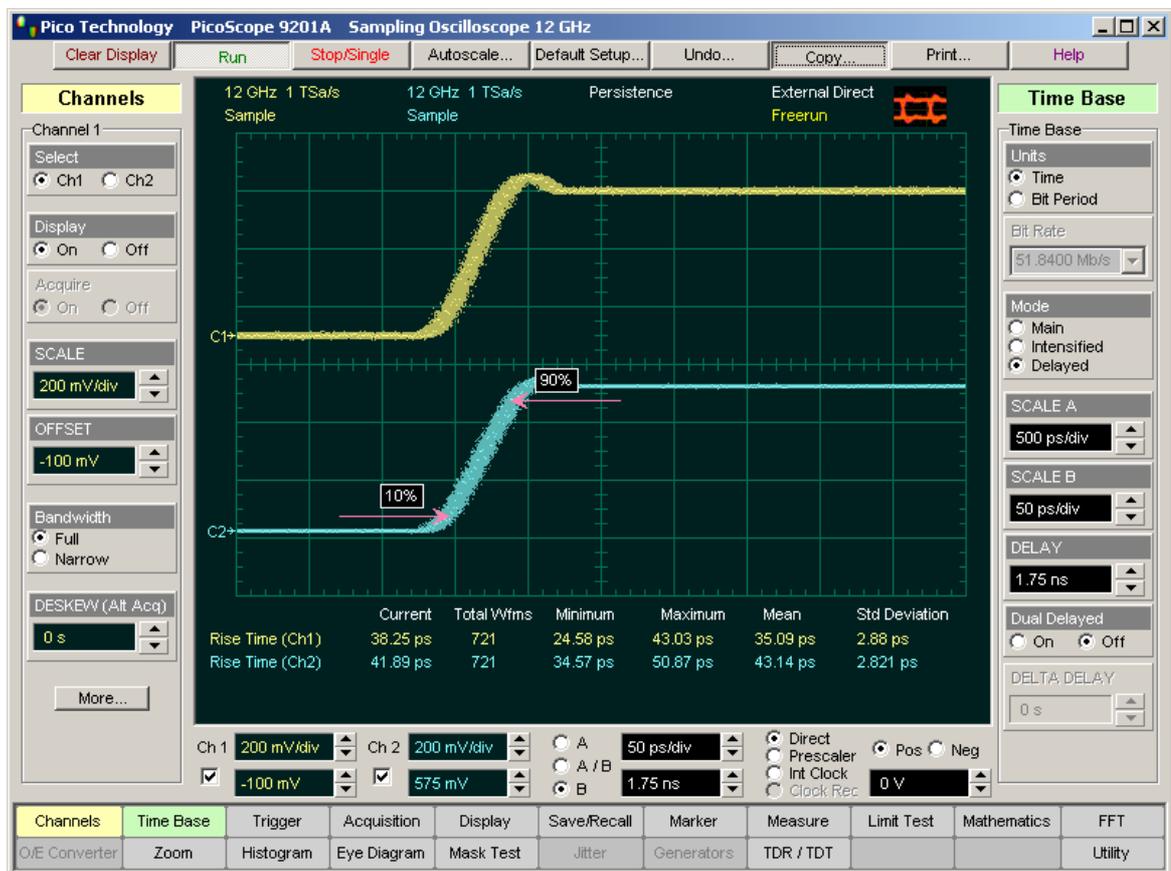
Bandwidth is the range of frequencies that an oscilloscope can acquire and display accurately (that is, with less than 3 dB attenuation). You can use the Bandwidth function to select either full or narrow bandwidth.

The channel bandwidth setting affects the width of the sampling pulse used by the instrument. The wider bandwidth option allows the instrument to respond to fast changes in a waveform. The increased bandwidth thus yields the highest measurement fidelity.

The narrow bandwidth offers the best sensitivity by reducing the noise on the input waveform while still maintaining good frequency response. A lower sampler bandwidth is especially useful for low-level signals that cannot be averaged, such as an eye diagram. If you do not need wide bandwidth, use the narrow bandwidth to keep the signal-to-noise ratio at the best possible level. Narrow bandwidth removes high-frequency noise from a particular channel's waveform.

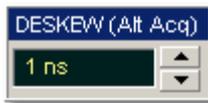
The Bandwidth does not affect the trigger signal.

- Full. This button selects a 12-GHz bandwidth.
- Narrow. This button selects an 8-GHz bandwidth.



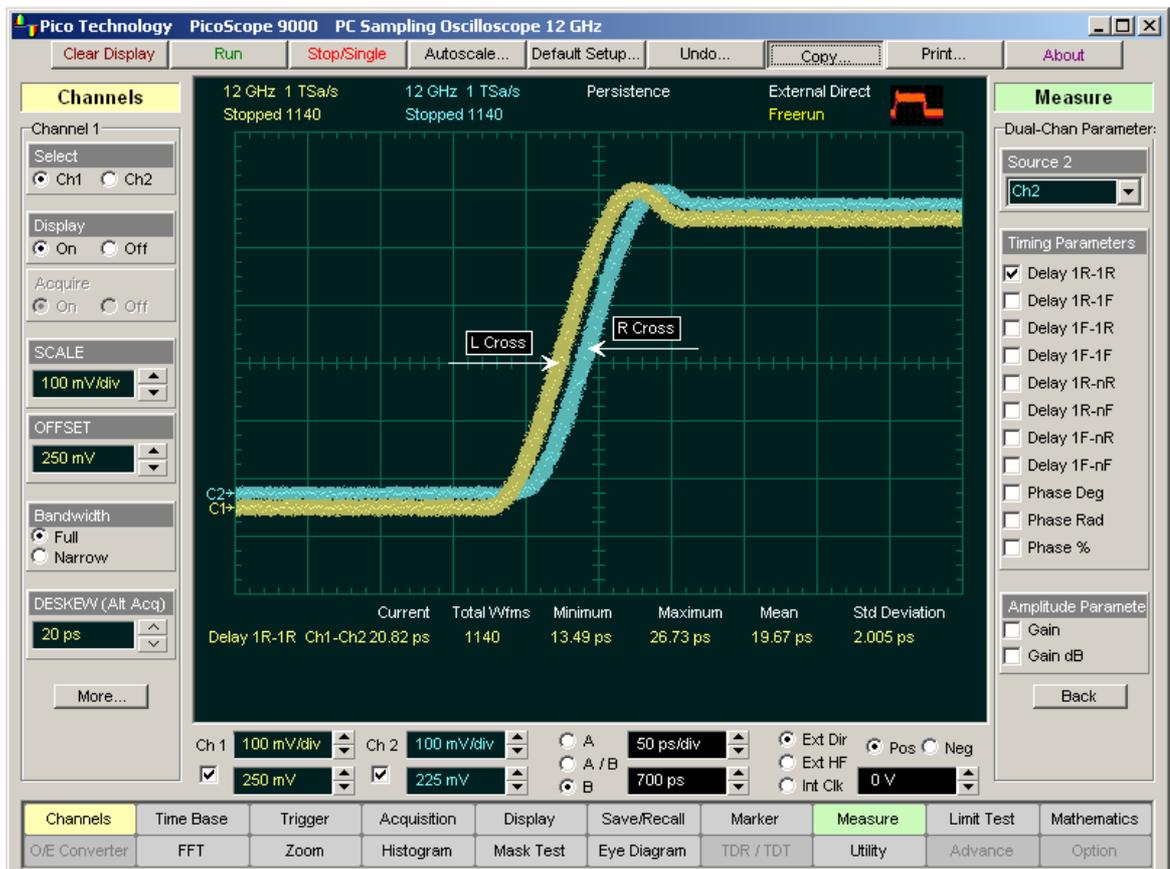
Channel 1 (yellow trace): full bandwidth 12 GHz
Channel 2 (blue trace): narrow bandwidth 8 GHz

5.2.7 Channel DESKEW



The DESKEW variable adjusts the skew to change the horizontal position of one active channel with respect to another on the instrument display. The deskew function has a range of +100 ns. You can use the function to compensate the time offset between two channels, and also differences in cable or probe lengths. It also allows you to place the triggered edge at the centre of the display when you are using a power splitter connected between the channel and trigger inputs. Another use for deskew is when you are comparing the shapes of two waveforms rather than the actual timing difference between them: you can use the DESKEW to overlay one waveform on top of the other.

Use the DESKEW function only when the [Alternate Sampling Mode](#)^[35] is selected in the [Acquisition](#)^[30] menu.



Two waveforms with entered deskew of 20 ps

The DESKEW function allows you to set the horizontal position of a waveform in one of two ways:

- Use the DESKEW spin box
- Use the [Pop-up Keypad](#)^[427] to enter specific settings

If fine mode is off, you can change the deskew value in 1 ns steps. When fine mode is on, you can change the deskew value in 1 ps steps.

5.2.8 Channel Input Impedance

The input channels of the PicoScope 9000A have 50- Ω input impedance with DC input coupling. This is useful for connecting to probes or circuits that require a 50- Ω termination. For example, you might choose an active probe to measure a very fast ECL, SiGe or GaAs circuit. Such a probe usually has an amplifier near the tip of the probe, which drives the signal through a 50- Ω cable. To minimize any waveform reflections, the scope input impedance must match the cable impedance as closely as possible so you would choose the 50- Ω setting for that channel's input impedance.



CAUTION!

To avoid damage to the input of the scope, make sure you do not exceed the channel's maximum rated input voltage ± 2 V (DC + peak AC).

Using resistive divider probes you can increase input impedance up to 5 k Ω , and using an active probe you can increase input impedance up to 10 M Ω .

5.2.9 Channel Coupling

The samplers used in the PicoScope 9000A provide only straight-DC coupling to sampling circuits, with no protection. The PicoScope 9000A specifies a maximum vertical non-destructive range that limits signals to small level ± 2 V (DC + peak AC) or 16 dBm (See "[Channel \(Vertical\) Specification and Characteristics](#)"^[12] for exact limits).



Do not exceed the limit, even momentarily, as the input channel may be damaged.



The PicoScope 9000A also specifies a maximum operating input voltage (dynamic range) that, if exceeded, could cause acquisition and measurement errors due to non-linearity. This limit is equal to 1 V p-p at ± 1 V range when digital feedback is used, and ± 300 mV relative to channel offset without digital feedback. Do not exceed this limit.

Also see "Channel (Vertical) Specification and Characteristics" for exact limits.

For removing the DC component of a particular channel's waveform to view AC waveforms with large DC offsets, use external wide-bandwidth HF blocking capacitors.

Use external attenuators if necessary to prevent exceeding the limits just described.

5.2.10 Channel External Scale

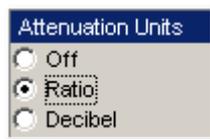
The External Scale functions allow you to set up a channel of the instrument to use external voltage attenuators or probes, current probes, and optical-to-electrical converters. Scaling is automatically adjusted to account and display information at the input side of an external device. For example, you may need to reduce the voltage level of a pulse generator that exceeds a channel's maximum input level. If you add a 20-dB attenuator, the voltage is reduced by a factor of 10:1. Although the voltage levels into the channel are within acceptable limits, your source measurements will be 1/10th of the actual source level. External scaling allows you to compensate for the 20 dB attenuation so your measurements reflect the source level prior to attenuation.

The measurement result reflects the actual value at the external device input. Once the number has been entered (1 is the default), the instrument then uses the total attenuation factor in scaling measurement results. Total attenuation is the product of the external attenuation multiplied by the hardware attenuation of the probe (or another external unit) or sampler.

When you enter attenuation, amplification, or conversion information with the External Scale menus, the channel settings change in the following ways:

- The unit values and amplitudes of the markers and vertical measurements reflect the signal at the input of a transducer, probe, attenuator, or amplifier. For example, you can connect an external device such as a photodiode to an electrical channel input and change the scale unit value to read watts, the unit value of the signal at the diode input.
- The maximum and minimum vertical scale settings change by a factor specified by the attenuation value entered.
- Offset minimum and maximum values change by a factor specified by the attenuation value entered.

5.2.11 Attenuation Units



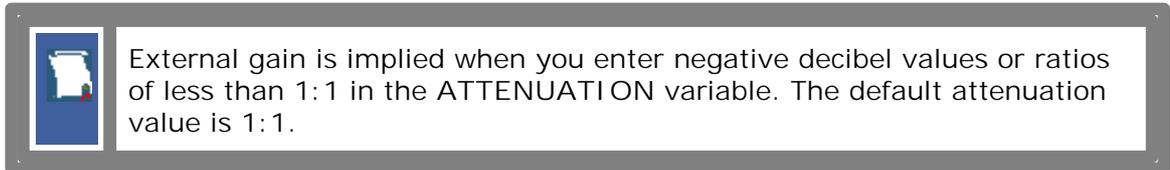
You can enter attenuation or gain characteristics of an external device when configuring a channel for external scaling. The Attenuation Units function lets you select how you want the attenuation factor represented. Click the Ratio or Decibel radio buttons to choose either ratio or decibel. The formula for calculating decibels is:

$$20 \log(V_{out}/V_{in}) \text{ or } 10 \log(P_{out}/P_{in})$$

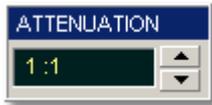
Decibels versus voltage ratio:

dB	Voltage Ratio
3 dB	1.41
6 dB	2.00
10 dB	3.16
20 dB	10
40 dB	100
60 dB	1000
120 dB	1 000 000
-80 dB	0.0001

Changing the channel attenuation factor does not attenuate the input signal; it only changes the database for generating prompts on the display and calculating the results of the automated waveform measurements. If the input signal must be attenuated, use external attenuators.



5.2.12 ATTENUATION



The ATTENUATION variable lets you select an attenuation that matches the device connected to the instrument. When the attenuation is set correctly, the instrument maintains the current scale factors if possible. All marker values and voltage, amperage or wattage measurements will reflect the actual signal at the input to the external device.

The channel attenuation factor is used to establish a database for:

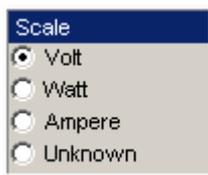
- Generating the vertical scale and offset prompts on the display
- Calculating the automated waveform measurements
- Y-marker levels
- Calculating functions

The attenuation factor can be adjusted from 0.0001:1 to 1000000:1 or from -80 dB to 120 dB.

The ATTENUATION function allows you to set attenuation of the selected channel in one of two ways:

- By using the ATTENUATION spin box
- By using the [Pop-up Keypad](#)⁴²⁷ to enter specific settings

5.2.13 Scale



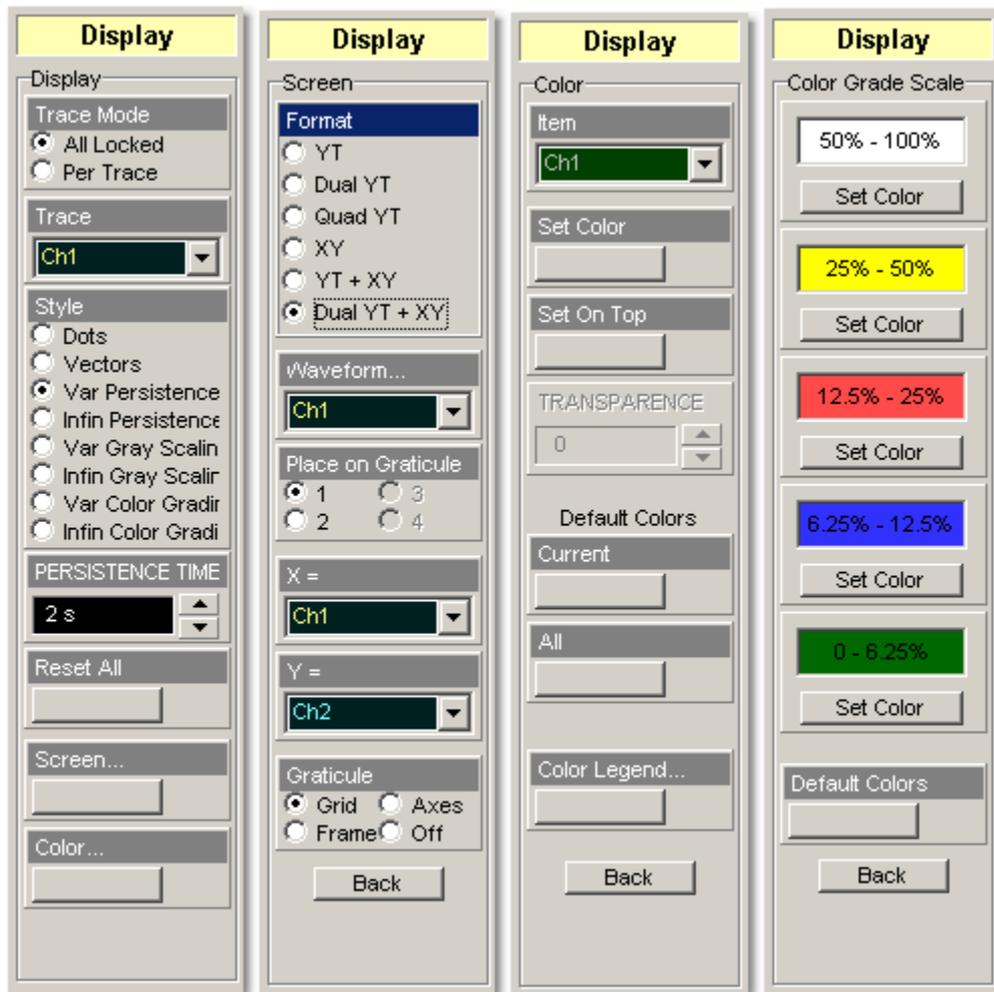
The (External) Scale function lets you select a unit of measure that is appended to the channel scale, offset and vertical measurement values. The units are Volt, Watt, Ampere, or Unknown.

Use Volt for voltage probes, Ampere for current probes, Watt for optical-to-electrical converters, and Unknown when there is no unit of measure or when the unit of measure is not one of the available choices.

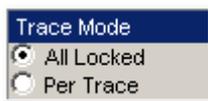
5.3 Display Menu



The Display menu controls most of the features that determine how the acquired data is displayed on the screen. You can configure the PicoScope 9000A for persistence or color-graded display style, select the graticule settings, define the waveform display area for single or multiple waveform displays, and you can change the color of most of the items that are displayed on the screen.



5.3.1 Trace Mode



The PicoScope 9000A gives you the choice of constraining all input channels to the same display style, or setting these for each trace individually.

All Locked. Set the same display style for all traces.

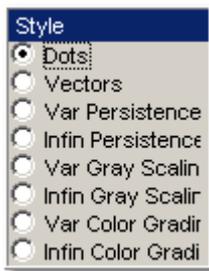
Per Trace. Set up traces individually.

5.3.2 Trace



Selects a trace to set Display Style. Is active only when Per Trace is selected from the Trace Mode.

5.3.3 Style

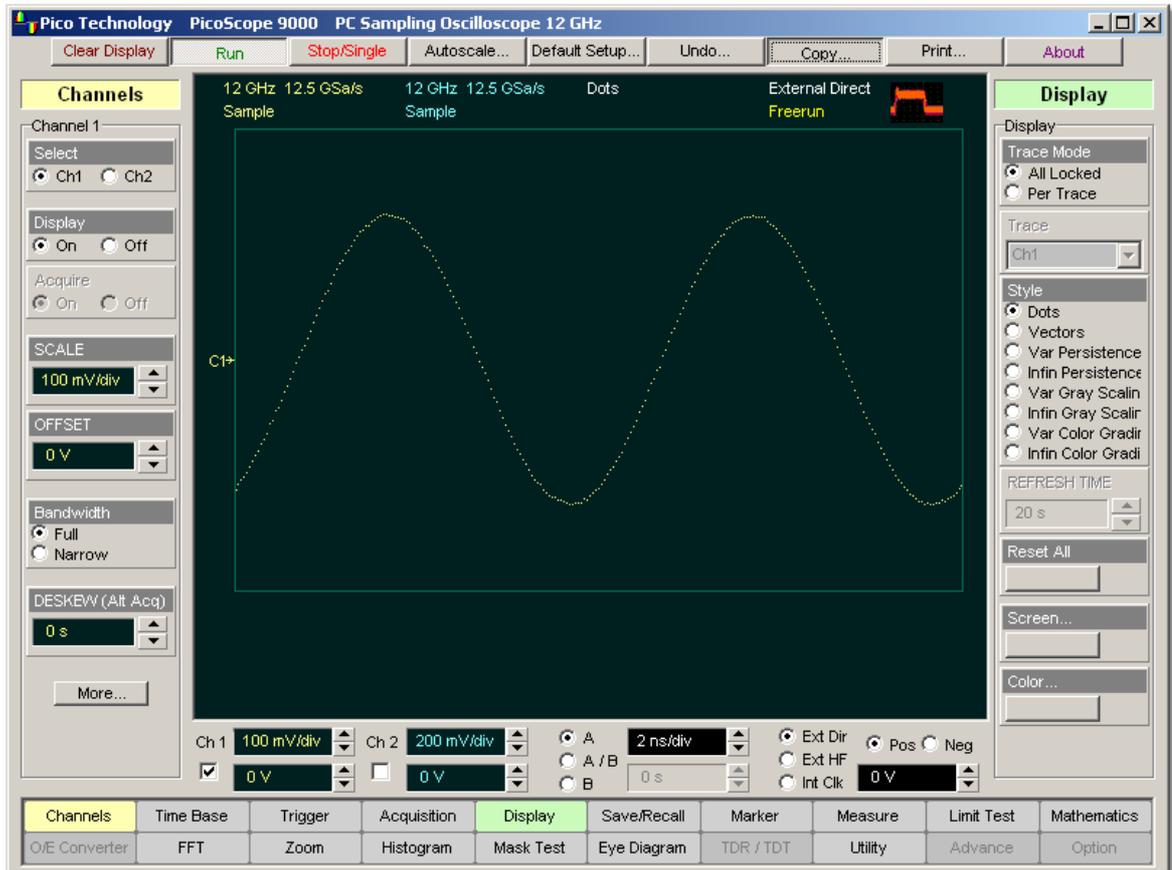


The Style menu determines how the data is displayed. There are eight choices for drawing waveforms:

- Dots
- Vectors
- Variable Persistence
- Infinite Persistence
- Variable Gray Scaling
- Infinite Gray Scaling
- Variable color Grading
- Infinite color Grading

Dots display

The Dots style displays waveforms without persistence: each new waveform record replaces the previously acquired record for a channel. Data points are plotted on the display as fast as possible. When the waveform record length is small, the throughput of the instrument is fast enough that you can use the Vector style without noticing much decrease in throughput.



Dot Display Style

Vector display

The Vector function draws a straight line through the data points on the display. This is also known as Connect Waveform Dots. The Vector style gives an analogue look to a digitized waveform and makes it possible to see steep edges on waveforms such as square waves. If you use the Vector style the approximate unaliased oscilloscope bandwidth is:

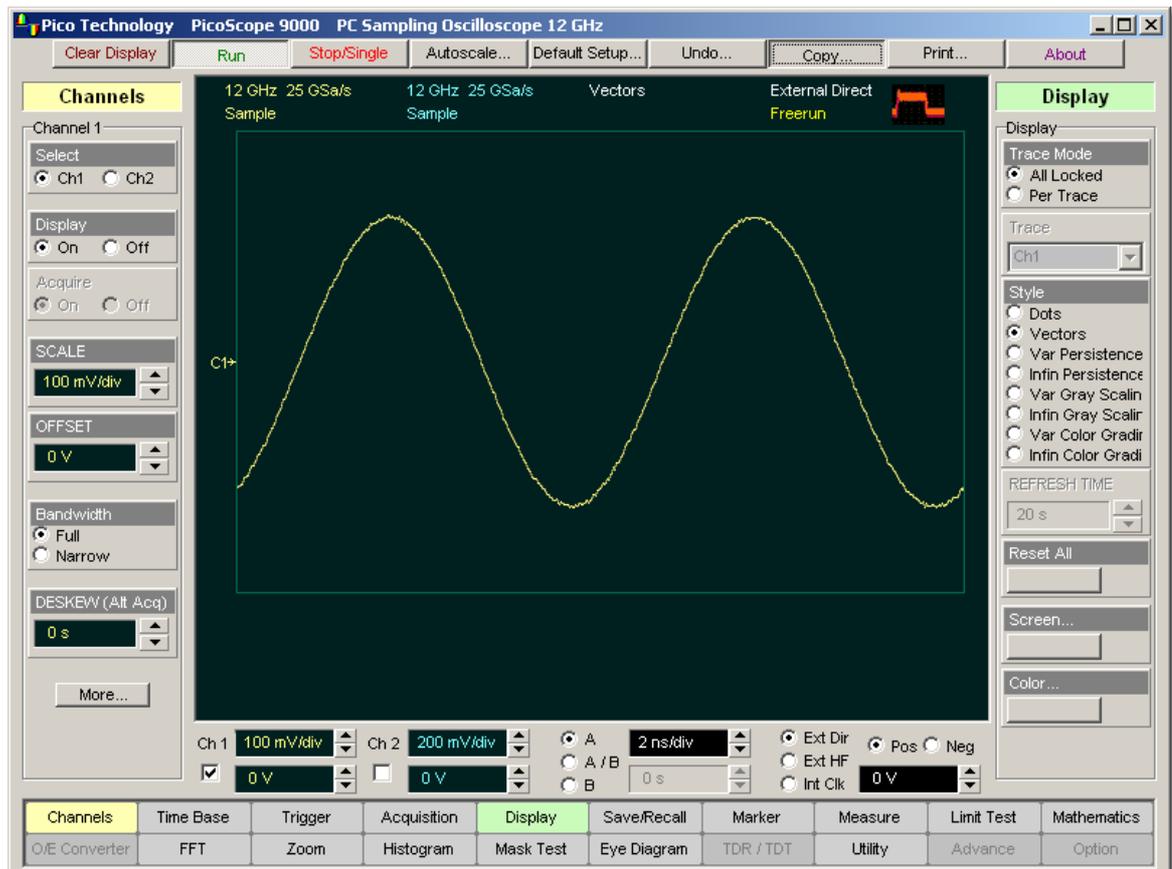
$$\text{Bandwidth} = \text{Equivalent Sample Rate} / 10.$$

In this configuration, a waveform can alias if its highest frequency component exceeds 1/10 the sample rate. On waveforms where there are only a few dots representing the acquired data points, such as when the record length is small, you may find it easier to have a sense of what the waveform looks like.



It is recommended to view spectrum when Vectors Style is enable.

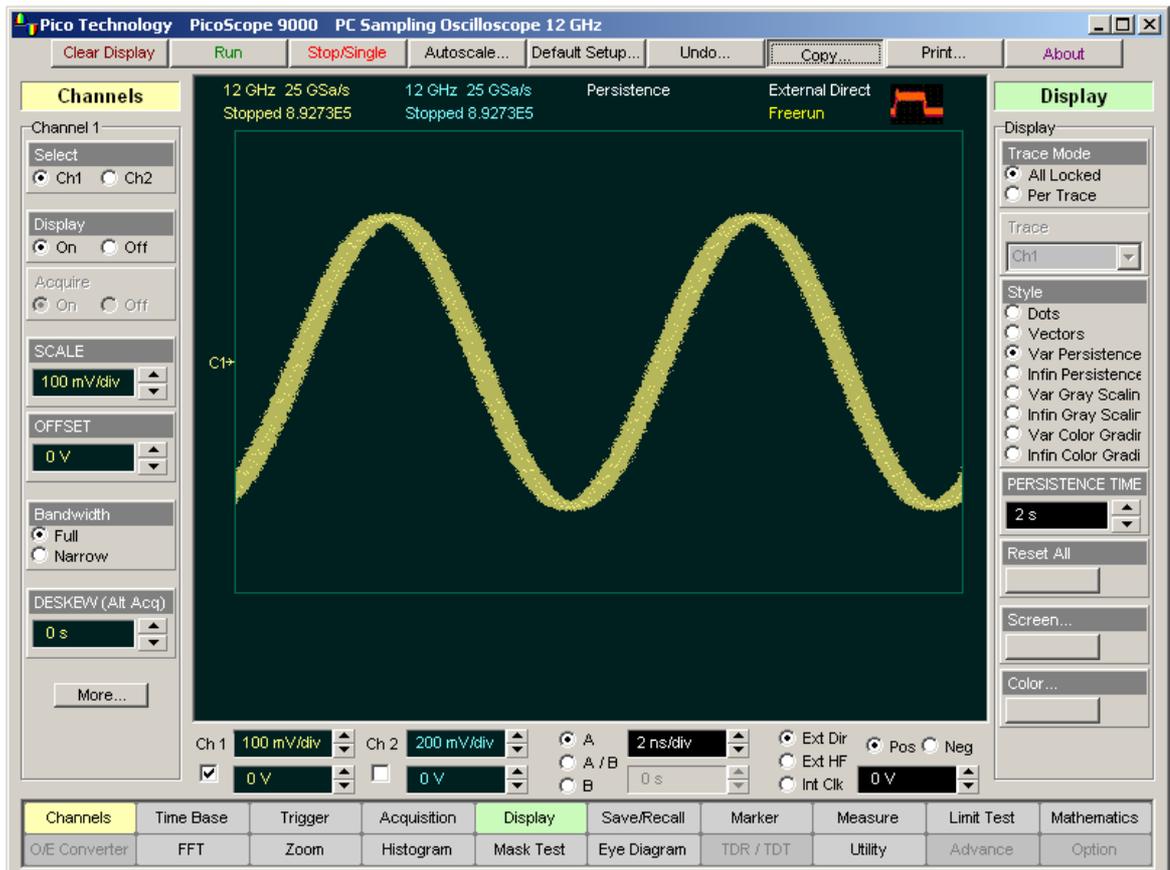
However it is not recommended to view eye diagrams when Vectors Style is enabled. For this reason, do not use the Vectors Style in the Eye Diagram and Mask Test menus.



Vector Display Style

Display Persistence

The Persistence function determines how long a data point is kept on the display before being erased. Normally, a waveform is displayed only for one trigger event. When the next trigger event occurs, the previous waveform is erased and the newly acquired waveform is drawn on the display. Persistence is a display memory function; therefore acquired waveforms are written only to display memory. Acquisition memory is where the current waveform data is stored. Therefore, only the last acquired waveform is held in acquisition memory. Display memory is what is seen on the display graticule.



Persistence Display Style

Persistence style applies to all waveforms. Use display persistence to control how waveform data ages. By adding persistence, you can see a visual history of a waveform's acquisitions over time. Setting the persistence to minimum allows for easiest viewing of variations in the acquired waveforms. Setting the persistence to infinite allows for a complete view of everything measured in the waveform. For example, you can see the accumulated peak-to-peak noise of a waveform over time, which may appear significantly different than in only one acquisition. You can see timing jitter, the variance of the waveform from the trigger event, by accumulating acquisitions on the display. By adding persistence, viewing a waveform's extremes over time is much easier.

You can have averaging and persistence on at the same time because when averaging is on, the averaging is done before the data is sent to the display. Use the [Acquisition](#) ^[30] menu to control averaging.



Waveform persistence is used only in the Display Area.



Use waveform persistence in the Eye Diagram and Mask Test menus. The Eye Diagram and Mask Test measurement algorithms are based on the statistical accumulation of the data.

The PicoScope 9000A uses two persistence settings:

- Variable Persistence
- Infinite Persistence

Variable Persistence

The Variable Persistence style accumulates the waveform-record points on screen and displays them for a specific time. The oldest waveform data continuously fades from the display as new waveform records are acquired.

By selecting the Variable Persistence display style, you can vary the persistence time from minimum of 100 ms to 20 s. When the persistence is set to minimum, all data points are kept on the display for 100 ms. After 100 ms all the previous data points are erased from the display, and new data points are written to the display. As you increase the persistence time, the previous data points are kept on the display depending on the persistence time you have selected. Therefore, the longer the persistence time, the longer each data point is left on the display before it is erased from the display. You can change the persistence time with the PERSISTENCE TIME variable.

A minimum persistence setting is used when the input signal is changing and you need immediate feedback. You can use the minimum persistence mode to view the fastest display update rate. For example, if you are rapidly probing a source, you may find that more persistence is useful for observing long-term changes in a signal or observing signals with low repetition rates. More persistence is useful when you are observing long-term changes in the signal or low signal repetition rates.



If you are adjusting the amplitude or frequency of a signal source, you may find that more persistence (variable or infinite) is useful for observing long-term changes in a signal or observing signals with low repetition rates. If you are adjusting signal parameters, such as scale or delay, you will find that minimum persistence is useful due to the fast update rate.

When the waveform acquisition is stopped, the last acquired data points are left on the display.

If one of the following is changed when the instrument is in the variable persistence mode, the displayed waveform is redrawn and any accumulated waveforms are cleared:

- Clear Display button is pressed
- An Autoscale button is executed
- A Default Setup button is executed
- The instrument is turned off

Infinite Persistence

When you select the Infinite Persistence display style, all the data points are kept on the display for an endless period of time, or until you change some control. Waveform data builds up as new data records are acquired. You can use infinite persistence for worst-case characterization of signal noise, jitter and drift, or to see a waveform's envelope, look for timing violations, and find infrequent events.

With infinite persistence, all sampled data points are left on the display until one of the following occurs:

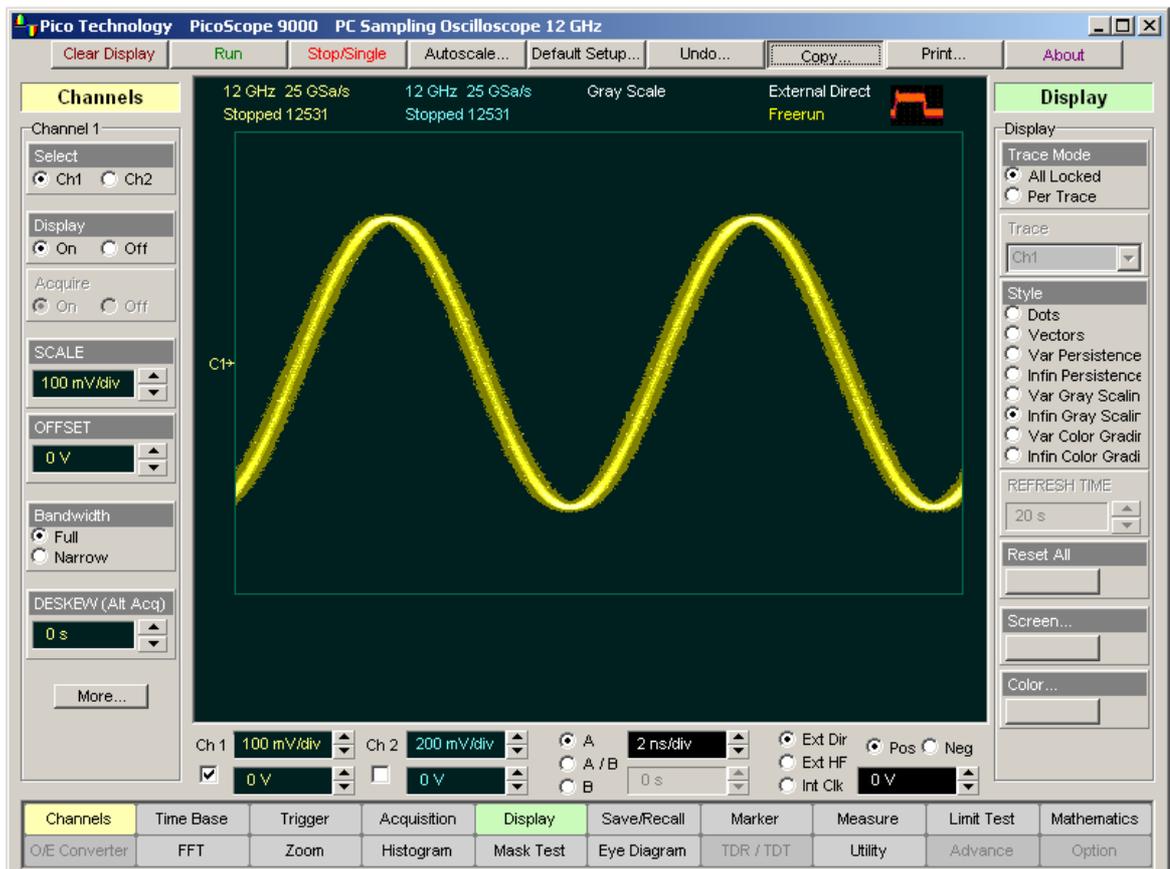
- Clear Display button is pressed
- An Autoscale button is executed
- A Default Setup button is executed
- The instrument is turned off

Gray Scaling

This mode is similar to persistence mode. The only difference is that the accumulated points are used are one color that is varied in saturation and luminosity levels (in other words, different shades of the same color). You can use the gray-scaling database with histograms, mask testing, statistical measurements, and eye diagrams. You can also use color grading to provide more visual information about the waveforms.

The Gray Scaling function uses the database in the size of the graticule area. Behind each pixel is a 16-bit counter. Each time a pixel is hit by data, the counter for that pixel is incremented. Each color used for the color grade mode represents a range of data counts. As the total count increases, the range of hits represented by each color also increases. The maximum count for each counter is 65,535.

There are five levels used in the gray-scaled mode. Each shade shows the number of hits per pixel over the graticule area, and represents a range of counts, which depends on the total number of hits. As the total count increases, the range of hits represented by each shade also increases. The shades are fixed and cannot be changed by the user.



Gray-scaling display style

You can use the gray-scaling persistence style to display waveforms that use the instrument measurement database. This database consists of all data samples displayed on the screen. The measurement database provides the data for the construction of histograms and performing mask tests.

If the gray-scaling persistence style is left active for a long period of time, the waveform will become saturated with the shades that represent the highest density of data counts.



Use gray-scaling in the Eye Diagram and Mask Test menus. The Eye Diagram and Mask Test measurement algorithms are based on the statistical accumulation of the data that the Gray Scaling mode uses internally.

Variable Gray Scaling

In the Variable Gray Scaling display style, the screen is not refreshed after every acquisition; instead, the screen is refreshed at a specified, user-selectable rate. You can vary the refresh time from minimum of 1 s to 200 s. You can change the refresh time with the REFRESH TIME variable.

If one of the following is changed when the instrument is in the Variable Gray Scaling display style, the displayed waveform is redrawn and any accumulated waveforms are cleared:

- Clear Display button is pressed
- An Autoscale button is executed
- A Default Setup button is executed
- The instrument is turned off

Infinite Gray Scaling

When you select the Infinite Gray Scaling display style, all the data points are kept on the display. With the Infinite Gray Scaling display style, all sampled data points are left on the display until one of the following occurs:

- Clear Display button is pressed
- An Autoscale button is executed
- A Default Setup button is executed
- The instrument is turned off

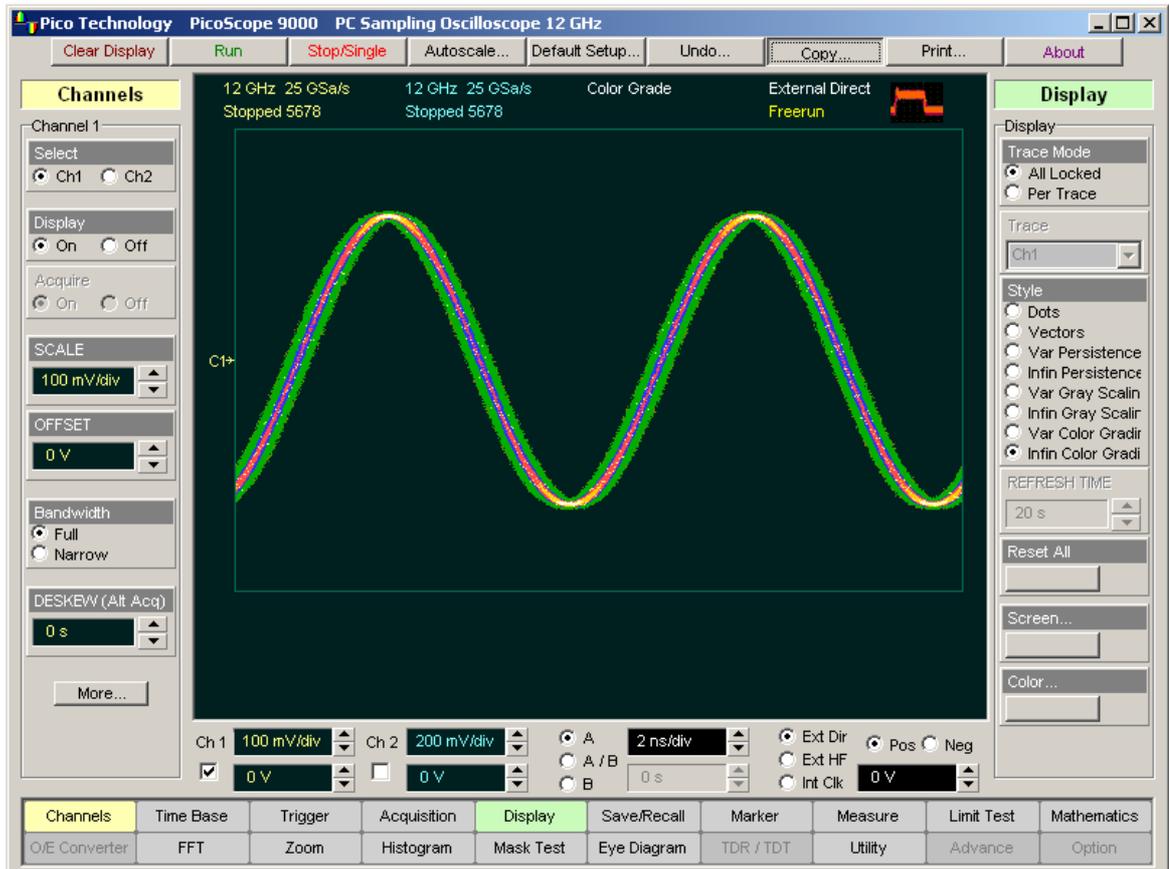
You can use infinite gray-scaling for worst-case characterization of signal noise, jitter and drift, or to see a waveform's envelope, look for timing violations, and find infrequent events.

Color Grading

This mode is similar to persistence mode. The only difference is that the accumulated points are color-graded (shaded with different colors) to indicate the density of the points, and a color-graded database is built. You can use the color-graded database with histograms, mask testing, statistical measurements, and eye diagrams. You can also use color grading to provide more visual information about the waveforms.

The Color Grading function uses the database in the size of the graticule area. Behind each pixel is a 16-bit counter. Each time a pixel is hit by data, the counter for that pixel is incremented. Each color used for the color grade mode represents a range of data counts. As the total count increases, the range of hits represented by each color also increases. The maximum count for each counter is 65,535.

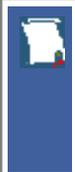
There are five colors used in the color-graded display. Each color shows the number of hits per pixel over the graticule area, and represents a range of counts, which depends on the total number of hits. As the total count increases, the range of hits represented by each color also increases. The colors can be changed from the [Color Grade](#) ^[72] menu.



Color-Graded Display Style

You can use the color grade persistence mode to display waveforms that use the instrument measurement database. This database consists of all data samples displayed on the screen. The measurement database provides the data for the construction of histograms and performing mask tests.

If the color grade persistence style is left active for a long period of time, the waveform will become saturated with the color that represents the highest density of data counts. The Color Grade Scale menu displays the color levels and the range of counts the color represents. Click the Color Grade Scale button to view the color levels.



Use gray-scaling in the Eye Diagram and Mask Test menus. The Eye Diagram and Mask Test measurement algorithms are based on the statistical accumulation of the data that the Gray Scaling mode uses internally.

The PicoScope 9000A has two color-grading settings:

- Variable Color Grading
- Infinite Color Grading

Variable Color Grading

In the Variable Color Grading display style the screen is not refreshed after every acquisition; instead, the screen is refreshed at a specified, user-selectable rate. You can vary the refresh time from minimum of 1 s to 200 s. You can change the refresh time with the REFRESH TIME variable.

If one of the following is changed when the instrument is in the Variable Color Grading display style, the displayed waveform is redrawn and any accumulated waveforms are cleared:

- Clear Display button is pressed
- An Autoscale button is executed
- A Default Setup button is executed
- The instrument is turned off

Infinite Color Grading

When you select the Infinite Color Grading display style, all the data points are kept on the display. With the Infinite Color Grading display style, all sampled data points are left on the display until one of the following occurs:

- Clear Display button is pressed
- An Autoscale button is executed
- A Default Setup button is executed
- The instrument is turned off

You can use infinite color grading for worst-case characterization of signal noise, jitter and drift, and to see a waveform's envelope, look for timing violations, and find infrequent events.

5.3.4 PERSISTENCE TIME / REFRESH TIME



PERSISTENCE TIME

The PERSISTENCE TIME variable works when the Variable Persistence display is selected in the [Style](#) ^[56] menu.

Persistence time is the amount of time for which a waveform sample appears on the display. In the Variable Persistence display style, a waveform sample point is displayed from 100 ms to 20 s. The default setting is 2 s.

This mode most closely simulates the phosphorescent persistence of an analog scope. Use variable persistence to view infrequent events and rapidly changing waveforms and watch the evolution of the waveform.

REFRESH TIME

The REFRESH TIME variable works with both the Variable Gray Scaling and the Variable Color Grading display styles.

Refresh time is a control of how often the screen is updated with new data. The range for refresh time is 1 to 200 s.

5.3.5 Reset All



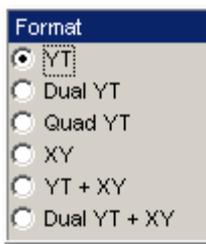
Click the Reset All button to return all traces setups to their default persistence settings.

5.3.6 Screen



The Screen... button gives you access to a second-level menu that allows you to define the display area in different ways.

5.3.6.1 Format



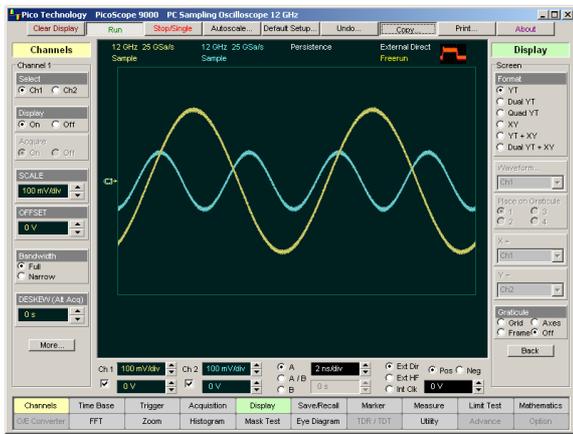
The Format menu determines how the instrument draws the waveforms on the display. Six formats are used in the PicoScope 9000A.

YT

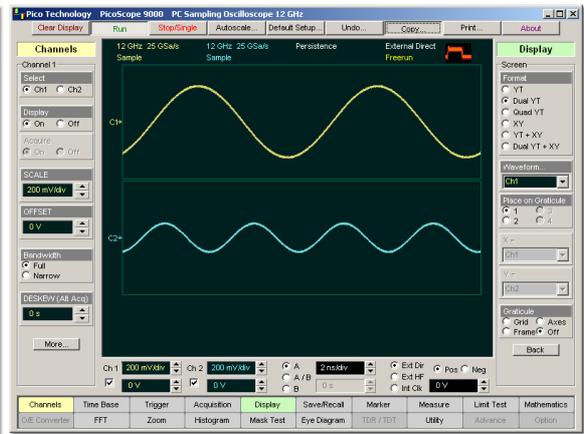
The YT format is the normal time (on the horizontal axis) versus voltage (on the vertical axis) format. The entire display area is one screen and any displayed waveforms are superimposed on top of each other.

Dual YT

The Dual YT format is the normal time (on the horizontal axis) versus voltage (on the vertical axis) format, but with the display area divided into two equal screens.



YT Display Format



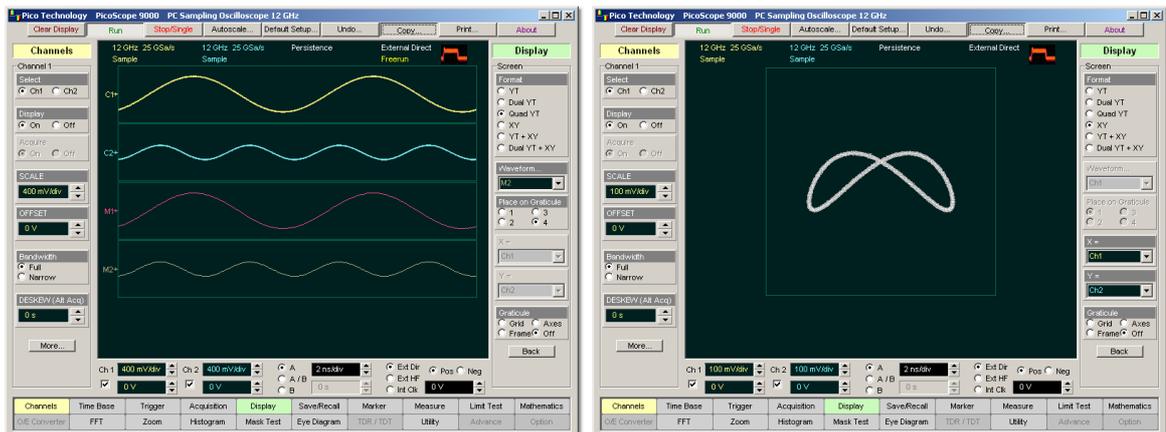
Dual YT Display Format

Quad YT

The Quad YT format is the normal time (on the horizontal axis) versus voltage (on the vertical axis) format, with the display area divided into four equal screens.

XY

The XY format displays voltages of two waveforms against each other, and draws the Source 1 versus Source 2 display of the two selected sources. Source 1's amplitude is plotted on the horizontal X axis and the Source 2's amplitude is plotted on the vertical Y axis.



Quad YT Display Format

XT Display Format

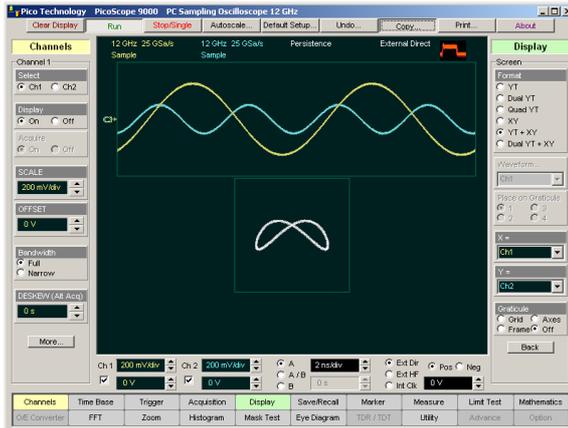
YT+XY

The YT + XY format displays both YT and XY pictures. The YT format appears on the upper part of the screen, and the XY format on the lower part of the screen. The YT format display area is one screen and any displayed waveforms are superimposed on top of each other.

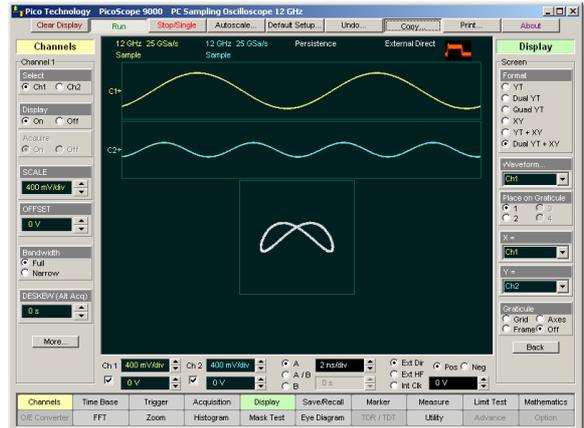
Dual YT + XY

The Dual YT + XY format displays both YT and XY pictures. The YT format appears on the upper part of the screen, and the XY format on the lower part of the screen. The YT format display area is divided into two equal screens.

You can use the XY format to compare frequency and phase relationships between two signals. The XY format can also be used with transducers to display strain versus displacement, flow versus pressure, volts versus current, or voltage versus frequency.

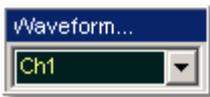


YT+XY Display Format



Dual YT+XY Display Format

5.3.6.2 Waveform



With the Waveform function you can set the waveform, which will be placed on the graticule, selected with the Place on Graticule menu.

The waveform source can be selected from:

- channels 1 and 2
- functions 1 through 4
- waveform memories 1 through 4
- spectrums 1 and 2

Any waveform selected with the Waveform function is placed on the graticule chosen with the Place on Graticule menu.

5.3.6.3 Place on Graticule



Place on Graticule

With the Place on Graticule menu you can place a waveform, selected by the Waveform function, on any possible graticule.

You can place any waveform selected as source to any graticule. For example, you can place the M1 waveform memory on the fourth graticule, or the F1 function on the first graticule.

5.3.6.4 X= and Y=



X=

The X= control selects the waveform source related to the horizontal X axis. You can set the X= source to:

- channels 1 and 2
- functions 1 through 4
- waveform memories 1 through 4
- spectrum 1 and 2

Y=

The Y= selects the waveform source related to the vertical Y axis. You can set the Y= source to:

- channels 1 and 2
- functions 1 through 4
- waveform memories 1 through 4
- spectrum 1 and 2

5.3.6.5 Graticule



The PicoScope 9000A has a 10 by 8 display graticule grid, which you can turn on or off. The Graticule menu selection is:

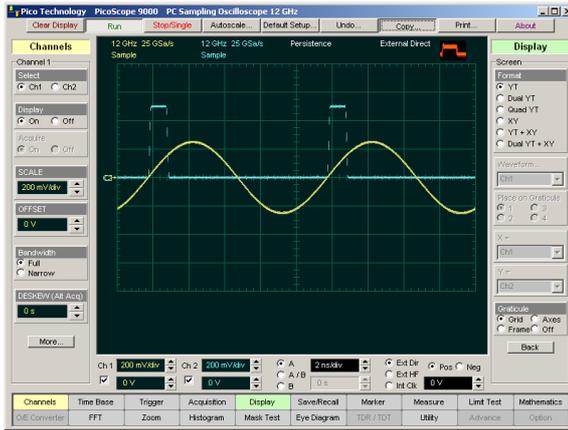
- Grid
- Axes
- Frame
- Off

Off. Turns the background graticule off. The displayed waveforms and waveform's information is not turned off.

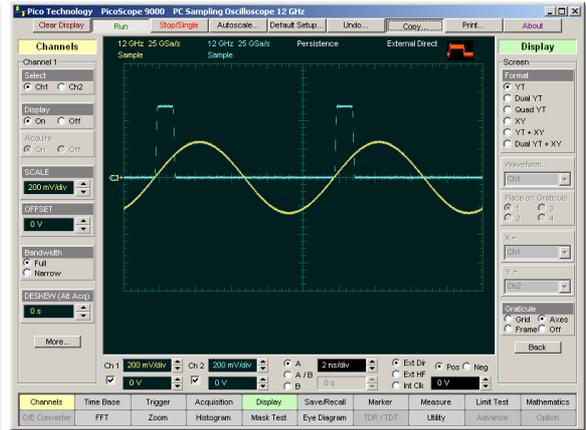
Frame. Displays the outside border with a measurement scale. The measurement scale is incremented/decremented with major divisions and minor divisions based on the vertical and horizontal measurement settings.

Axes. Displays the outside border with a measurement scale and a measurement scale crossing at mid-screen.

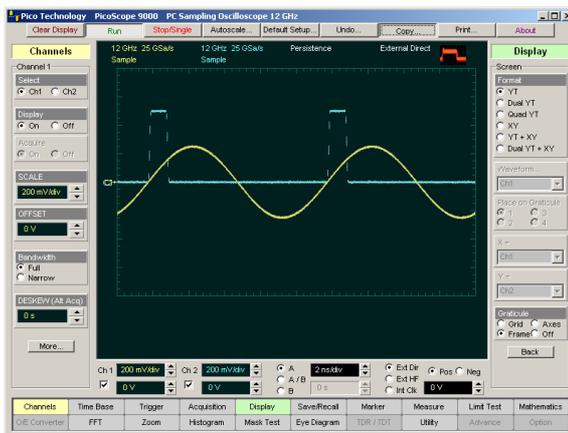
Grid. The Grid background is complete graticule with ten horizontal major divisions and eight vertical major divisions. Vertically one minor division is one-quarter of a major division; and horizontally, one minor division is one-fifth of a major division.



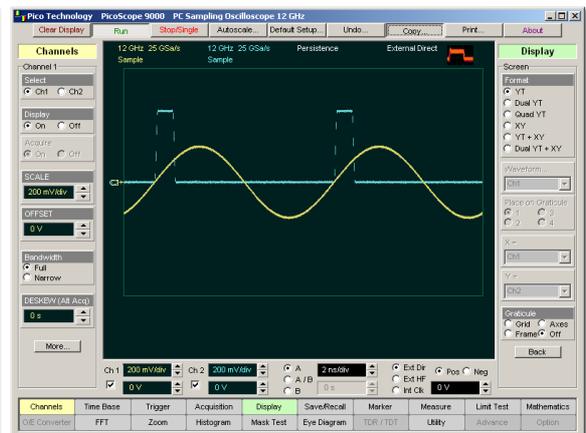
Grid Graticule



Axes Graticule



Frame Graticule



Graticule is off

5.3.7 Color



The Color... button gives you access to a second-level menu that allows you to define the display colors. You may modify the color of many items (display elements) that are displayed on the screen. For example, you can change the color of an input waveform channel for better visibility.

5.3.7.1 Item



The Item allows you to choose from the list of display elements. You can modify the color of the channels, functions, display memories, spectrums, histogram, graticule, or screen. The color of the selected display element can be changed with the Set Color menu.

5.3.7.2 Set Color



Clicking the Set Color button recalls the Windows Color Dialog:



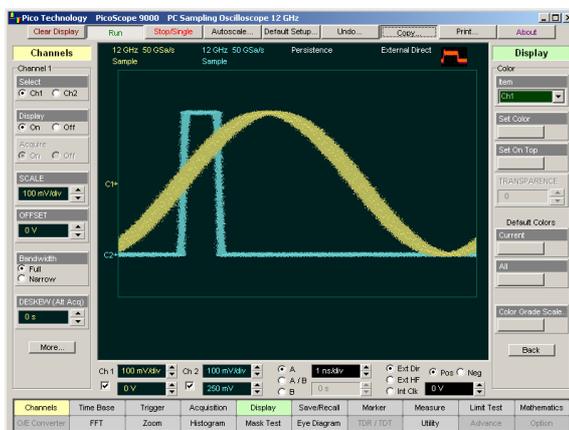
Windows Color Dialog

You can change the color of every item selected from the I tem drop-down list box.

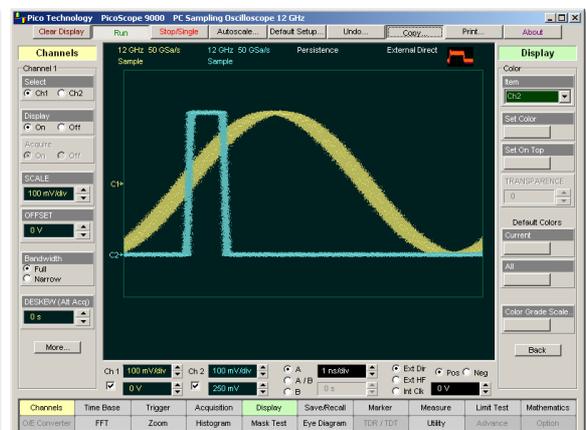
5.3.7.3 Set On Top



Click the Set On Top if you want to superimpose the display element selected from the I tem list over all another display elements.



Channel 1 is superimposed on top



Channel 2 is superimposed on top

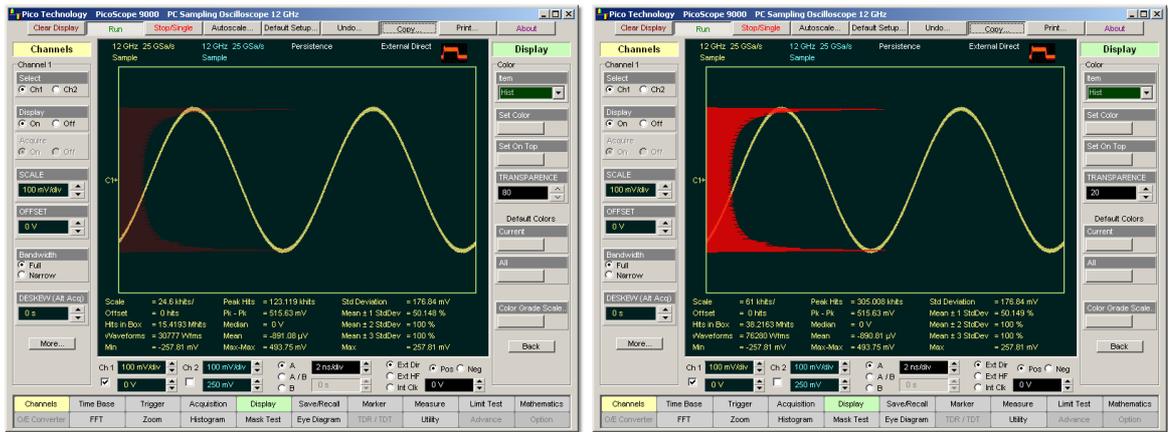
5.3.7.4 TRANSPARENCY



You can change the transparency of several display elements selected from the I tem menu. They are:

- Histogram
- Mask

The TRANSPARENCY control increases or decreases the transparency effect.



A histogram with 80% transparency

A histogram with 20% transparency

5.3.7.5 Current



Clicking the Current button returns the selected display element to the factory default color.

5.3.7.6 All



Clicking the All returns all display elements to the factory default colors.

5.3.7.7 Color Grade Scale



Clicking the Color Grade Scale... button opens the Color Grade Scale menu with a list of five colors used in the color grade display.

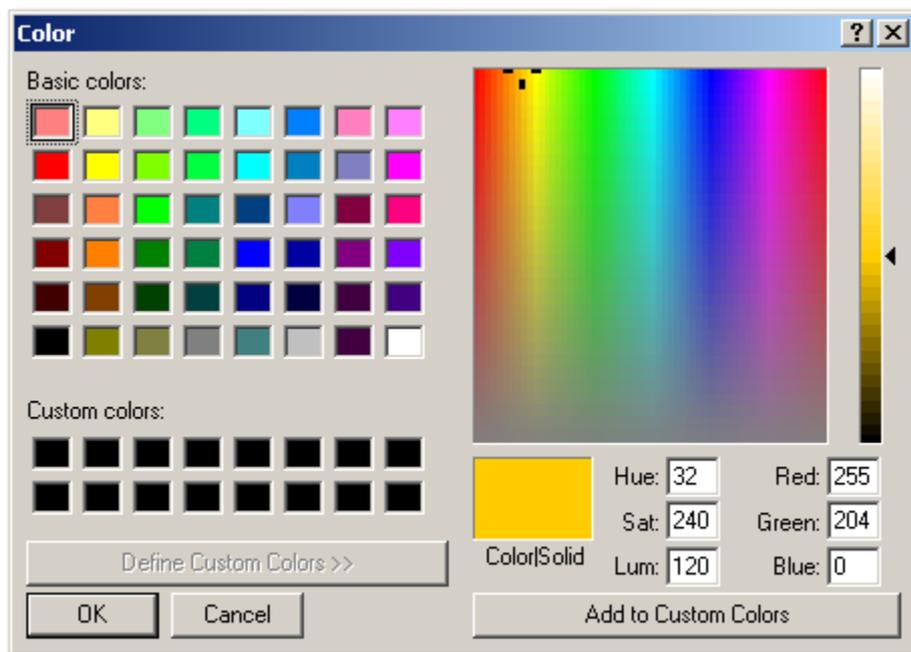
5.3.7.7.1 Color Grade Scale

The Color Grade Scale menu defines the five colors used in the color grade display. The algorithm used in the PicoScope 9000A depends on the maximum number of hits for any pixel in the display. An example of the assignment of colors is shown in the table below. Maximum in the table represents the maximum number of hits in any bin, which for this algorithm must be at least 16.

A sample assignment of colors to Hit Density:

Hit Density	Default color	Color
50% to 100%	White	<div style="border: 1px solid gray; padding: 5px; width: fit-content;"> 50% - 100% <input type="button" value="Set Color"/> </div>
25% to 50%	Yellow	<div style="border: 1px solid gray; padding: 5px; width: fit-content;"> 25% - 50% <input type="button" value="Set Color"/> </div>
12.5% to 25%	Rose	<div style="border: 1px solid gray; padding: 5px; width: fit-content;"> 12.5% - 25% <input type="button" value="Set Color"/> </div>
6.25% to 12.5%	Light Blue	<div style="border: 1px solid gray; padding: 5px; width: fit-content;"> 6.25% - 12.5% <input type="button" value="Set Color"/> </div>
0% to 6.25%	Green	<div style="border: 1px solid gray; padding: 5px; width: fit-content;"> 0 - 6.25% <input type="button" value="Set Color"/> </div>

Click Set Color to recall the Windows Color Dialog:



Windows Color Dialog

5.3.7.7.2 Default Colors

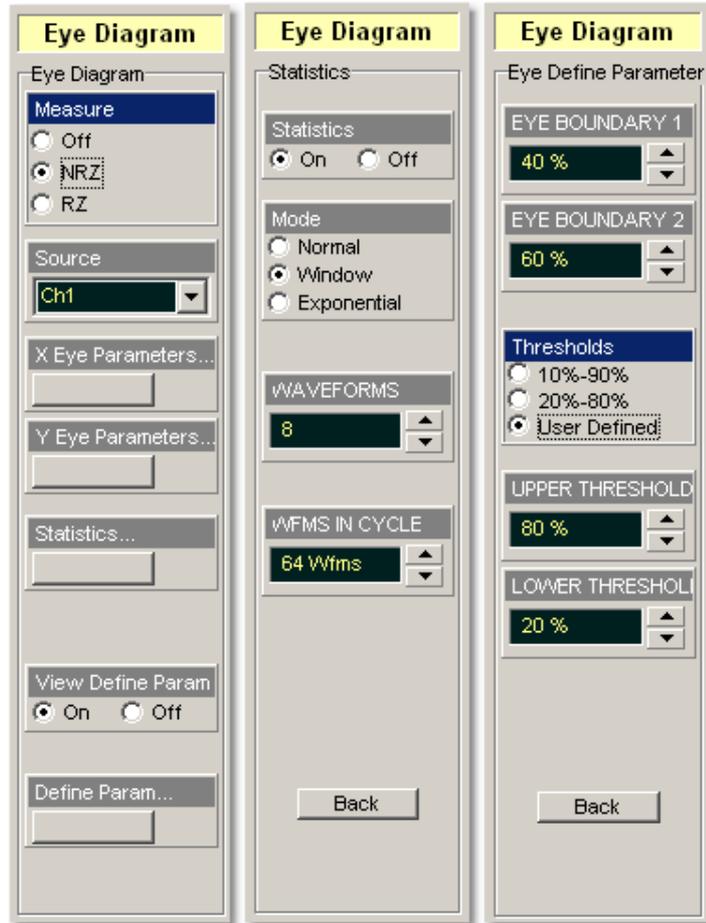


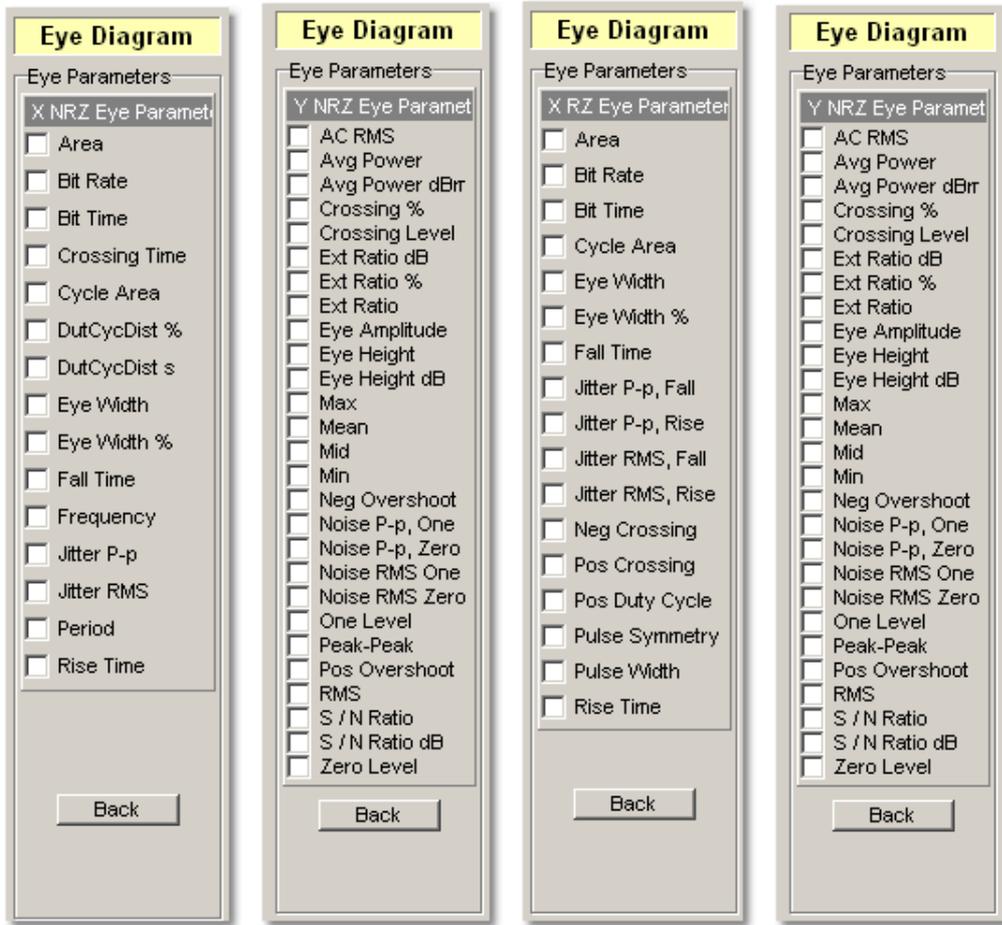
Clicking the Default Colors button returns all five colors used in the color-graded display to the factory default.

5.4 Eye Diagram Menu



The Eye Diagram menu allows you to perform eye diagram measurements.





The Eye Diagram menu



The measurement algorithms for Eye Parameters will only work when an eye diagram, and not a pulse, is present on the screen.

Eye measurements are based on statistical data that is acquired and stored in the measurement database. The algorithms are dependent upon histogram means calculated from the measurement database. Therefore, if you want to perform eye measurements, it is necessary that you first produce an eye diagram by triggering the instrument with a synchronous clock signal. Measurements made on a pulse waveform while in the Eye Diagram menu will fail.

Once the Eye Diagram measure menu has been selected, the measurement database is enabled. This database consists of all data samples displayed on the screen. The measurement database provides the data for the construction of histograms, generation of mask tests, and a visual representation of the eye via the color-graded display mode.



Once you are in the Eye Diagram menu, perform an Autoscale. This will ensure that an optimum eye diagram is displayed on the graticule. An optimum eye diagram consists of a full display of the eye in addition to portions of the waveform preceding and following the eye.

Data is acquired, histograms are built, and absolute maximum and minimum voltage/power levels as well as relative maximum (one) and minimum (zero) voltage/power levels are determined. The crossing points of the eye are located, the threshold levels are calculated, and then, depending on the specific measurement(s) activated, the requested parametric measurements are calculated.

Eye measurements are made in a fashion similar to many of the automatic measurements built into the instruments such as Rise and Fall Time, Peak-Peak, and Frequency. Up to four parametric measurements can be active whenever valid data exists. These measurements can include any of the eye measurements under the X Eye Parameters... and Y Eye Parameters... menus.

Eye measurements can be performed on a persistence or color-graded database.

5.4.1 Measure



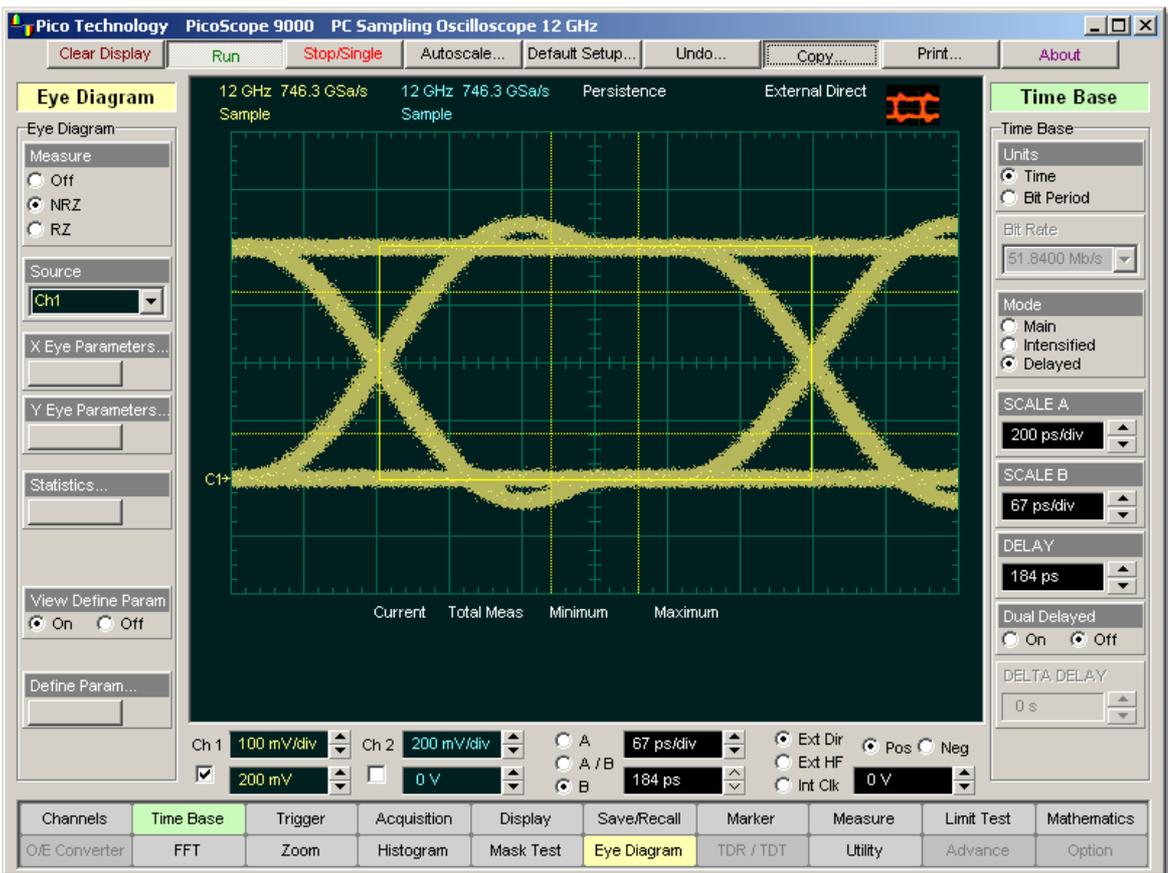
NRZ

Clicking the NRZ radio button in the Measure menu starts the instrument calculating the One Level, Zero Level, Left Crossing and Right Crossing for NRZ types of signal. After the calculations are finished the Eye Window, which has a red color, will appear.



NRZ (Non-return to zero)

A type of signal coding that ensures, in any one bit period, that the signal is turned on for the entire duration of a logical one pulse and turned off (or nearly off) for the entire duration of a logical zero pulse.



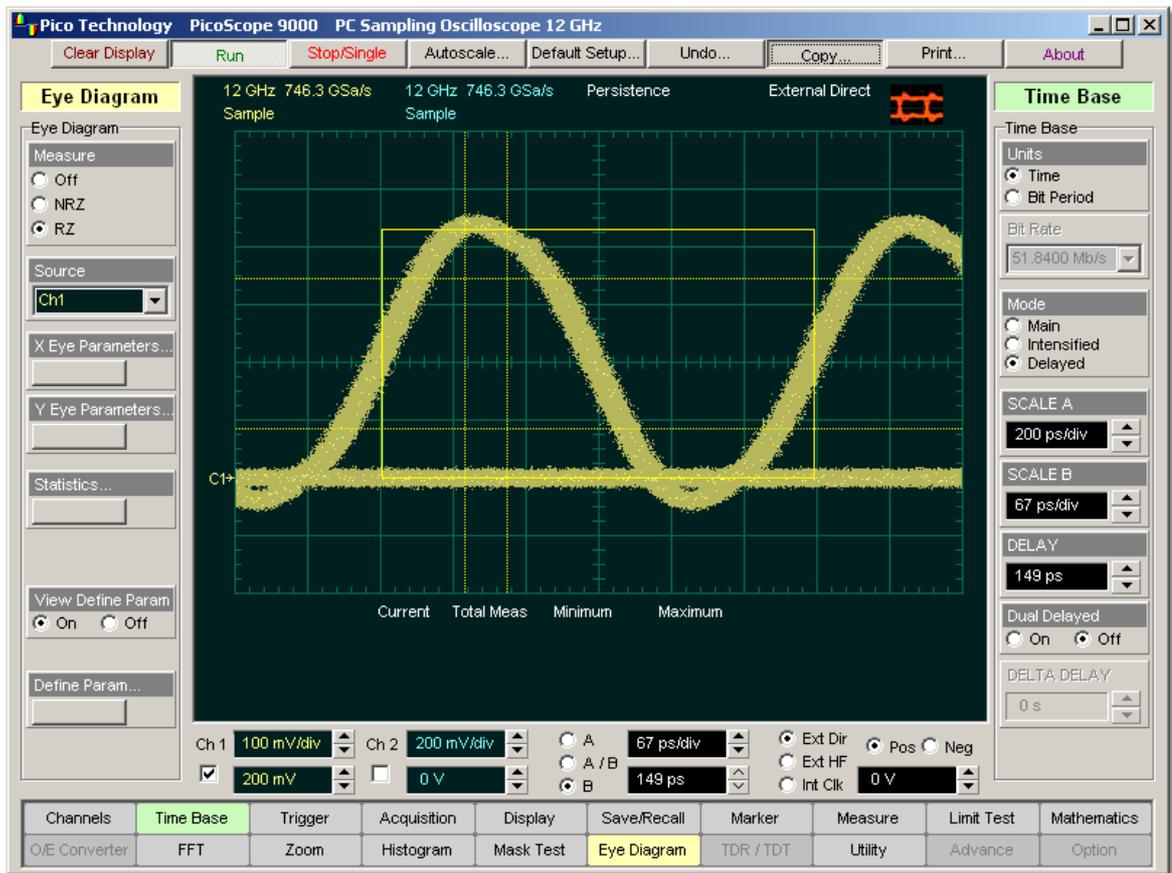
The Levels, Crossings and Eye Boundaries of the NRZ Eye Window

RZ

Clicking the RZ radio button in the Measure menu starts the instrument calculating the One Level, Zero Level, Left Crossing and Right Crossing for RZ types of signal. After the calculations are finished the Eye Window, which has a red color, will appear.

RZ (Return to zero)

A type of signal coding that ensures, in any one bit period, that the signal is turned on for the first half of a logical one pulse and turned off (or nearly off) for the second half of the logical one pulse. As with NRZ coding, the signal is turned off (or nearly off) for the entire duration of a logical zero pulse.



The Levels, Crossings and Eye Boundaries of RZ Eye Window

Off

Clicking the Off radio button stops running the test. The Eye Window, which has a red color, disappears.

The Eye Boundaries provide the time boundaries within which signal parameters for eye diagrams are measured.

Measurements Results

The instrument displays the results of eye diagram measurements in the Measurement Area of the GUI. These values are displayed on tabs.

	Current	Total Meas	Minimum	Maximum
Bit Rate (Ch1)	2.508 GBit/s	2063	2.507 GBit/s	2.508 GBit/s
Eye Width (Ch1)	365.7 ps	1867	365.6 ps	366.6 ps
Crossing % (Ch1)	50.02 %	1346	49.99 %	50.03 %
Eye Height (Ch1)	353.4 mV	1136	353.3 mV	353.4 mV

An example of the Eye Diagram Measure tab

The tabs only appear as the selected measurements are performed. For example, if you perform a Bit Rate measurement on channel 1, only this tab will appear on the display.

The measurement database and the graticule display will clear when you perform the following events:

- Switch between operating modes in the Display menu
- Change vertical and horizontal scale and position
- Click on the Clear Display button

The Eye Diagram Measure tab displays a maximum of four measurements at one time. The measurements are listed in the order in which they were performed.

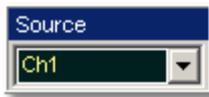
The Measure tab displays the following measurement statistics for each measurement:

- Current: the current value measured in the measurement database
- Total Meas: the total number of acquired measurement cycles
- Minimum: the minimum current value measured in the measurement database
- Maximum: the maximum current value measured in the measurement database



The measurement statistics reported will vary depending on the mode of operation selected.

5.4.2 Source



The Source control selects the source you are measuring. The measurement read-outs of parameters will have the same color as the selected source.

5.4.3 X Eye Parameters



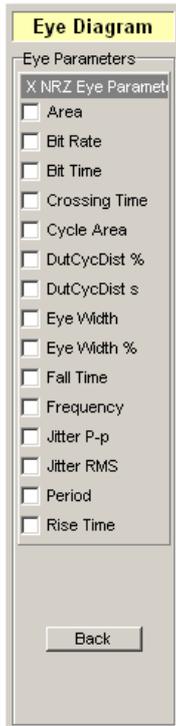
Click the X Eye Parameters... button to open the list of NRZ or RZ eye parameters and select any of the eye parameters for measurements.

5.4.4 Y Eye Parameters

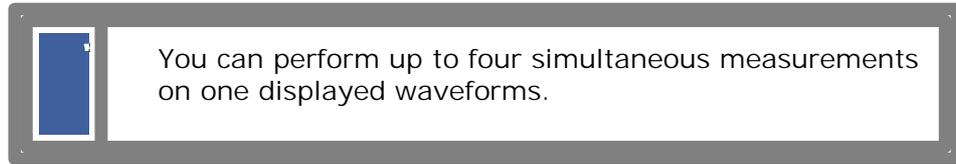


Clicking the Y Eye Parameters... button opens the list of NRZ or RZ eye parameters to select any of the eye parameters for measurements.

5.4.5 X NRZ Eye Parameters



The list of X NRZ Eye Parameters includes fifteen eye parameters.



The measurement algorithms for X NRZ Eye Parameters will only work when an NRZ eye diagram, and not an RZ eye diagram or a pulse, is present on the screen. Eye measurements are based on statistical data that is acquired and stored in the measurement database. The algorithms are dependent upon histogram means calculated from the measurement database. Therefore, if you want to perform eye measurements, it is necessary that you first produce an eye diagram by triggering the instrument with a synchronous clock signal.

Measurements made on an RZ eye diagram or a pulse waveform while in the X NRZ Eye Parameters menu will fail.

5.4.5.1 NRZ Area

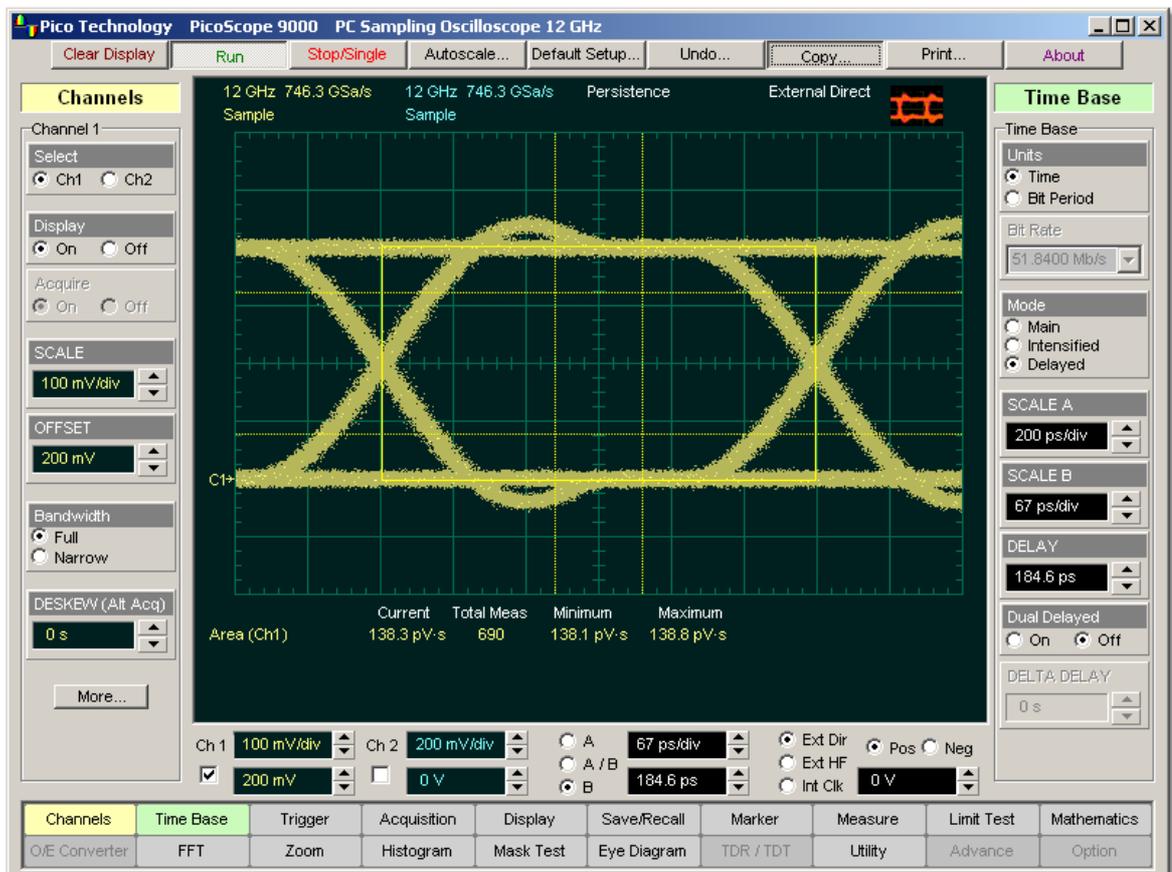


NRZ Area is a measure of the area under the curve for the NRZ waveform within the full display window. The area measured above ground is positive; the area measured below ground is negative.

The NRZ Area is determined as follows:

$$NRZ_Area = \frac{\Delta t}{N} \sum_{n=1}^N VertPos(s_n)$$

over all N samples $s_{1...N}$ in the measured region (full display window) of duration t .



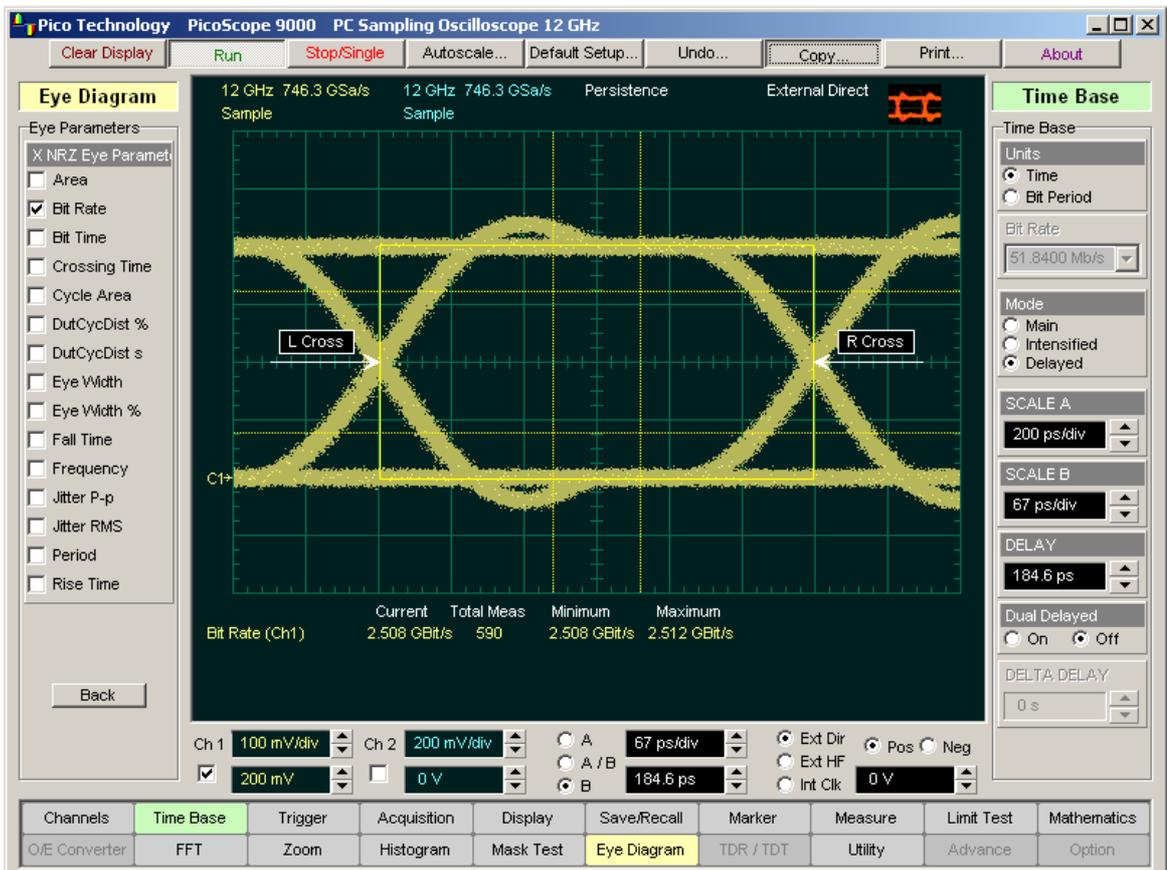
NRZ Area definition

This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.5.2 NRZ Bit Rate

 Bit Rate

NRZ Bit Rate is the inverse of bit time (1/bit time). The bit time is a measure of the horizontal opening of an eye diagram at the crossing points of the eye.



NRZ Bit Rate definition

To compute bit time (bit period), the crossing points of the eye are first located. Then a vertically thin measurement window is placed horizontally through the crossing points. The data within this measurement window is analysed. This measurement window is created to be extremely small so that the width of the crossing points is not affected by the rise time and fall time of the waveform.

Once the bit period has been determined, the inverse value is calculated to determine the bit rate.

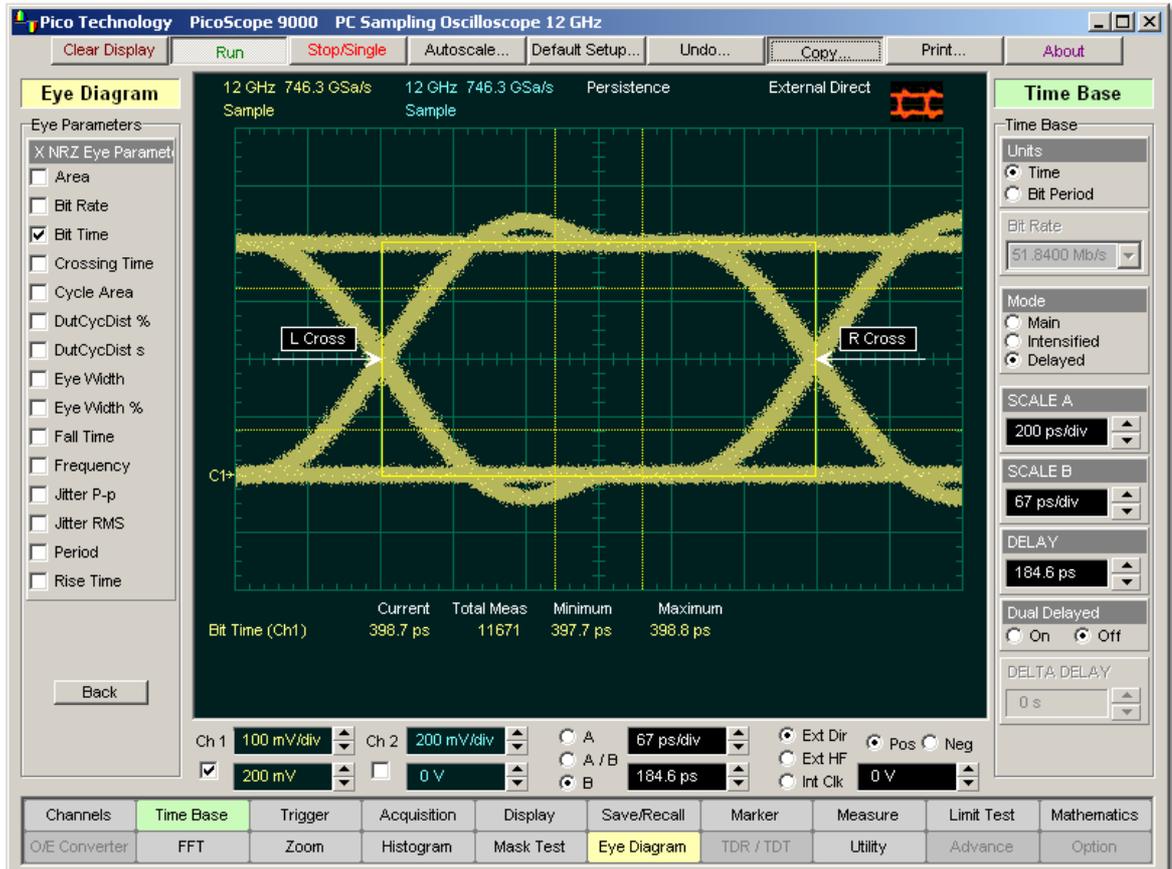
$$NRZ \text{ Bit Rate} = 1 / \text{Bit Time}$$

Also see [NRZ Bit Time](#) ^[85].

5.4.5.3 NRZ Bit Time



NRZ Bit Time is a measure of the horizontal opening of an eye diagram at the crossing points of the eye.



NRZ Bit Time definition

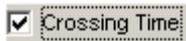
NRZ Bit Time can be determined as:

$$NRZ\ Bit\ Time = T_{cross2} - T_{cross1}$$

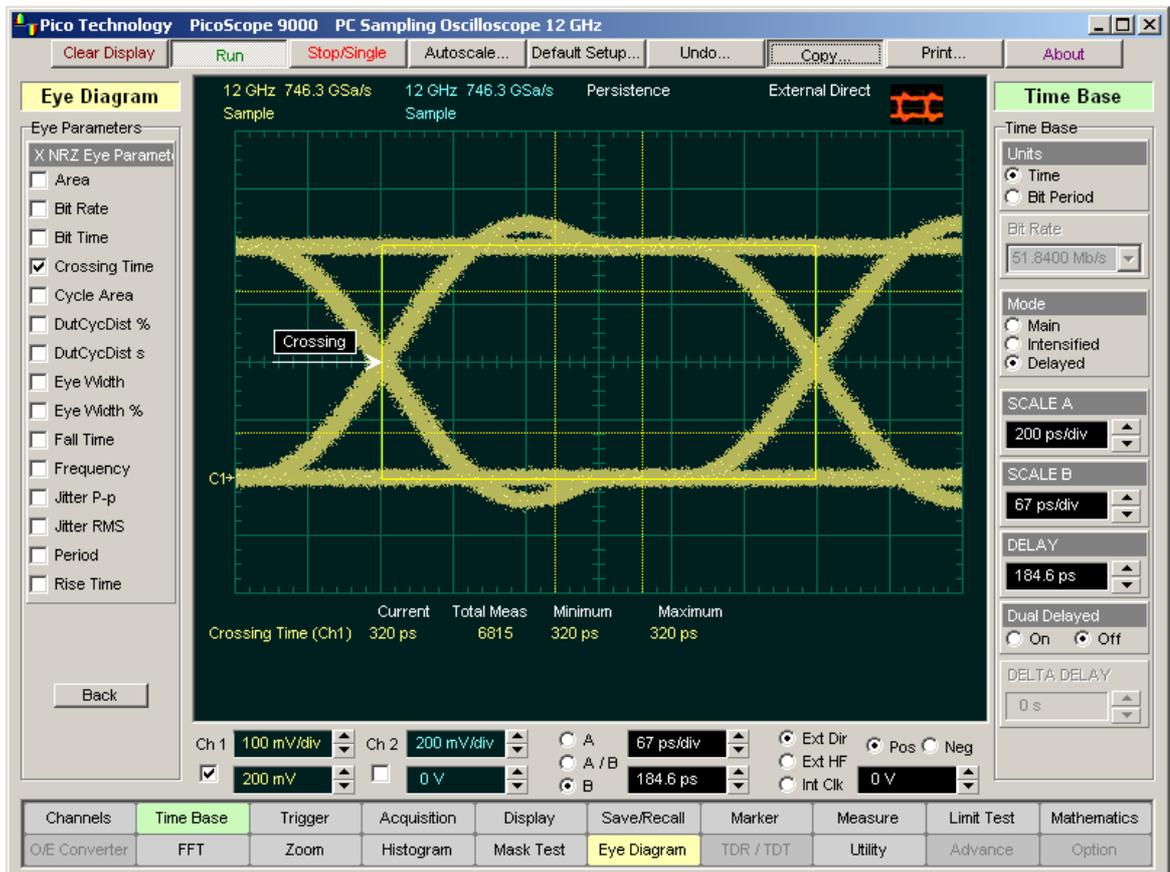
Where T_{cross2} and T_{cross1} are the mean of the histogram of the two consecutive eye crossings (Right Crossing and Left Crossing).

This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.5.4 NRZ Crossing Time



NRZ Crossing Time is a measure of the horizontal position of the leftmost eye crossing.



NRZ Crossing Time definition.

Data is sampled on a horizontal slice at the eye crossing, and the mean of the horizontal histogram returns the crossing time.

NRZ Crossing Time can be determined as:

$$NRZ\ Crossing\ Time = T_{cross1} + T_{delay}$$

This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.5.5 NRZ Cycle Area

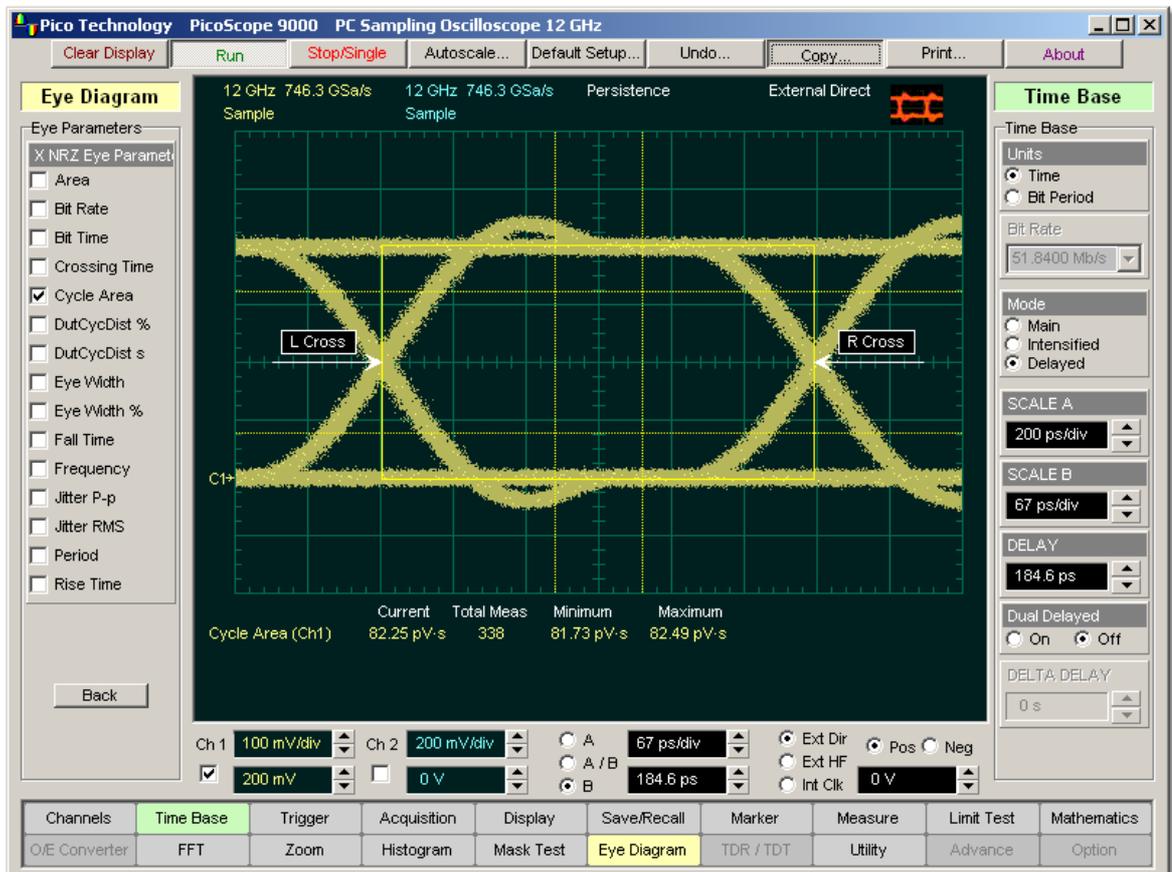


NRZ Cycle Area is a measure of the area under the curve for the first NRZ bit time within the measurement region. Area measured above ground is positive; area measured below ground is negative.

The NRZ Cycle Area is determined as follows:

$$NRZ_CycleArea = \frac{\Delta t}{N} \sum_{n=1}^N VertPos(s_n)$$

over all N samples $S_1...S_N$ within the measured region (eye window) of duration t between Left Crossings and Right Crossings. Neither slope nor direction is settable.



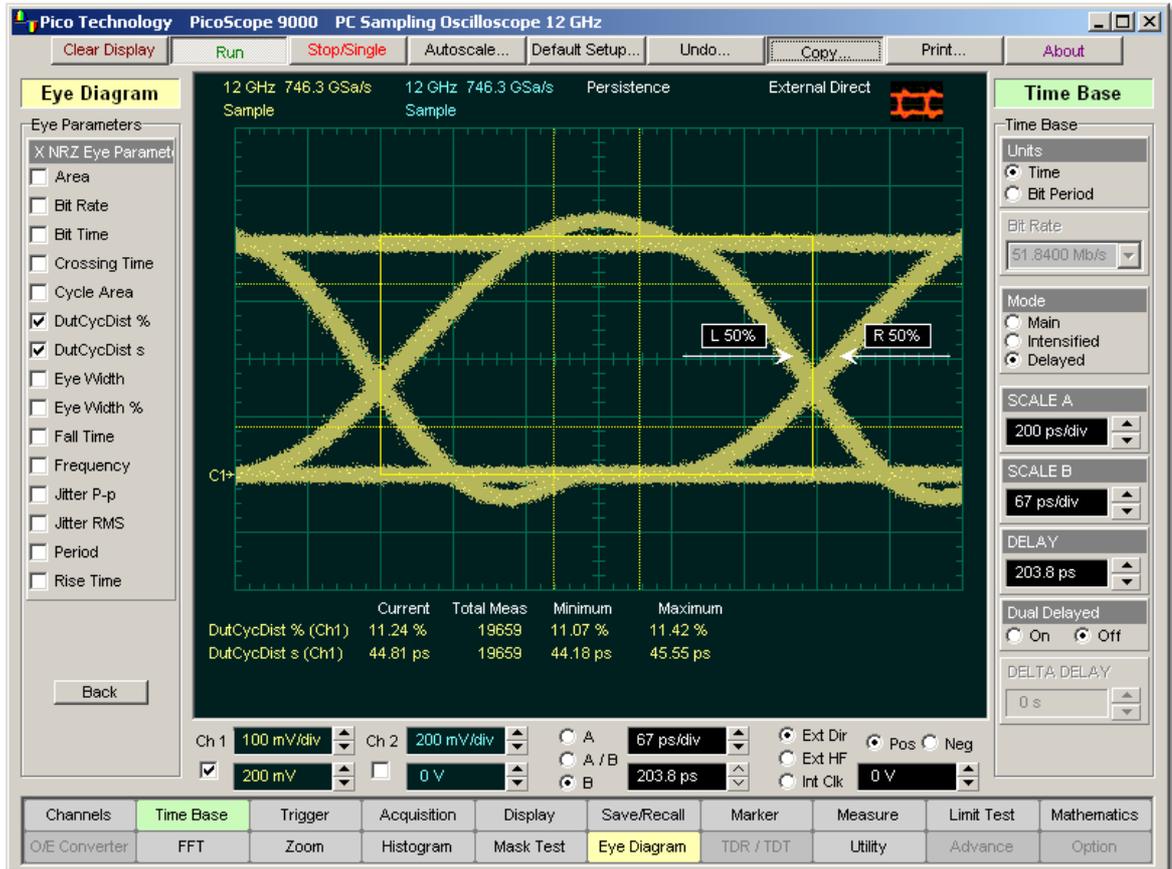
NRZ Cycle Area definition

This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.5.6 NRZ Duty Cycle Distortion % and NRZ Duty Cycle Distortion s

- DutCycDist %
- DutCycDist s

NRZ Duty Cycle Distortion is a measure of the time between the falling edge and the rising edge of the eye pattern at the middle threshold (50% level).



Measurement of Duty Cycle Distortion. NRZ eye diagram has significant distortion.

The instrument constructs a histogram that records the time at which the rising edge and falling edge cross the middle threshold. If the falling edge and the rising edge intersect precisely at the middle thresholds, there is no duty cycle distortion. NRZ Duty Cycle Distortion is measured by histogram analysis at the crossing points and middle threshold.



The algorithm for calculating NRZ Duty Cycle Distortion is dependent upon the edge that crosses the threshold first. Therefore, the falling edge may occur prior to the rising edge. Ideally, both the rising and falling edges intersect precisely at the 50% threshold level. That results in no duty cycle distortion.

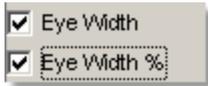
NRZ Duty Cycle Distortion can be displayed in two formats: time or percent. In the time format (DutCycDis s), the actual time between the median falling edge and the median rising edge at the middle thresholds is determined. In the percentage format (DutCycDis %), the time difference is determined as a percentage of the full bit time.

The NRZ Duty Cycle Distortion is determined as follows:

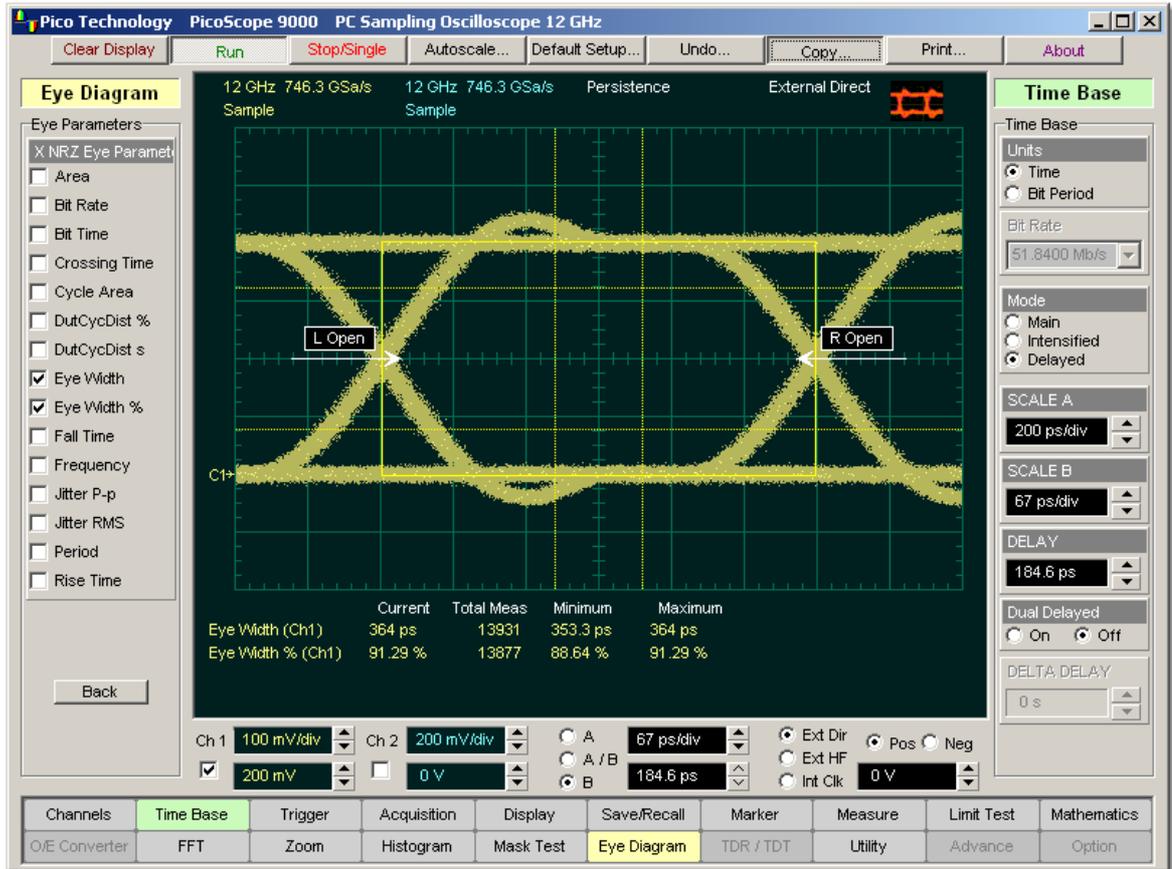
$$NRZ_DutyCycleDistortion = Trise_{50\text{ percent}} - Tfall_{50\text{ percent}}$$

$$NRZ_DutyCycleDistortion = \frac{Trise_{50\text{ percent}} - Tfall_{50\text{ percent}}}{BitPeriod}$$

5.4.5.7 NRZ Eye Width and NRZ Eye Width %



NRZ Eye Width is a measure of the horizontal opening of an eye diagram. Ideally, the eye width would be measured between the crossing points of the eye. A horizontal time histogram is constructed to determine the mean location at the crossing points, as well as statistical distribution of the crossing points. As would be expected, noise and jitter will cause a large variance in the location of the crossing points and result in the closure of the eye.



NRZ Eye Width definition

The eye width is determined using the time difference between the 3 (standard deviation) points of the crossing point histograms (Eye Width measurement).

$$NRZ_EyeWidth = (T_{cross2} - 3\sigma_{cross2}) - (T_{cross1} - 3\sigma_{cross1})$$

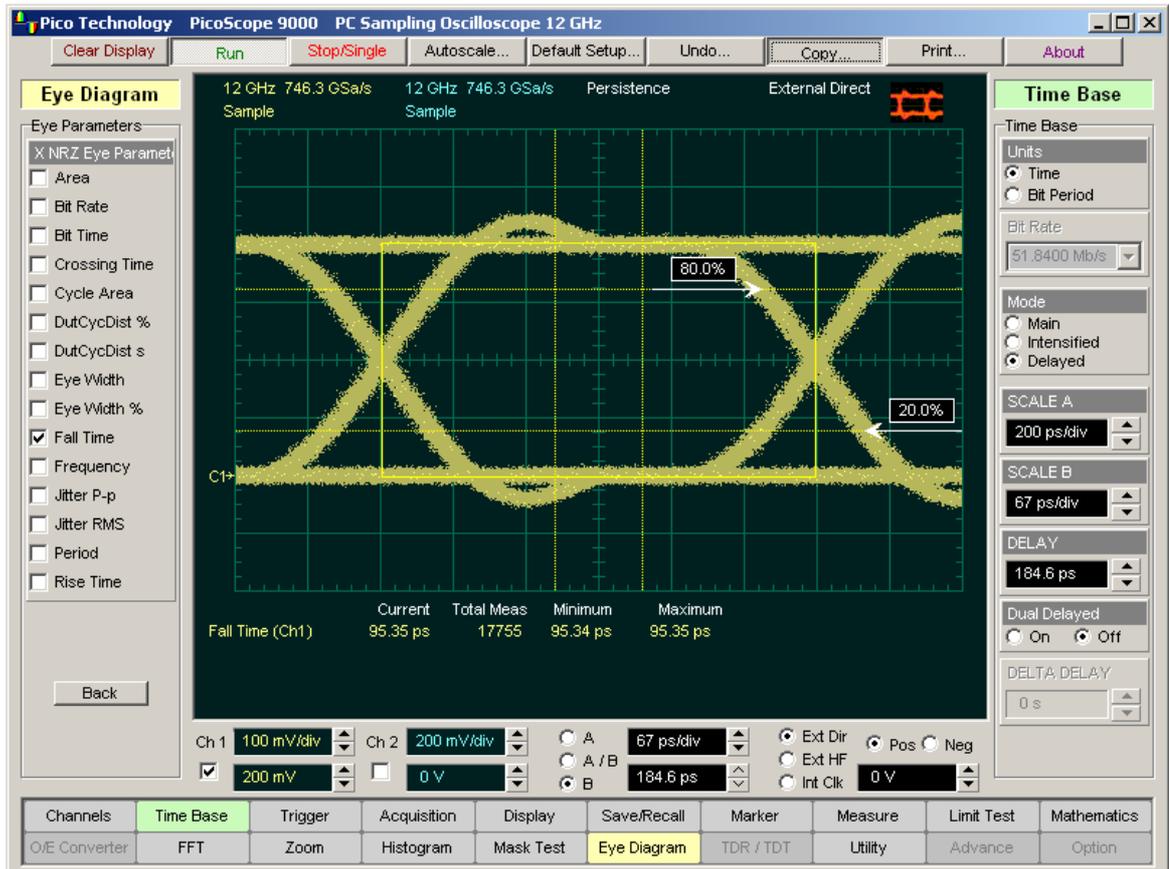
You can choose to view eye width as a ratio of the time difference between the 3 points of the crossing point histograms relative to the time between adjacent crossing points (bit period). The eye width can then be expressed in percent of the bit period (Eye Width % measurement).

$$NRZ_EyeWidth_ \% = \frac{(T_{cross2} - 3\sigma_{cross2}) - (T_{cross1} - 3\sigma_{cross1})}{T_{cross2} - T_{cross1}}$$

5.4.5.8 NRZ Fall Time

 Fall Time

NRZ Fall Time is a measure of the mean transition time of the data on the downward slope of an eye diagram. The data crosses through the following three thresholds: the upper, middle, and lower thresholds, as well as through the eye crossing points.



NRZ Fall Time definition

A histogram is first constructed to find the mean location of the crossing points relative to the one level and zero level. Histograms are then constructed at each of the three threshold levels (for example, the 10%, 50%, and 90% points on the transition). The instrument analyses each histogram to determine the histogram mean at which the data crosses the separate threshold levels.

Once the scanning of the waveform is complete, and the instrument has identified the mean location for each threshold crossed, then fall time can be computed.

$$\text{NRZ Fall Time} = (\text{Time at the Lower Threshold Crossing}) - (\text{Time at the Upper Threshold Crossing})$$

The instrument has two standard threshold levels for which fall time may be measured. The default setting is between the 20% and 80% points on the transition, and the second is between the 10% and 90% points on the transition. The 20% to 80% transition is recommended for devices with significant pulse distortion. Also, user defined threshold levels can be selected. You can define the threshold settings that you want by going to the [Define Parameters/Thresholds](#) ⁽¹⁶⁵⁾ menu.



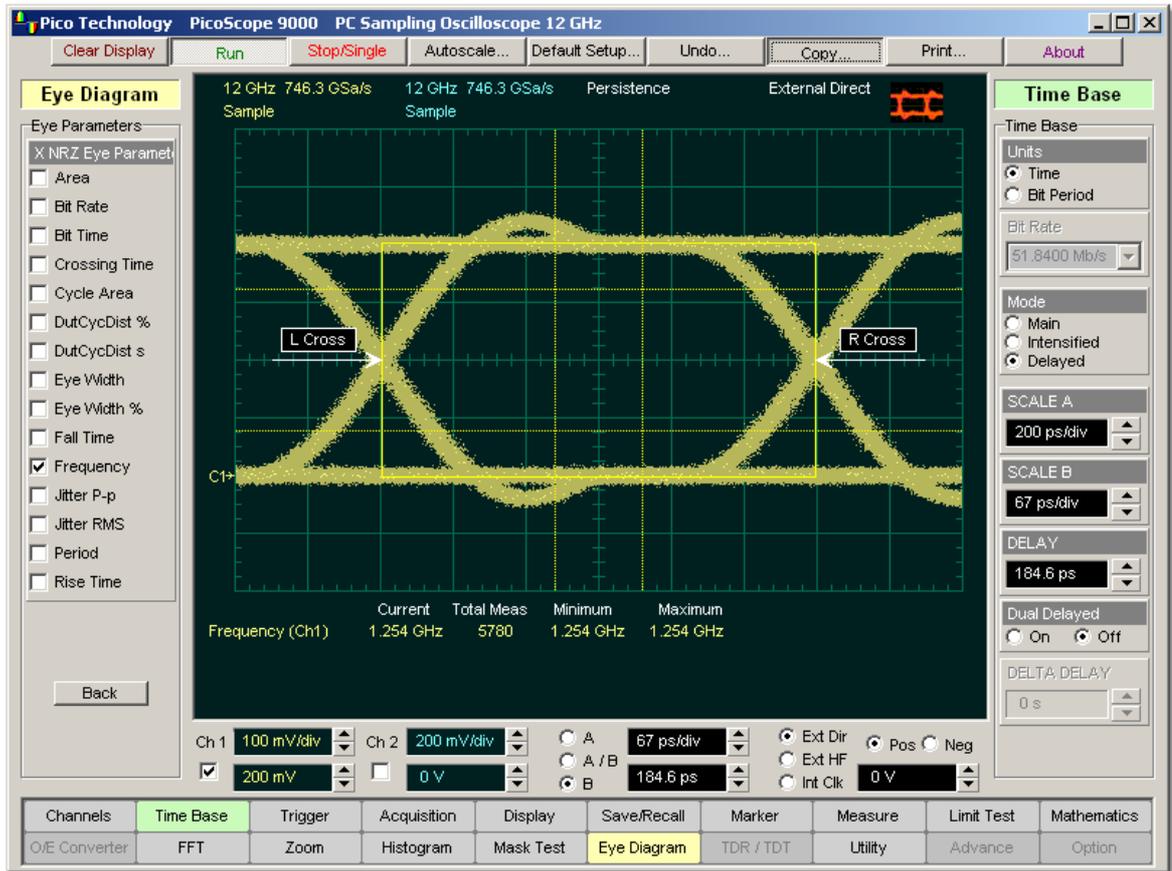
If the fall time relative to the time per division is a small value, the data acquired at the threshold levels on the falling edge will not yield accurate measurement results. (The falling edge will appear very steep on the display screen.)

If the falling edge of your eye diagram is steep, increase the timebase (horizontal scale) on the display so that the falling edge covers at least half a graticule division. The instrument will be able to discern the data at the threshold levels, producing more accurate results.

5.4.5.9 NRZ Frequency



NRZ Frequency is defined as half of the inverse of the time interval between two consecutive eye crossing points (i.e. the reciprocal of the Period). It would be the frequency of a digital signal of a 0-1-0-1... stream.



NRZ Frequency definition

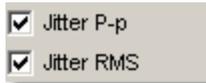
The NRZ Frequency is determined as follows:

$$NRZ_Frequency = \frac{1}{2(T_{cross2} - T_{cross1})}$$

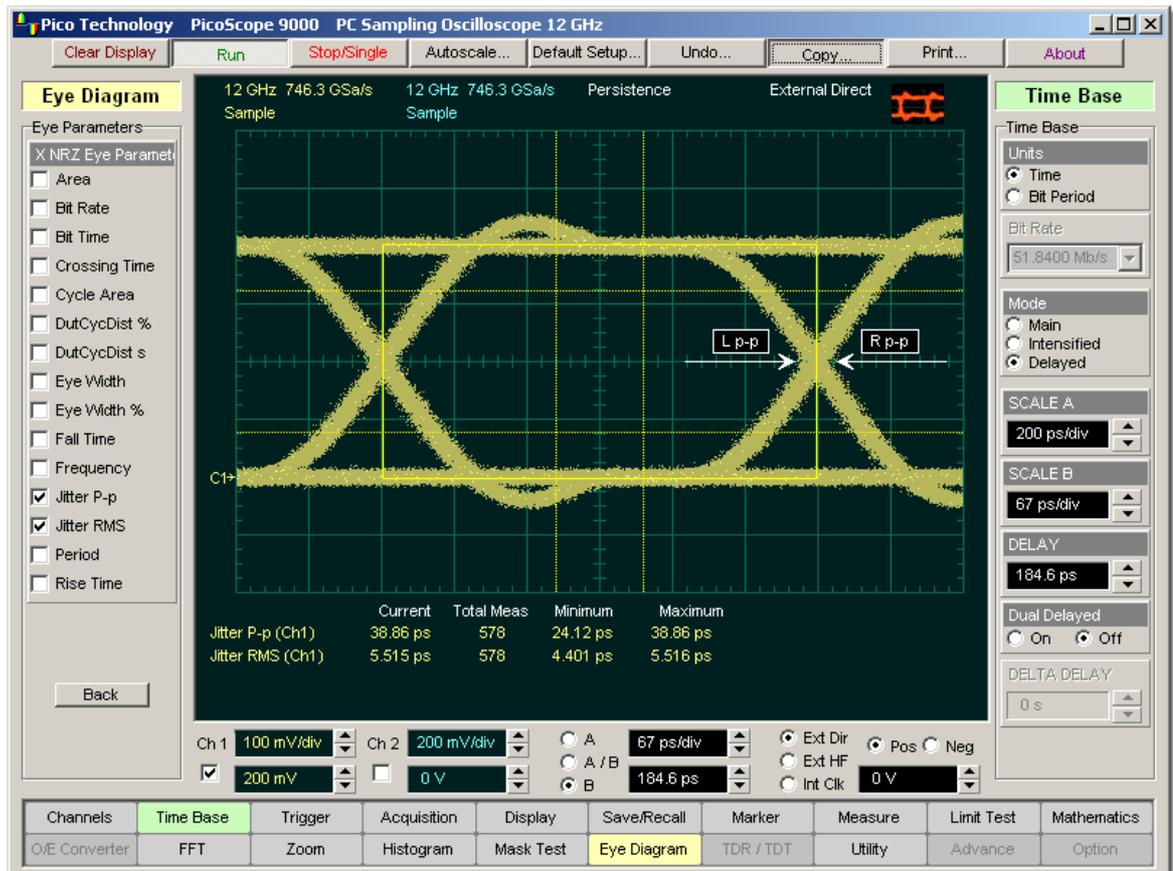
where T_{cross1} and T_{cross2} are the means of the histograms of the two crossings.

This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.5.10 NRZ Jitter p-p and NRZ Jitter RMS



NRZ Jitter is a measurement of the time variance of the crossing points. Horizontal time histograms are constructed to determine the location of the crossing points. An iterative process is used to narrow the histogram window to precisely determine the crossing points and the variance. The measurement window is kept extremely small so that the width of the crossing points is not influenced by the rise time and fall time of the waveform. The amount of jitter on the waveform is directly related to the width of the crossing points.



NRZ Jitter definition

NRZ Jitter can be displayed in one of two formats: peak-to-peak (NRZ Jitter p-p measurement) or RMS (NRZ Jitter RMS measurement). Both values are based on the standard deviation of the crossing point position.

NRZ Jitter peak-to-peak is equal to the full width of the histogram at the eye crossing point:

$$NRZ\ Jitter\ p-p = 6 \quad (\text{crossing})$$

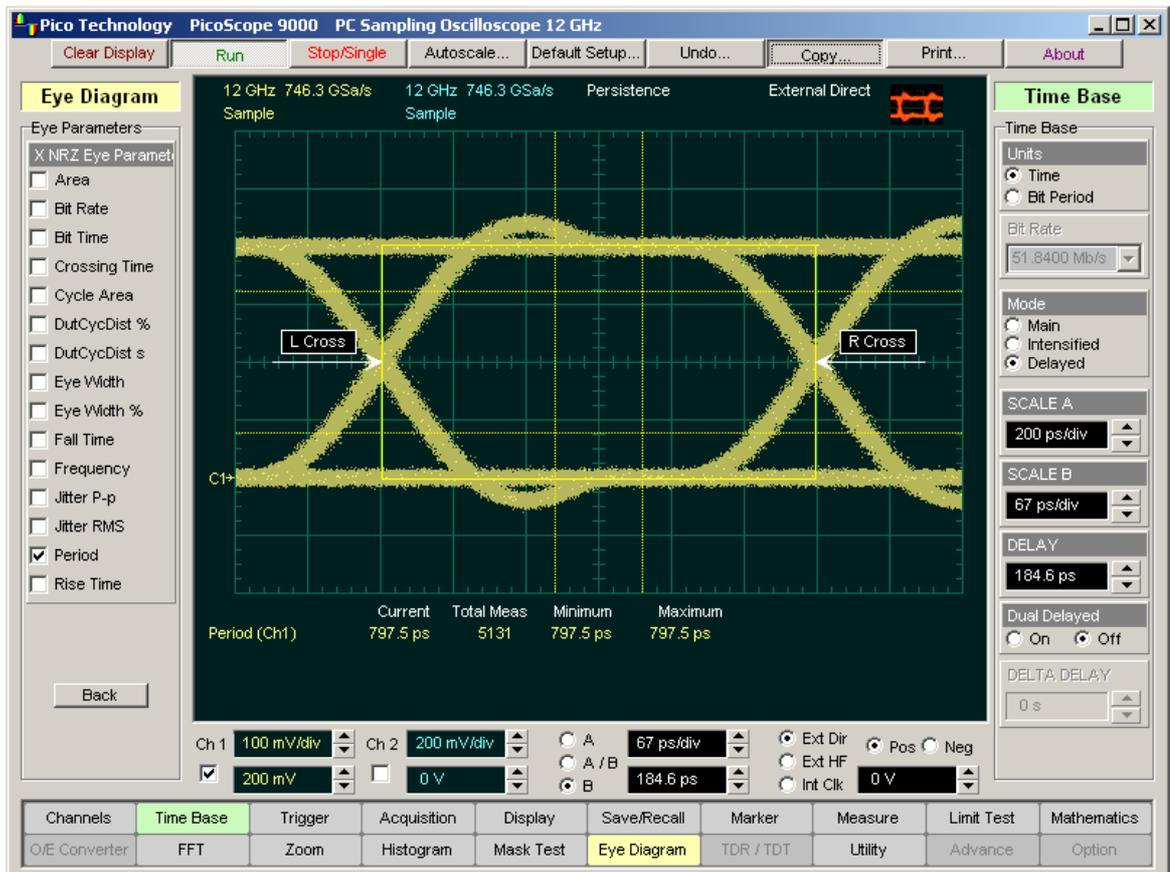
NRZ Jitter RMS is defined as one standard deviation from the histogram mean at the eye crossing point:

$$NRZ\ Jitter\ RMS = 1 \quad (\text{crossing})$$

5.4.5.11 NRZ Period



NRZ Period is twice the time interval between two consecutive eye-crossing points. It would be the period of a digital signal of a 0-1-0-1... stream.



NRZ Period definition

NRZ Period can be defined as:

$$NRZ_Period = 2(T_{cross2} - T_{cross1}) = 2(NRZ_BitTime)$$

where T_{cross1} and T_{cross2} are the means of the histograms of the two crossings of the eye diagram (Right Crossing and Left Crossing).

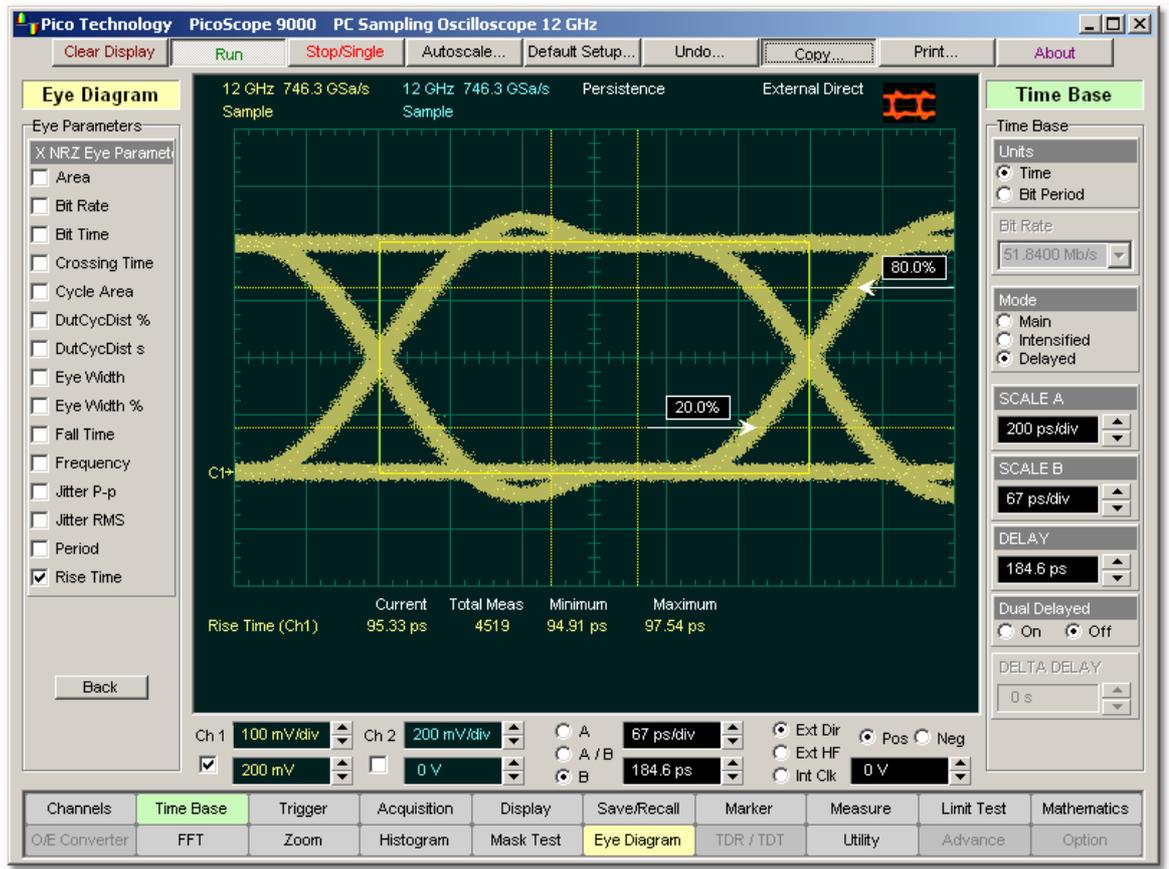
This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

Also see [NRZ Bit Time](#)^[85].

5.4.5.12 NRZ Rise Time

 Rise Time

NRZ Rise Time is a measure of the mean transition time of the data on the upward slope of an eye diagram. The data crosses the lower, middle, and upper thresholds, as well as the eye crossing points.



NRZ Rise Time definition

A histogram is first constructed to find the mean location of the crossing points relative to the one level and zero level. Histograms are then constructed at each of the three threshold levels (for example, the 10%, 50%, and 90% points on the transition). The instrument analyses each histogram to determine the histogram mean at which the data crosses the separate threshold levels.

Once the scanning of the waveform is complete, and the instrument has identified the mean location for each threshold crossed, then rise time can be computed.

$$\text{NRZ Rise Time} = (\text{Time at the Upper Threshold Crossing}) - (\text{Time at the Lower Threshold Crossing})$$

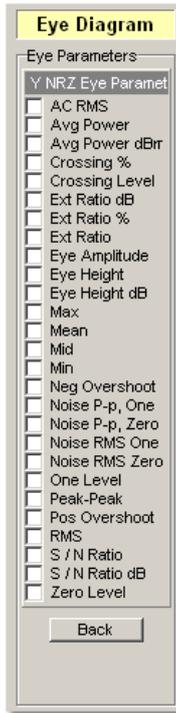
The instrument has two standard threshold levels for which fall time may be measured. The default setting is from the 10% to the 90% point on the transition, and the second is from the 20% to the 80% point on the transition. The 20% to 80% transition is recommended for devices with significant pulse distortion. Also, user defined threshold levels can be selected. You can define the threshold settings that you want by going to the [Define Parameters/Thresholds](#) ^[165] menus.



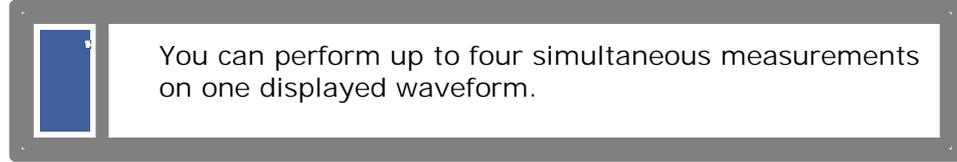
If the rise time relative to the time per division is a small value, the data acquired at the threshold levels on the falling edge will not yield accurate measurement results. (The rising edge will appear very steep on the display screen.)

If the rising edge of your eye diagram is steep, increase the timebase (horizontal scale) on the display so that the rising edge covers at least half a graticule division. The instrument will be able to discern the data at the threshold levels, producing more accurate results.

5.4.6 Y NRZ Eye Parameters



The list of Y NRZ Eye Parameters includes twenty-seven eye parameters. Two of the them (Avg Power and Avg Power dBm) can be used in optical models only.



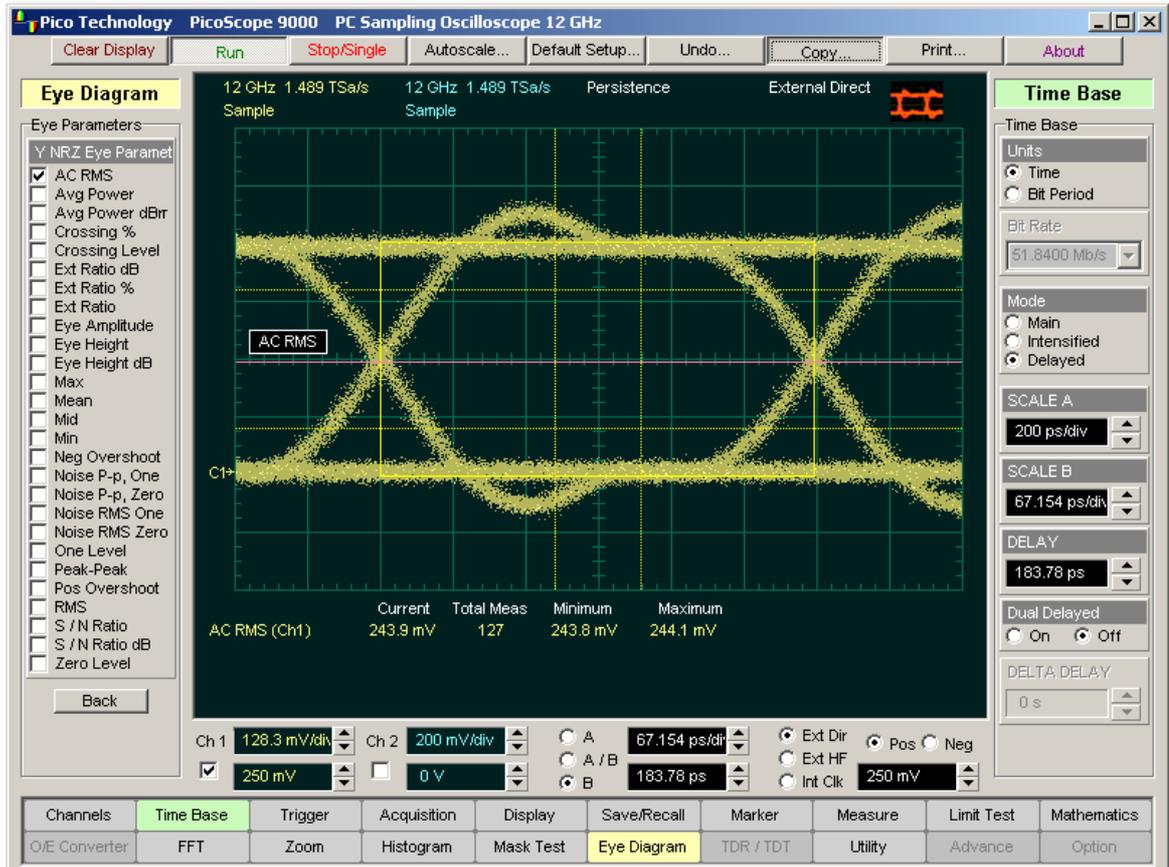
The measurement algorithms for Y NRZ Eye Parameters will only work when an NRZ eye diagram, and not an RZ eye diagram or a pulse, is present on the screen. Eye measurements are based on statistical data that is acquired and stored in the measurement database. The algorithms are dependent upon histogram means calculated from the measurement database. Therefore, if you want to perform eye measurements, it is necessary that you first produce an eye diagram by triggering the instrument with a synchronous clock signal.

Measurements made on an RZ eye diagram or a pulse waveform while in the X NRZ Eye Parameters menu will fail.

5.4.6.1 NRZ AC RMS



NRZ AC RMS is a measure of the root mean square amplitude, minus the DC component, of the selected waveform.



NRZ AC RMS definition

The NRZ AC RMS is defined as follows:

$$NRZ_AC_RMS = \sqrt{\frac{\sum_{i=1}^N \{[VertPos(s_i) - mean[VertPos(s)]]^2\}}{N}}$$

where s is the set of N samples $s_{1...N}$ within the measured region.

When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.6.2 NRZ Crossing % and NRZ Crossing Level



NRZ Crossing percentage is a measure of the location of the eye crossing points relative to the separation between the One Level (V_{one}) and the Zero Level (V_{zero}).

Typically, it is desirable to have the crossing points located midway between V_{one} and V_{zero} . In this case the crossing percentage would be 50% according to the following formula:

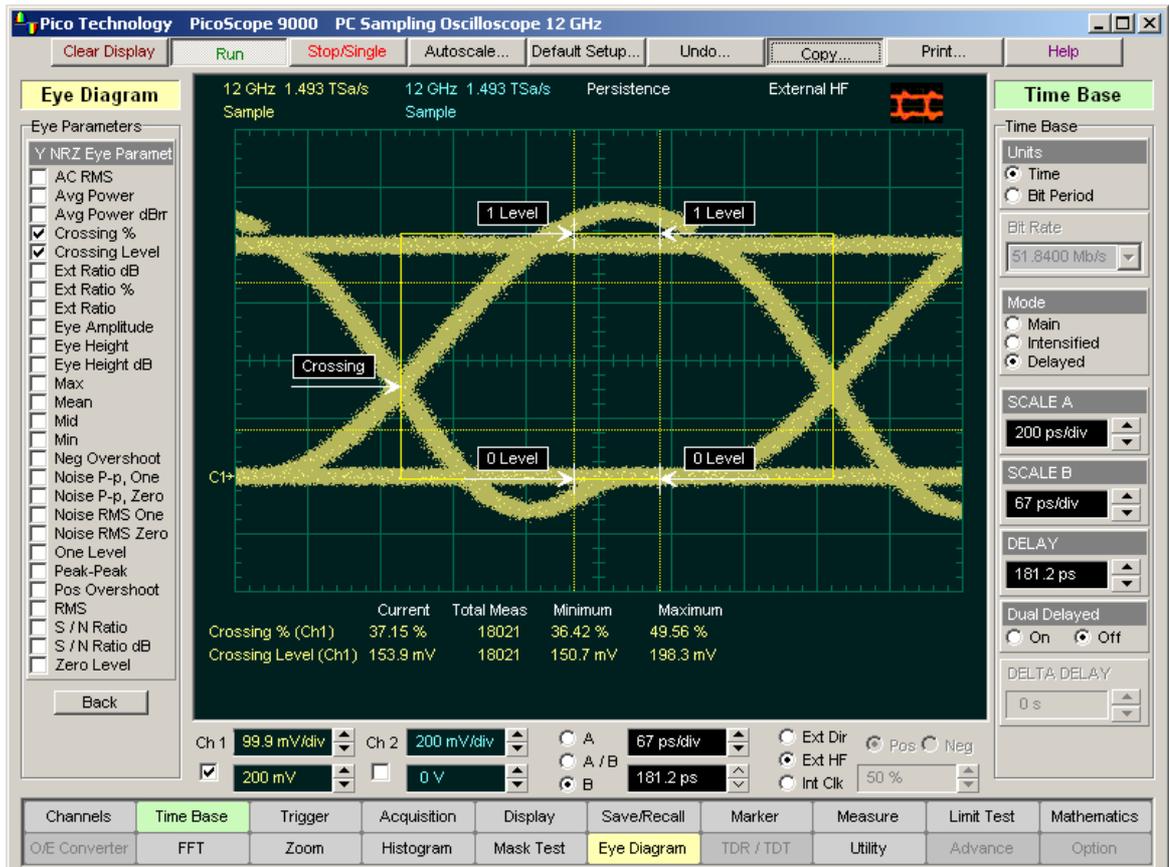
$$\text{NRZ Crossing percentage} = 100 (V_{cross} - V_{zero}) / (V_{one} - V_{zero})$$

NRZ Crossing Level is the mean signal level at the eye crossing point:

$$\text{NRZ Crossing Level} = \text{mean}[VertPos(s)]$$

where s is the set of samples in a vertical slice at the eye crossing point.

V_{cross} is the more prevalent vertical location or amplitude of the crossing points. A horizontal histogram over the entire display is used to determine the time location of the crossing points. Narrow vertical histograms are then used to determine the vertical location of V_{cross} . The mean derived from the horizontal and vertical histogram results in V_{cross} .



Example of eye diagram with low Crossing Level value

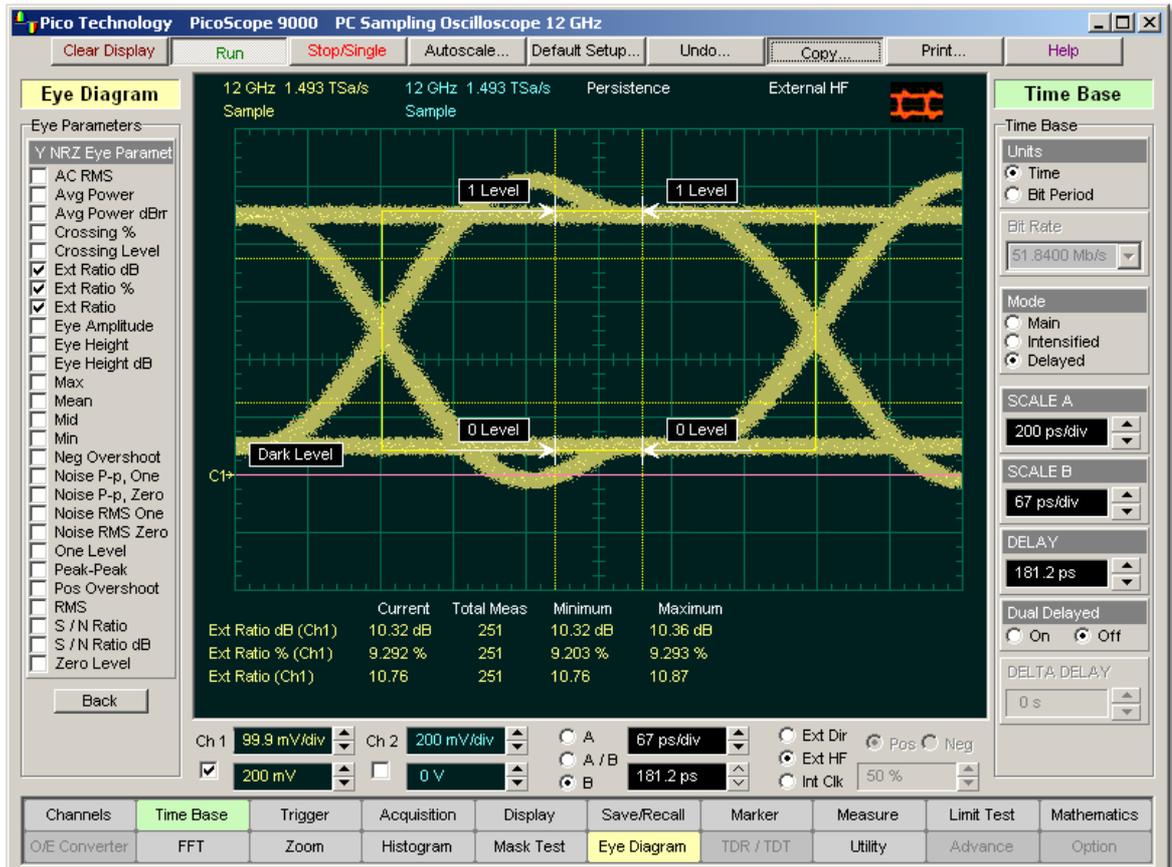


Vone and *Vzero* are calculated from a histogram using data within the eye window. These measurements are made in the central of the bit period (within Eye Boundaries). The default value is 20% of the NRZ bit time.

5.4.6.3 NRZ Extinction Ratio dB, NRZ Extinction Ratio % and NRZ Extinction Ratio



NRZ Extinction Ratio for an eye diagram is simply the ratio of the logic “high” level (V_{one} or P_{one}) to the logic “low” level (V_{zero} or P_{zero}). A very high extinction ratio typically implies that the logic low level is very small. In the case of an optical transmitter, the logic low level would approach a condition where the laser is nearly turned off.



NRZ Extinction Ratio definition

The accuracy of the extinction ratio can be dominated by the accuracy with which the low level was measured. This in turn can be significantly affected by any noise generated by the measurement system such as external converters, DC offsets, or electrical offsets in the instrument electronics. When these offsets occur, they add to the incoming signal. This will change the values of the one and zero levels. When the extinction ratio measurement is computed, the result may appear much smaller or larger than the true value, depending on the value of the offset.

To minimize extinction ratio measurement errors due to offsets, an extinction ratio calibration is recommended. This procedure allows the instrument to identify any internal signals present and remove them during the extinction ratio calculations. After the calibration is performed, a more accurate extinction ratio measurement can be executed.

Thus the extinction ratio measurements can be defined in one of the three following formats:

$$NRZ_ExtinctionRatio(dB) = 10 \log_{10} \left(\frac{V_{one} - V_{dark}}{V_{zero} - V_{dark}} \right)$$

$$NRZ_ExtinctionRatio(\%) = \frac{V_{one} - V_{dark}}{V_{zero} - V_{dark}} \times 100$$

$$NRZ_ExtinctionRatio = \frac{V_{one} - V_{dark}}{V_{zero} - V_{dark}}$$

V_{one} (or P_{one}) and V_{zero} (P_{zero}) are determined from vertical histograms of the eye window. The histogram is typically bimodal, and V_{one} and V_{zero} correspond to the two means of the histogram. Histograms are constructed using the sampled portions of the eye diagram within the central 20% of the bit period (between the Eye Boundaries). One histogram is composed of data points from only the upper half of the eye diagram (one level). The second histogram is composed of data points from the lower half of the eye (zero level). The instrument analyses the histograms and determines the histogram means.



The vertical scale setting affects the magnitude of the offset.

For best accuracy, perform the extinction ratio calibration at the vertical scale at which you will make your measurement. You can then adjust the vertical scale between and up to the next closest scale value in the 1-2-5 sequence. For example, if you set the vertical scale to 50 mV and then performed an extinction ratio calibration, you can adjust the scale between and up to 20 mV and 100 mV. If you exceed those upper and lower values, the instrument will recommend that you perform another extinction ratio calibration at the new value. This recommendation is to ensure best measurement accuracy. You will still get valid measurement results without a new extinction ratio calibration, but with potentially lower precision.

Since the extinction ratio measurement is based on the histogram means of the one and zero levels, noise on the waveform typically does not have a significant effect on the accuracy of the measurement.

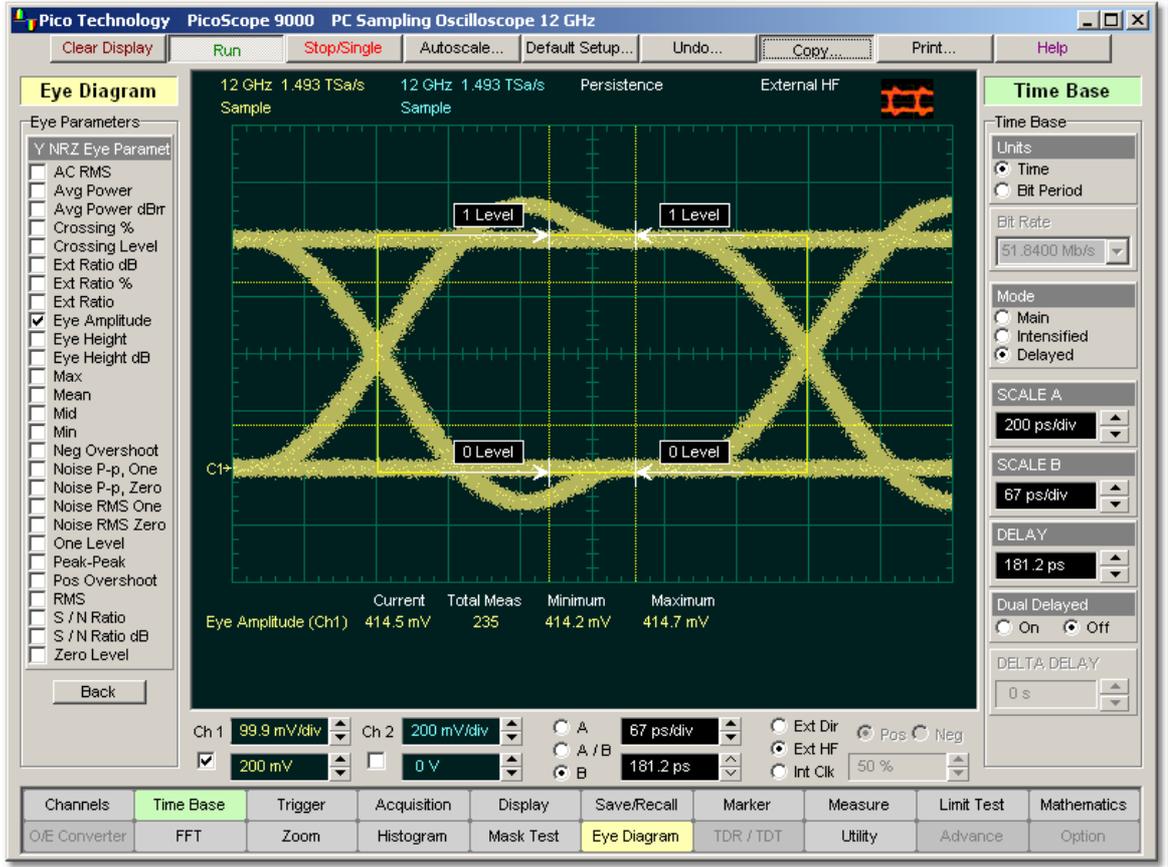


V_{one} and V_{zero} are calculated from a histogram using data within the eye window. These measurements are made in the central of the bit period (within Eye Boundaries). The default value is 20% of the NRZ bit time.

5.4.6.4 NRZ Eye Amplitude

 Eye Amplitude

NRZ Eye Amplitude is the difference between the logic 1 level and the logic 0 level histogram mean values of an eye diagram.



NRZ Eye Amplitude definition

V_{one} and V_{zero} are calculated from a histogram using data within the eye window. These measurements are made in the centre of the bit period (within the Eye Boundaries). The default value is 20% of the NRZ bit time.

A histogram is constructed using the sampled portion of the eye diagram within the eye window. This histogram is composed of data points from the upper and lower halves of the eye diagram. The instrument analyses the histogram and determines the mean values of the logic 1 and logic 0 levels.

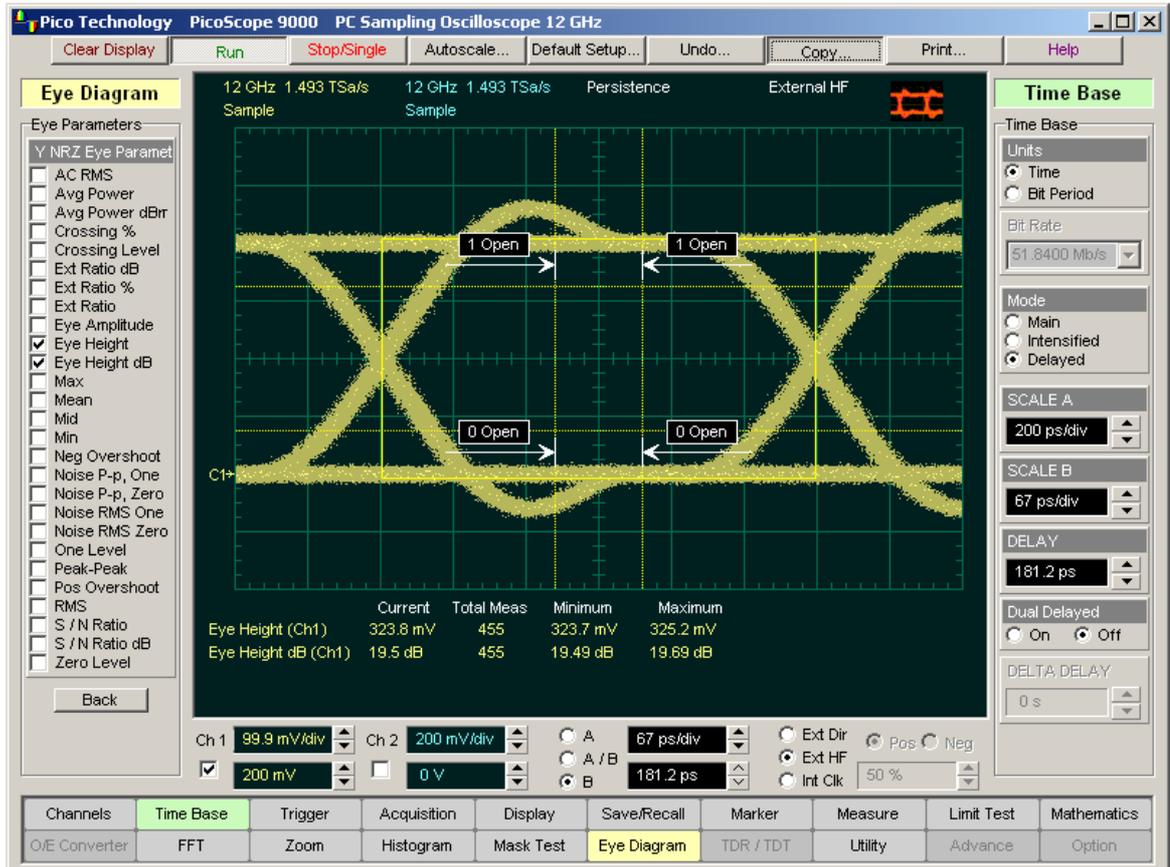
The eye amplitude is determined as follows:

$$\text{NRZ Eye Amplitude} = \text{One Level} - \text{Zero Level}$$

5.4.6.5 NRZ Eye Height and NRZ Eye Height dB



NRZ Eye Height is a measurement of the vertical opening of an eye diagram. An ideal eye opening would be measured from the one level to the zero level. However, noise on the eye will cause the eye to close. The eye height measurement determines eye closure due to noise.



NRZ Eye Height definition

Similarly to the extinction ratio measurements, a vertical histogram is calculated on the data. V_{one} and the high-level distribution are determined, and similar patterns are determined for the low levels. The V_{one} and V_{zero} levels are the relative means of the histograms. The noise is measured through the histograms as three standard deviations (σ) from both the one level and zero level into the eye opening.

The eye height can be defined in one of the two following formats:

$$NRZ_EyeHeight = (V_{one} - 3\sigma_{one}) - (V_{zero} + 3\sigma_{zero})$$

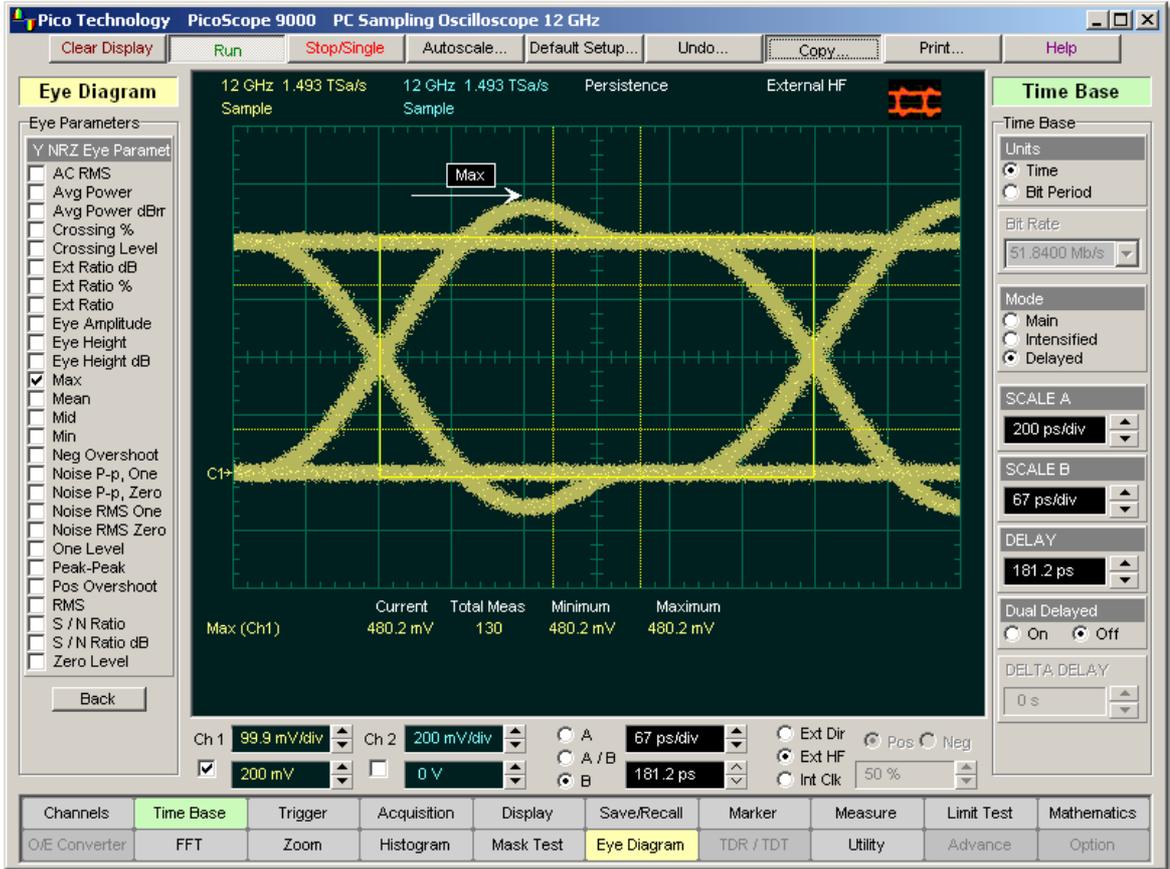
$$NRZ_EyeHeight(dB) = -10 \log_{10} \frac{(V_{zero} + 3\sigma_{zero})}{(V_{one} - 3\sigma_{one})}$$

V_{one} and V_{zero} are calculated from a histogram using data within the eye window. These measurements are made in the center of the bit period (within the Eye Boundaries). The default value is 20% of the NRZ bit time.

5.4.6.6 NRZ Max



NRZ Max is a measure of the maximum vertical value of the waveform that is sampled within the eye window.



NRZ Maximum definition

The NRZ maximum eye amplitude is determined as follows:

$$NRZ\ Maximum = \max[VertPos(s)]$$

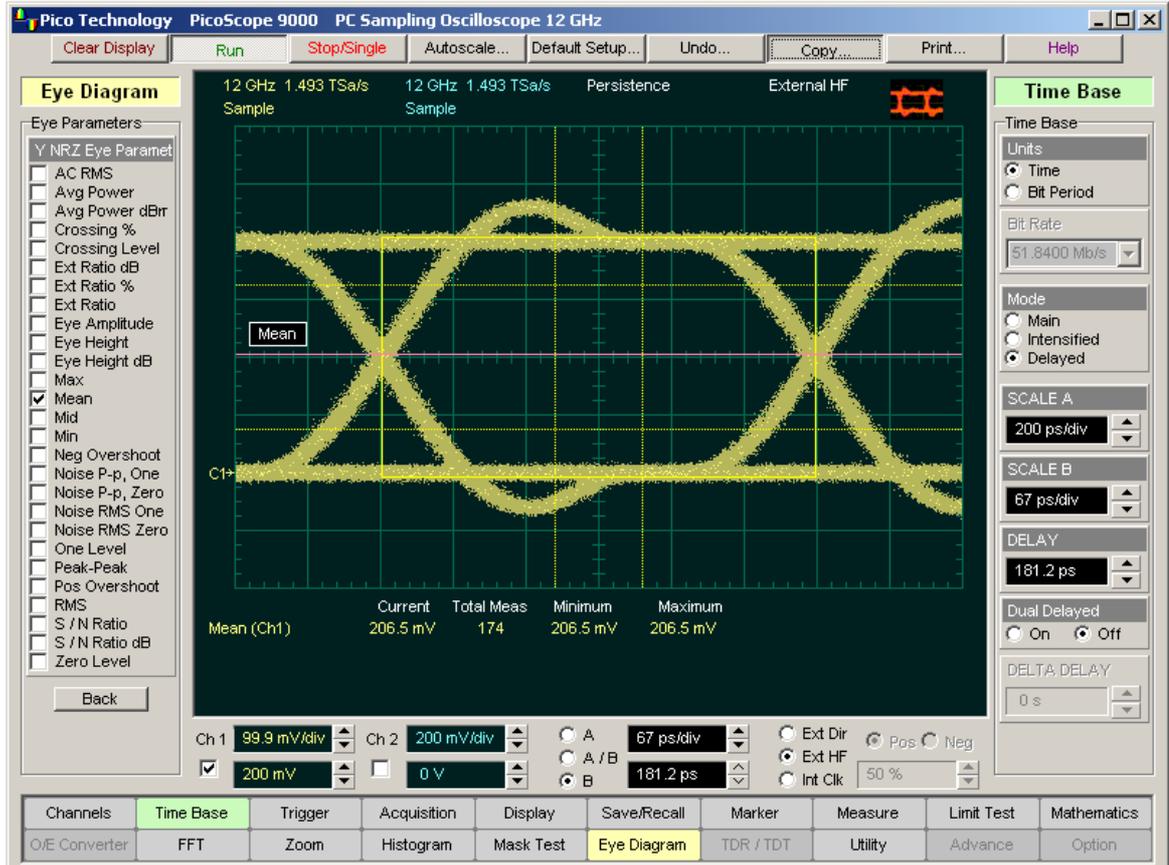
where s is the set of samples within the eye window.

When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.6.7 NRZ Mean

 Mean

NRZ Mean is a measure of the arithmetic mean of the selected waveform within the eye window.



NRZ Mean definition

The NRZ mean is determined as follows:

$$NRZ_Mean = mean[VertPos(s)] = \frac{1}{N} \sum_{i=1}^M VertPos(s_i)$$

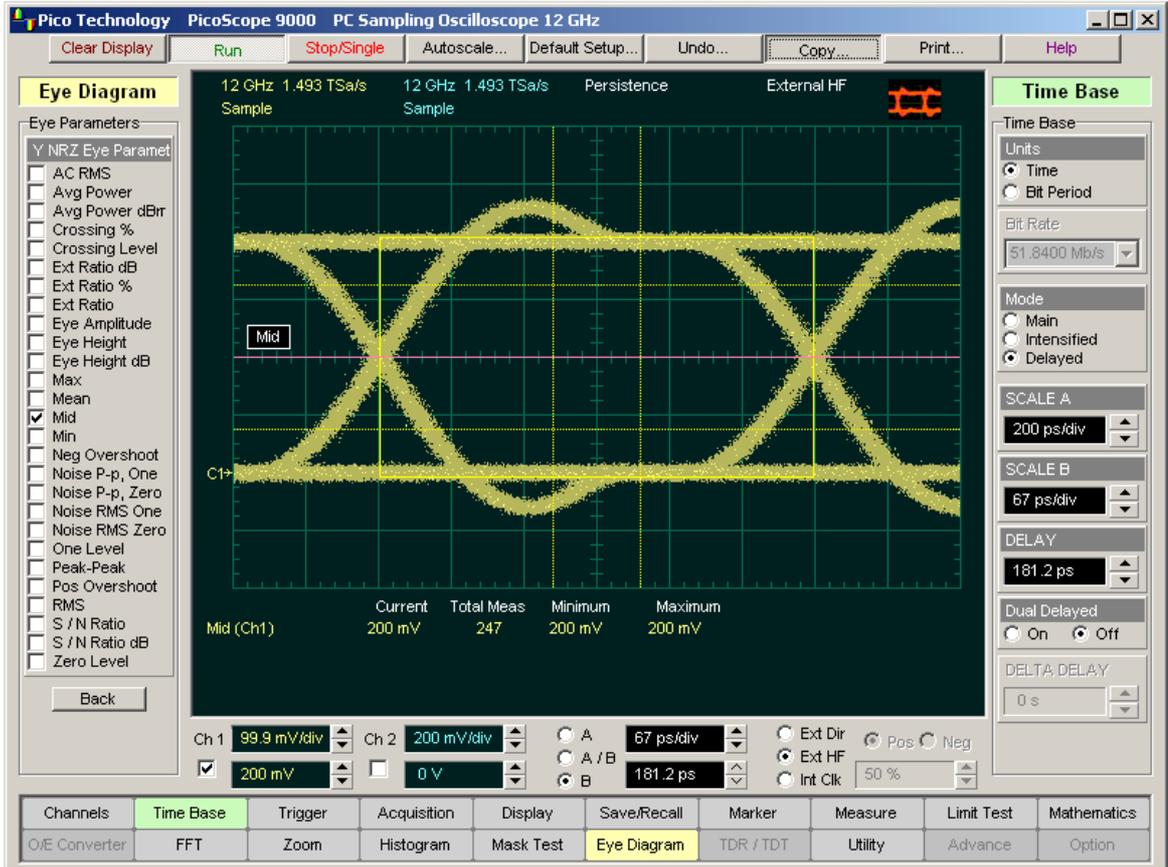
over all samples $s_{1...N}$ within the eye window.

When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.6.8 NRZ Mid



NRZ Mid is a measure of the middle level between the Max and Min vertical values of the eye window.



NRZ Middle definition

The NRZ middle is determined as follows:

$$NRZ\ Mid = (Max + Min) / 2$$

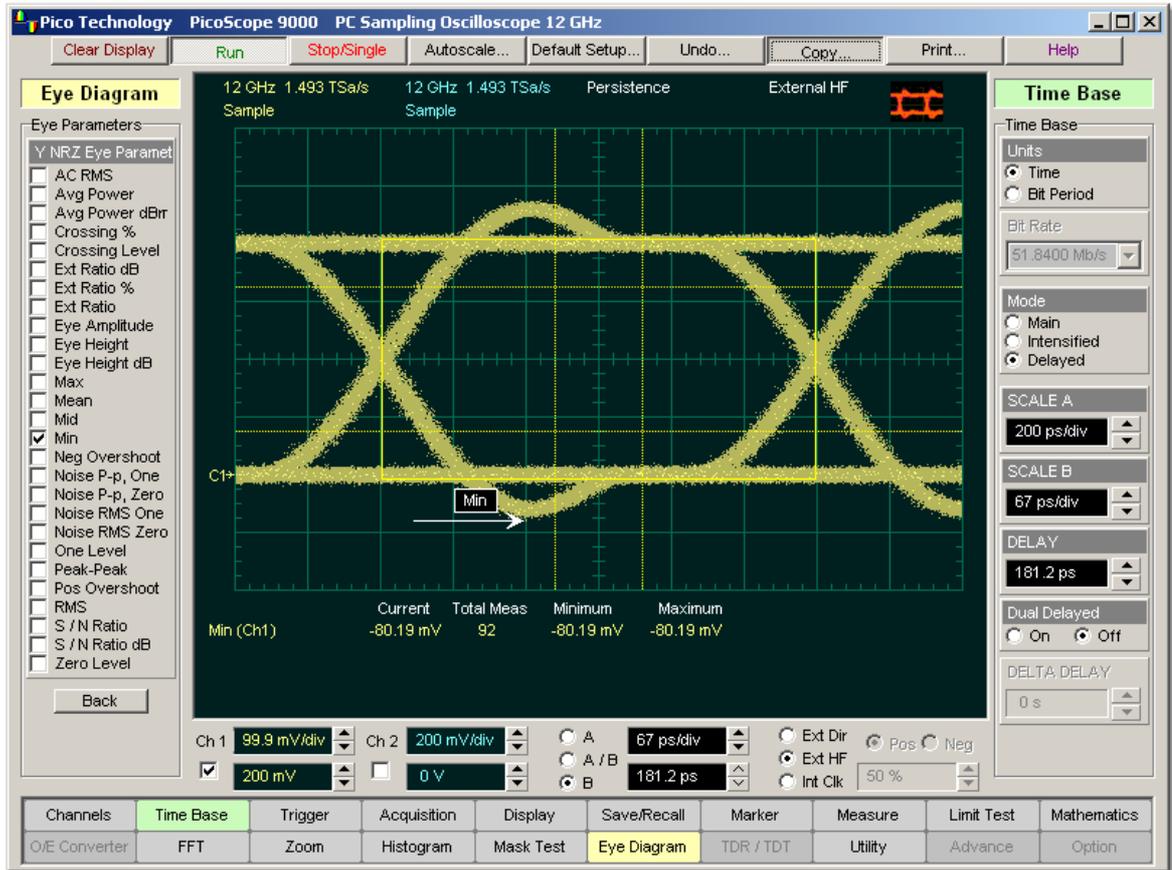
where *Max* and *Min* are the maximum and minimum measurements. See also [NRZ Max](#)^[106] and [NRZ Min](#)^[109].

When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.6.9 NRZ Min



NRZ Min is a measure of the minimum vertical value of the selected waveform of the eye window.



NRZ Minimum definition

The NRZ minimum eye amplitude is determined as follows:

$$NRZ\ Minimum = \max[VertPos(s)]$$

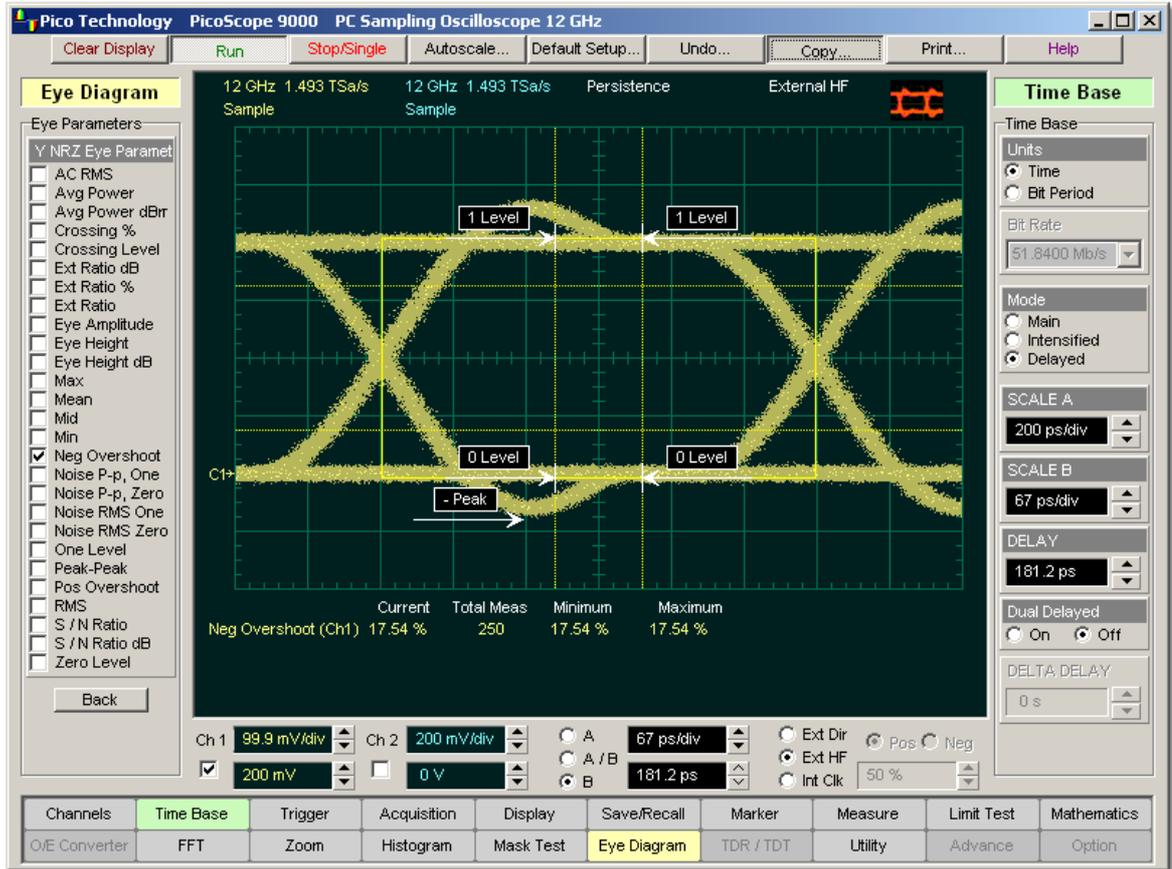
where s is the set of samples within the eye window.

When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.6.10 NRZ Negative Overshoot



NRZ Negative Overshoot is a measure of the ratio of the minimum value of the measured signal to its amplitude, expressed as a percentage. The waveform is scanned for the minimum value within the eye window, while the amplitude is measured in the Eye Aperture.



NRZ Negative Overshoot definition

The NRZ Negative Overshoot is determined as follows:

$$NRZ_NegativeOvershoot = \frac{V_{zero} - V_{min}}{V_{one} - V_{zero}} \times 100$$

where V_{min} is the signal minimum, and V_{one} and V_{zero} are the logical 1 and 0 levels.



V_{one} and V_{zero} are calculated from a histogram using data within the eye window. These measurements are made in the center of the bit period (within the Eye Boundaries). The default value is 20% of the NRZ bit time.

When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.6.11 NRZ Noise P-p, One and NRZ Noise P-p, Zero

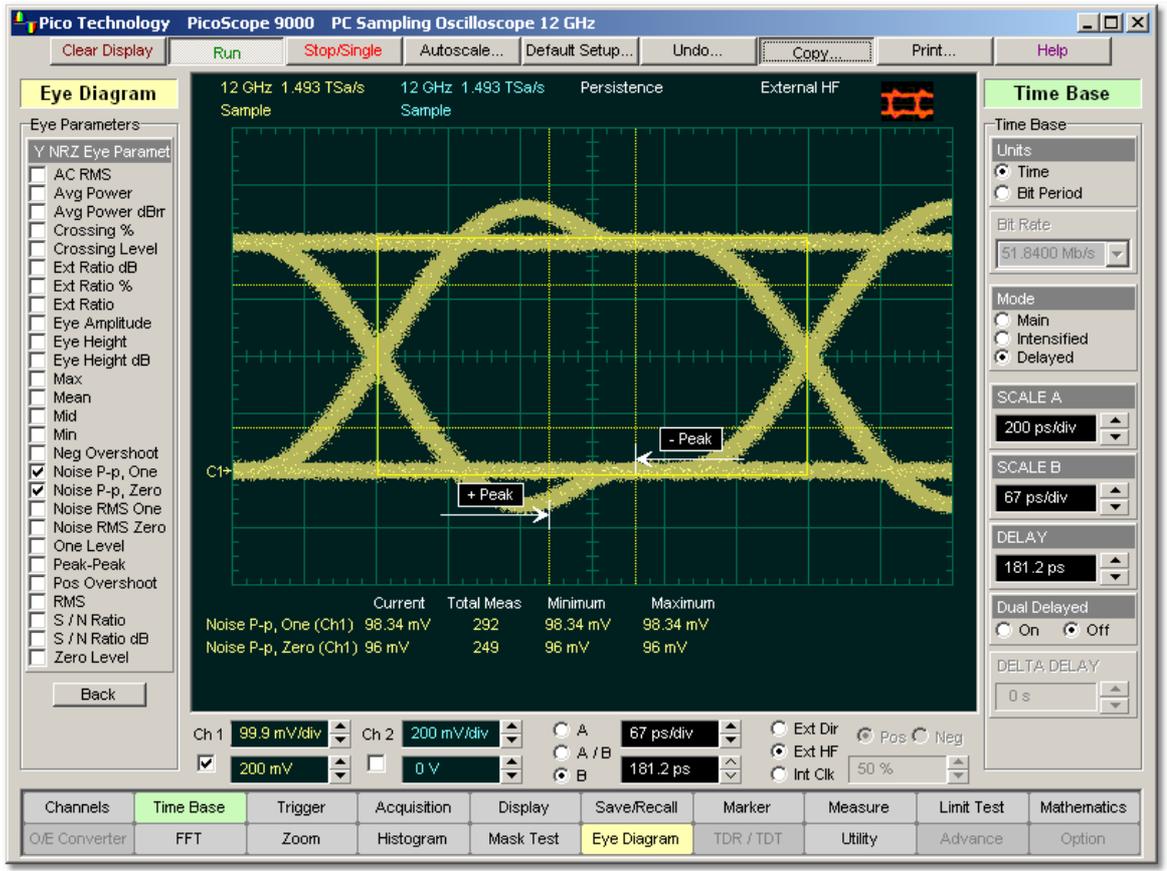


NRZ Noise P-p, One is a measurement of the maximum range of the amplitude variance sampled within a fixed-width vertical slice located at the center of the Eye Aperture at the One Level.

NRZ Noise P-p, Zero is a measurement of the maximum range of the amplitude variance sampled within a fixed-width vertical slice located at the center of the Eye Aperture at the Zero Level.



NRZ Noise P-p, One definition



NRZ Noise P-p, Zero definition

The NRZ Noise P-p, One is determined as follows:

$$NRZ\ Noise\ P-p,\ One = One\ P-p$$

The NRZ Noise P-p, Zero is determined as follows:

$$NRZ\ Noise\ P-p,\ Zero = Zero\ P-p$$

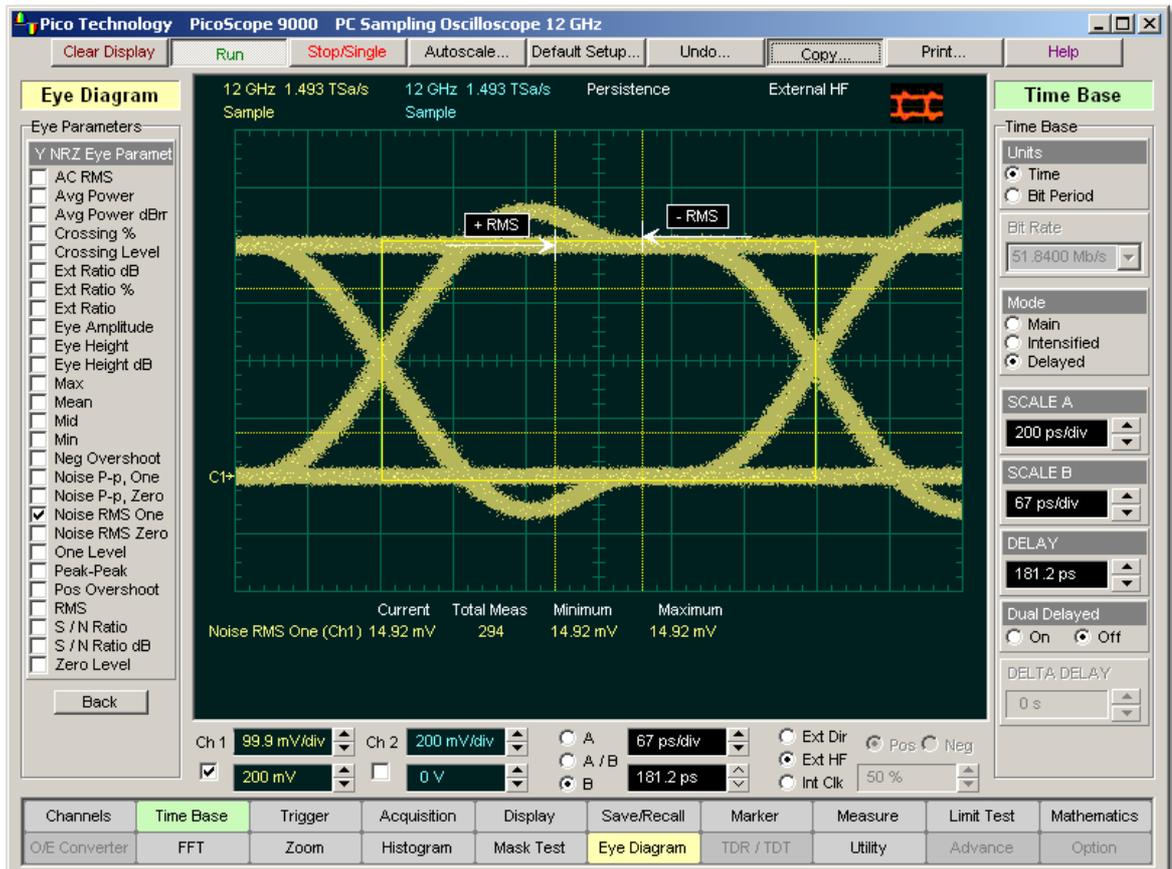
V_{one} and V_{zero} are calculated from a histogram using data within the eye window. These measurements are made in the center of the bit period (within the Eye Boundaries). The default value is 20% of the NRZ bit time.

This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

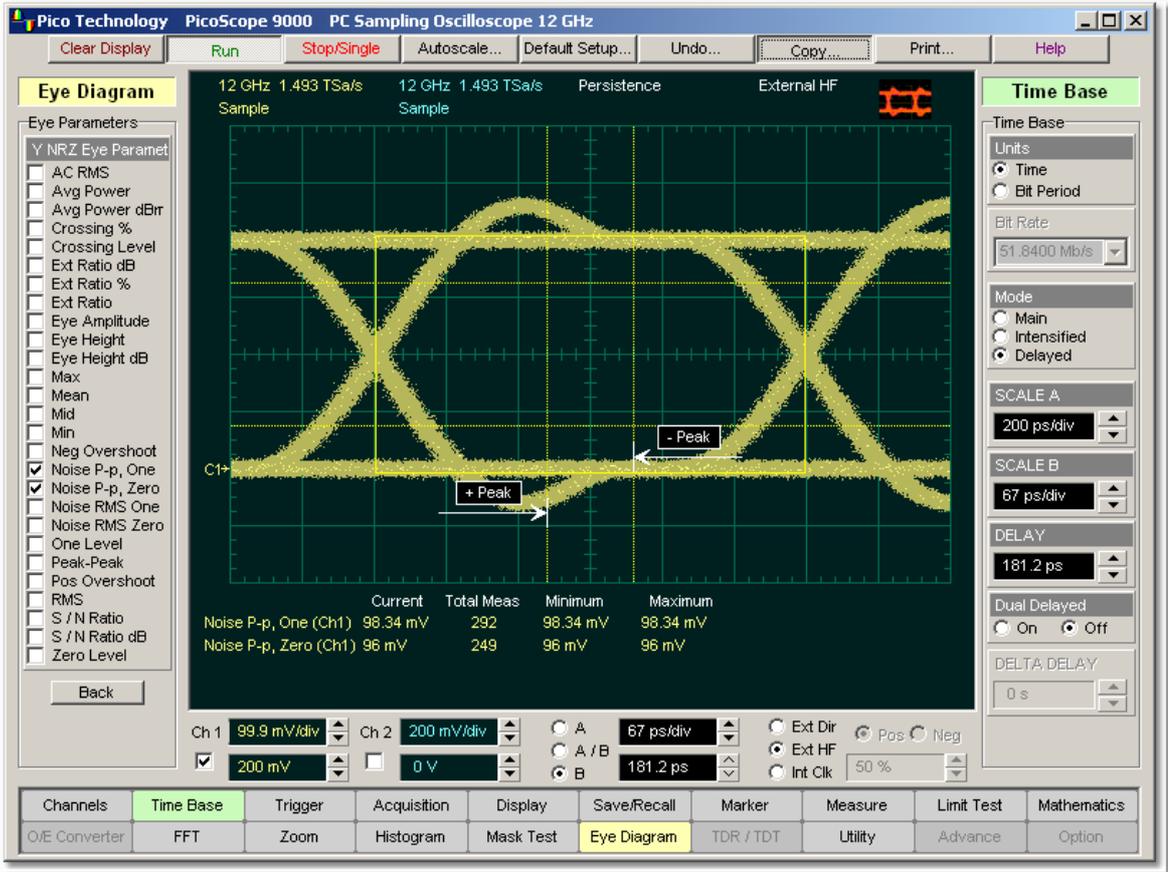
5.4.6.12 NRZ Noise RMS, One and NRZ Noise RMS Zero



NRZ Noise RMS is a measurement of the unit standard deviation of the amplitude variance sampled within a fixed-width vertical slice located at the center of the Eye Aperture at the High (logical 1) or Low (logical 0) levels.



NRZ Noise RMS, One definition



NRZ Noise RMS, Zero definition

$$NRZ\ RMS = High$$

$$NRZ\ RMS = Low$$

The Eye Aperture is adjustable and defaults to 20% of the NRZ bit time. This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

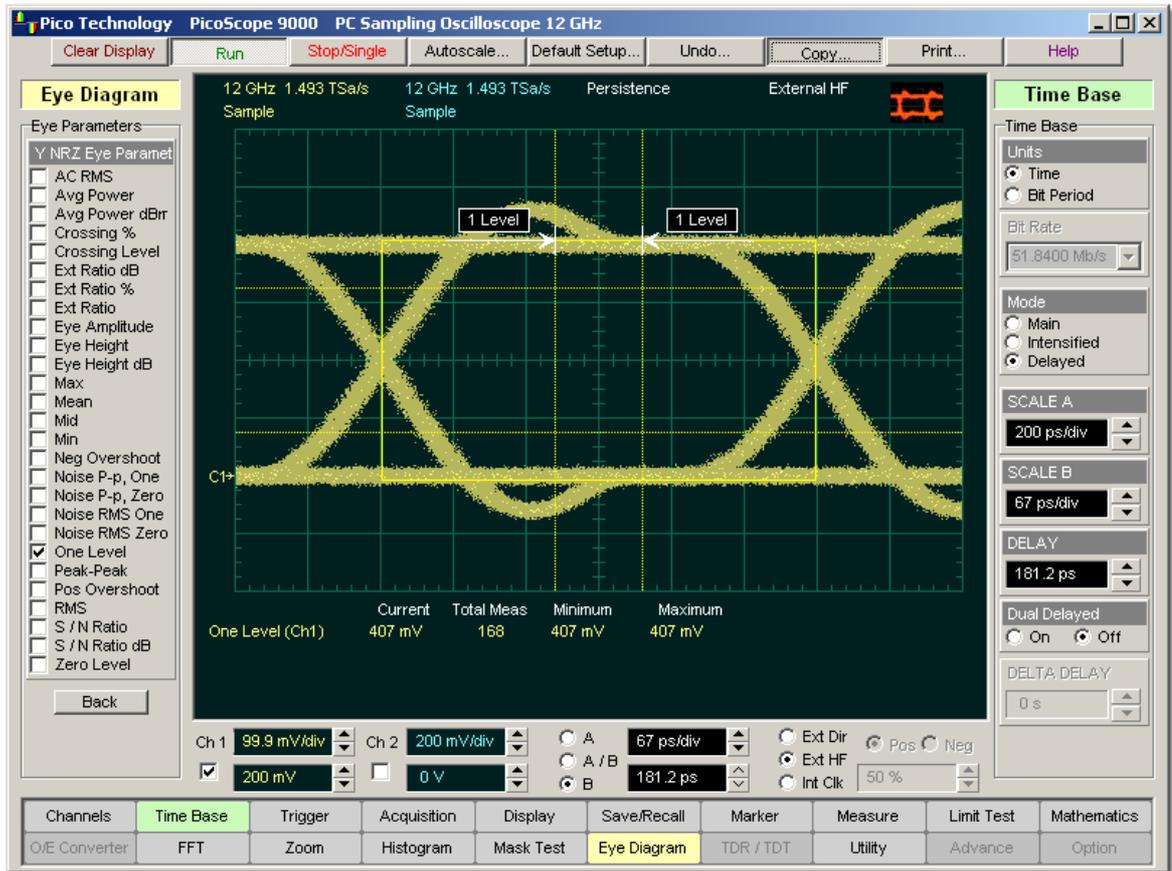


Vone and *Vzero* are calculated from a histogram using data within the eye window. These measurements are made in the central of the bit period (within Eye Boundaries). The default value is 20% of the NRZ bit time.

5.4.6.13 NRZ One Level



NRZ One Level is a measure of the mean value of the logical 1 of an eye diagram.



NRZ One Level definition

*V*_{one} and *V*_{zero} are calculated from a histogram using data within the eye window. These measurements are made in the center of the bit period (within the Eye Boundaries). The default value is 20% of the NRZ bit time.

A histogram is constructed using the sampled portion of the eye diagram within the eye window. This histogram is composed of data points from only the upper half of the eye diagram. The instrument analyses the histogram and determines histogram mean.

The One Level is determined as follows:

$$NRZ\ One\ Level = Histogram\ Mean$$

All data at the zero level is disregarded.

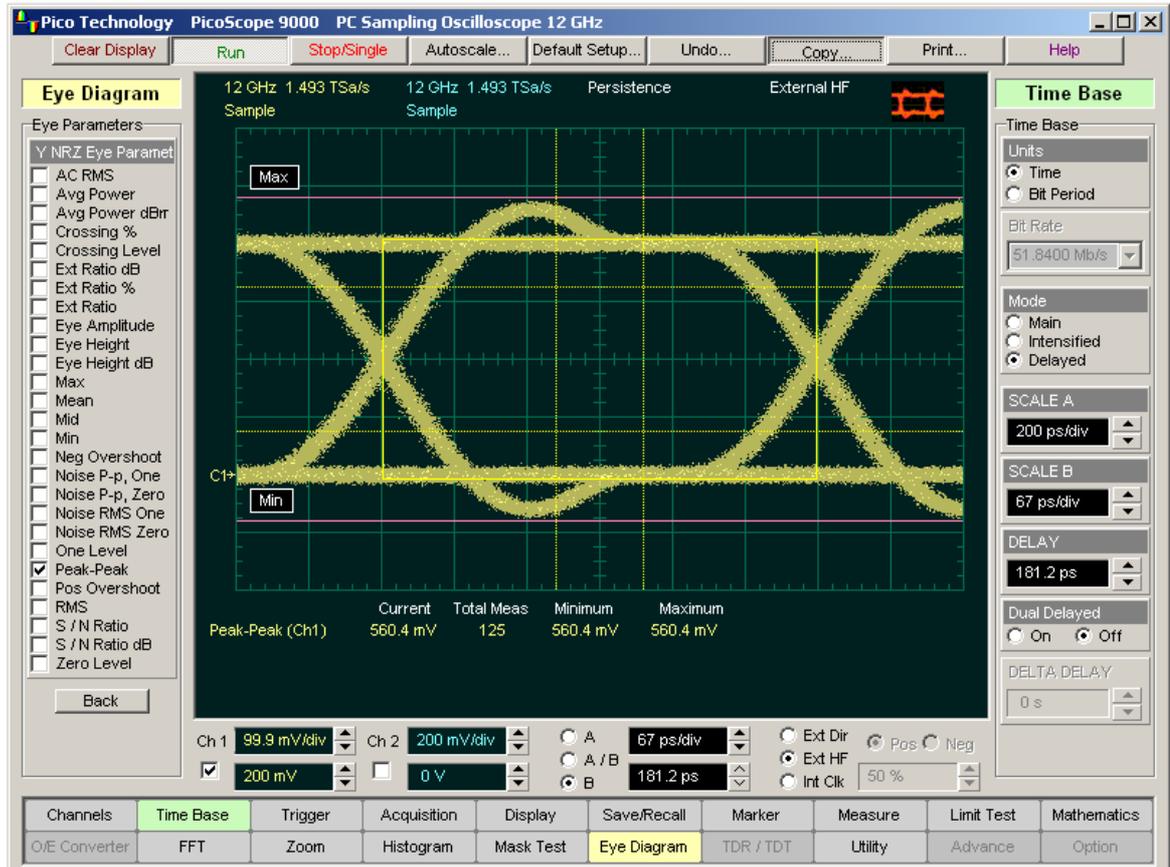


The standard deviation that is reported on the instrument display as part of the measurement results is derived from the statistical analysis of the one level measurement result. It is not the same as the standard deviation derived from the histogram analysis of the signal.

5.4.6.14 NRZ Peak-Peak

 Peak-Peak

NRZ Peak-Peak is a measure of the difference between the Max and Min vertical values of the selected waveform within the eye window.



NRZ Peak-Peak definition

The NRZ Peak-Peak is determined as follows:

$$NRZ \text{ Peak-Peak} = Max - Min$$

where *Max* and *Min* are the maximum and minimum measurements. See also [NRZ Max](#)^[106] and [NRZ Min](#)^[109].

When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.6.15 NRZ Positive Overshoot

Pos Overshoot

NRZ Positive Overshoot is a measure of the ratio of the maximum value of the measured signal to its amplitude, expressed as a percentage. The waveform is scanned for the maximum value within the eye window, while the amplitude is measured in the Eye Aperture.



NRZ Positive Overshoot definition

The NRZ Positive Overshoot is determined as follows:

$$NRZ_PositiveOvershoot = \frac{V_{max} - V_{one}}{V_{one} - V_{zero}} \times 100$$

where V_{max} is the signal maximum, and V_{one} and V_{zero} are the logical 1 and 0 levels.

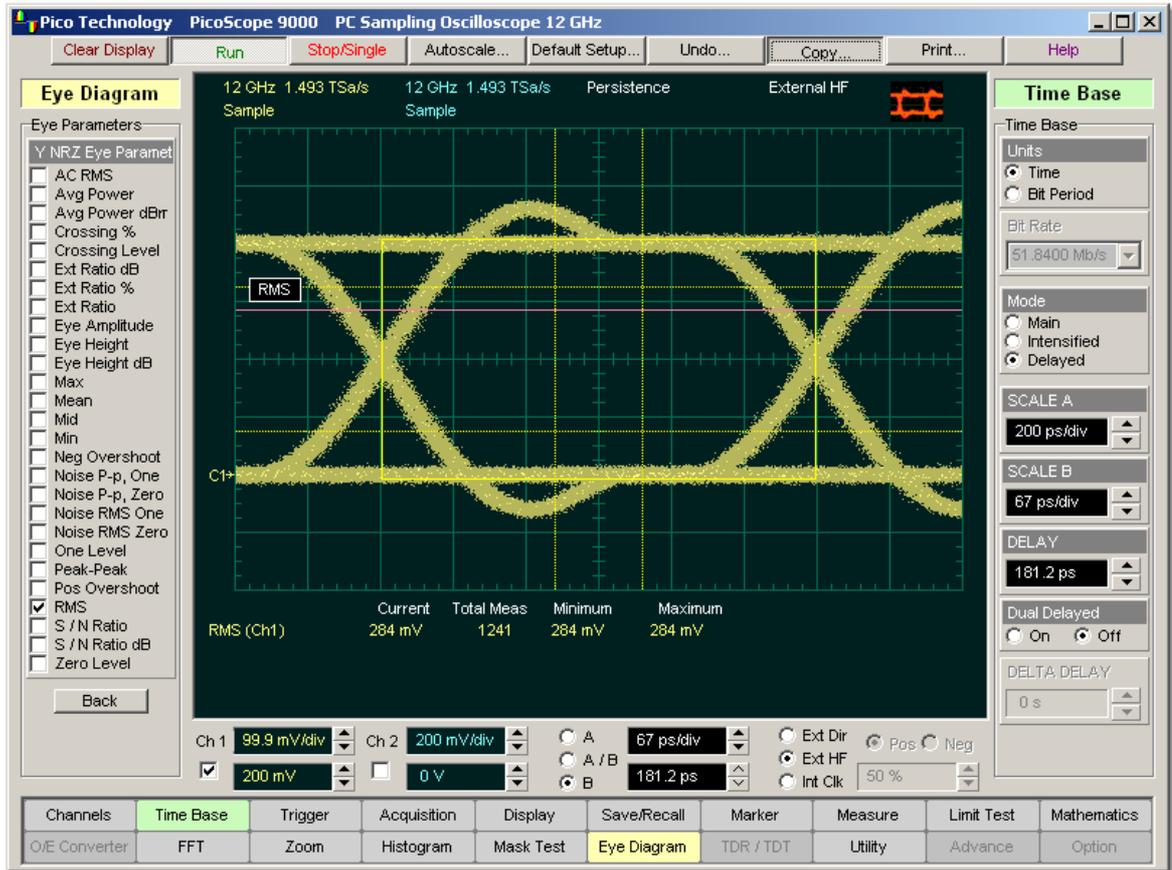
V_{one} and V_{zero} are calculated from a histogram using data within the eye window. These measurements are made in the center of the bit period (within the Eye Boundaries). The default value is 20% of the NRZ bit time.

When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.6.16 NRZ RMS



NRZ RMS is a measure of the true root mean square amplitude of the selected waveform within the eye window.



NRZ RMS definition

The NRZ RMS is determined as follows:

$$NRZ_RMS = \sqrt{\frac{\sum_{n=1}^N [VertPos(s_n)]^2}{N}}$$

over all N samples within the measured region; i.e., one standard deviation of the amplitude, i.e., RMS amplitude.

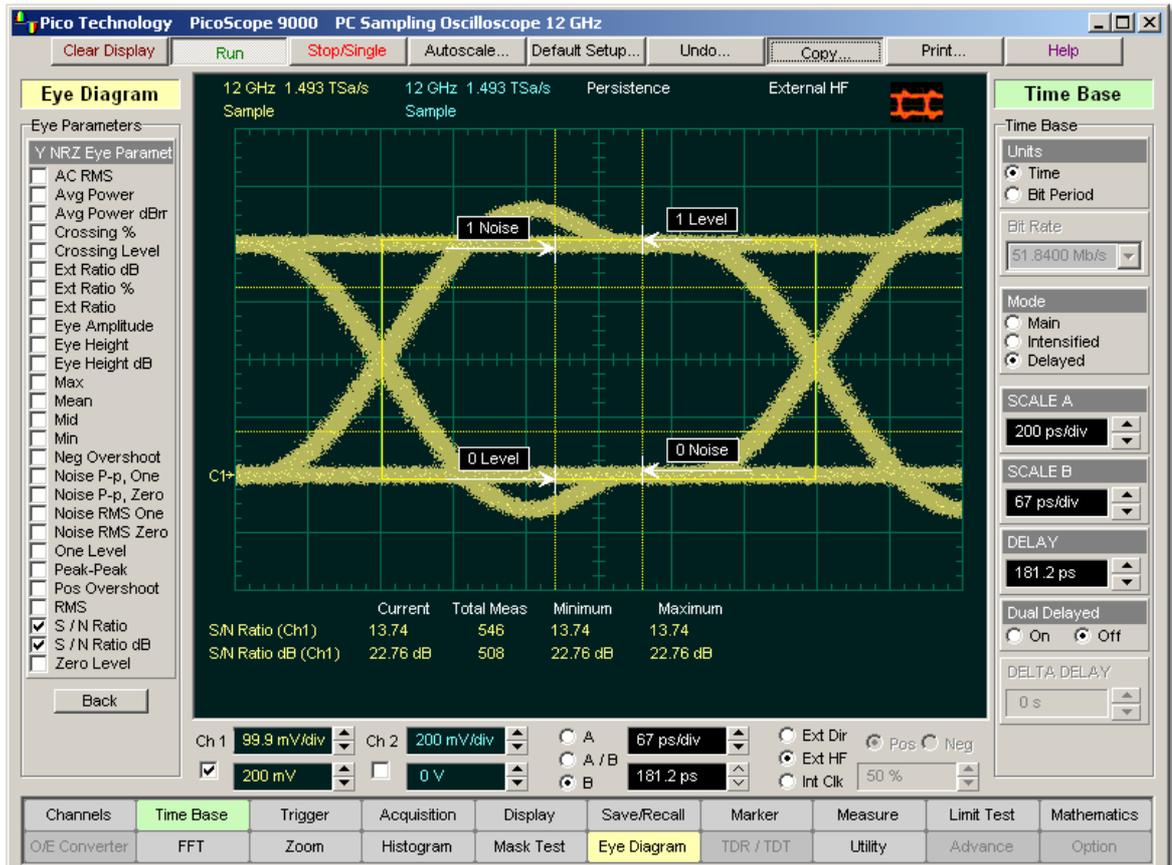
When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

V_{one} and V_{zero} are calculated from a histogram using data within the eye window. These measurements are made in the center of the bit period (within the Eye Boundaries). The default value is 20% of the NRZ bit time.

5.4.6.17 NRZ S/N Ratio and NRZ S/N Ratio dB

S / N Ratio S / N Ratio dB

NRZ Signal to Noise is a ratio of the signal difference between one level and zero level relative to the noise present at both levels. Signal to Noise is similar in construction to a Q-factor measurement. However, noise levels contributed by the instrument cannot be removed, and therefore a slightly pessimistic Q-factor measurement may result.



NRZ Signal to Noise Ratio definition

V_{one} and V_{zero} are calculated from a histogram using data within the eye window. These measurements are made in the center of the bit period (within the Eye Boundaries). The default value is 20% of the NRZ bit time.

To define the signal, histograms are constructed using the sampled portions of the eye diagram within the eye window boundaries. One histogram is composed of data points from only the upper half of the eye diagram (one level). The second histogram is composed of data points from the lower half of the eye (zero level). The instrument analyses the histograms and determines the histogram means and standard deviations. The noise is defined as 1 (standard deviation) of the histogram at the one and zero levels.

The RZ Signal to Noise is determined as follows:

$$NRZ_Signal_to_Noise_Ratio = \frac{V_{one} - V_{zero}}{\sigma_{one} + \sigma_{zero}}$$

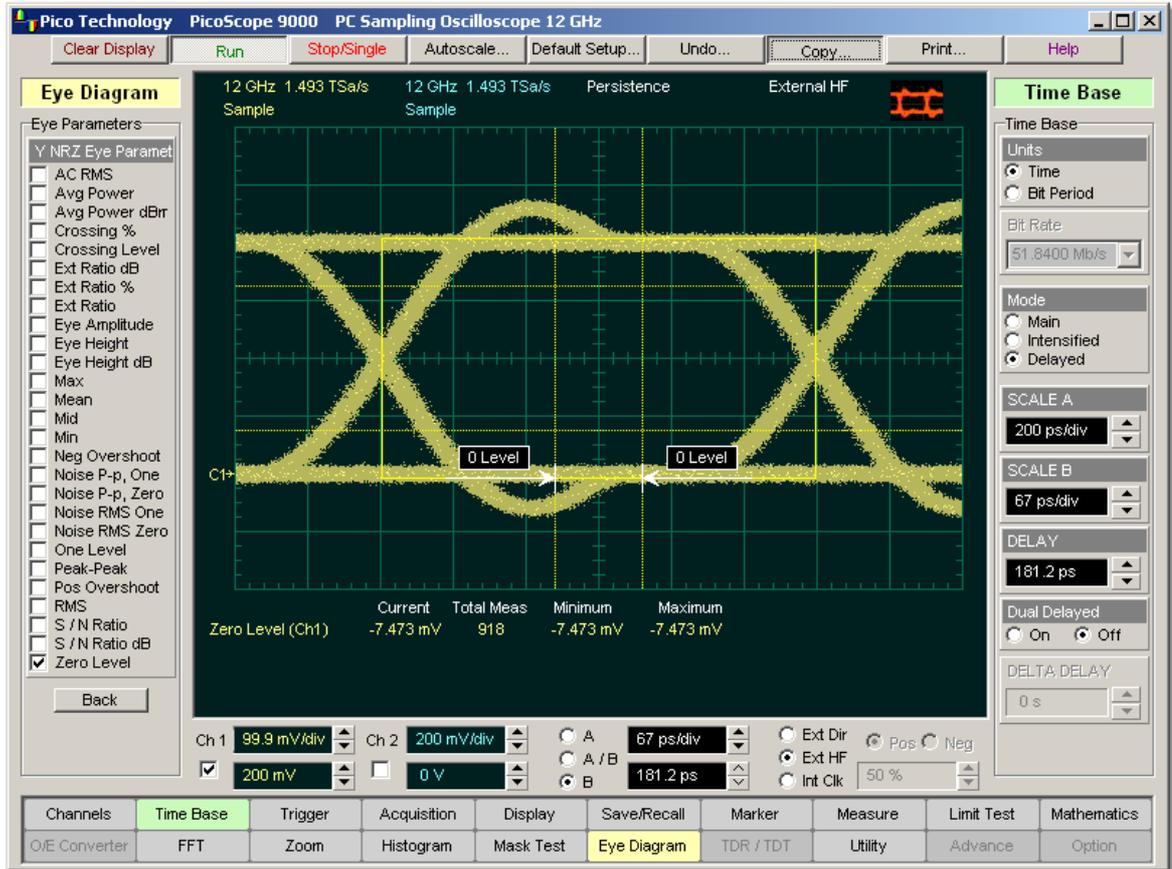


This measurement does not remove the effect of noise generated by the instrument. If the noise on the signal being tested is of a magnitude similar to that of the instrument or smaller, the signal-to-noise measurement error will be significant.

5.4.6.18 NRZ Zero Level



NRZ Zero Level is a measure of the mean value of the logical 0 of an eye diagram.



NRZ Zero Level definition

*V*_{one} and *V*_{zero} are calculated from a histogram using data within the eye window. These measurements are made in the center of the bit period (within the Eye Boundaries). The default value is 20% of the NRZ bit time.

A histogram is constructed using the sampled portion of the eye diagram within the eye window. This histogram is composed of data points from only the lower half of the eye diagram. The instrument analyses the histogram and determines histogram mean.

The RZ Zero Level is determined as follows:

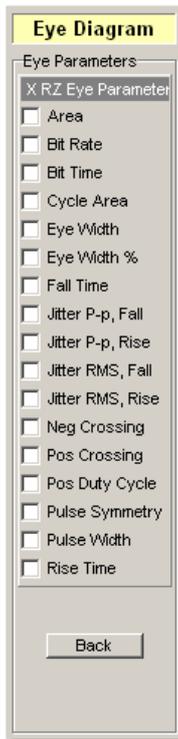
$$NRZ\ Zero\ Level = Histogram\ Mean$$

All data at the one level is disregarded.

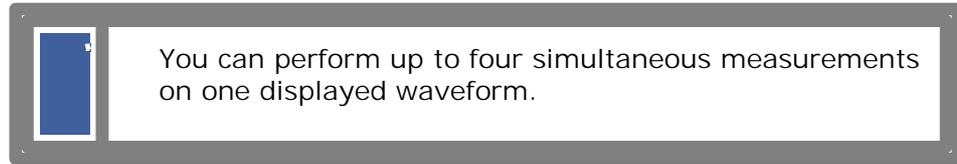


The standard deviation that is reported on the instrument display as part of the measure results is derived from the statistical analysis of the zero level measurement result. It is not the same as the standard deviation derived from the histogram analysis of the signal.

5.4.7 X RZ Eye Parameters



The list of X RZ Eye Parameters includes seventeen eye parameters.



The measurement algorithms for X RZ Eye Parameters will only work when an RZ eye diagram, and not an NRZ eye diagram or a pulse, is present on the screen. Eye measurements are based on statistical data that is acquired and stored in the measurement database. The algorithms are dependent upon histogram means calculated from the measurement database. Therefore, if you want to perform eye measurements, you must first produce an eye diagram by triggering the instrument with a synchronous clock signal. Measurements made on an NRZ eye diagram or a pulse waveform while in the X RZ Eye Parameters menu will fail.

5.4.7.1 RZ Area

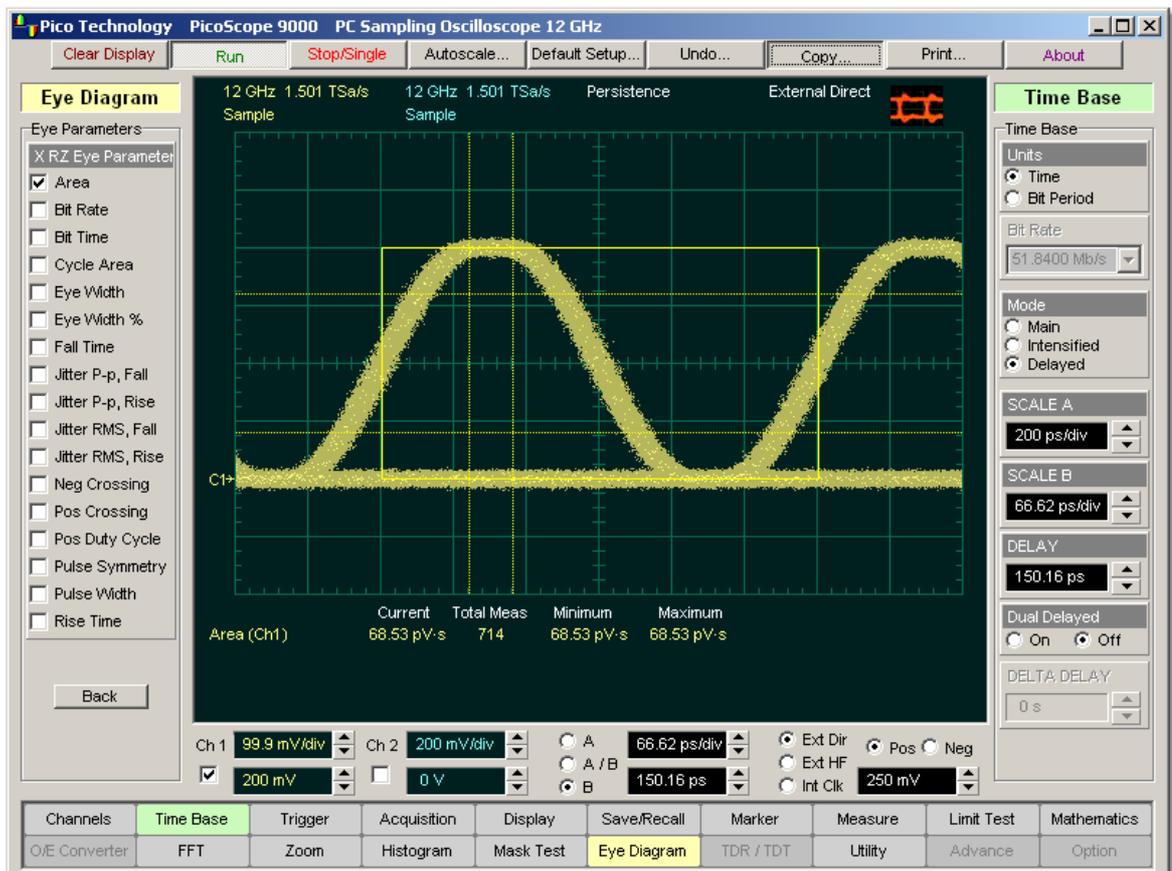


RZ Area is a measure of the area under the curve for the RZ waveform within the full display window. Area measured above ground is positive; area measured below ground is negative.

The RZ Area is determined as follows:

$$RZ_Area = \frac{\Delta t}{N} \sum_{x=1}^N VertPos(s_x)$$

over all N samples $s_{1...N}$ within the measured region (full display window) of duration t .



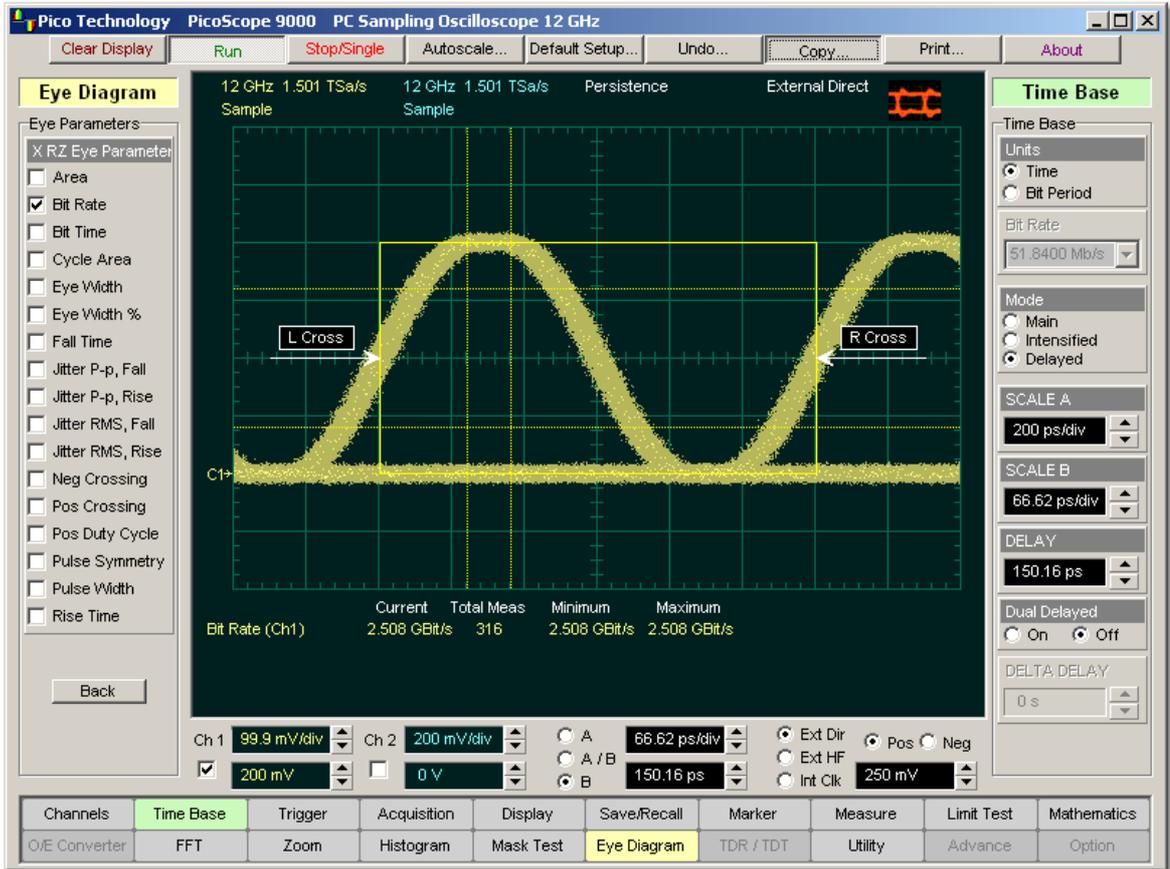
RZ Area definition

This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.7.2 RZ Bit Rate



The RZ Bit Rate is a measure of the inverse of the bit time (1/bit time or 1/period) of the RZ eye rising edges. The bit time is a measure of the time between the 50% rising edges of two consecutive eyes.



RZ Bit Rate definition

To compute bit time (period), the 50% heights of consecutive eyes are first determined. Then a vertically thin measurement window is placed horizontally through the 50% levels. The data within this measurement window is analysed. The measurement window is created to be extremely small so that the measurement is not affected by the fall or rise time of the waveforms.

Once the bit period has been determined, the inverse value is calculated to determine the RZ bit rate:

$$RZ_BitRate = \frac{1}{RZ_BitTime} = \frac{1}{2(T_{RightCross} - T_{LeftCross})}$$

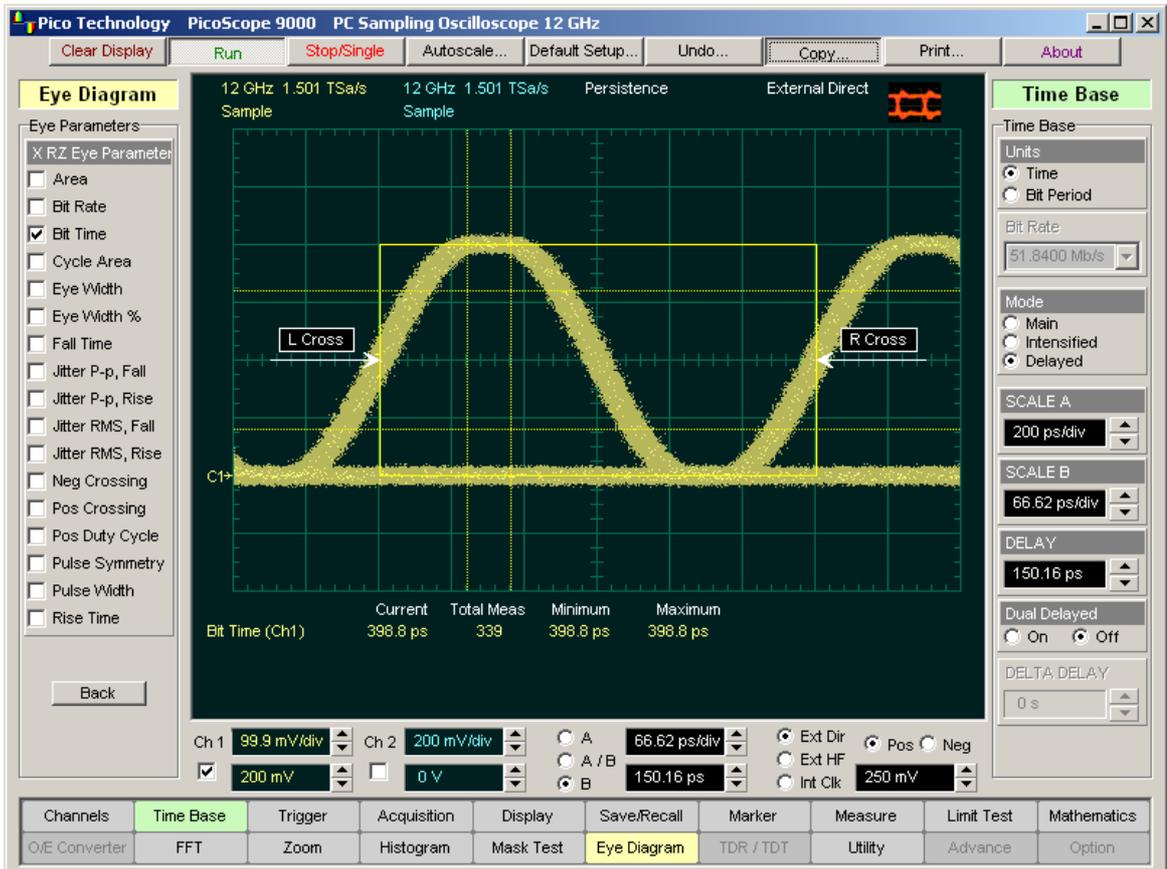
where $T_{RightCross}$ and $T_{LeftCross}$ are the mean of the histogram of the two consecutive crossings on the rising slope at the mid-reference level.

See also [RZ Bit Time](#)^[127].

5.4.7.3 RZ Bit Time

 Bit Time

The RZ Bit Time is a measure of the time interval between two consecutive rising edges. The crossing times are computed as the mean of the histogram of the data slice at the mid-reference level.



RZ Bit Time definition

The RZ Bit Time is determined as follows:

$$RZ_BitTime = T_{RightCross} - T_{LeftCross}$$

where $T_{RightCross}$ and $T_{LeftCross}$ are the mean of the histogram of the two consecutive crossings on the rising slope at the mid-reference level.

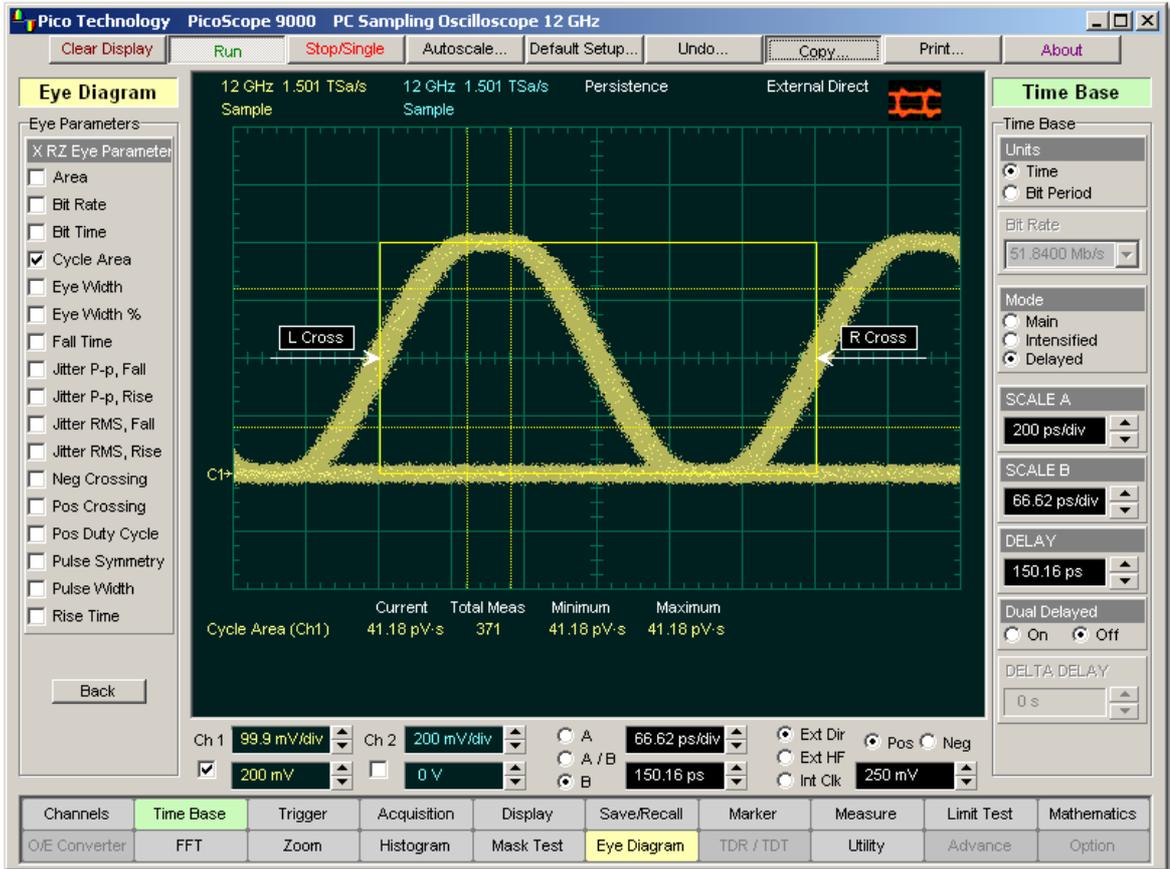
This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

RZ Bit Time also is called RZ Bit Period.

5.4.7.4 RZ Cycle Area



RZ Cycle Area is a measure of the area under the curve for the RZ waveform within the eye window. Area measured above ground is positive; area measured below ground is negative.



RZ Cycle Area definition

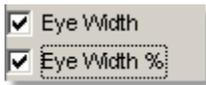
The RZ Cycle Area is determined as follows:

$$RZ_CycleArea = \frac{\Delta t}{N} \sum_{n=1}^N VertPos(s_n)$$

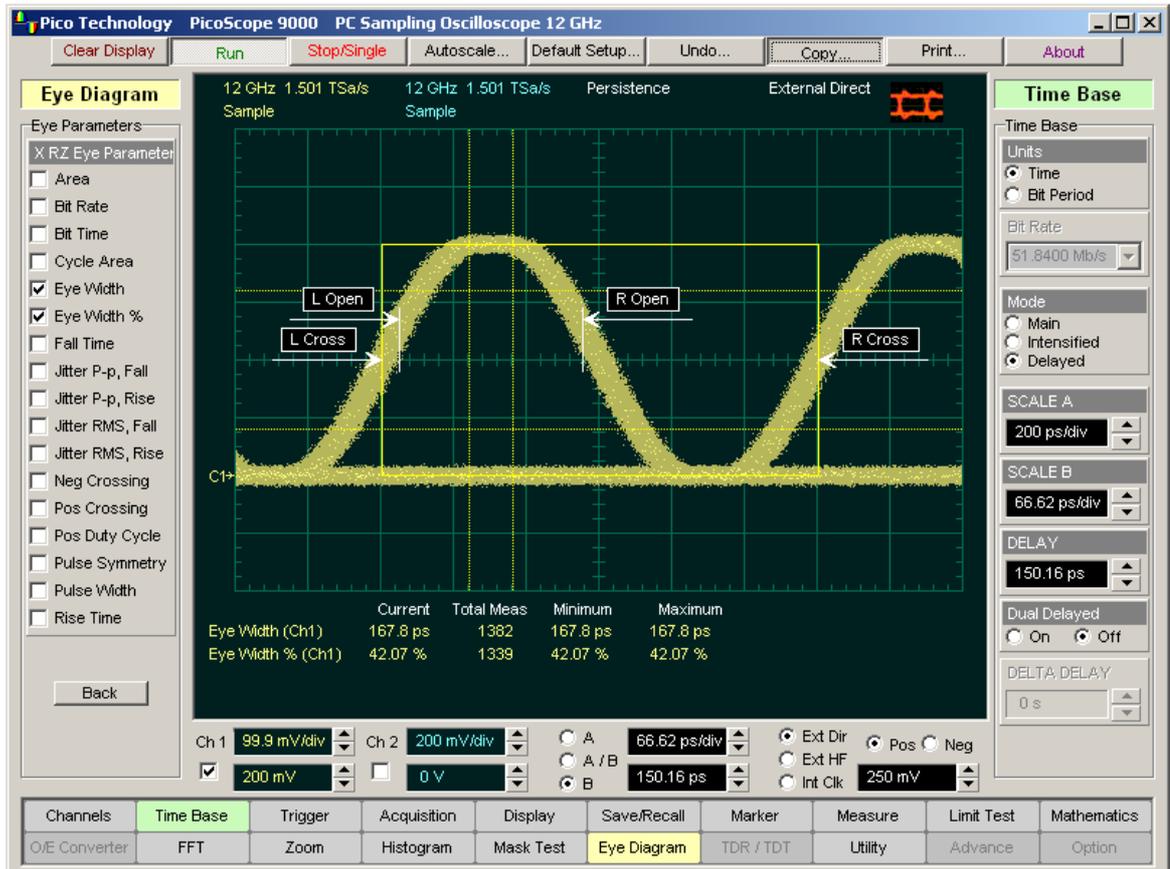
over all N samples $s_{1...N}$ in the measured region (eye window) of duration t between two consecutive edges of the rising slope at the Mid reference level.

This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.7.5 RZ Eye Width and RZ Eye Width %



RZ Eye Width is a measure of the horizontal opening of an RZ eye diagram. The amount of jitter or noise that may appear on the waveform is measured to determine the actual horizontal opening of the eye.



RZ Eye Width definition

To compute eye width, the 50% height of the eye is first determined. Then a vertically thin measurement window is placed horizontally through the 50% levels, and the data within this measurement window is analysed. This measurement window is created to be extremely small so that the measurement is not affected by the rise time and fall time of the waveform.

The RZ eye width is determined using the time difference between the 3 (standard deviation) points of the 50% level histograms.

$$RZ_EyeWidth = (T_{Fall50\%} - 3\sigma) - (T_{Rise50\%} - 3\sigma)$$

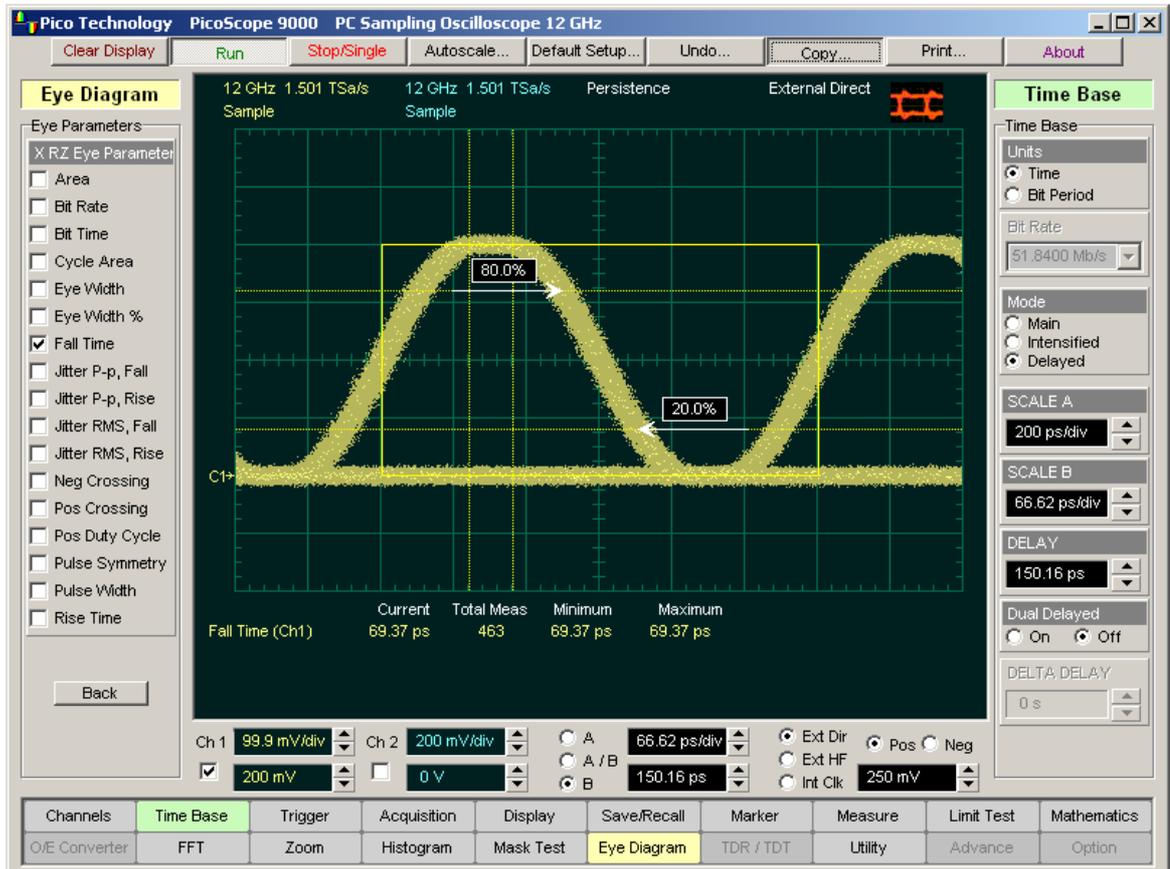
The RZ eye width can also be expressed as the ratio of the 3 standard deviation time difference between edges to the bit time (bit period) of the eye pulses:

$$RZ_EyeWidth_% = \frac{(T_{Fall50\%} - 3\sigma) - (T_{Rise50\%} + 3\sigma)}{BitTime}$$

5.4.7.6 RZ Fall Time

 Fall Time

RZ Fall Time is a measure of the mean transition time of the data on the downward slope of an RZ eye diagram. The data crosses through the following three thresholds: the upper, middle, and lower thresholds.



RZ Fall Time definition

A histogram is first constructed to find the mean locations of the eye one level and zero level. Histograms are then constructed at each of the three threshold levels (for example, the 20%, 50%, and 80% points on the transition). The instrument analyses each histogram to determine the histogram mean at which the data crosses the separate threshold levels. Once the scanning of the waveform is complete, and the instrument has identified the mean location for each threshold crossed, then fall time can be computed.

$$\text{RZ Fall Time} = (\text{Time at the Lower Threshold Crossing}) - (\text{Time at the Upper Threshold Crossing})$$

The default setting for the threshold levels is the 20% to 80% points on the transition. These levels give more consistent results for eyes with distortion at the top or bottom. You can define the threshold settings that you want in the [Define Parameters](#) menu.



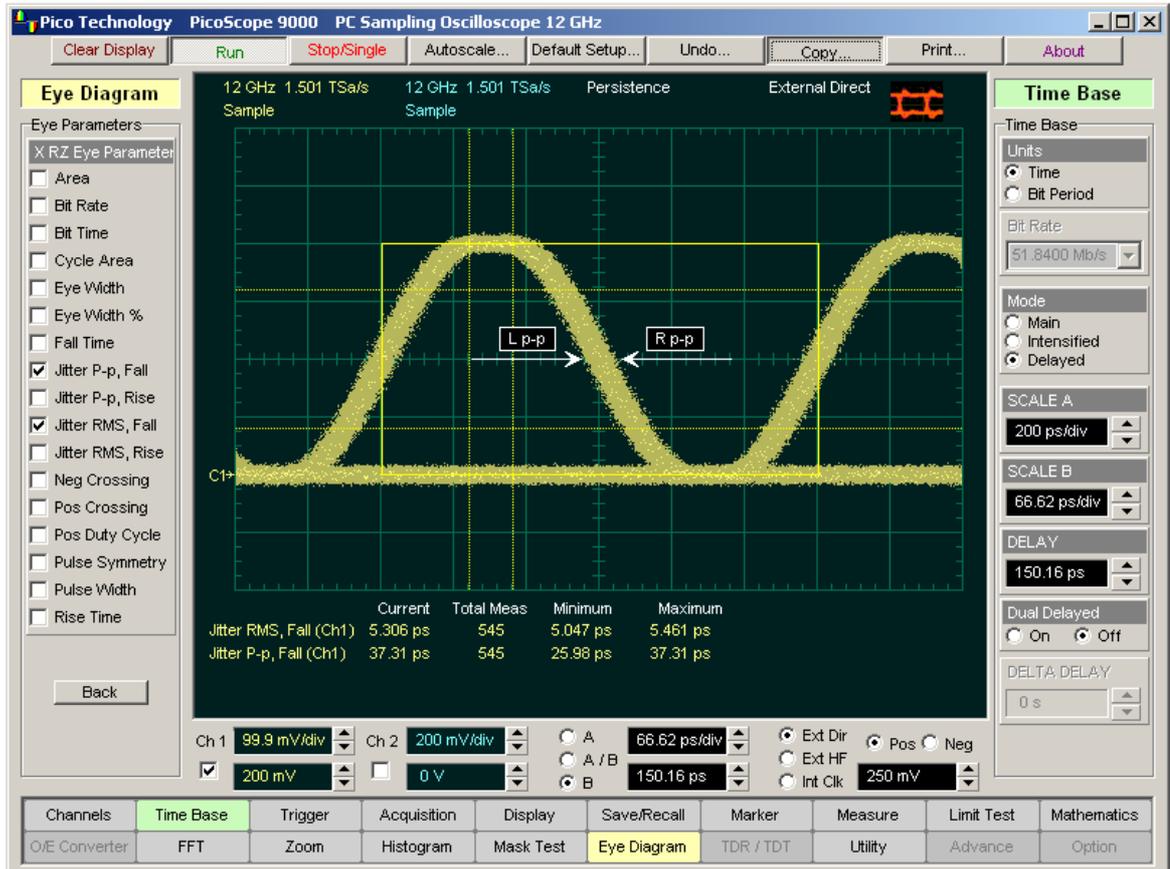
If the fall time relative to the time/division is a small value, the data acquired at the threshold levels on the falling edge will not yield accurate measurement results. (The falling edge will appear very steep on the display screen.)

If the falling edge of your eye diagram is steep, increase the timebase (horizontal scale) on the display so that the falling edge covers at least half a graticule division. The instrument will be able to discern the data at the threshold levels, producing more accurate results.

5.4.7.7 RZ Jitter P-p, Fall and RZ Jitter RMS, Fall



RZ Jitter P-p, Fall and RZ Jitter RMS, Fall are the measures of signal instability relative to its ideal position in time.



RZ Jitter P-p, Fall and RZ Jitter RMS, Fall definition

To compute jitter peak-to-peak, the standard deviation is measured at a 50% level of the first measurable falling edge. The measurement window is kept extremely small so that the width at the 50% level is not influenced by the slope of the waveform. The histograms are then analysed to determine the amount of RMS jitter, which is defined as 1 (standard deviation) from the histogram mean.

The RZ peak-to-peak jitter is the full width of the histogram at the eye 50% level:

$$RZ \text{ Jitter } P-p, \text{ Fall} = 6 \text{ (crossing)}$$

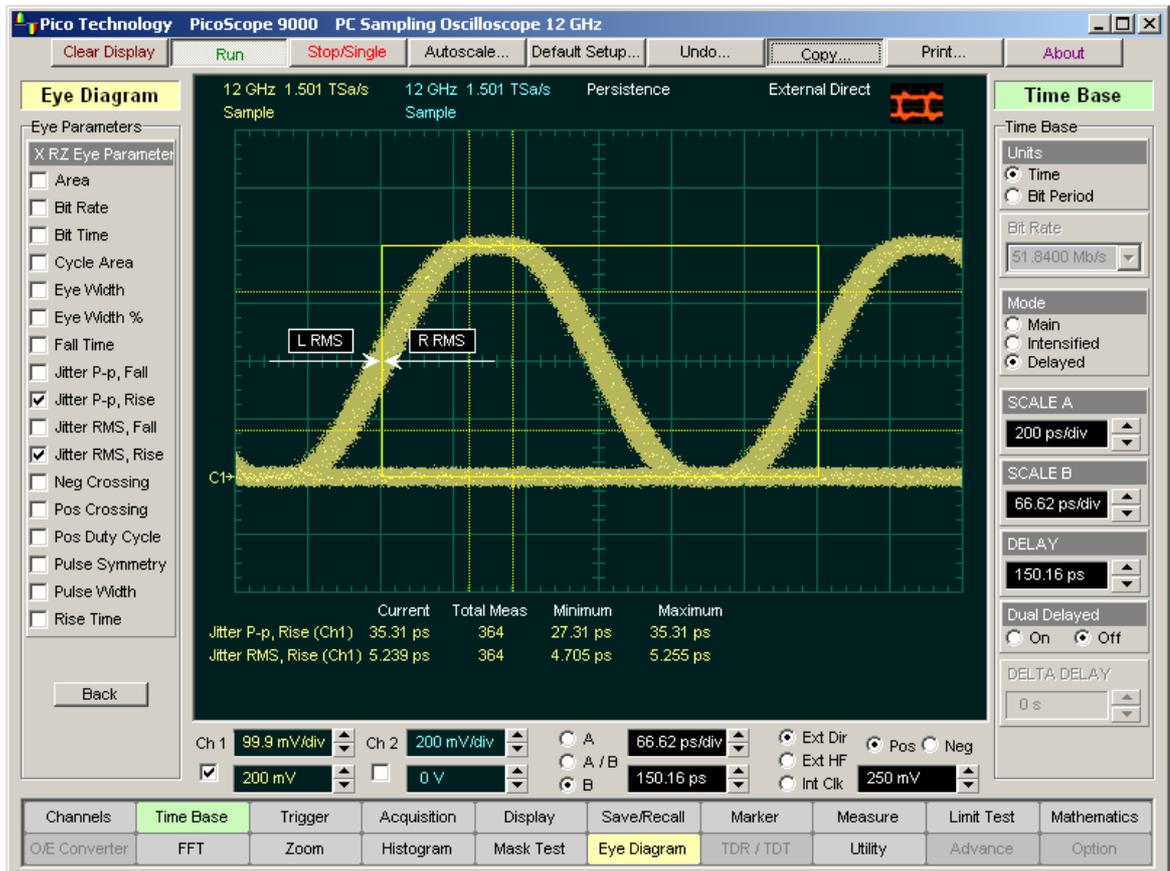
The RZ RMS jitter is defined as one standard deviation from the histogram mean at the eye crossing point:

$$RZ \text{ Jitter } RMS, \text{ Fall} = 1 \text{ (crossing)}$$

5.4.7.8 RZ Jitter P-p, Rise and RZ Jitter RMS, Rise



RZ Jitter P-p, Rise and RZ Jitter RMS, Rise are the measures of signal instability relative to its ideal position in time.



RZ Jitter P-p, Rise and RZ Jitter RMS, Rise definition

To compute jitter peak-to-peak, the standard deviation is measured at a 50% level of the left measurable rising edge. The measurement window is kept extremely small so that the width at the 50% level is not influenced by the slope of the waveform. The histograms are then analysed to determine the amount of RMS jitter, which is defined as 1 (standard deviation) from the histogram mean.

The RZ peak-to-peak jitter is the full width of the histogram at the eye 50% level:

$$RZ\ Jitter\ P-p,\ Rise = 6 \text{ (crossing)}$$

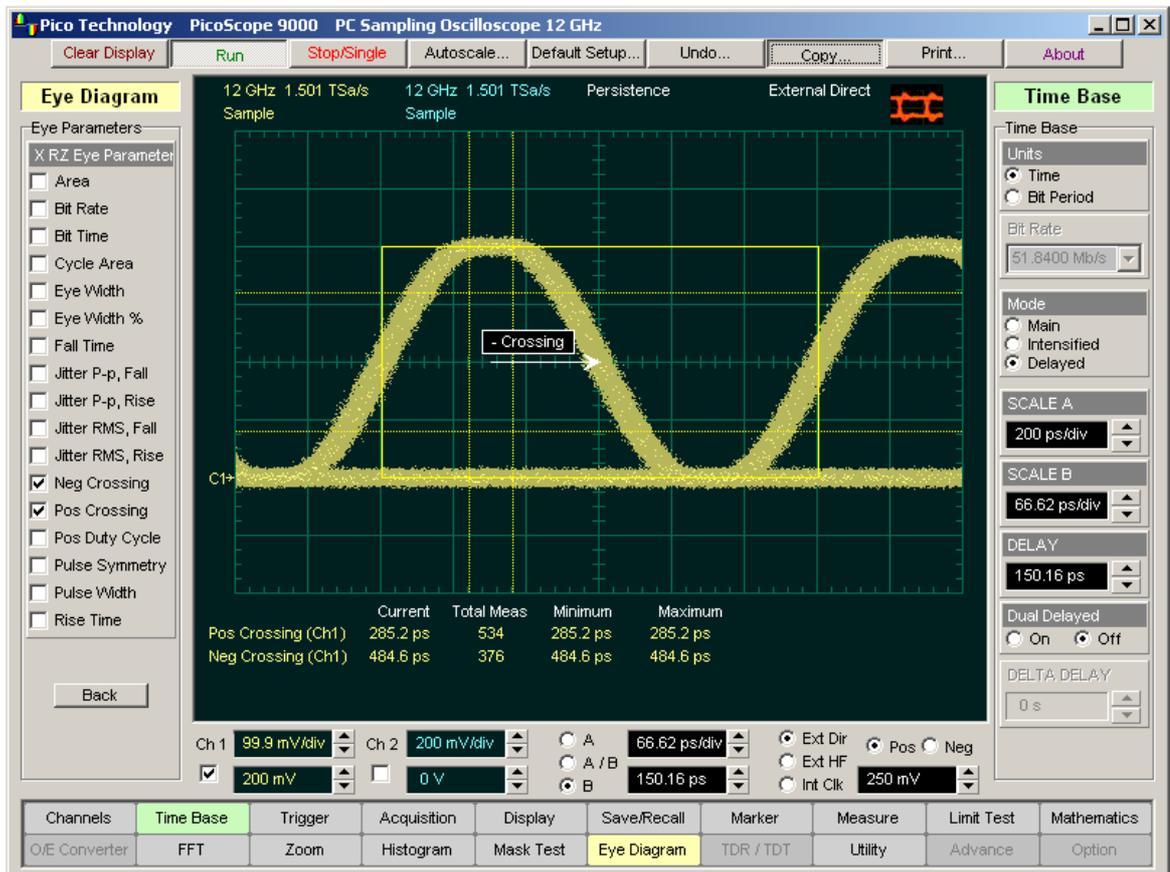
The RZ RMS jitter is defined as one standard deviation from the histogram mean at the eye crossing point:

$$RZ\ Jitter\ RMS,\ Rise = 1 \text{ (crossing)}$$

5.4.7.9 RZ Negative Crossing



RZ Negative Crossing is a measure of the time of a negative crossing, defined as the mean of the histogram of the data sampled at the 50% reference level.



RZ Negative Crossing definition

The RZ Negative Crossing is determined as follows:

$$RZ\ Negative\ Crossing = T_{CrossNeg}$$

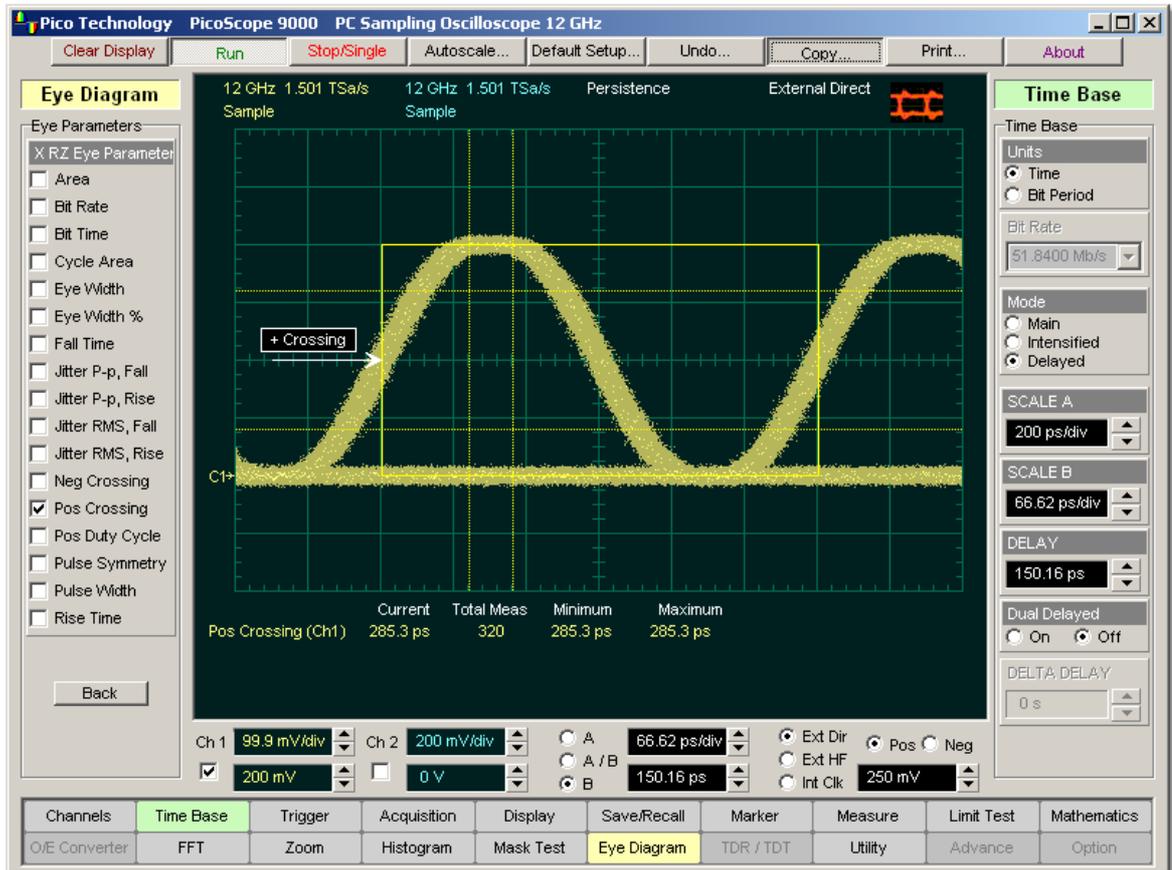
where $T_{CrossNeg}$ is the mean of the histogram of a negative crossing.

This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.7.10 RZ Positive Crossing



RZ Positive Crossing is a measure of the time of a left positive crossing, defined as the mean of the histogram of the data sampled at the 50% reference level.



RZ Positive Crossing definition

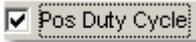
The RZ Positive Crossing is determined as follows:

$$RZ\ Positive\ Crossing = T_{CrossPos}$$

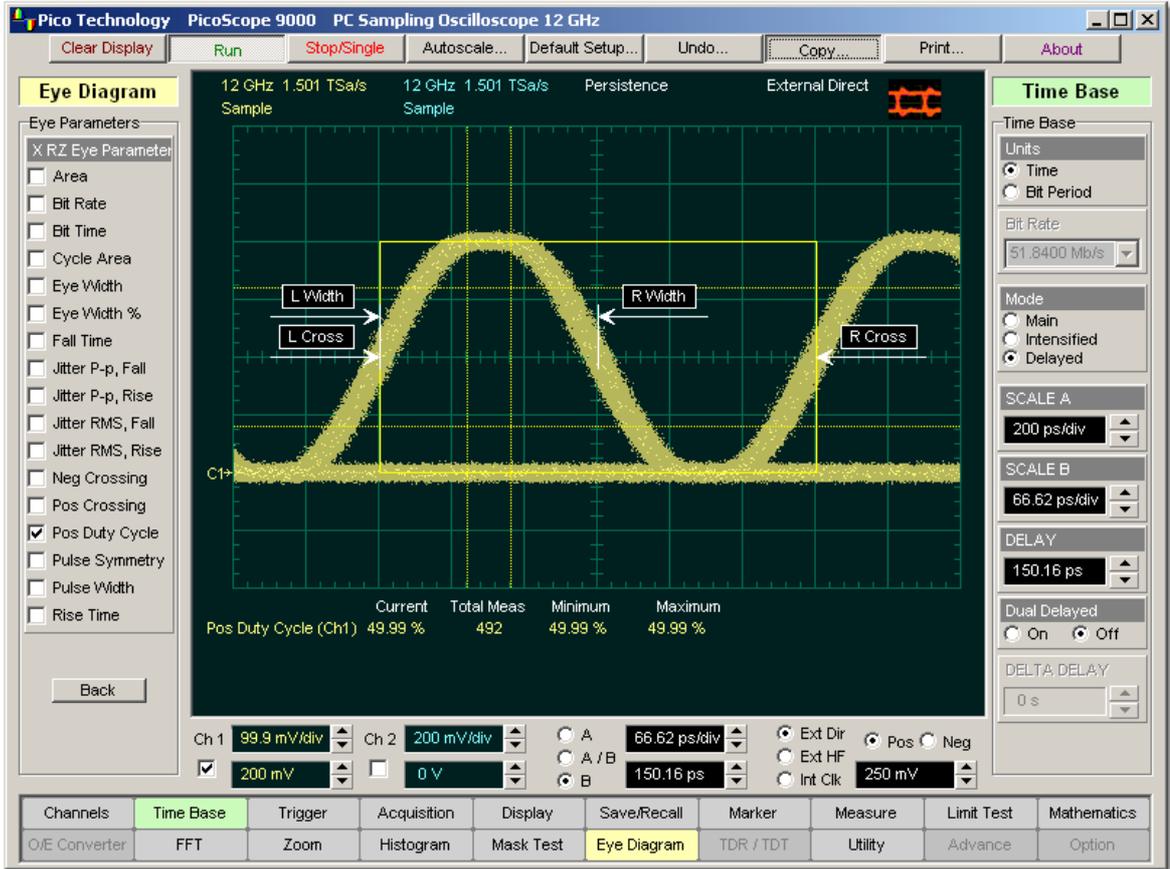
where $T_{CrossPos}$ is the mean of the histogram of a positive crossing.

This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.7.11 RZ Positive Duty Cycle



RZ Positive Duty Cycle is a measure of the ratio of the RZ positive pulse width to the RZ bit time.



RZ Positive Duty Cycle definition

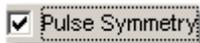
The RZ Positive Duty Cycle is determined as follows:

$$RZ_DutyCycle = \frac{T_{Fall50\%} - T1_{Rise50\%}}{T2_{Rise50\%} - T1_{Rise50\%}} = \frac{RZ_PositivePulseWidth}{RZ_BitTime}$$

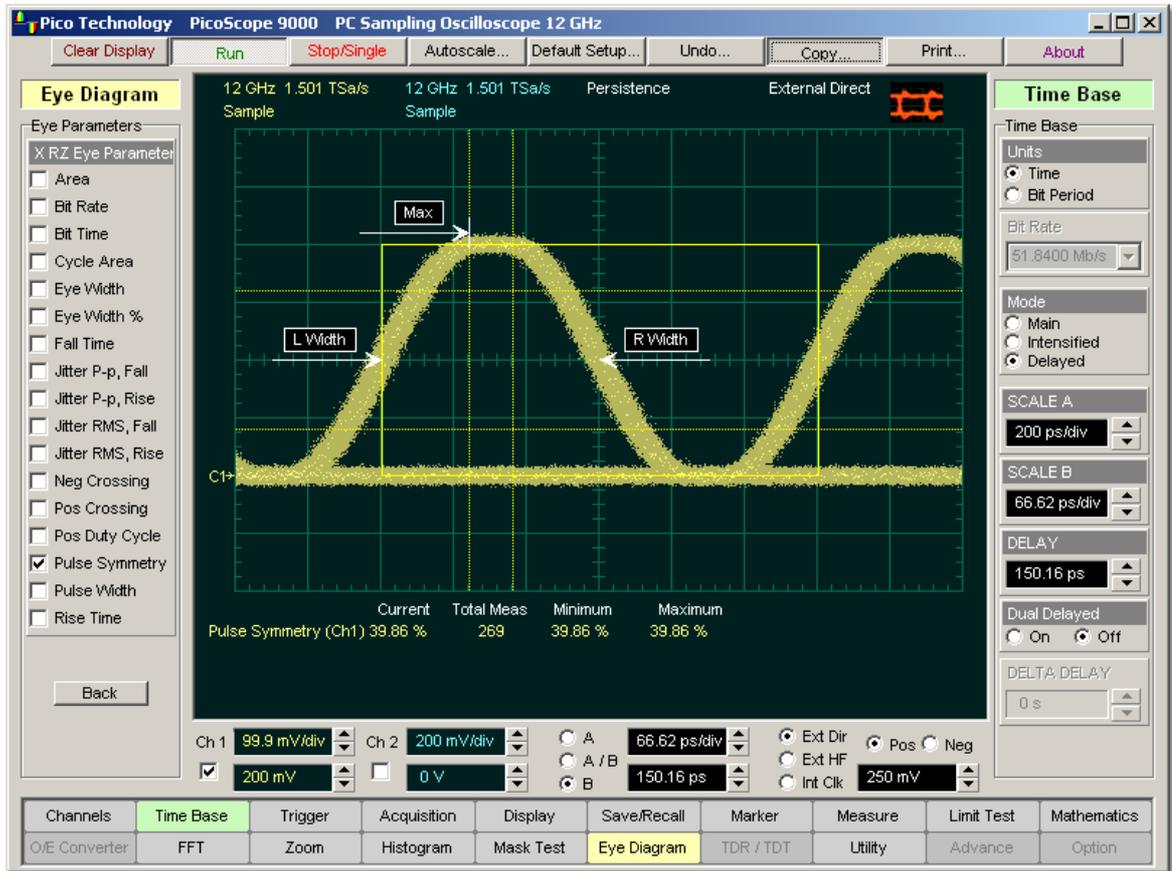
Where $T1_{Rise50\%}$, $T1_{Fall50\%}$ and $T2_{Rise50\%}$ are the mean of the histogram of the first three consecutive crossings at the 50% reference level.

This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.7.12 RZ Pulse Symmetry



RZ Pulse Symmetry measures to what extent the RZ pulse is symmetrical around the peak at the 50% reference level. The pulse peak is the center of the interval, sized to Eye Aperture, which yields the maximum mean vertical value.



RZ Pulse Symmetry definition

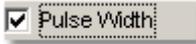
The RZ Pulse Symmetry (%) is determined as follows:

$$RZ_PulseSymmetry, \% = 100 \frac{T_{Peak} - T_{Rise50\%}}{T_{Fall50\%} - T_{Rise50\%}}$$

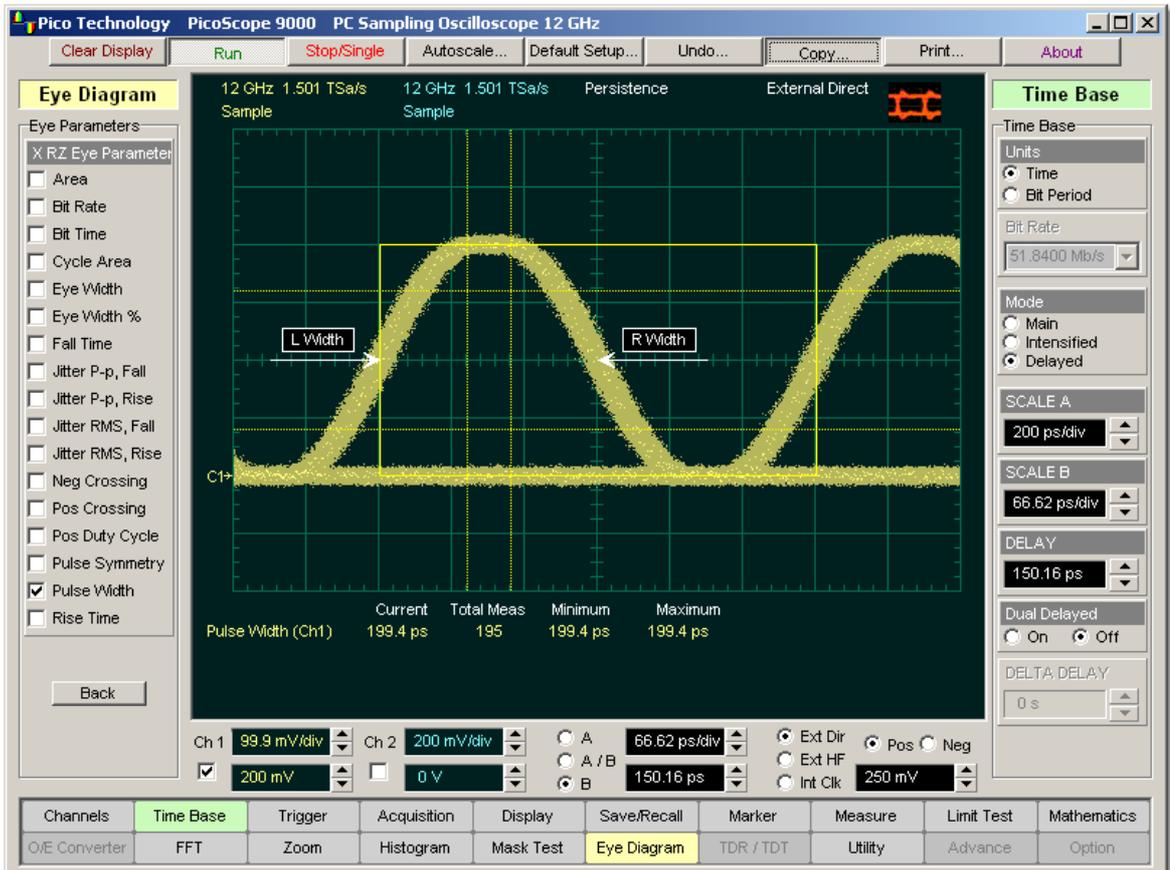
where $T_{Rise50\%}$ and $T_{Fall50\%}$ are the time crossings of the RZ pulse of the 50% reference level, and T_{Peak} is the time coordinate of the pulse peak.

This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.7.13 RZ Pulse Width



RZ Pulse Width is the time measured between histogram means of the 50% rising and 50% falling edges of an RZ eye diagram.



RZ Pulse Width definition

The pulse width is determined as follows:

$$RZ \text{ Pulse Width} = T_{Fall50\%} - T_{Rise50\%}$$

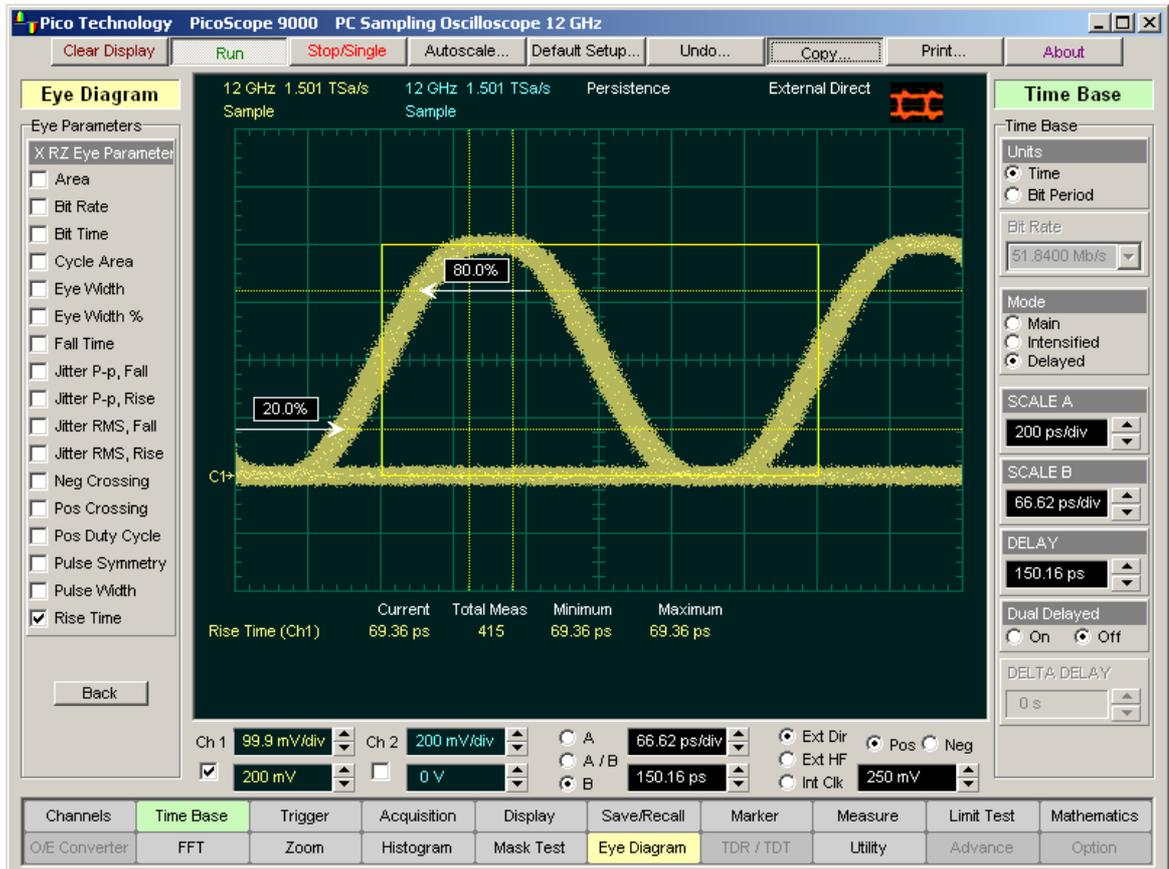
where $T_{Fall50\%}$ and $T_{Rise50\%}$ are the time crossings of the RZ pulse at the 50% reference level.

This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.7.14 RZ Rise Time



RZ Rise Time is a measure of the mean transition time of the data on the upward slope of an RZ eye diagram. The data crosses through the lower, middle, and upper thresholds.



RZ Rise Time definition

A histogram is first constructed to find the mean locations of the eye one level and zero level. Histograms are then constructed at each of the three threshold levels (for example, the 20%, 50%, and 80% points on the transition). The instrument analyses each histogram to determine the histogram mean at which the data crosses the separate threshold levels. Once the scanning of the waveform is complete, and the instrument has identified the mean location for each threshold crossed, then fall time can be computed:

$$RZ \text{ Rise Time} = (\text{Time at the Upper Threshold Crossing}) - (\text{Time at the Lower Threshold Crossing})$$

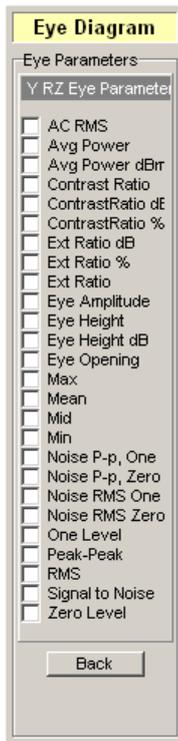
The default setting for the threshold levels is between the 20% and 80% points on the transition. These levels give more consistent results for eyes with distortion at the top or bottom. You can define the threshold settings that you want in the [Define Parameters](#) ^[64] menu.



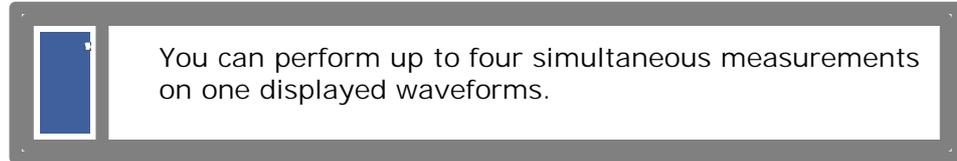
If the rise time relative to the time per division is a small value, the data acquired at the threshold levels on the falling edge will not yield accurate measurement results. (The rising edge will appear very steep on the display screen.)

If the rising edge of your eye diagram is steep, increase the timebase (horizontal scale) on the display so that the rising edge covers at least half a graticule division. The instrument will be able to discern the data at the threshold levels, producing more accurate results.

5.4.8 Y RZ Eye Parameters



The list of Y RZ Eye Parameters includes twenty-six eye parameters. Two of the them (Avg Power and Avg Power dBm) can be used in optical models only.



The measurement algorithms for Y RZ Eye Parameters will only work when an RZ eye diagram, and not an NRZ eye diagram or a pulse, is present on the screen. Eye measurements are based on statistical data that is acquired and stored in the measurement database. The algorithms depend upon histogram means calculated from the measurement database. Therefore, if you want to perform eye measurements, it is necessary that you first produce an eye diagram by triggering the instrument with a synchronous clock signal.

Measurements made on NRZ eye diagram or a pulse waveform while in the X RZ Eye Parameters menu will fail.

5.4.8.1 RZ AC RMS



RZ AC RMS is a measure of the root mean square amplitude, minus the DC component, of the waveform within the eye window.



RZ AC RMS definition

The RZ AC RMS is determined as follows:

$$RZ_AC_RMS = \sqrt{\frac{\sum_{i=1}^N \langle (VertPos(s_i) - mean[VertPos(s)])^2 \rangle}{N}}$$

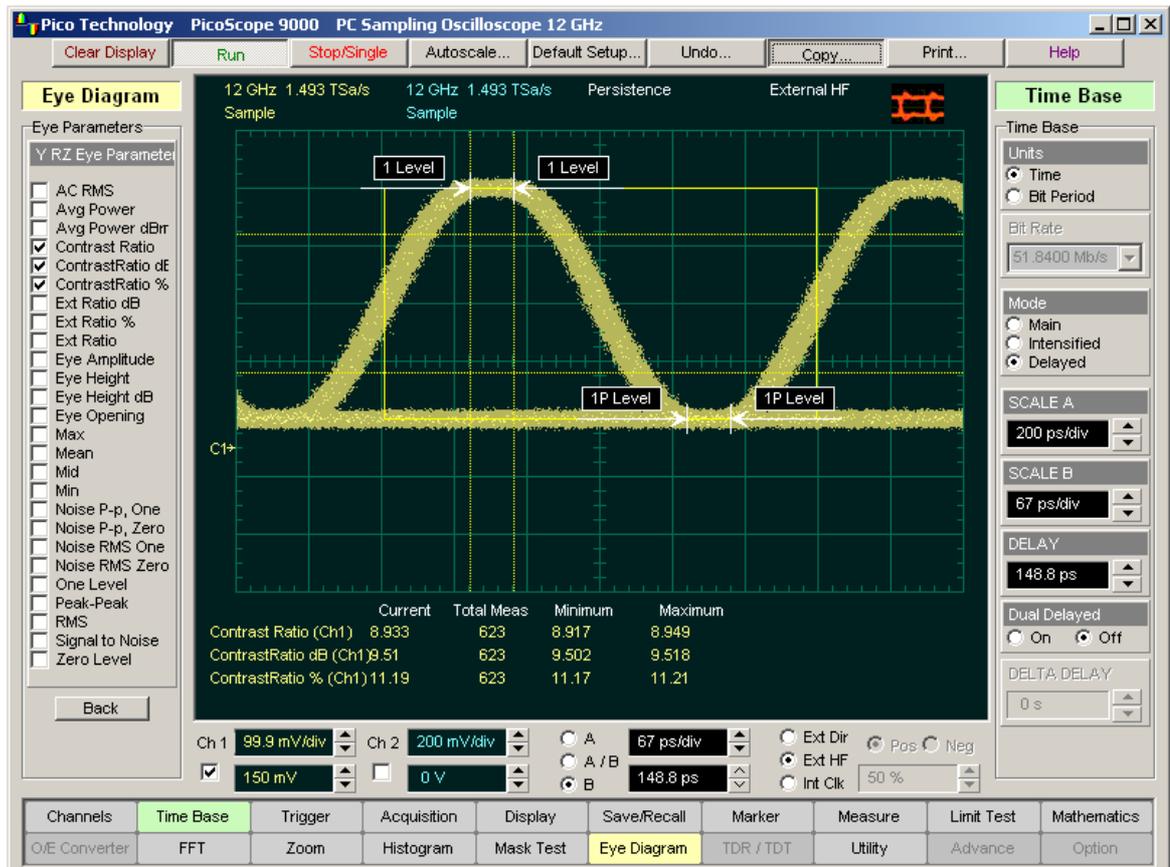
where S is the set of N samples $s_{1...N}$ within the measured region.

This measurement requires the use of a waveform database. When this measurement is turned on, it will automatically set the measurement system to use a waveform database if available.

5.4.8.2 RZ Contrast Ratio, RZ Contrast Ratio dB and RZ Contrast Ratio %



RZ Contrast Ratio is a measure of the ratio of the one level at the centre of the eye diagram to the one level (after removal of the zero level contribution) found midway between eye diagram peaks. This measurement indicates how well the logic 1 levels return to the logic zero level. Like the RZ extinction ratio measurement, contrast ratio relies on determining and removing the dark level components from the measurement calculation. In order to perform an accurate contrast ratio measurement, you should first perform an extinction ratio calibration in order to minimize the dark level contribution.



RZ Contrast Ratio definition

RZ Contrast Ratio also is called RZ Suppression Ratio.

RZ Contrast Ratio measurement is made in a section of the eye referred to as the Eye Boundaries, and at the centre of the zero level between pulses. The default value for RZ Eye Boundaries is the central 5% p-p of the Bit Time, or 47.5% (Eye Boundary 1) and 52.5% (Eye Boundary 2).

Histograms are constructed using the sampled portions of the eye diagram within the eye window boundaries, and within equivalent eye window boundaries positioned between eye diagram peaks. The one level histogram mean is composed of data points taken from the upper half of the eye window located within the eye diagram, the zero level histogram is composed of data points taken from the lower half of the eye window located within the eye diagram, and the remaining histogram is composed of data points taken from the eye window located between peaks. The instrument analyses the histogram data, removes the zero level data from the between peaks histogram, then determines the ratio of the one level mean and the one level mean between peaks.

The accuracy of the contrast ratio measurement can be affected by offsets, including the dark level, generated within the instrument electronics, typically following the photodiode. When these offsets occur, they add to the incoming signal. This will change the values of the one and zero levels. When the contrast ratio measurement is computed, the result may appear much smaller or larger than the true value, depending on the value of the offset. To minimize contrast ratio measurement errors due to offsets, an extinction ratio calibration is recommended. This procedure allows the instrument to identify any internal signals present and remove them during the contrast ratio calculations. After the calibration is performed, a more accurate contrast ratio measurement can be executed.

With a valid extinction ratio calibration, the contrast ratio measurement can be computed and displayed in one of the three following formats:

$$NRZ_ContrastRatio = \frac{OneLevel - DarkLevel}{OneLevel(between_peaks) - DarkLevel}$$

$$NRZ_ContrastRatio(dB) = 10 \log_{10} \left[\frac{OneLevel - DarkLevel}{OneLevel(between_peaks) - DarkLevel} \right]$$

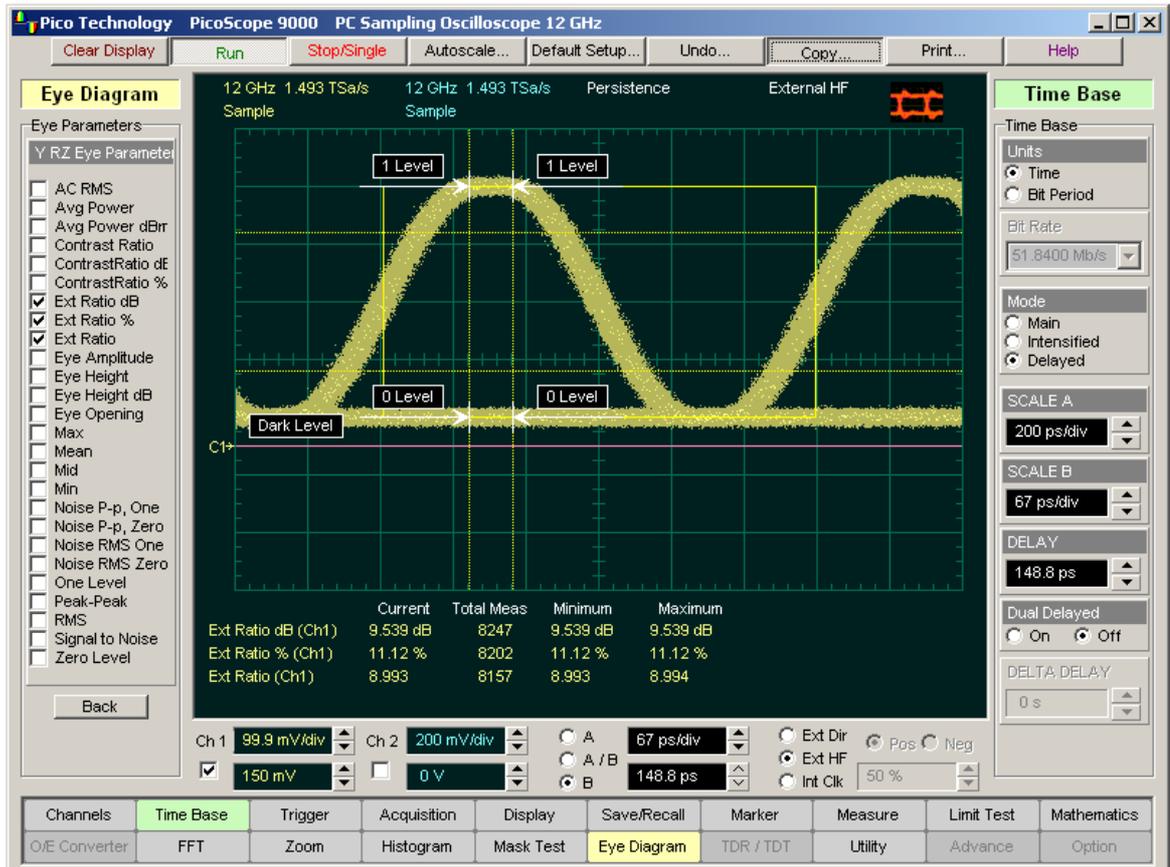
$$NRZ_ContrastRatio(\%) = \frac{OneLevel(between_peaks) - DarkLevel}{OneLevel - DarkLevel} \times 100$$

where: *One Level* = One level histogram mean at eye window, *One Level (between peaks)* = Histogram mean calculated from subtraction of zero level histogram from the between peaks histogram.

5.4.8.3 RZ Extinction Ratio dB, RZ Extinction Ratio % and RZ Extinction Ratio



RZ Extinction Ratio is a measure of the ratio of the one level and the zero level of an RZ eye diagram. The accuracy of this measurement relies on determining and removing the dark level components from the measurement calculation. In order to perform an accurate extinction ratio measurement, you should first perform an extinction ratio calibration in order to minimize the dark level contribution.



RZ Extinction Ratio definition

RZ Extinction Ratio measurement is made in a section of the eye referred to as the Eye Boundaries, and at the centre of the zero level between the pulses. The default value for RZ Eye Boundaries is the central 5% p-p of the Bit Time, or 47.5% (Eye Boundary 1) and 52.5% (Eye Boundary 2).

Histograms are constructed using the sampled portions of the eye diagram within the eye window boundaries. One histogram is composed of data points from only the upper half of the eye diagram (one level), and the second histogram is composed of data points from the lower half of the eye (zero level). The instrument analyses the histograms and determines the histogram means.

The accuracy of the extinction ratio measurement can be affected by offsets, including the dark level, generated within the instrument electronics, typically following the photodiode. When these offsets occur, they add to the incoming signal. This will change the values of the one and zero levels. When the extinction ratio measurement is computed, the result may appear much smaller or larger than the true value, depending on the value of the offset. To minimize extinction ratio measurement errors due to offsets, an extinction ratio calibration is recommended. This procedure allows the instrument to identify any internal signals present and remove them during the extinction ratio calculations. After the calibration is performed, a more accurate extinction ratio measurement can be executed.

With a valid extinction ratio calibration, the extinction ratio measurement is computed and can be displayed in one of the three following formats:

$$RZ_ExtinctionRatio(dB) = 10 \log_{10} \left[\frac{OneLevel(eye_center) - DarkLevel}{ZeroLevel(eye_center) - DarkLevel} \right]$$

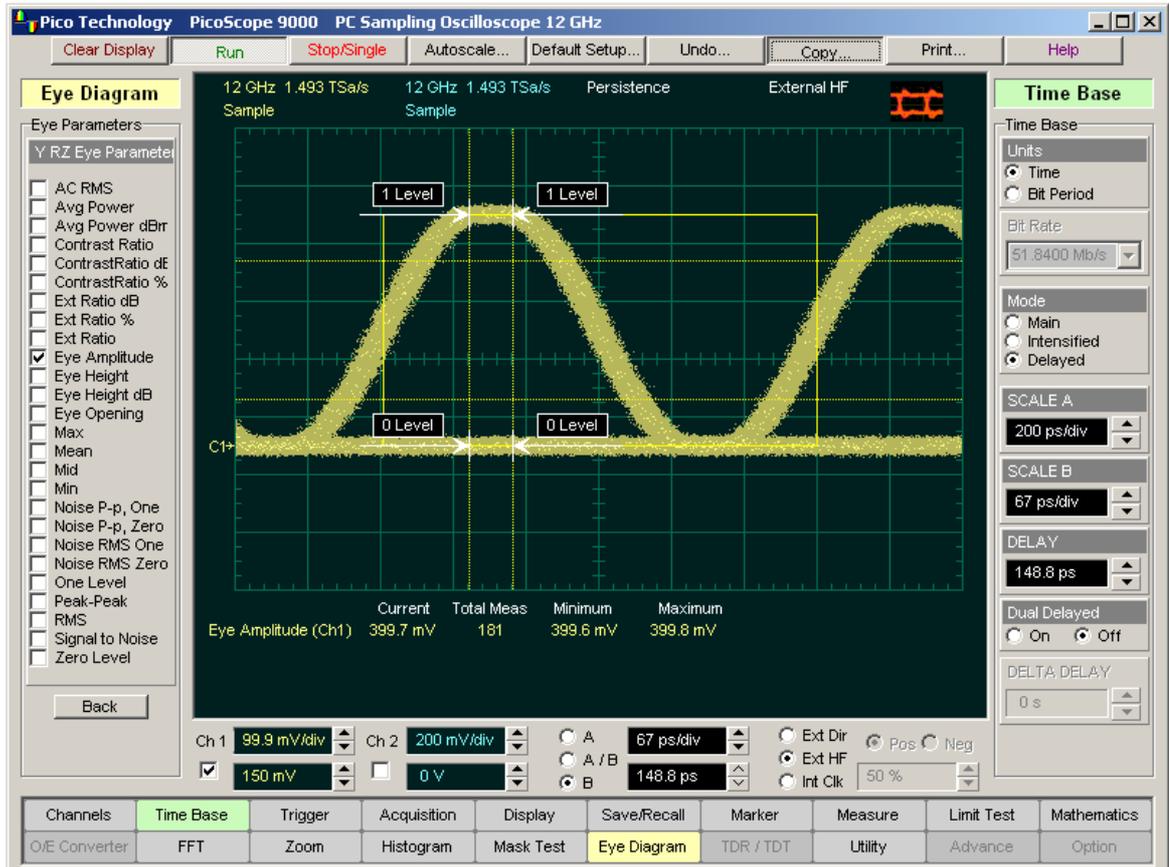
$$RZ_ExtinctionRatio(\%) = \frac{ZeroLevel(eye_center) - DarkLevel}{OneLevel(eye_center) - DarkLevel} \times 100$$

$$RZ_ExtinctionRatio = \frac{OneLevel(eye_center) - DarkLevel}{ZeroLevel(eye_center) - DarkLevel}$$

5.4.8.4 RZ Eye Amplitude

 Eye Amplitude

RZ Eye Amplitude is a measure of the difference between the logic 1 level and the logic 0 level histogram mean values of an RZ eye diagram. It differs from eye height in that it does not account for the noise on the signal.



RZ Eye Amplitude definition

RZ Eye Amplitude measurement is made in a section of the eye referred to as the Eye Boundaries, and at the centre of the zero level between pulses. The default value for RZ Eye Boundaries is the central 5% p-p of the Bit Time, or 47.5% (Eye Boundary 1) and 52.5% (Eye Boundary 2).

A histogram is constructed using the sampled portion of the eye diagram within the eye window. This histogram is composed of data points from the upper and lower halves of the eye diagram. The instrument analyses the histogram and determines the mean values of the logic 1 and logic 0 levels.

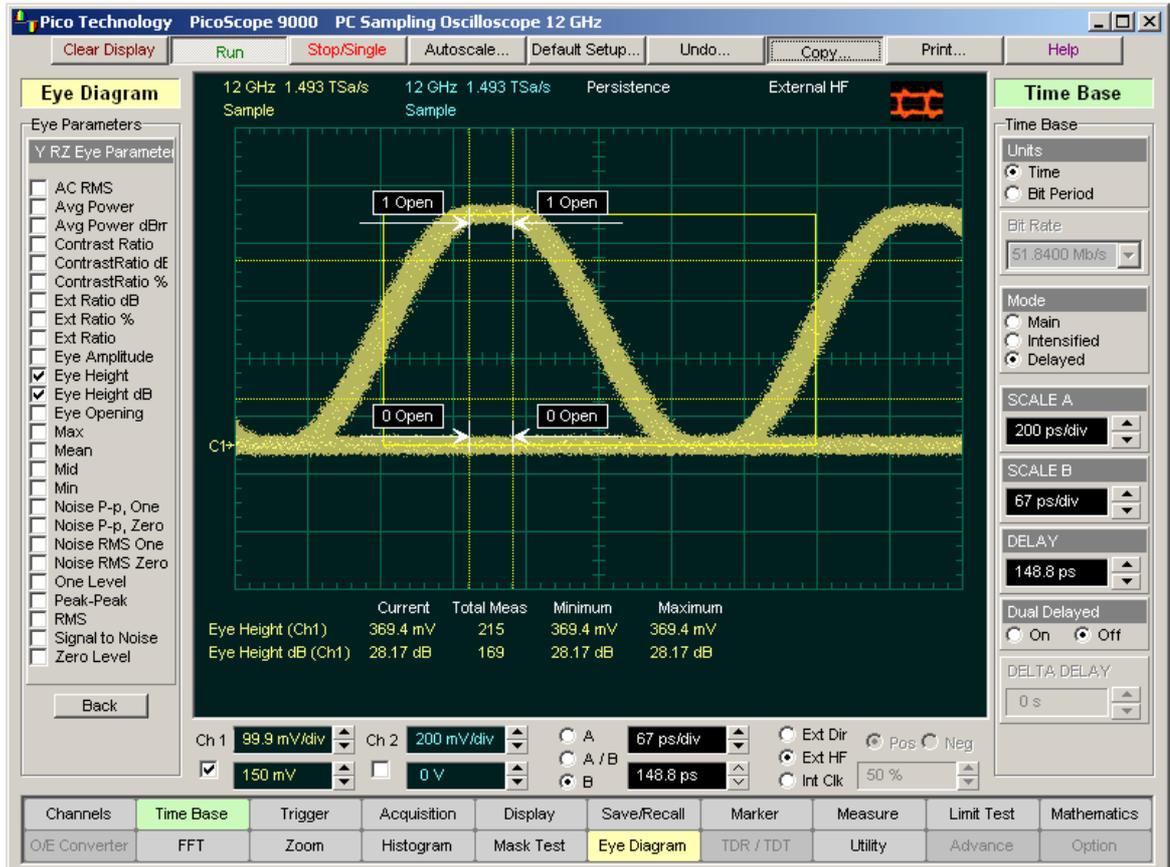
The eye amplitude is determined as follows:

$$RZ \text{ Eye Amplitude} = \text{One Level} - \text{Zero Level}$$

5.4.8.5 RZ Eye Height and RZ Eye Height dB



RZ Eye Height is a measure of the vertical opening of an RZ eye diagram. An ideal eye opening would be measured from the one level to the zero level, but noise on the eye causes the eye to close. The eye height measurement determines eye closure due to noise.



RZ Eye High definition

RZ Eye High measurement is made in a section of the eye referred to as the Eye Boundaries, and at the centre of the zero level between pulses. The default value for RZ Eye Boundaries is the central 5% p-p of the Bit Time, or 47.5% (Eye Boundary 1) and 52.5% (Eye Boundary 2).

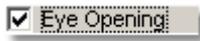
In order to make an accurate RZ eye height measurement, histograms are constructed to characterize both the one and zero levels and their noise levels within the eye window boundaries. The one and zero levels are the relative means of the histograms. The noise is measured through the histograms as three standard deviations () from both the one level and zero level into the eye opening.

The eye height is determined as follows:

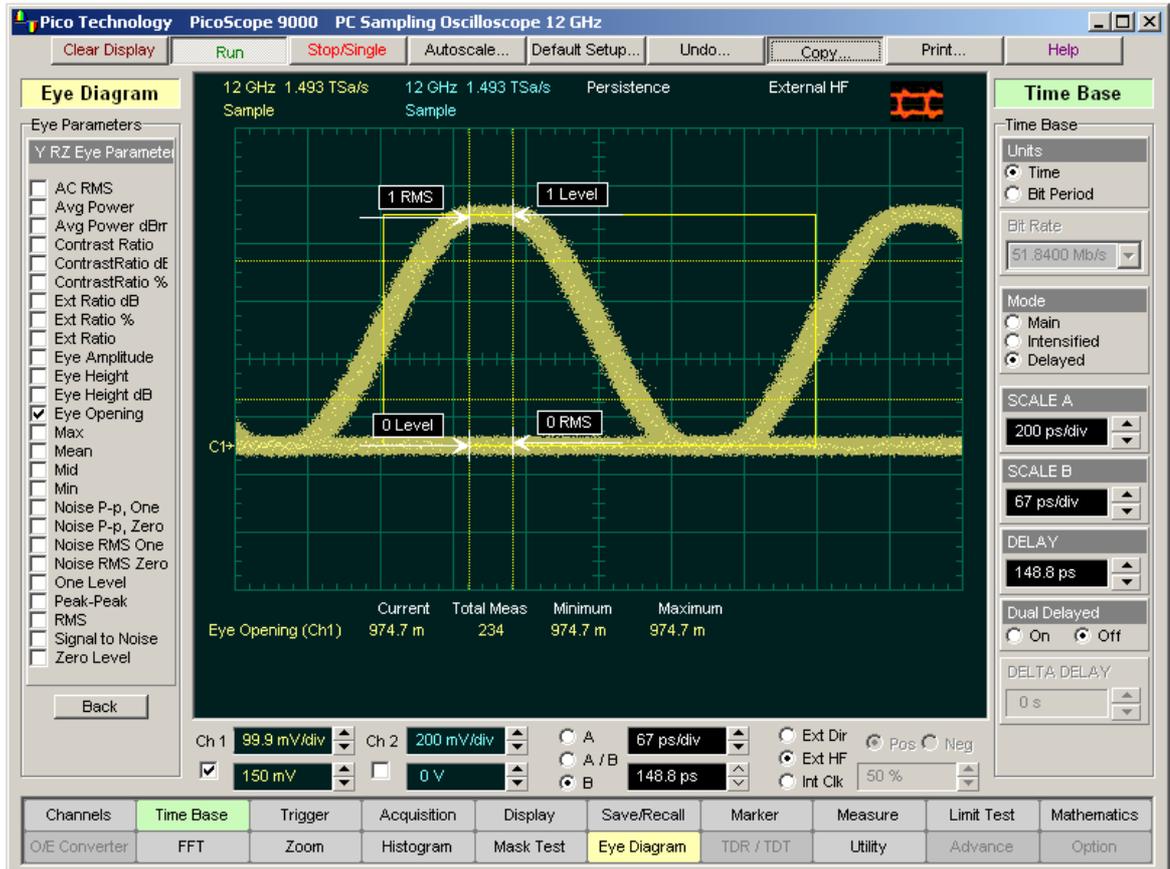
$$RZ_EyeHeight = (OneLevel - 3\sigma_{one}) - (ZeroLevel + 3\sigma_{zero})$$

$$RZ_EyeHeight(dB) = -10 \log_{10} \frac{(ZeroLevel + 3\sigma_{zero})}{(OneLevel - 3\sigma_{one})}$$

5.4.8.6 RZ Eye Opening



RZ Eye Opening Factor is similar to eye height. It measures the actual eye opening relative to an ideal noise-free eye. While the eye height measurement uses 3 σ for the noise contribution, the eye opening measurement uses 1 σ .



RZ Eye Opening Factor definition

The RZ Eye Opening Factor measurement is made in a section of the eye referred to as the Eye Boundaries, and at the centre of the zero level between pulses. The default value for RZ Eye Boundaries is the central 5% p-p of the Bit Time, or 47.5% (Eye Boundary 1) and 52.5% (Eye Boundary 2).

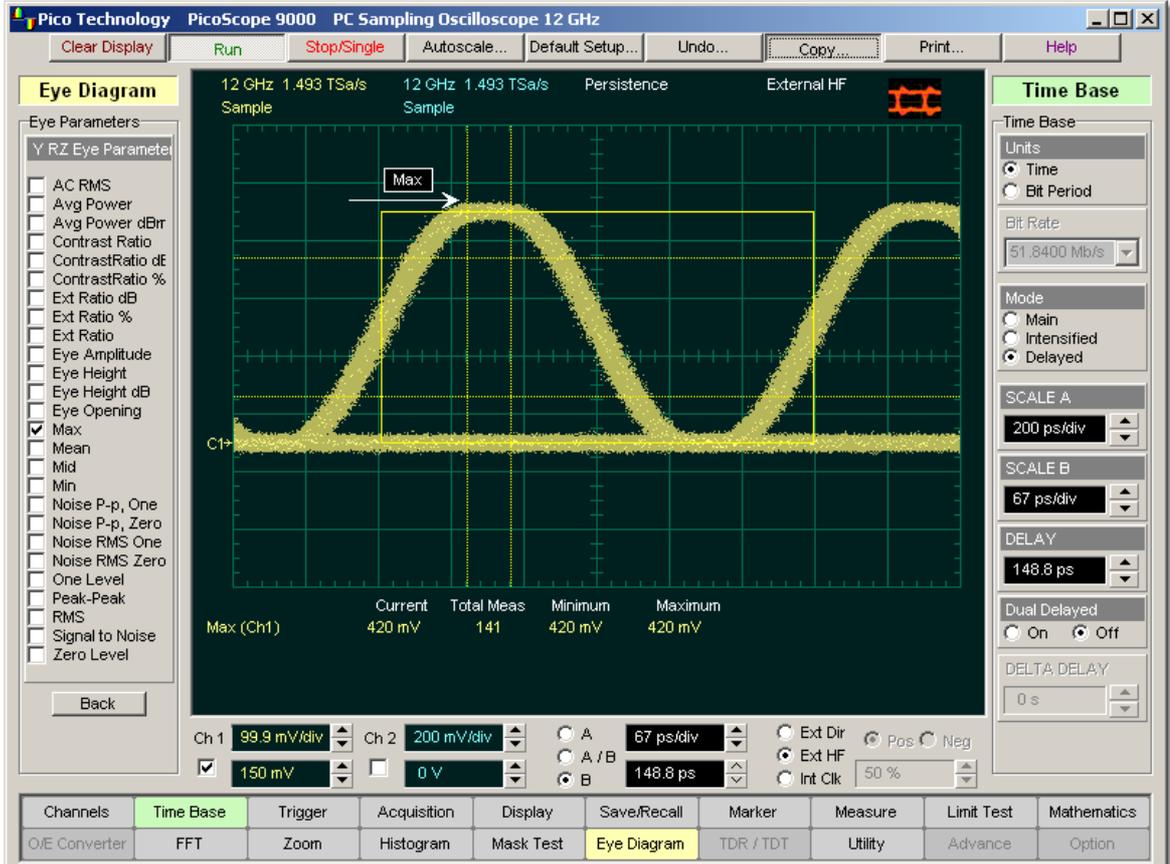
The eye opening factor is determined as follows:

$$RZ_EyeOpeningFactor = - \frac{(OneLevel - \sigma_{one}) - (ZeroLevel + \sigma_{zero})}{OneLevel - ZeroLevel}$$

5.4.8.7 RZ Max



RZ Max is a measure of the maximum vertical value of the waveform that is sampled within the eye window.



RZ Maximum definition

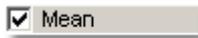
The RZ maximum eye amplitude is determined as follows:

$$RZ\ Maximum = \max[VertPos(s)]$$

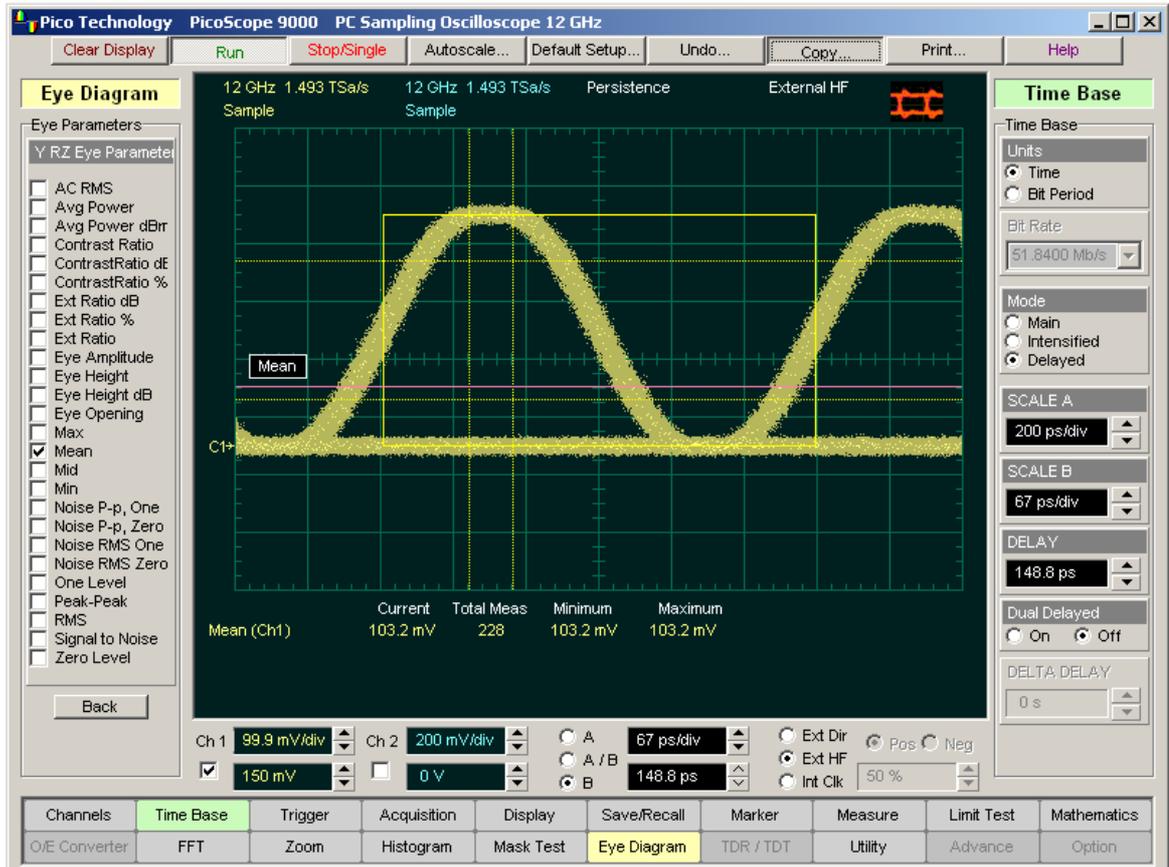
where s is the set of samples within the eye window.

When this measurement is turned on, it automatically sets the measurement system to use a waveform database if available.

5.4.8.8 RZ Mean



RZ Mean is a measure of the arithmetic mean of the waveform that is sampled within the eye window.



RZ Mean definition

The RZ Mean is determined as follows:

$$RZ_Mean = \text{mean}[VertPos(s)] = \frac{1}{N} \sum_{i=1}^N VertPos(s_i)$$

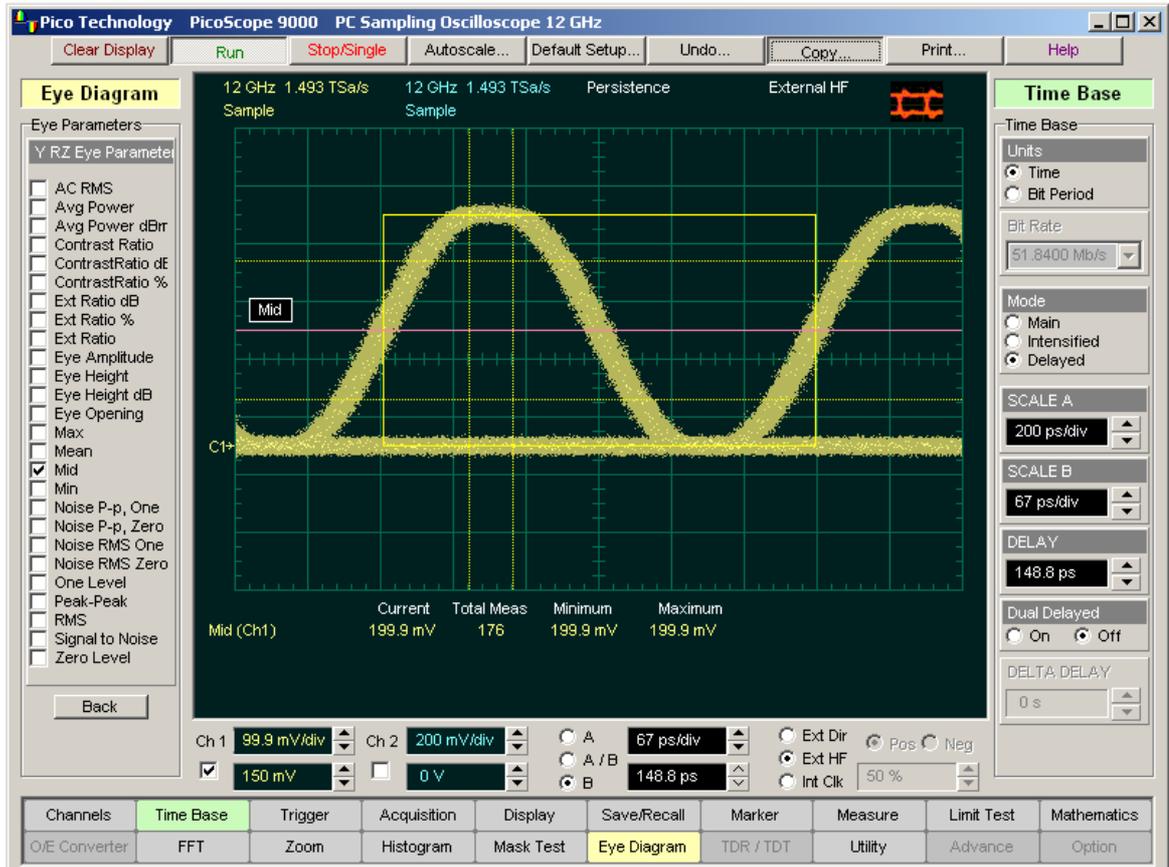
over all samples $s_{i...N}$ within the eye window.

When this measurement is turned on, it automatically sets the measurement system to use a waveform database if available.

5.4.8.9 RZ Mid



RZ Mid is a measure of the middle level between the Max and Min vertical values of the waveform that is sampled within the eye window.



RZ Mid definition

The RZ Mid is determined as follows:

$$RZ\ Mid = (Max + Min) / 2$$

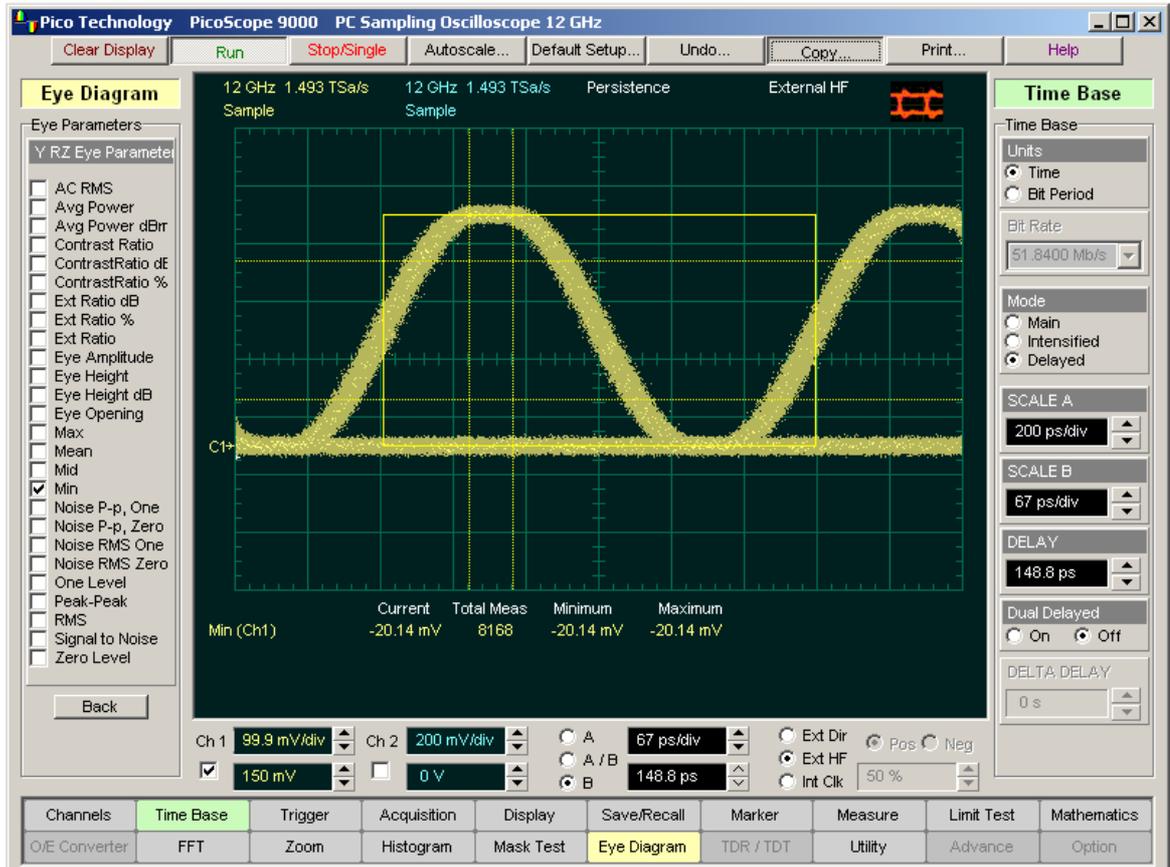
where *Max* and *Min* are the maximum and minimum measurements.

When this measurement is turned on, it automatically sets the measurement system to use a waveform database if available.

5.4.8.10 RZ Min



RZ Min is a measure of the minimum vertical value of the waveform that is sampled within the eye window.



RZ Min definition

The RZ minimum eye amplitude is determined as follows:

$$RZ\ Minimum = \max[VertPos(s)]$$

where s is the set of samples in the measured region. Minimum has no settable references.

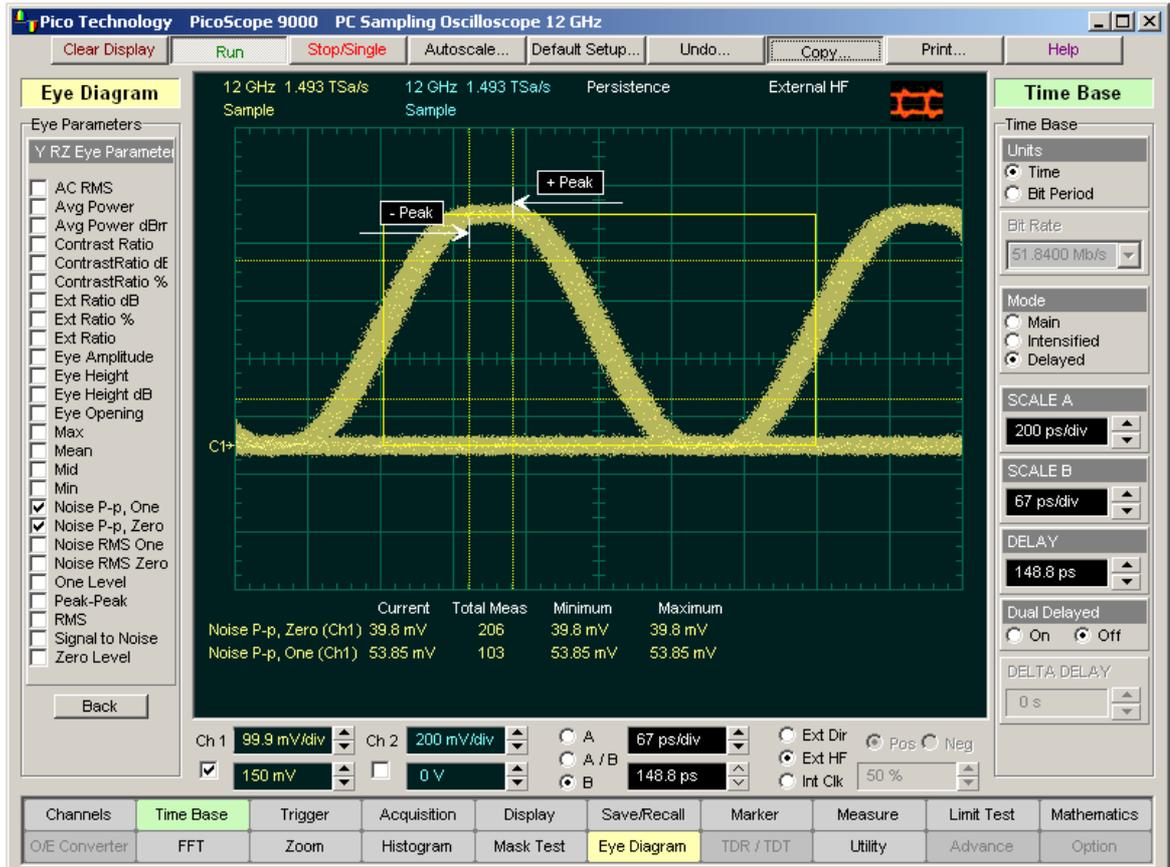
When this measurement is turned on, it automatically sets the measurement system to use a waveform database if available.

5.4.8.11 RZ Noise P-p, One and RZ Noise P-p, Zero



RZ Noise P-p, One is a measure of the maximum range of the data distribution sampled within a fixed RZ Eye Boundaries slice located at the center of the Eye Aperture at the One Level.

RZ Noise P-p, Zero is a measure of the maximum range of the data distribution sampled within a fixed RZ Eye Boundaries slice located at the center of the Eye Aperture at the Zero Level.



RZ Noise P-p, One and RZ Noise P-p, Zero definition

The RZ Noise P-p is determined as follows:

$$RZ_Noise, P-p = \max[VertPos(s)] - \min[VertPos(s)]$$

where s is the set of samples within a fixed width vertical slice located at the center of the eye aperture at either the High or the Low level (settable: RZ Noise P-p, One, and RZ Noise P-p, Zero).

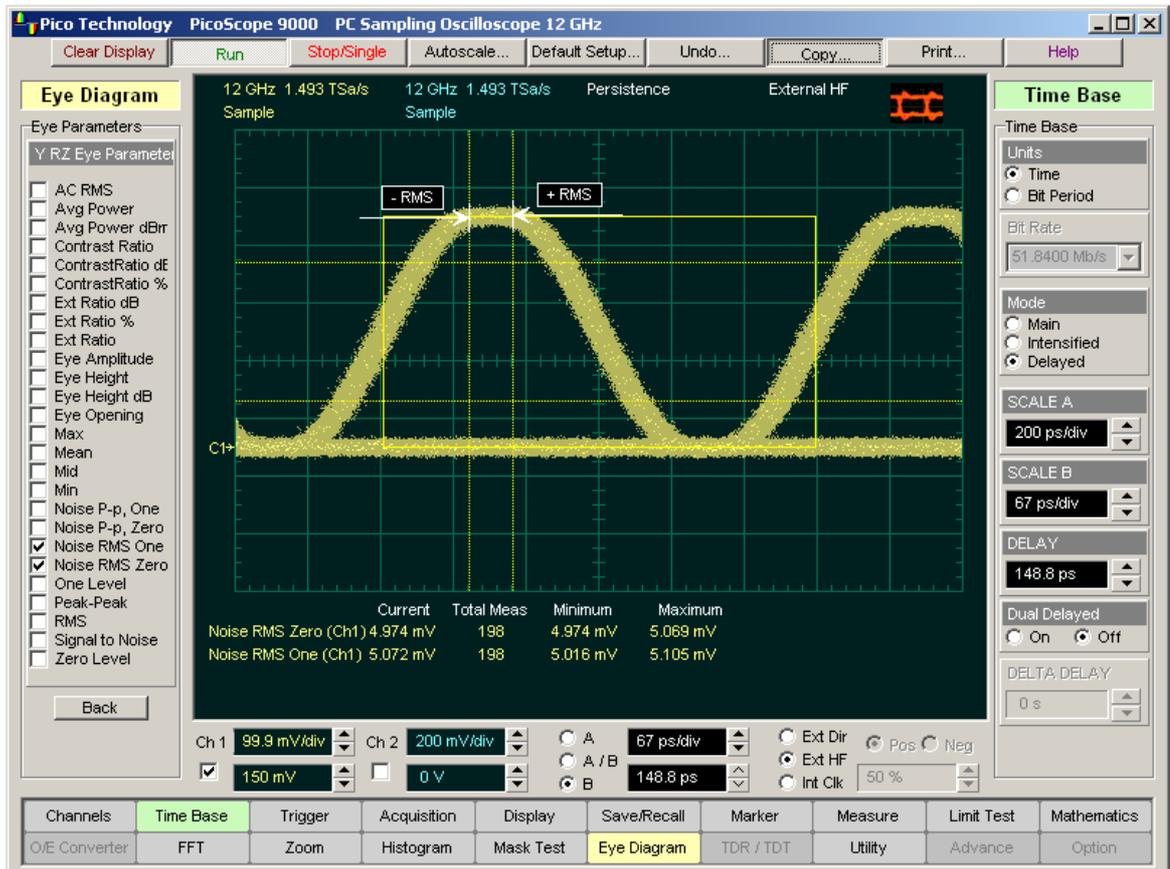
The RZ Noise P-p, One and RZ Noise P-p, Zero measurements are made in a section of the eye referred to as the Eye Boundaries, and at the centre of the zero level between pulses. The default value for RZ Eye Boundaries is the central 5% p-p of the Bit Time, or 47.5% (Eye Boundary 1) and 52.5% (Eye Boundary 2).

This measurement requires the use of a waveform database. When this measurement is turned on, it automatically sets the measurement system to use a waveform database if available.

5.4.8.12 RZ Noise RMS, One and RZ Noise RMS Zero



NRZ Noise RMS is a measurement of the single standard deviation of the data distribution sampled within a fixed-width vertical slice located at the center of the Eye Aperture at the High (logical 1) or Low (logical 0) levels.



RZ Noise RMS, One and RZ Noise RMS, Zero definition

The RZ Noise RMS is determined as follows:

$$RZ\ RMS = High$$

$$RZ\ RMS = Low$$

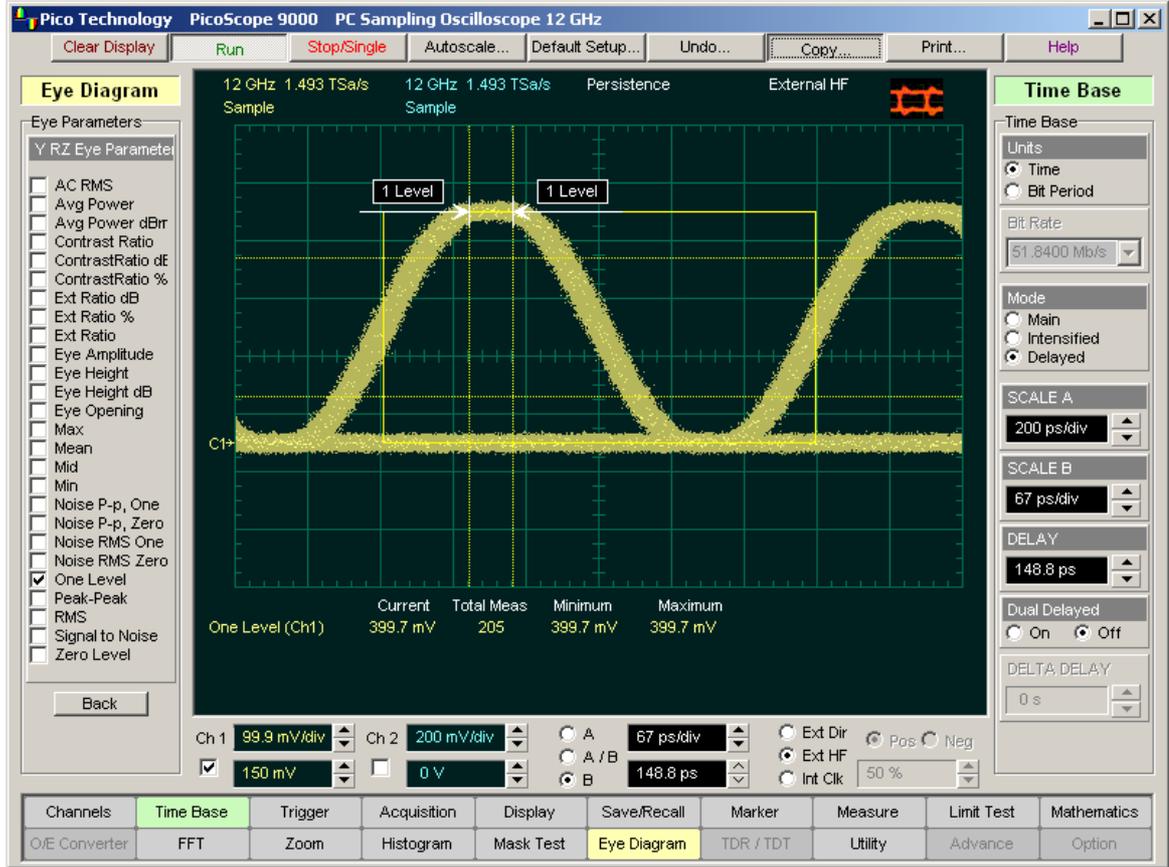
The Eye Aperture is adjustable and defaults to 5% of the RZ pulse width. The High or Low selection for noise control in the Measurement Setup dialog instructs the measurement to be performed on the logical 1 or 0 levels.

This measurement requires the use of a waveform database. When this measurement is turned on, it automatically sets the measurement system to use a waveform database if available.

5.4.8.13 RZ One Level



RZ One Level is a measure of the mean value found at the peak of the eye diagram logical 1.



RZ One Level definition

The RZ One Level measurement is made in a section of the eye referred to as the Eye Boundaries, and at the centre of the zero level between pulses. The default value for RZ Eye Boundaries is the central 5% p-p of the Bit Time, or 47.5% (Eye Boundary 1) and 52.5% (Eye Boundary 2).

A histogram is constructed using the sampled portion of the eye diagram within the eye window. This histogram is composed of data points from only the upper half of the eye diagram. The instrument analyses the histogram and determines the histogram mean.

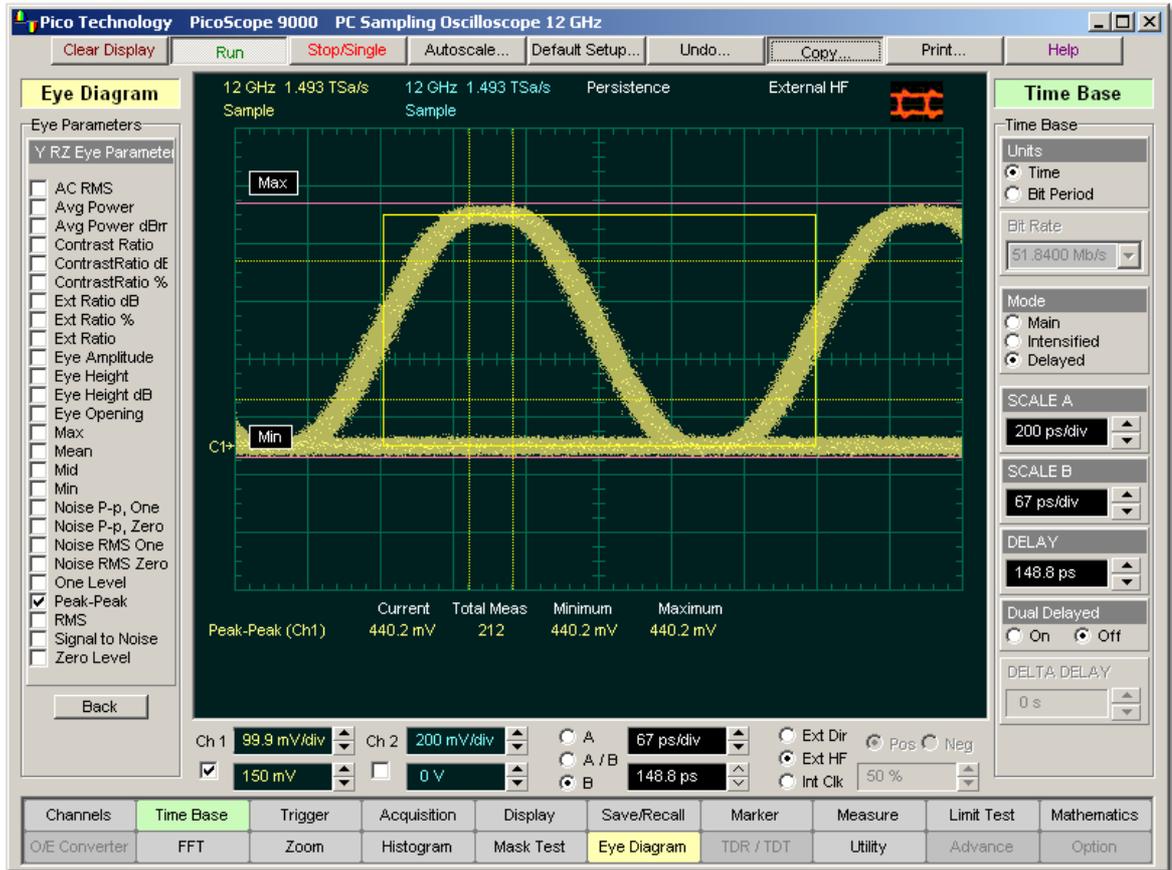
The RZ One Level is determined as follows:

$$RZ\ One\ Level = Histogram\ Mean$$

5.4.8.14 RZ Peak-Peak



RZ Peak-Peak is a measure of the difference between the maximum and minimum vertical values of the waveform.



RZ Peak-Peak definition

The RZ Peak-Peak is determined as follows:

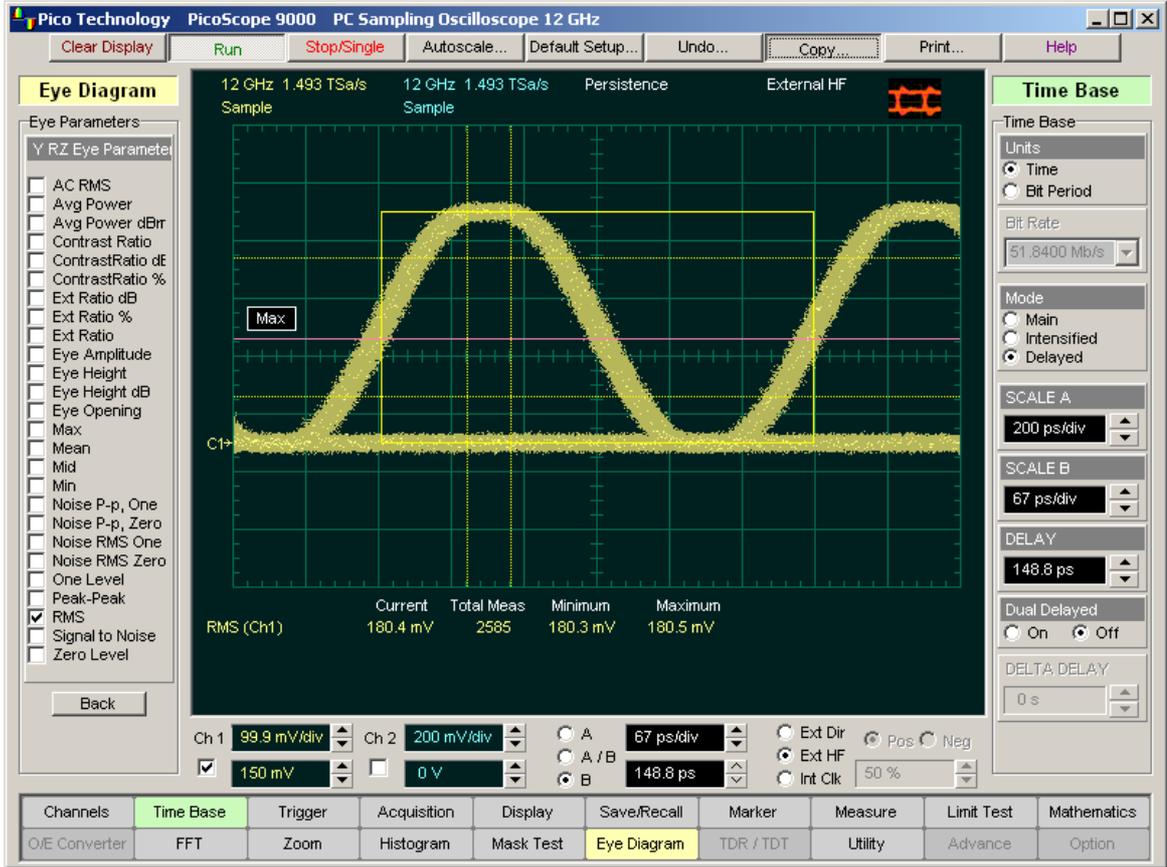
$$RZ\ Peak-Peak = Max - Min$$

where *Max* and *Min* are the maximum and minimum measurements.

5.4.8.15 RZ RMS



RZ RMS is a measure of the true root mean square of the waveform that is sampled within the eye window.



RZ RMS definition

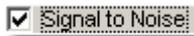
The RZ RMS is determined as follows:

$$RZ_RMS = \sqrt{\frac{\sum_{n=1}^N [VertPos(s_n)]^2}{N}}$$

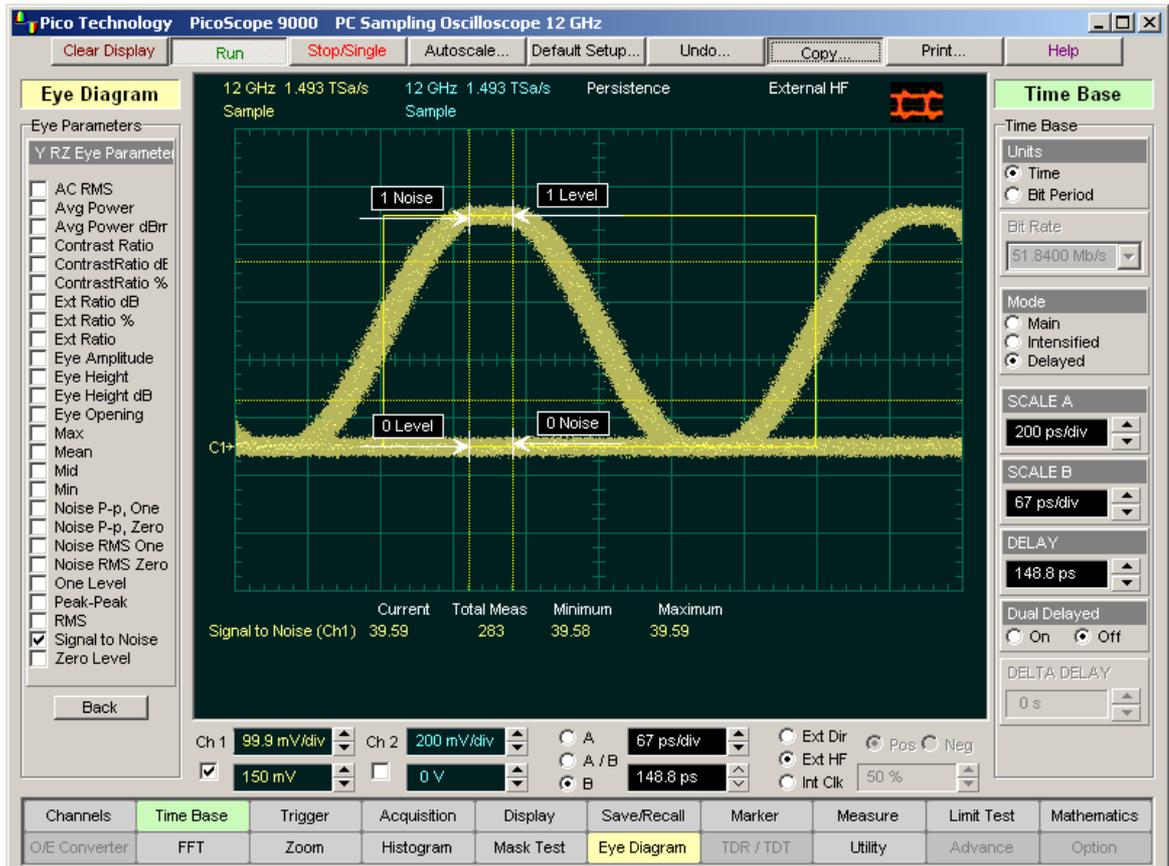
which is the RMS amplitude over all N samples $s_{1...N}$ within the measured region (eye window); or one standard deviation of the amplitude.

When this measurement is turned on, it automatically sets the measurement system to use a waveform database if available.

5.4.8.16 RZ Signal to Noise



RZ Signal to Noise is a measure of the ratio of the signal difference between one level and zero level relative to the noise present at both levels. Signal-to-noise is similar in construction to a Q-factor measurement. However, noise levels contributed by the instrument cannot be removed, therefore a slightly pessimistic Q-factor measurement may result.



RZ Signal to Noise definition

RZ Signal to Noise ratio is computed as:

$$RZ_Signal_to_Noise_Ratio = \frac{OneLevel - ZeroLevel}{\sigma_{one} + \sigma_{zero}}$$

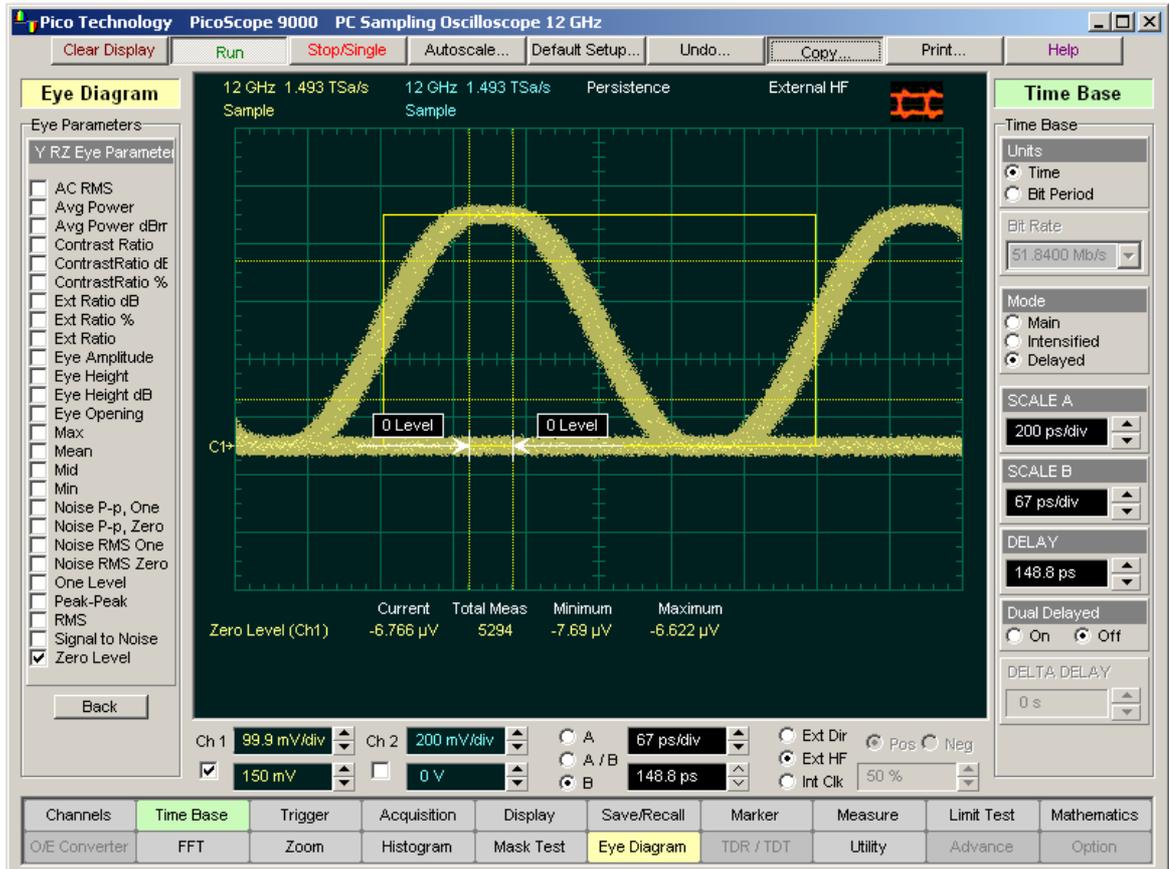
The RZ One Level and Zero Level measurements are made in a section of the eye referred to as the Eye Boundaries, and at the centre of the zero level between pulses. The default value for RZ Eye Boundaries is the central 5% p-p of the Bit Time, or 47.5% (Eye Boundary 1) and 52.5% (Eye Boundary 2).

To define the signal, histograms are constructed using the sampled portions of the eye diagram within the eye window boundaries. One histogram is composed of data points from only the upper half of the eye diagram (one level), and the second histogram is composed of data points from the lower half of the eye (zero level). The instrument analyses the histograms and determines the histogram means and standard deviations. The noise is defined as 1 (standard deviation) from the histogram means for the one and zero levels.

5.4.8.17 RZ Zero Level



RZ Zero Level is a measure of the mean value of the logical 0 at a time position found directly below the peak of the eye diagram logical 1.



RZ Zero Level definition

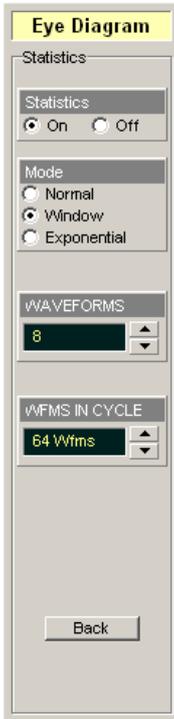
The RZ Zero Level measurement is made in a section of the eye referred to as the Eye Boundaries, and at the centre of the zero level between pulses. The default value for RZ Eye Boundaries is the central 5% p-p of the Bit Time, or 47.5% (Eye Boundary 1) and 52.5% (Eye Boundary 2).

A histogram is constructed using the sampled portion of the eye diagram within the eye window. This histogram is composed of data points from only the upper half of the eye diagram. The instrument analyses the histogram and determines the histogram mean.

The RZ Zero Level is determined as follows:

$$RZ\ Zero\ Level = Histogram\ Mean$$

5.4.9 Statistics



Click the Statistics... menu to open an eye diagram calculation statistical menu.

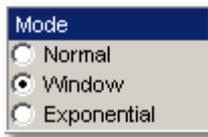
5.4.9.1 Statistics



On. Turns on statistical calculation of the eye diagram.

Off. Turns off statistical calculation of the eye diagram.

5.4.9.2 Mode



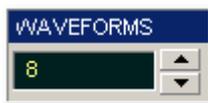
The Mode... menu defines one of three modes for statistical calculations.

Normal. Each of the acquired waveforms has equal influence on the eye diagram statistics. The [WAVEFORMS](#)^[162] and [WEIGHT](#)^[162] variables are not active in this mode.

Window. Only the last specified number of acquired waveforms will have equal influence on the eye diagram statistics. The [WAVEFORMS](#)^[162] variable specifies the number of these influenced waveforms.

Exponential. Each of the acquired waveforms has a weighted influence on the result of the eye diagram statistics. The [WEIGHT](#)^[162] variable specifies the degree of this influence.

5.4.9.3 WAVEFORMS & WEIGHT



The WAVEFORMS variable specifies the number of influenced waveforms when the Window is selected in the [Mode](#)^[162] menu. WAVEFORMS can be varied from 8 to 8192 in multiples of two.



The WEIGHT variable specifies the degree of influence of the latest acquired waveform against more remote waveforms. The WEIGHT variable is active when Exponential is selected in the [Mode](#)^[162] menu. WEIGHT can be varied from 8 to 8192 in multiples of two.

5.4.9.4 WFMS IN CYCLE



The WFMS IN CYCLE variable determines how many acquired waveforms will be used for the one-measurement cycle in eye diagram calculations.

The WFMS IN CYCLE variable can be selected from 64 to 1024 waveforms per one-measurement cycle.

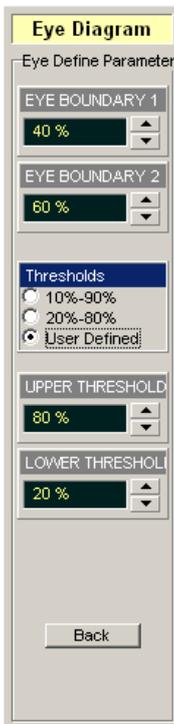
5.4.10 View Define Parameters



Setting View Define Param to On gives you a visual indicator of the calculation of the Eye Window placement. The Eye Window is red.

Setting the control to Off makes the Eye Window disappear.

5.4.11 Define Parameters



The Define Param... menu sets the measurement points (boundaries and thresholds) where the automatic measurements are made. The menu influences the measurement algorithm by allowing you to use the standard measurement points, or customize the measurements with user-defined selections.

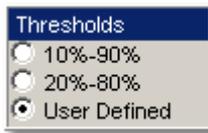
5.4.11.1 EYE BOUNDARY 1 & EYE BOUNDARY 2



The EYE BOUNDARY 1 (left boundary) and the EYE BOUNDARY 2 (right boundary) variables set the time for the eye boundaries. These settings determine what horizontal portion of the eye will be used to generate histograms for eye diagram amplitude measurements. Both boundaries directly determine One Level and Zero Level values. You can use the instrument's default values of 40% and 60% for NRZ eye diagrams, and 47.5% and 52.5% for RZ eye diagrams, or you can enter the values you want for the boundaries.

EYE BOUNDARY 1 allows you to set the percentage time for the left eye boundary, while EYE BOUNDARY 2 allows you to set the percentage time for the right eye boundary.

5.4.11.2 Thresholds



The Thresholds menu sets the upper, middle, and lower measurement points that the eye diagram measurements use for calculating the timing measurement results. For example, rise time is measured from the lower threshold to the upper threshold, while a RZ Pulse Width measurement is made between two middle thresholds.

Thresholds are not visible.

The three threshold choices are the standard measurement points:

- 10% -90%
- 20% -80%
- User Defined

The UPPER THRESHOLD and LOWER THRESHOLD variables are displayed when User Defined is selected. Middle threshold is fixed at the 50% level.

10% -90% and 20% -80%

These are two standard pulse measurement thresholds for all measurements. These standard thresholds are calculated as a percentage of the One-Zero Level value, while the One Level and Zero Level values are calculated from the eye diagram that is on the display.

10% -90% means: Lower threshold = 10%, Upper threshold = 90%. Use these thresholds for typical eye diagrams.

20% -80% means: Lower threshold = 20%, Upper threshold = 80%. Use these thresholds for eye diagrams with excessive ringing or overshoot.

Make sure that the eye diagram is expanded vertically and horizontally so that the instrument can accurately determine the One Level and Zero Level values of the eye. However, if too much of the One Level and Zero Level of the eye diagram is on the display, it may reduce the repeatability of your measurements. A good rule of thumb is to have two divisions of One Level and two divisions of Zero Level.

User Defined

You can use the User Defined setting to define thresholds for eye diagrams at the positions you want.

5.4.11.3 UPPER THRESHOLD & LOWER THRESHOLD



The UPPER THRESHOLD and LOWER THRESHOLD variables are displayed only when User Define option of the [Thresholds](#) menu is selected.

UPPER THRESHOLD can be set from 55% to 95%, while the LOWER THRESHOLD can be set from 5% to 45%.

5.5 FFT Menu



The FFT menu allows you to control the operation of the FFT, including spectrum selection and display, and also a choice of six FFT windowing functions. Two signal spectrums can be active simultaneously.

Refer to the [Zoom](#) ⁴¹⁴ menu for formatting a spectrum with different complex scales, and also for scaling and positioning it.

5.5.1 FFT Basics

The PicoScope 9000A displays and measures signals in the time domain where the vertical axis is amplitude and the horizontal axis is time. This is the best way to view most waveforms. However, there are times when you want to know the frequency content of a waveform.



In 1807 the French mathematician Jean Baptiste Fourier developed the Fourier series and Fourier transform to solve thermodynamics problems. Using the Fourier series, any periodic waveform can be constructed by adding a DC term to a series of sine and cosine terms. You can use the Fourier transform to mathematically relate the time domain and the frequency domain.

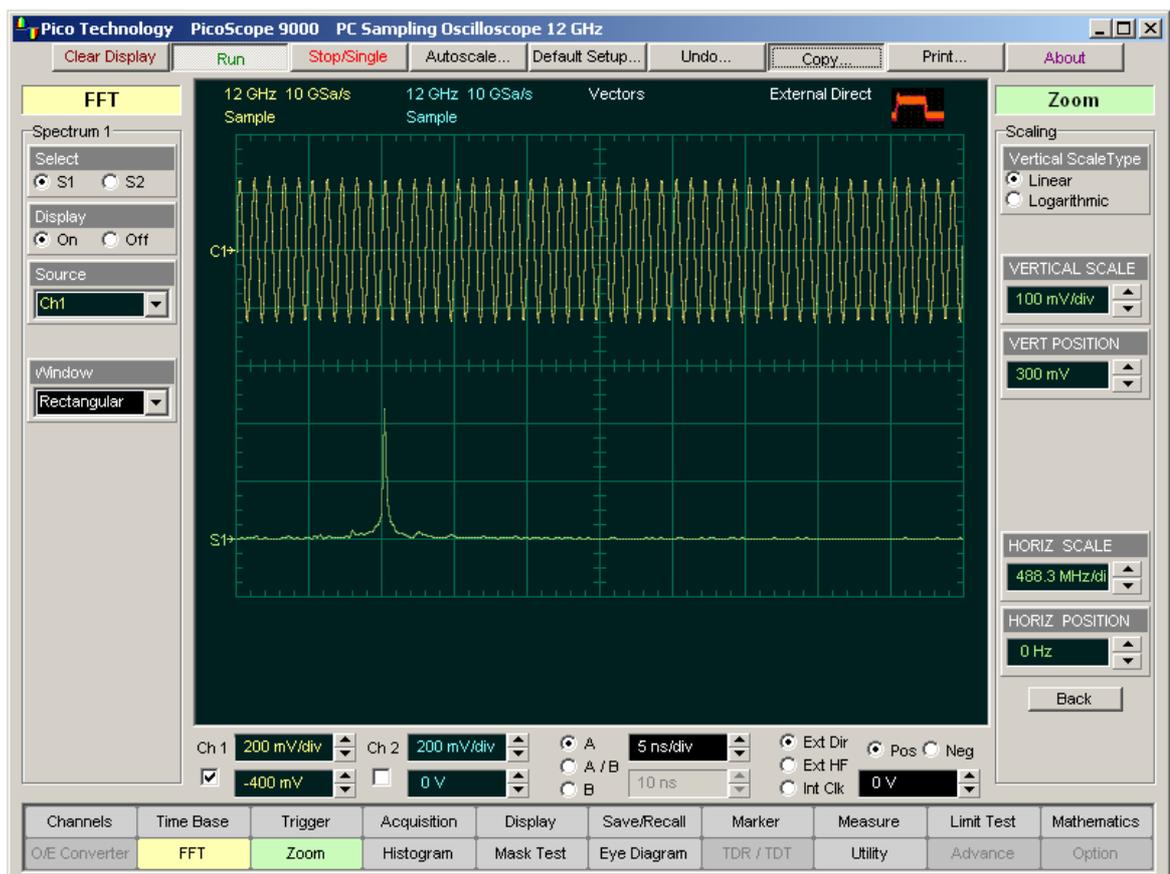
The Discrete Fourier Transform (DFT) is used to convert sampled time domain waveform data into the frequency domain. However, the DFT is slow because it requires a large number of calculations. This led to the development of the Fast Fourier Transform (FFT), which runs faster than the DFT on digital computers.

When an FFT, or fast Fourier transform, is added to an instrument, signals can also be displayed in the frequency domain. The frequency domain allows you to see the frequency content of a signal. FFT functionality added to an instrument allows you to analyse a signal from two different, but complementary points of view: the frequency domain and the time domain. The FFT process mathematically converts the standard (in this case repetitive) time-domain signal into its frequency components, providing spectrum analysis capabilities. Being able to quickly look at a signal's frequency components and spectrum shape is a powerful research and analysis tool.

FFT is an excellent troubleshooting aid for:

- finding cross-talk problems
- finding distortion problems in analog waveforms caused by non-linear amplifiers
- adjusting filter circuits designed to filter out certain harmonics in a waveform
- testing impulse responses of systems
- identifying and locating noise and interference sources

The FFT display shows the amplitude for each frequency component in your waveform on the vertical axis, and frequency on the horizontal axis. The figure below illustrates what an FFT does. The FFT transforms a time record of N samples into a frequency record of N points from 0 Hz to F_s , where F_s is the sampling frequency. The resolution or the spacing between the points in the frequency record is F_s/N .



The 1-GHz sine-wave signal shown in both the Time Domain and the Frequency Domain

The frequency $F_s/2$ is a unique frequency referred to as the Nyquist frequency. At the Nyquist frequency there are exactly two samples on every cycle of the input signal. Signals above the Nyquist frequency become aliased, which means that they appear as signals of a lower frequency, because there are not enough sample points on each cycle of the signal to determine the correct frequency.

It turns out that the points above $F_s/2$ are mirror images of the points below $F_s/2$. They are not displayed because they do not provide any additional information. Therefore, N time samples results in $N/2$ displayed frequency points.

You can use the FFT capability to display both the magnitude and the phase, or the real and the imaginary parts of the frequency components of the signal, using a linear or decibel vertical scale.



Use the [Zoom](#)^[414] menu for further magnification and spanning of the FFT, and for selecting the Complex Scale of the display.

You can perform an FFT on any waveform. The record length of the waveform can be up to 4096 points. Because the PicoScope 9000A performs FFT calculations on a complex trace record, you should use the shortest record length that provides adequate resolution, as FFT waveforms update slowly at long record length.

The PicoScope 9000A offers a choice of six FFT windowing functions, which modify the time-domain data to minimize “leakage” of energy across frequency components.

The five automated measurements FFT Magnitude, FFT Delta Magnitude, THD (Total Harmonic Distortion), FFT Frequency, and FFT Delta Frequency are intended for FFT waveforms. You can also use the markers to make magnitude and phase measurements on frequency domain traces.



Use the [Measure](#)^[246] and [Marker](#)^[192] menus for further spectral measurements of FFT waveforms.

FFT Resolution

Amplitude Resolution

Amplitude resolution is influenced by the windowing function used and the vertical adjustment of the time domain waveform. For maximum amplitude resolution, the time domain waveform should be adjusted so that it is centred vertically on the graticule and is tall as possible without going beyond the graticule, above or below.

Frequency Range and Resolution

The range and resolution of the frequency spectrum displayed by the PicoScope 9000A are determined by the sample rate and record length. The sample interval is determined by the time base and record length. You can increase the record length for better FFT resolution but all points must be on the display for them to be included in the FFT calculation. The FFT calculation time will also increase because more waveform samples must be processed.

The FFT's resolution is expressed as follows:

$$\text{FFT Resolution} = \text{Equivalent Sample Rate} / \text{Record Length}$$

The FFT frequency range before scaling will be from 0 Hz to one half of the sample rate. Ensure that the sample rate is at least twice the highest anticipated frequency component of the waveform source you are measuring. Otherwise, the measurement results will exhibit aliasing and any measurements will be inaccurate.

The FFT's frequency range is expressed as follows:

$$\text{FFT Frequency Range} = \text{Equivalent Sample Rate} / 2$$

FFT Aliasing

Aliasing occurs when the input signal includes components at frequencies higher than the Nyquist frequency. These frequency components appear in the FFT waveform display as peaks at lower frequency. The higher-frequency components are reflected around the Nyquist frequency. For example, a frequency component 1 GHz above the Nyquist frequency will appear as a peak 1 GHz below the Nyquist frequency in the FFT waveform display.

You can eliminate aliasing by setting the equivalent sampling rate to be at least twice the highest frequency in the input signal. Increasing the record length or decreasing the time base scale will increase the equivalent sampling rate.

5.5.2 Select



The Select menu allows you to select either FFT S1 or S2.

Clicking the S1 / S2 radio buttons:

- selects FFTs S1 or S2, and
- assigns the function softkeys to the selected FFT

5.5.3 Display



The Display function turns the FFT functions on or off. When FFT is on, a new waveform is displayed on the screen corresponding to the FFT magnitude function. This FFT waveform is displayed in the color used to represent the S1 spectrum.

5.5.4 Source



The Source function determines which signals the instrument uses to generate the FFT function.

As source of the FFT function, you can select any of the following:

- channels 1 and 2
- functions 1 through 4
- waveform memories 1 through 4

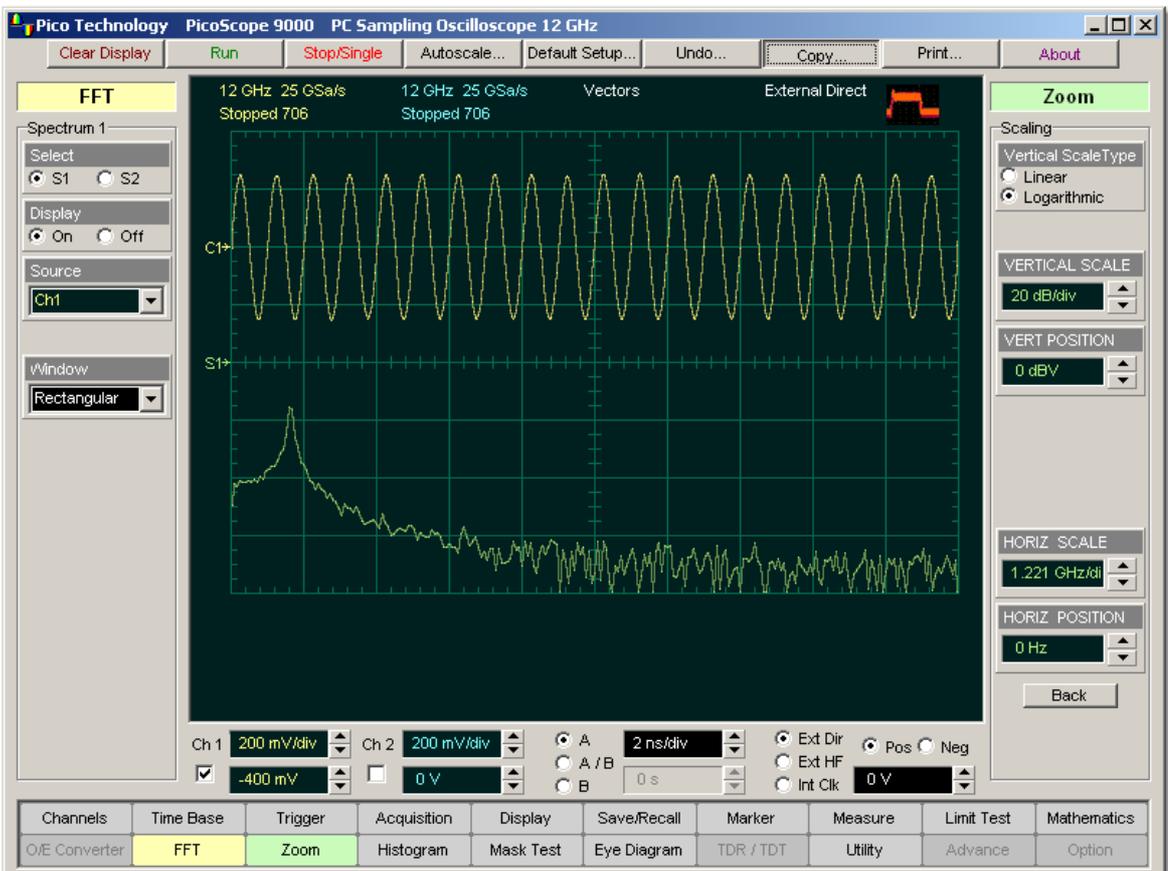
5.5.5 FFT Window



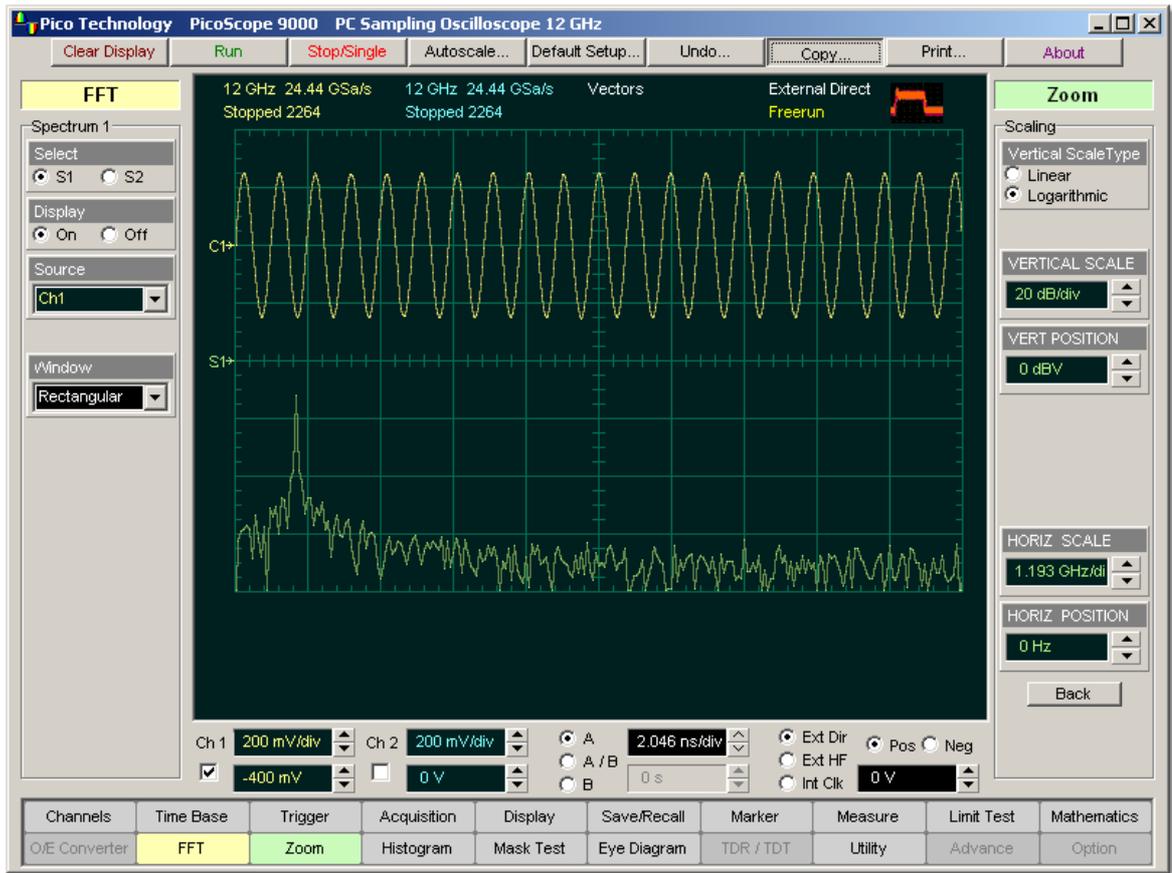
FFT Window

Windowing is a technique that compensates for some of the limitations of FFT analysis. The FFT operation assumes the time record repeats infinitely. Unless there are an integral number of cycles of the sampled waveform in the record, a discontinuity is created as the end of the record.

A pure sine wave transforms into a single spectral component, but a discontinuity in the time domain causes a frequency-domain widening or spreading out of the waveform, referred to as "spectral leakage". Two figures below show a sine wave FFT with and without leakage.



FFT with leakage

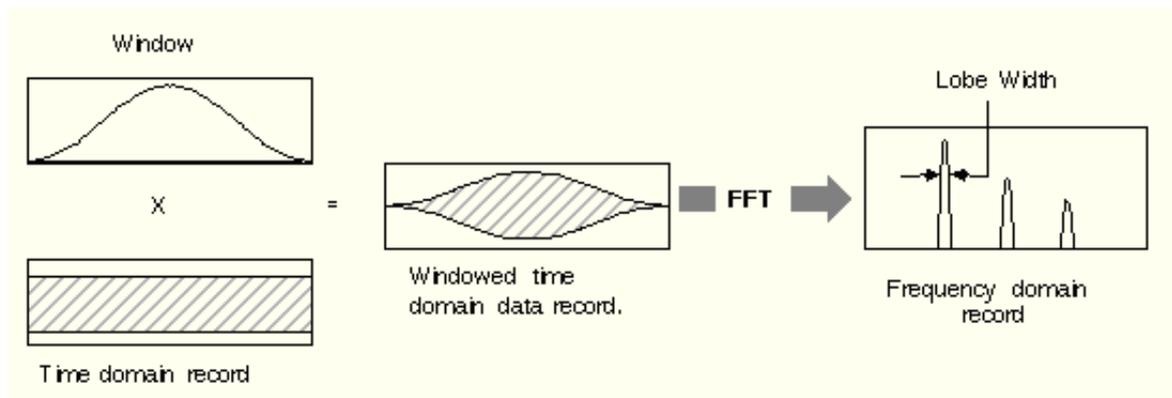


FFT having small amount of leakage

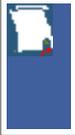
A solution to the leakage problem is to force the waveform to zero at the beginning and end of the time record so that no transient is present when the time record is replicated. This is done by multiplying the time record by a window function, which produces its own effect in the frequency domain. However, the effect produced by the window function is a big improvement over using no window function at all.

Windowing Process

The process of windowing the data is shown below. The FFT time domain record is multiplied point by point with the FFT window. When the Hanning or Blackman/Harris window is used, the data point amplitudes taper to zero at the end of the record.



Multiplying the time domain data record by a window



When using windows, be sure that the most interesting parts of the signal in the time domain record are positioned in the centre of the window so the tapering does not cause significant errors.

Types of FFT Window



The window type defines the bandwidth and shape of the equivalent filter associated with the FFT processing. The PicoScope 9000A provides a rectangular FFT window, which does not taper the time domain data, and five tapering FFT windows of different shapes.

The six supported FFT window functions are:

- Rectangular window,
- Hamming window,
- Hann window,
- Flattop window,
- Blackman-Harris window,
- Kaiser-Bessel window.



Remember that windows work by weighting points in the middle of the waveform record higher than those at the ends of the record.

Each time-domain FFT windowing function corresponds to a filter in the frequency domain. Each frequency domain filter has a high central lobe, or passband, whose width determines how well adjacent frequency components can be resolved. The height of the side lobes surrounding the central lobe determines how much leakage can occur.

Equations for the FFT Windows

Four windows used in the PicoScope 9000A (Hamming, Hann, Flattop, and Blackman-Harris) are derived from a cosine series. The window type is obtained by substituting the correct coefficients for the cosine terms into the following equation:

$$f_n = \sum_{i=0}^m \left\langle a_i \cos\left[\frac{2\pi}{N} \left(n - \frac{N-1}{2}\right)\right] \right\rangle$$

where: n is the window data area, a is the array of window coefficients, N is the window length, m is the window order, i is the index to the window coefficient array, and n is the index to the window data array. $n = 0$ to $N-1$.

The table of correction coefficients for different FFT windows indicates the values to substitute into equation to obtain the various windows.

Correction coefficients for different FFT windows

Coefficients	Rectangular	Hamming	Hanning	Flattop	Blackman-Kaiser-Harris	Kaiser-Bessel
M	0	1	1	2	3	3
a0	1.0	0.543478	0.5	0.281	0.35875	0.40243
a1	0.0	0.456522	0.5	0.521	0.48829	0.49804
a2	0.0	0.0	0.0	0.198	0.14128	0.09831
a3	0.0	0.0	0.0	0.0	0.01168	0.00122
Highest side lobe	-13 dB	-43 dB	-32 dB		-94 dB	-69 dB
3 dB Bandwidth in bins	0.89	1.3	1.44		1.92	1.72
Scallop loss	3.96 dB	1.78 dB	1.42 dB		0.81 dB	1.02 dB
Zero Phase Reference	50%	50%	50%		50%	50%

For the Rectangular window: $n = 1$.

The best window for a given application depends on various factors. Most measurements require the use of a window such as the Hanning or Flattop windows, which are the appropriate windows for typical frequency analysis measurements. Choosing between different windows involves a trade-off between frequency resolution and amplitude accuracy.

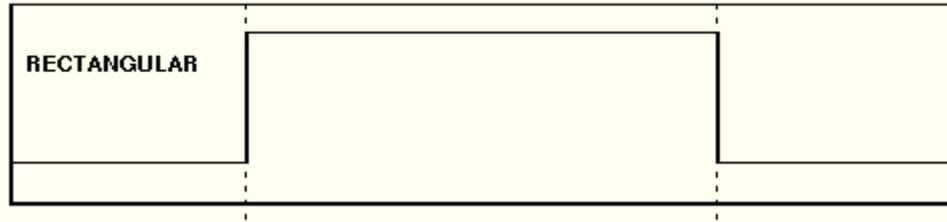
For harmonic analysis of continuous-time signals, the best window choice depends on the signal characteristics and on the particular characteristics that are of most interest. The use of Blackman-Harris, Kaiser-Bessel, Hanning or Hamming windows typically makes harmonics observation easier.

The rectangular window can be typically used for impulse response testing since the beginning points are usually zero and the data tapers to zero at the end of the record. The beginning points are zero because the impulse is normally placed in the centre of the time-domain record at the zero-phase reference point. Other windows can be used if desired. If phase is not important, the impulse can be placed at the beginning of the record. For this case, the window must be Rectangular.

5.5.5.1 Rectangular Window



The rectangular window (also referred to as the Uniform window) is essentially no window because the samples are left unchanged. All points in the record are multiplied by 1. In the frequency domain, the filter shape is $\sin(x)/x$.



Time-domain characteristics for rectangular window

The rectangular window is useful for transient signals and signals where there are an integral number of cycles in the time record. It is the best window to use when you want to examine the frequency spectrum of a non-repetitive signal. Also, it can be typically used for impulse response testing since the beginning points are usually zero and the data tapers to zero at the end of the record. The beginning points are zero because the impulse is normally placed in the centre of the time domain record at the zero phase reference point. Other windows can be used if desired. If phase is not important, the impulse can be placed at the beginning of the record. For this case, the window must be rectangular.

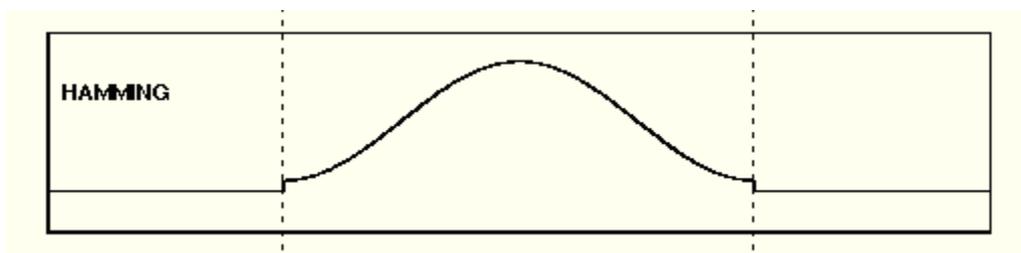
The rectangular window generally gives the best frequency resolution because it results in the narrowest lobe width in the FFT output record. It gains frequency resolution at the expense of amplitude accuracy if the frequency of the signal being observed has a non-integer number of cycles in the FFT time record. Signals not in this class show varying amounts of spectral leakage and scallop loss, which can be corrected by using one of the other windows.

Although the rectangular window has the potential for severe leakage problems, in some cases the waveform data in the time record has the same value at both ends of the record, thereby eliminating the transient introduced by the FFT. Such waveforms are called self-windowing. Waveforms such as sine bursts, impulses and decaying sinusoids can all be self-windowing.

5.5.5.2 Hamming Window



The Hamming window is a bell-shaped window. It has lower side lobes adjacent to the main lobe than, for example, the Hann window.



Time-domain characteristics for Hamming window

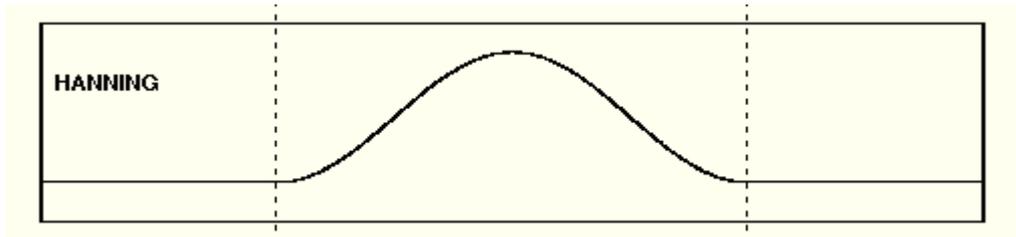
The Hamming window tapers the data to smaller values, but not to zero. It decreases the amount of energy spillover into adjacent frequency bins, increasing the amount of amplitude accuracy at the expense of decreasing the frequency.

Use the Hamming window for resolving frequencies that are very close to the same value with somewhat improved amplitude accuracy over the rectangular window.

5.5.5.3 Hann Window



The Hann (or Hanning, or cosine) window is bell-shaped window, and it looks like the first half of a sine wave. The Hann window multiplies the points in the centre of the record by 1 and multiplies the points at the start and the end of the record by zero. It decreases the amount of energy spillover into adjacent frequency bins, increasing the amount of amplitude accuracy at the expense of decreasing the frequency resolution because of wider lobe widths. The shape of Hann window is a compromise between amplitude accuracy and frequency resolution.



Time domain characteristics for Hann window

The Hann window is useful for frequency resolution and general-purpose use. Even though the overall shape of the time-domain signal has changed, the frequency content remains basically the same. The spectral line associated with the sinusoid spreads out a small amount in the frequency domain. It is good for resolving two frequencies that are close together or for making frequency measurements. The Hann window also improves amplitude accuracy.

The Hann window, compared to other common windows, provides good frequency resolution at the expense of somewhat less amplitude accuracy.

5.5.5.4 Flattop Window



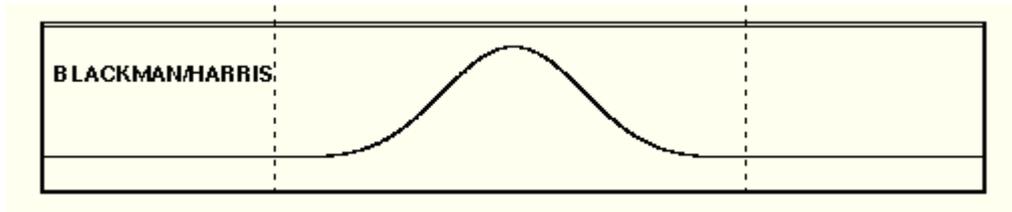
The Flattop window has fatter (and flatter) characteristic in the frequency domain. The flatter top on the spectral line in the frequency domain produces improved amplitude accuracy, but at the expense of poorer frequency resolution when compared with the Hann window.

The flattop window is the best window for making accurate amplitude measurements or frequency peaks.

5.5.5.5 Blackman-Harris Window



A Blackman-Harris window is a bell-shaped window. It reduces the leakage to a minimum, has the widest pass band (lowest frequency resolution) and lowest side lobes. It decreases the amount of energy spillover into adjacent frequency bins, increasing the amount of amplitude accuracy at the expense of decreasing the frequency resolution because of wider lobe widths.



Time domain characteristics for Blackman-Harris window

The Blackman-Harris window is the best window for measuring the amplitude of frequencies but worst at resolving frequencies. This window is especially good for viewing a broad spectrum.

5.5.5.6 Kaiser-Bessel Window



This window has resolution bandwidths and scallop losses close to the Blackman-Harris window. Choose the Kaiser-Bessel window to view the signal characteristics you are interested in.

5.6 Generators

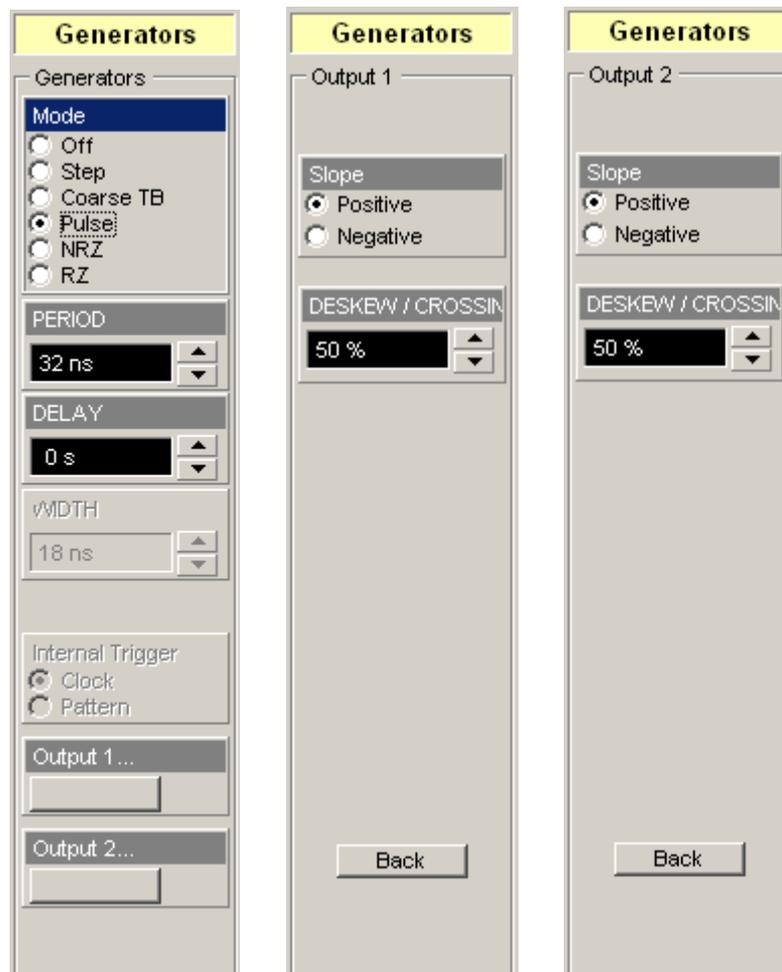
Generators

The Generators menu allows you to set up your scope device's test signal outputs. This menu appears only when you are using a scope with a built-in signal generator (PicoScope 9211A/9231A).

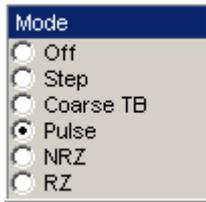
The PicoScope 9000A scopes have a pulse/pattern generator with two output channels. It is capable of generating standard pulses and patterns of pulses needed to test ECL logic technologies having CML (current-mode logic) I/O levels. The instrument features precision timing, accurate delay and deskew at maximum output frequency of 125 MHz and typical 100-ps @ 20%-80% rise/fall time. This contributes to reliable measurements and more accurate and confident characterizations of the device under test.

As a reference the instrument uses an accurate and stable internal oscillator. The output channels can be used separately. They are controlled equally, excluding output slope and deskew.

Clicking the Generators button opens the Generators menu.



5.6.1 Mode



The Mode selects the type of signal to be generated on both outputs.

Off

Click Off to disable the generators. When Off is selected, the output voltage on the OUTPUT 1/2 connectors is DC. If Positive is selected from [Output 1\(2\)/Slope](#) menu, the output voltage has CML low logic level between -330 mV and -470 mV @ 50 external termination. If Negative is selected from the [Output 1\(2\)/Slope](#) menu, the output voltage has CML high logic level between 0 mV and -50 mV @ 50 external termination.

Pulse Formats

Step

Generates a pulse having one leading step per acquisition cycle. Pulse width is fixed and delay can be controlled with the lowest jitter level. The negative-going step is used for TDR/TDT measurements.

Coarse Time Base

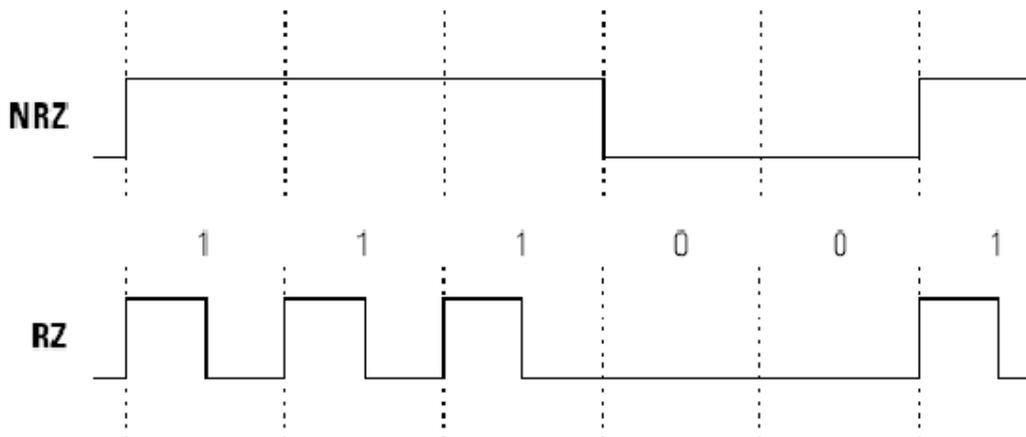
Generates oscillations synchronous with the coarse timebase generator and having frequency near 210 MHz.

Pulse

Generates pulses with selectable period, width, and delay. Slope and deskew can be selected for each channel independently.

Pattern Formats

In pattern modes, the pulse output format of a pattern can be selected from NRZ and RZ. The timing of the different formats is shown in the figure below.



NRZ

Outputs a selectable PRBS (pseudorandom binary sequence) polynomial of NRZ format. Clock, delay and pattern length are selectable. Internal trigger is selectable between clock and pattern. Slope and deskew between channels can be selected for each channel independently.

RZ

Outputs a selectable PRBS polynomial of RZ format. Clock, delay and pattern length are selectable. Internal trigger is selectable between clock and pattern. Slope and deskew between channels can be selected for each channel independently.

5.6.2 PERIOD/CLOCK



Selects pulse period or data clock value.

When [Pulse](#)^[178] mode is selected, the PERIOD changes the value of period from 8 ns to 524 μ s with 8 ns increment. When [NRZ](#)^[178] or [RZ](#)^[178] mode is selected, CLOCK changes the value of clock also from 8 ns to 524 μ s with 8 ns increment.

5.6.3 DELAY



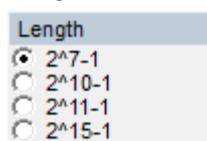
DELAY controls the delay position of a pulse. The delay value is limited by period or clock value.

5.6.4 WIDTH



When [Pulse](#)^[178] mode is selected, WIDTH controls pulse width. The width value is limited by period value.

5.6.5 Length



When [NRZ](#)^[178] or [RZ](#)^[178] mode is selected, Length controls the repetition length of the PRBS sequence, specify the parameter N of the PRBS Polynom 2^N-1 . The value range is 7, 10, 11 and 15. This allows to specify repetition lengths of 127, 1023, 2047 and 32767.

5.6.6 Internal Trigger



Internal Trigger defines the type of trigger signal used for oscilloscope triggering in [NRZ^{\[178\]}](#) and [RZ^{\[178\]}](#) mode.

Clock

The clock signal is used for oscilloscope triggering when it is necessary to get an eye diagram display format.

Pattern

The pattern signal is used for oscilloscope triggering when it is necessary to display a data pattern signal.

5.6.7 Output 1..., Output 2...



Clicking Output 1... or Output 2... opens the output control menu. You can control the slope and deskew functions of the output signal independently.

5.6.7.1 Slope



Slope selects the signal slope of the selected output.

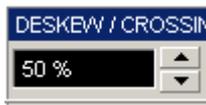
Positive

Selects positive slope.

Negative

Selects negative slope.

5.6.7.2 DESKEW/CROSSING



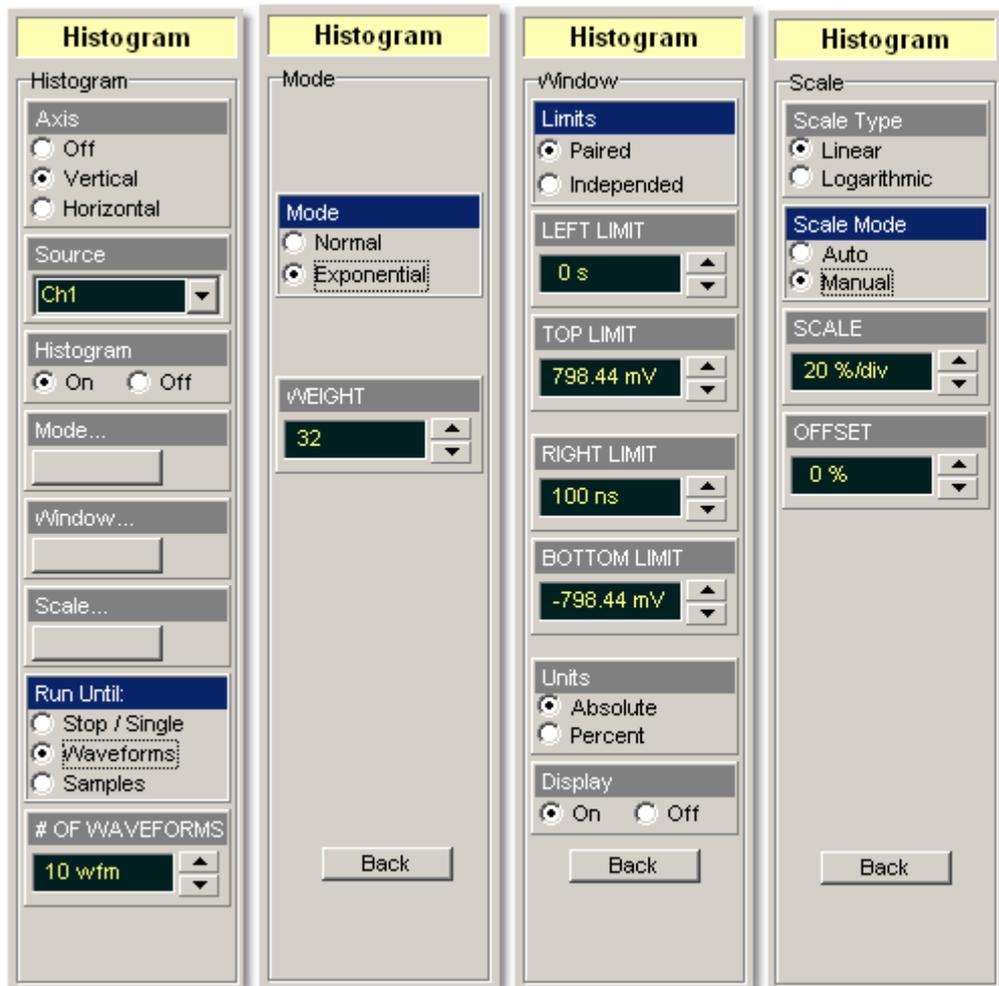
The DESKEW/CROSSING smoothly adjusts the timing skew to change the horizontal position of the selected signal. Deskew can be typically adjusted within a ± 250 ps range with resolution of 1 ps for each channel independently.

In [Pulse Formats^{\[178\]}](#) you can use this function to compensate the time offset between two generators and also differences in cables. In [Pattern Formats^{\[178\]}](#) you can use use this function to get an output eye diagram with minimized crossing distortions (with 50% crossing level).

5.7 Histogram Menu

Histogram

A histogram is a probability distribution diagram that shows the distribution of acquired data from a source within a user-definable window. The information gathered by the histogram is used to perform statistical analysis on the source. You can display the histogram either vertically for voltage measurements or horizontally for timing measurements.



The Histogram menu

Histograms are derived from the instrument measurement database. The measurement database consists of all data samples displayed on the display graticule. Every time a display sample point is acquired on a display coordinate, the counter for that coordinate is incremented. As the total count increases, the range of hits also increases. The maximum count for each counter is 63,488. If the histogram is left on for a very long time, the database will become saturated.

The two most common uses for histograms are measuring and characterizing noise or jitter on displayed waveforms. Noise is measured by sizing the histogram window to a narrow portion of time and observing a vertical histogram that measures the noise on an edge. Jitter is measured by sizing the histogram window to a narrow portion of voltage and observing a horizontal histogram that measures the jitter on an edge.

When the histogram is turned on, the instrument begins to build its measurement database. Then the following events occur:

- The histogram is displayed as a series of lines on the display graticule
- The histogram data is analysed
- The results of the histogram are displayed on the Measurement Area of the display

The histogram is displayed as a series of horizontal or vertical lines (depending on the axis selected in the Axis menu). Each line is the width of one pixel on the display graticule. Each line is carefully positioned on the display graticule within the histogram window and appears above the waveforms. Therefore, the source waveform may not be viewed through the histogram waveform.

The measurement database continues to build until the instrument stops acquiring data or the histogram.



The measurement database is active in the persistence display style or color-graded display style.



To avoid erroneous data, reset the measurement database by pressing the Clear Display button. Changing the vertical scale, offset, time base scale, delay, and trigger settings will not reset the measurement database.

Histogram measurement results

You will see the histogram statistics listed in the Measurement Area of the GUI. These values are displayed on tabs.

Scale	= 6.17 khits/	Peak Hits	= 30.843 khits	Std Deviation	= 176.99 mV
Offset	= 0 hits	Pk - Pk	= 515.63 mV	Mean ± 1 StdDev	= 50.281 %
Hits in Box	= 2.01753 Mhits	Median	= 0 V	Mean ± 2 StdDev	= 100 %
Waveforms	= 4027 Wfms	Mean	= 578.5 µV	Mean ± 3 StdDev	= 100 %
Min	= -257.81 mV	Max-Max	= 496.88 mV	Max	= 257.81 mV

An example of the Histogram Measure tab

The tabs only appear as the one of the histogram measurements is performed. For example, if you performed a vertical histogram measurement on the channel 1, only this tab will appear on the display.

The measurement database and the graticule display will clear when you perform the following actions:

- Switch between operating modes in the Display menu
- Change vertical and horizontal scale and position
- Click on the Clear Display button

The Measure tab displays the following measurement statistics for each measurement:

- Scale. Lists the display scale in hits per division or dB per division.
- Offset. Lists the offset in hits or dB. Offset is the number of hits or dB at the bottom of the display, as opposed to the centre of the display.

- Hits in Box. The total number of samples included in the histogram box.
- Waveforms. The number of waveforms that have contributed to the histogram.
- Peak Hits. The number of hits in the histogram's greatest peak.
- Pk – Pk. The width of histogram. For horizontal histograms, width is the difference time between the first and last pixel columns that contains data. For vertical histograms, width is the difference in time between the first and last pixel rows that contain data.
- Median. 50% of the histogram samples are above the median and 50% are below the median.
- Mean. Mean is the average value of all the points in the histogram.
- StdDev. The standard deviation () value of the histogram.
- Mean ± 1 StdDev. The percentage of points that are within ± 1 of the mean value.
- Mean ± 2 StdDev. The percentage of points that are within ± 2 of the mean value.
- Mean ± 3 StdDev. The percentage of points that are within ± 3 of the mean value.
- Min. Min is the minimum value of all the points in the histogram.
- Max. Max is the maximum value of all the points in the histogram.
- Max-Max. The width between the vertical histogram's greatest peak.



The measurement statistics reported will vary depending on the mode of operation selected.

Mean and Standard Deviation

The PicoScope 9000 calculates the mean and standard deviation automatically. It does not rely on the assumption that the data is of a particular distribution to determine the sample mean or standard deviation. The microprocessor-controlled acquisition allows the oscilloscope to store and display every data point. Therefore, the sample mean and standard deviation are easily computed by the microprocessor using the following equations respectively:

$$\bar{X} = \frac{\sum_{i=1}^n X_i}{n}$$

$$S = \frac{\sum_{i=1}^n (X_i - \bar{X})^2}{n - 1}$$

where: \bar{X} - mean, S - standard deviation, n - number of samples, and X_i - value of each sample.

The mean for time histogram is the time from the trigger point (without taking into account minimum delay) to the sample average. The mean for voltage histograms is the average voltage with respect to the ground reference.

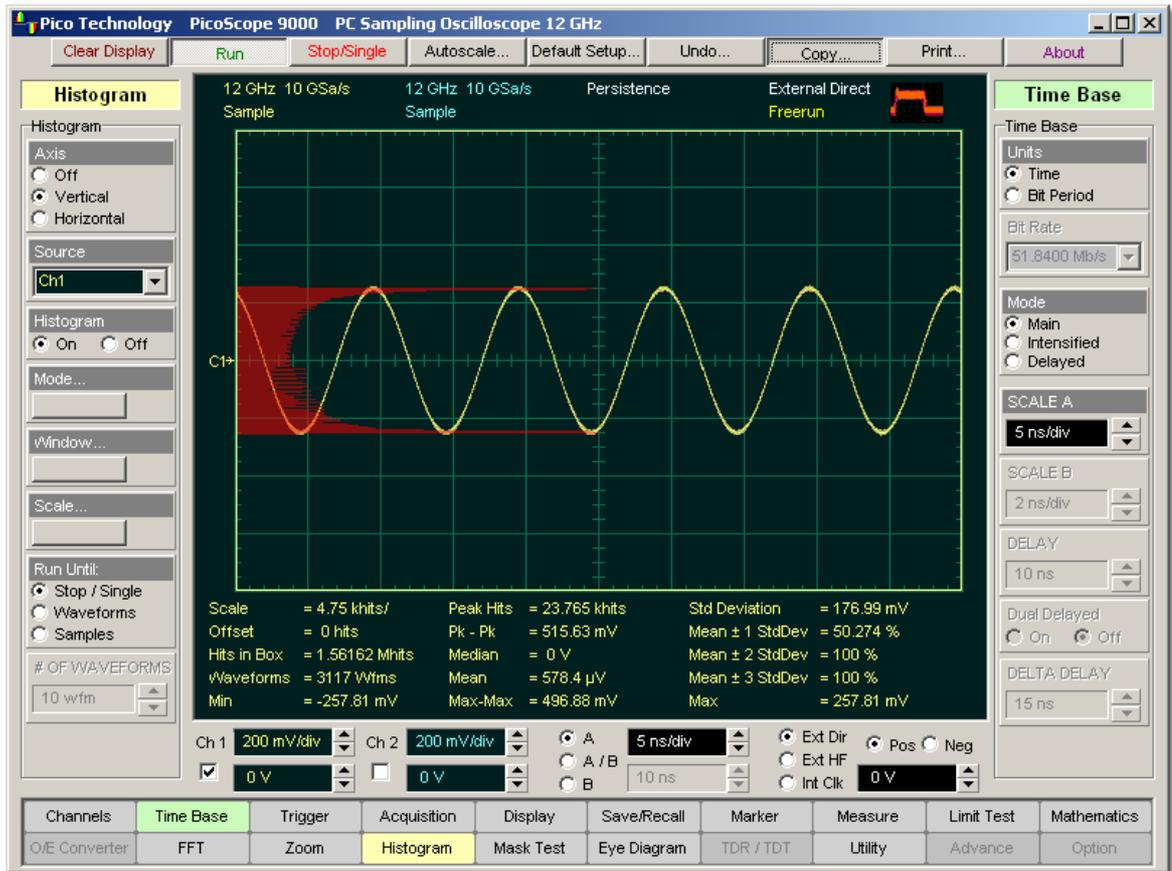
5.7.1 Axis



The Axis function turns the display of the histogram off or orients the histogram vertically or horizontally.

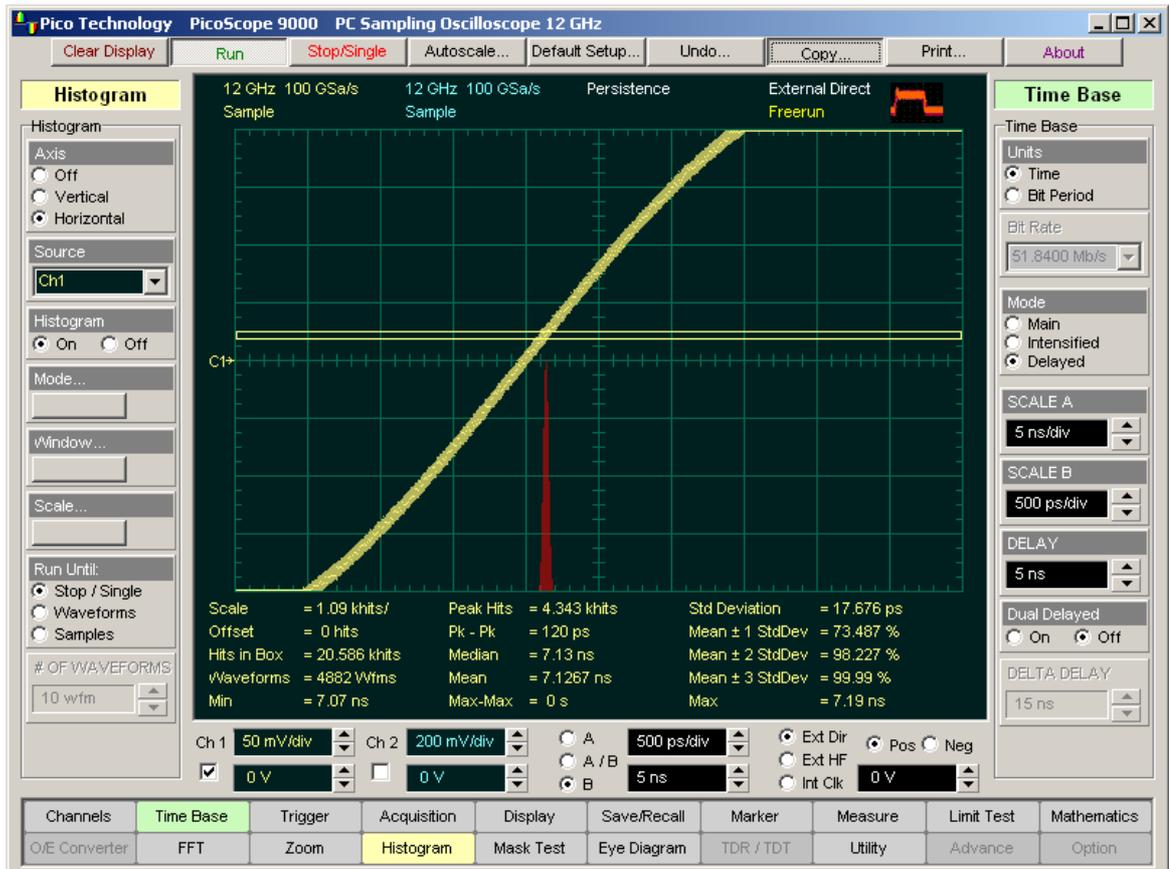
Off. Removes the histogram and histogram value from display.

Vertical. Places the histogram at the left side of the graticule, which allows for voltage measurements.



An example of the vertical histogram display

Horizontal. Places the histogram at the bottom of the graticule area, which allows for timing measurements.



An example of the horizontal histogram display

5.7.2 Source



Histogram measurements can be made on only one source at a time. Select the source you want to measure using the Source menu. Be aware that even if the display shows only the most recent acquisitions, the measurement database keeps track of all display coordinates hit while the measurement database is building.

You can set the histogram source:

- Channel
- Function
- Waveform memory
- Spectrum

5.7.3 Histogram



The Histogram turns on or off the display a histogram.

On. Turns on the display of a histogram.

Off. Turns off the display of a histogram. Turning off a histogram does not turns off measurement process.

5.7.4 Mode



Clicking the Mode... menu opens a histogram calculation statistical menu.

5.7.4.1 Mode



The Mode menu defines one of two modes that determine an algorithm for statistical calculation.

Normal. When the Normal mode is selected, each of the acquired waveforms has equal influence on the result of the statistical calculations on the histogram. The [WEIGHT](#)^[186] variable is not active in this mode.

Exponential. When the Exponential mode is selected, each of the acquired waveforms has a weighted influence on the result of statistical calculations on the eye diagram. The [WEIGHT](#)^[186] variable specifies the degree of this influence.

5.7.4.2 WEIGHT



The WEIGHT variable specifies the degree of influence of the nearest acquired waveform against more remote waveforms. The WEIGHT variable is active when Exponential is selected in the [Mode](#)^[186] menu. The WEIGHT can be varied from 8 to 8192 in multiples of two.

5.7.5 Window



Two common uses for histograms are measuring and characterizing noise or jitter on displayed waveforms.

Noise is measured by sizing the histogram window to a narrow portion of time and observing a vertical histogram that measures the noise on a flat section of a waveform.

Jitter is measured by sizing the histogram window to a narrow portion of voltage and observing a horizontal histogram that measures the jitter on an edge.

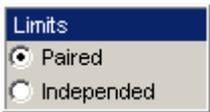
The histogram window determines which region of the database will be used to construct the histogram. The instrument will use only this region of the database to calculate the histogram results.

To define the histogram window, choose Window... from the [Histogram](#) ¹⁸⁶ menu. The histogram Window menu gives you access to a second-level menu that allows you to select a region of the database to include in the histogram. Opening the Window... menu opens the histogram window markers. The markers consist of:

- Two solid vertical lines (the LEFT LIMIT and RIGHT LIMIT variables)
- Two solid horizontal lines (the TOP LIMIT and BOTTOM LIMIT variables)

You can then define the size of the histogram window within the horizontal and vertical scale limits of the instrument.

5.7.5.1 Limits



The Limits menu defines a method of how the histogram window can be positioned with the LEFT LIMIT, RIGHT LIMIT, TOP LIMIT and BOTTOM LIMIT variables.

Paired

With the Paired method, the following conditions are used for positioning of the histogram window:

- The LEFT LIMIT variable changes the full histogram window to left or to right
- The RIGHT LIMIT variable changes the right limit of the histogram window to left or to right
- The TOP LIMIT variable changes the full histogram window up or down
- The BOTTOM LIMIT variable changes the bottom limit of the histogram window up or down

Independent

When the Independent is selected, each of the LEFT LIMIT, RIGHT LIMIT, TOP LIMIT and BOTTOM LIMIT variables changes the position of corresponding limit independently.

5.7.5.2 LEFT LIMIT, RIGHT LIMIT, TOP LIMIT and BOTTOM LIMIT



The LEFT LIMIT, RIGHT LIMIT, TOP LIMIT and BOTTOM LIMIT variables allow you to use the histogram limits to select a region of the database.

When the Independent mode in the [Limits](#) ⁽¹⁸⁷⁾ menu is selected, the TOP LIMIT and BOTTOM LIMIT variables move the vertical histogram limits vertically across the display, while the LEFT LIMIT and RIGHT LIMIT variables move the horizontal histogram limits horizontally across the display.

When the Paired mode in the [Limits](#) ⁽¹⁸⁷⁾ menu is selected, the TOP LIMIT variable moves the full histogram window up or down, and the LEFT LIMIT variable moves the full histogram window left or to right. At the same time the BOTTOM LIMIT variable moves the bottom limit of the histogram window up or down, while the RIGHT LIMIT variable moves the right limit of the histogram window left or to right.

Because the database that the histogram is derived from is limited to the size of the graticule area, placing the histogram limits beyond the graticule area results in a histogram of only the graticule area.

For jitter measurements you would position the TOP LIMIT and BOTTOM LIMIT histogram limits so that the histogram is built from a very narrow horizontal slice of the graticule area. For noise measurements, you would position the LEFT LIMIT and RIGHT LIMIT histogram limits so that the histogram is built from a very narrow vertical slice of the graticule area.



The histogram window limits are only visible when the [Histogram](#) ⁽¹⁸⁷⁾ menu is opened.

The default setup positions the histogram markers as follows:

- LEFT LIMIT < RIGHT LIMIT
- BOTTOM LIMIT < TOP LIMIT

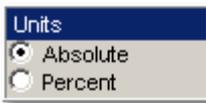
The values of LEFT LIMIT and BOTTOM LIMIT cannot be made greater than the values of RIGHT LIMIT and TOP LIMIT by repositioning the limits. The histogram window is always the area inside the boundaries of all of LEFT LIMIT, RIGHT LIMIT, TOP LIMIT and BOTTOM LIMIT, regardless of the limit values.

You can use the mouse to click and drag the histogram limits to new positions: click and hold the left mouse button while the mouse pointer is on one of the limits, then drag the marker to the position you want and release the mouse button. Clicking and dragging a limit makes it easy to quickly move the limit to the desired waveform event.



The values of the limits and the position arrows are dependent upon the vertical and horizontal scale settings.

5.7.5.3 Units



The Units function lets you select how you want the LEFT LIMIT, RIGHT LIMIT, TOP LIMIT and BOTTOM LIMIT variables represented.

Absolute. Represents all limits in current unit.

Percent. Represents all limits as percentages of the full vertical or horizontal scale.

5.7.5.4 Display



The Display menu is used to show histogram windows with both vertical and horizontal histogram limits.

Clicking the On / Off radio buttons:

- Turns the display of the selection on or off.

5.7.6 Scale



Histograms are derived from the instrument measurement database. The histogram values correspond to a row or column in the database. The database that is used to construct the histogram is dependent upon the selected source. The instrument converts the row and column numbers to time (seconds) and amplitude (volts) values using the scaling values of the selected the database source. Therefore, the histogram results from each source vary depending on the scaling of the source.

Histograms are displayed as a series of lines (vertical or horizontal). The length of each line represents the frequency or number of hits of data on that row (or column) of the display. Zero hits correspond to the left edge of the graticule (vertical histogram), or the bottom edge of the graticule (horizontal histograms).

The histogram Scale menu gives you access to a second-level menu that allows you to set the scale of the histogram.

5.7.6.1 Scale Type



The Scale Type menu defines how to display histogram data. Two options can be set from the Scale Type menu: Linear and Logarithmic.

Linear. Sets the display of the histogram results to the number of hits per division.

Logarithmic. Sets the display of the histogram results to dB.

5.7.6.2 Scale Mode



The Scale Mode menu determines how much of the histogram is displayed on the screen.

Auto

If the Axis menu is set to Horizontal, the Auto sets the base of the histogram to the bottom of the graticule area and displays the histogram using half of the graticule height.

If the Axis menu is set to Vertical, the Auto sets the base of the histogram to the left edge of the graticule area and displays the histogram using half of the graticule width.

Manual

Manual lets you window in on the histogram by allowing you to change the scale and offset settings. Depending on the setting of the [Scale Type](#) ^[189] menu, the scale value is in either percent of a division or dB. By changing the scale, you can zoom in or out on the histogram. Offset allows you to pan across the histogram by moving the base of the histogram. Depending on the setting of the [Scale Type](#) ^[189] menu, the offset value is also in either percent of peak or dB per division.

5.7.6.3 SCALE



Linear scale

For the linear scale type, the scale is the percentage of the peak per division. For example, on a horizontal histogram, 20% places one-fifth of the histogram in each of eight divisions with the top of the peak (100%) at the middle of the display.

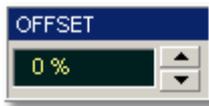
Logarithmic scale

For the log scale type, the scale is in decibels per division. The histogram is plotted according to the following formula:

$$dB = 20 \log_{10} \frac{X}{Peak}$$

where: X is the number of hits in a histogram row for vertical histograms, or the number of hits in a histogram column for horizontal histograms, $Peak$ is the number of hits in the largest histogram column or row, and dB is the log value that gets plotted.

5.7.6.4 OFFSET



Linear offset

For the linear scale type, the offset is the percentage of the peak at the left edge or lower edge of the display. For example, on a horizontal histogram, an offset of 20% places 20% of the peak at the lower edge of the display. Therefore, 20% of the histogram will be below the display and the other 80% of the histogram will be above the lower edge of the display (displayed on the screen).

Logarithmic offset

For the log scale type, the offset is in decibels at the left edge or lower edge of the display. The histogram is plotted according to the following formula:

$$dB = 20 \log_{10} \frac{X}{Peak}$$

where: X is the number of hits per row for vertical histograms, or the number of hits per column for horizontal histograms, $Peak$ is the number of hits in the peak, and dB is the log value that gets plotted.

This means 0 dB is at the peak of the histogram and the offset can only contain negative values. For example, with a horizontal histogram, an offset of -20 dB places 10% or $10^{\frac{-20}{20}}$ of the peak at the lower edge of the display.

5.7.7 Run Until



The Run Until menu allows you to determine when the acquisition of data stops.

Stop / Single. You must press the Stop/Single key to stop the acquisition of data.

Waveforms. After the number of waveforms is reached, acquisition stops.

Samples. After the number of samples is reached, acquisition stops.

5.7.8 # OF WAVEFORMS and # OF SAMPLES



OF WAVEFORMS. Sets the number of waveforms. After the selected number of waveforms is reached, acquisition stops.

OF SAMPLES. Sets the number of samples. After the selected number of samples is reached, acquisition stops.

5.8 Marker Menu



Markers are movable lines on the display. You set their value by positioning them on the display. Their actual value, however, comes from internal data, so they are more precise than graticules. They use numeric readouts to present results.

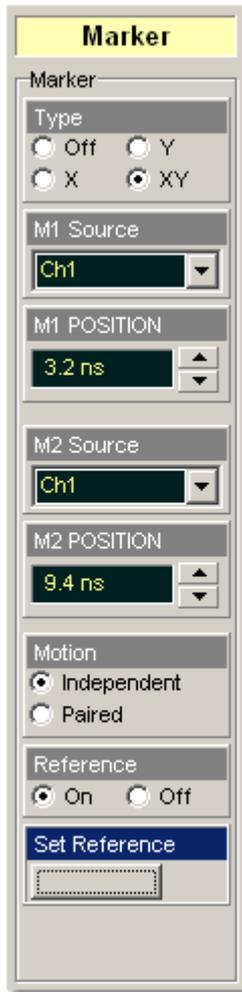
Markers can be positioned on either:

- a selected waveform source (input channel, waveform memory, function or spectrum)
- independently anywhere on the display graticule

Markers allow you to make:

- absolute vertical measurements (voltage, spectrum magnitude, spectrum phase, rho, ohms)
- ratiometric vertical measurements
- absolute horizontal measurements (timing, bit period, frequency, distance)
- ratiometric horizontal measurements

The markers are display-limited, so you cannot move them off screen. Also, if you resize waveforms, the markers do not track. That is, a marker stays at its screen position, ignoring changes to horizontal and vertical scale and position.



The Marker menu allows you to turn on and position calibrated colored markers on the display. For example, you can use the M1 POSITION (solid line) control to move the X1 marker horizontal position. The position value of the marker will be displayed in the Measurement Area of the display.

However, it can be changed to a different color in the display menu. You can use the markers to make custom measurements or to use as visual reference point on the display.

Marker measurement results

The Measurement Area of the GUI displays the values of the marker positions and measurements on tabs. The marker position readout is based on the units of the source waveform. The marker resolution is limited to the resolution of the display. As you move a marker, its position is displayed in the Measurement Area. The horizontal value (X-axis) is the time delay from the left border of the display graticule and the vertical position (Y-axis) is measured with respect to the corresponding source ground.

The following information is displayed for the selected source or waveform:

- XM1. Position of the M1 marker (solid line). The X-axis units may be displayed in seconds, Hz, bits, meters or feet.
- YM1. Position of the M1 marker (solid line). The Y-axis units depend upon the channel input, and may be displayed in volts, watts, amperes, phase degrees, rho, ohms.
- M2. Position of the M2 marker (dashed line). The X-axis units may be displayed in seconds, Hz, bits, meters or feet.
- YM2. Position of the M2 marker (dashed line). The Y-axis units depend upon the channel input; and may be displayed in volts, watts, amperes, phase degrees, ρ , ohms.
- dXM. The difference between the M1 and M2 marker values, if both markers are turned on. dXM is calculated as follows:

Where XM2 represents the dashed line marker, and XM1 represents the solid line marker.

If XM1 is more positive than XM2, dXM will be a negative number, which can result in negative time interval measurements.

- The instrument will also calculate and display the $1/dXM$ frequency value when both X-axis markers are turned on. If XM1 is more positive than XM2, $1/dXM$ will display a negative frequency.

- YM1. Position of the M1 marker (solid line). The Y-axis units depend upon the channel input, and may be displayed in volts, watts, amperes, phase degrees, [rho](#)⁴⁶², ohms.

Where YM2 represents the dashed line marker, and YM1 represents the solid line marker.

If YM1 is more positive than YM2, dYM will be a negative number.

5.8.1 Type



There are three types of markers:

- X-markers (manual markers)
- Y-markers (manual markers)
- XY-markers (waveform markers)

Click the button for the marker type that you need.

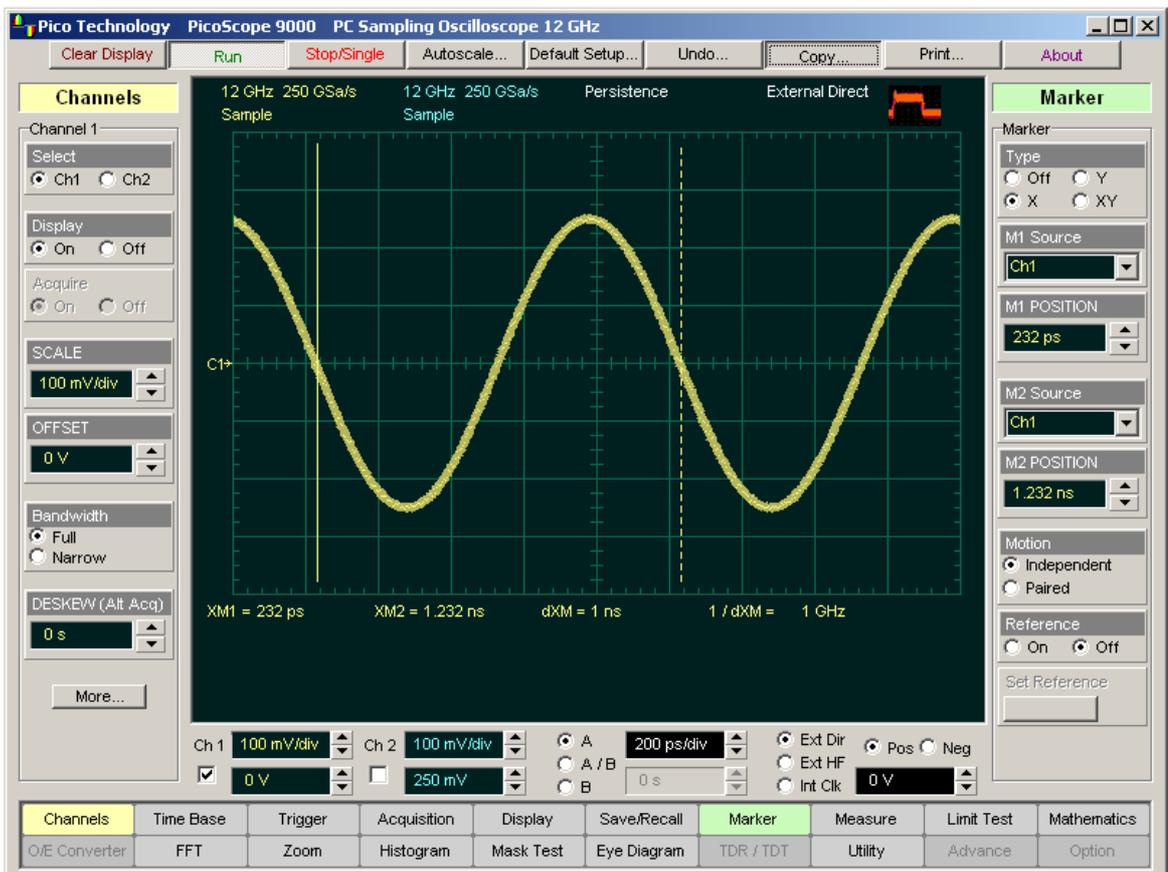
Off

Removes the markers and marker value from display.

X Markers

The X manual markers (XM1 and XM2 markers) are two vertical lines you can move horizontally. The XM1 is displayed as a solid line, and the XM2 is displayed as dashed line.

You can position the X-markers anywhere on the display, which allows you to make custom measurements. The X-markers track the time values as the timebase scale is changed, which allows you to make accurate delay measurements. The position readout is based on the scale factors of the source waveform. Marker resolution is limited to the pixel resolution of the display.

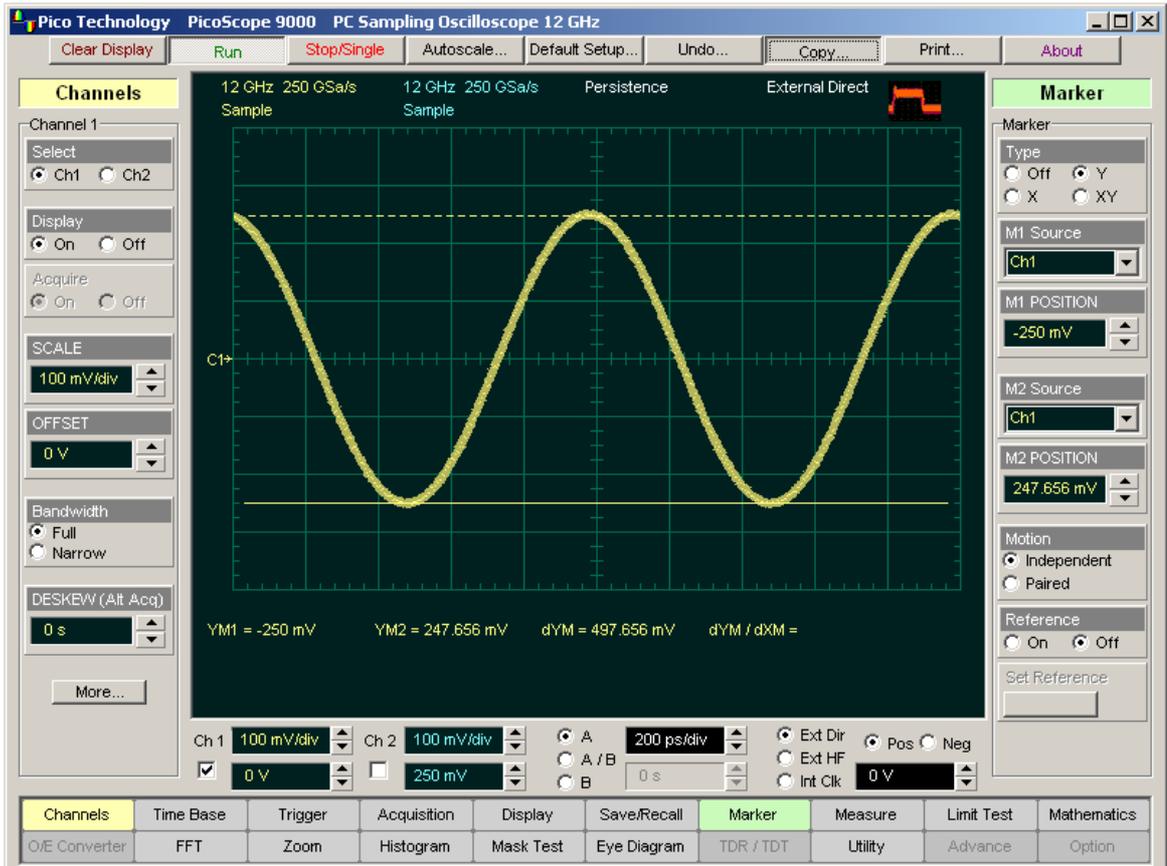


Period measurement with the X Markers

Y Markers

The Y manual markers (YM1 and YM2 markers) are two horizontal lines you can move vertically. The YM1 is displayed as a solid line, and the YM2 is displayed as a dashed line.

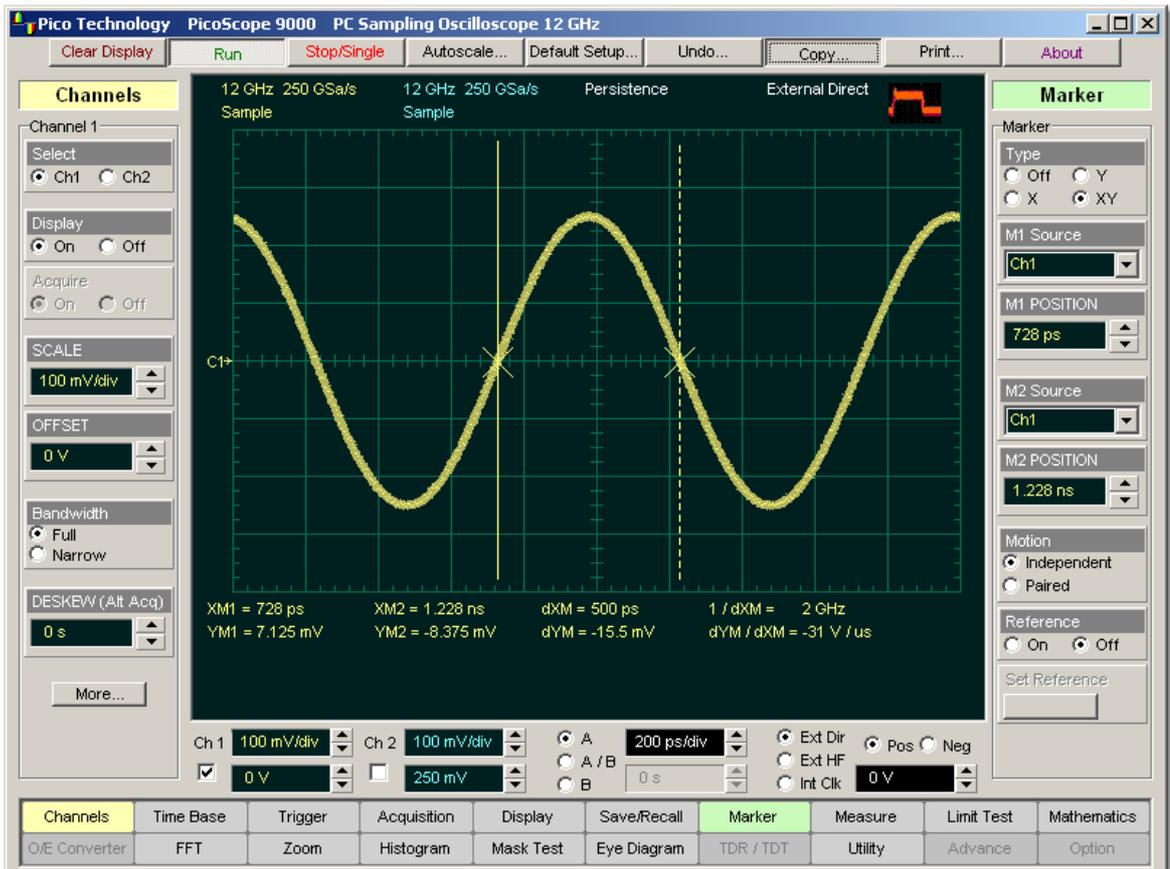
You can position the Y-markers anywhere on the display, which allows you to make custom measurements. The Y-markers track the voltage values as the vertical scale is changed, which allows you to make accurate voltage measurements. The position readout is based on the scale factors of the source waveform. Marker resolution is limited to the pixel resolution of the display.



Amplitude measurement with the Y Markers

XY Markers

The XYM1 and XYM2 are two waveform markers. Their displays are: + and X. Each marker is in effect, both a horizontal and vertical marker. Neither of these markers can be moved off the waveform. The XY-markers track the waveform data in memory rather than on the displayed waveform. Because the waveform data in memory has a much greater resolution than the display, the measurements you make with the XY-markers are much more precise than measurements made with the manual markers. The XY-markers track the time as changes of the source signal. This allows you to make accurate delay measurements without having both markers on the display.



Customized measurement with the Y Markers

5.8.2 M1 Source and M2 Source



You may set the source for each marker:

- Channels 1 and 2
- Functions 1 through 4
- Waveform memories 1 through 4
- Spectra 1 and 2

For example, you could set the M1 Source to a waveform on channel 1, and the M2 Source to a waveform in memory M1. The scale used to position each marker on the display is based on the scale of the waveform source to which the marker is tied.



You cannot select a marker source that is turned off.



When you are placing markers on a waveform, make sure the source is set to that waveform.

5.8.3 M1 POSITION and M2 POSITION



You can use different methods to control the positions of the markers:

- Use the spin box
- Use the mouse to click and drag markers to a new position
- Use the keyboard
- Use the [Pop-up Keypad](#)⁴²⁷ for quickly entering numeric data using the mouse

Manual X Markers

The M1 POSITION variable moves the XM1 marker horizontally, and the M2 POSITION variable moves the XM2 marker horizontally. The position of each marker is displayed, in the same color as the markers.

You can make timing measurements using X markers on the signal. The difference between the marker's positions is the timing measurement or dXM:

$$dXM = XM2 - XM1$$

If XM1 is more positive than XM2, dXM will be a negative number, which can result in negative time interval measurements. Also notice the 1/dXM value. If you are measuring the period of a signal with the X-markers, then 1/dXM is the frequency of the signal. You can also make a channel-to-channel skew measurement by placing the XM1 marker on one channel and the XM2 marker on another channel.

Manual Y Markers

The M1 POSITION variable moves the YM1 marker vertically, and the M2 POSITION variable moves the YM2 marker vertically. The position of each marker is displayed, in the same color as the markers.

You can make voltage measurements on the signal by placing the Y-markers on the signal.

The difference between the markers is the voltage measurement or dYM:

$$dYM = YM2 - YM1$$

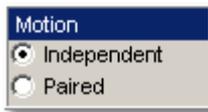
If YM1 is more positive than YM2, dYM will be a negative number. You can also make a channel-to-channel voltage measurement by placing the YM1 marker on one channel and the YM2 marker on another channel.

Waveform XY Markers

The X marker is controlled by the M1 POSITION variable and the + marker is controlled by the M2 POSITION variable. The position of each marker is displayed, in the same color as the markers.

Each XY marker has an YM position and XM position. Vertical measurements are made with the YM positions, and dYM is the difference between the YM positions (see $dYM = YM2 - YM1$). Timing measurements are made with the XM positions, and dXM is the difference between the XM positions (see $dXM = XM2 - XM1$). Notice $1/dXM$. If you are using the markers to measure the period of a signal, then $1/dXM$ is the frequency of the signal. Also notice dYM/dXM . If you are measuring such parameters as the rise or fall of an impulse with the XY markers, then dYM/dXM is the slope of the signal.

5.8.4 Motion



There are two options for the way in which PicoScope 9000 moves the markers:

- Independent
- Paired

Independent. When Independent motion is selected you can move each marker independently. The [M1 POSITION](#)^[199] variable moves the XM1, or the YM1, or the XYM1 marker. The [M2 POSITION](#)^[199] variable moves the XM2, or the YM2, or the XYM2 marker.

Paired. When Paired motion is selected you can move both markers with the [M1 POSITION](#)^[199] variable simultaneously, while the difference between markers can be moved with the [M2 POSITION](#)^[199] variable.

5.8.5 Reference



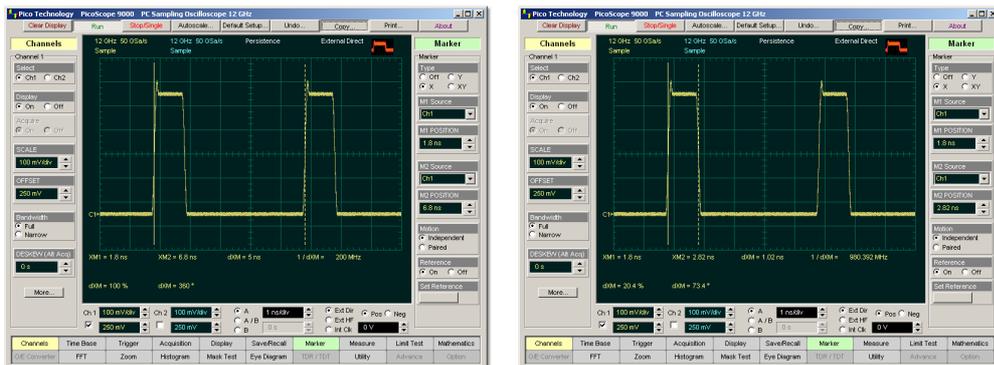
The Marker menu provides ratiometric measurements. These measurements give results in such ratiometric units as %, dB, and Degrees.

Ratiometric measurements require a reference for comparison.

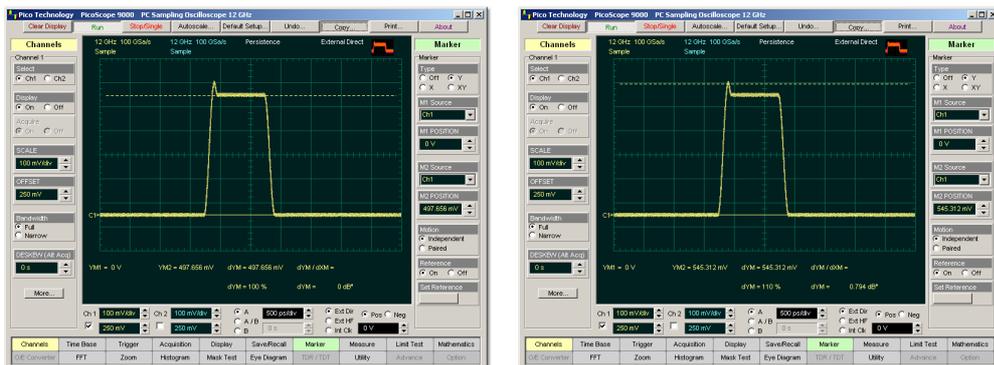
The user can set the reference:

1. First adjust the markers to a predetermined positional difference representing an absolute reference or position the markers on a reference waveform to define a specific parameter such as peak-to-peak voltage or period.
2. Then clicking the Set Reference button the ratiometric values for the reference in the Marker Measure tab becomes 100 %, 0 dB or 360°. These values are displayed, in the same color as the markers. When you change position of any marker, the results will be displayed in ratiometric values.

Click the On button to select ratiometric measurements.



Ratiometric Measurement of Duty Cycle with X Markers



Ratiometric Measurement of Overshoot with Y Markers

5.8.6 Set Reference



Clicking the Set Reference button sets the ratiometric values for the reference. As an example, they can be 100 %, 0 dB or 360°. These values are displayed, in the same color as the markers. When you begin to change the position of any marker, the results will be displayed in ratiometric values.

5.9 Main Menu

Channels	Time Base	Trigger	Acquisition	Display	Save/Recall	Marker	Measure	Limit Test	Mathematics	FFT
O/E Converter	Zoom	Histogram	Eye Diagram	Mask Test	Jitter	Generators	TDR / TDT			Utility

The Main Menu buttons are located at the bottom of the instrument display.

The Main Menu is used to:

- Set up the oscilloscope operating modes ([Channels](#)^[45], [Time Base](#)^[390], [Trigger](#)^[399], [Acquisition](#)^[30], [Display](#)^[55], [O/E Converter](#)^[320], [Generators](#)^[25] and [Zoom](#)^[414] Menus)
- Set up and execute waveform measurements ([Marker](#)^[192], [Measure](#)^[246], Limit Test , [Histogram](#)^[181], [Eye Diagram](#)^[75], [Mask Test](#)^[204] and [TDR/TDT](#)^[356] Menus)
- Control file management tasks ([Save/Recall](#)^[329] Menu)
- Perform waveform analysis ([Mathematics](#)^[239] and [FFT](#)^[166] Menus)
- Set up and execute instrument calibration, and to use a demo mode ([Utility](#)^[423] Menu)

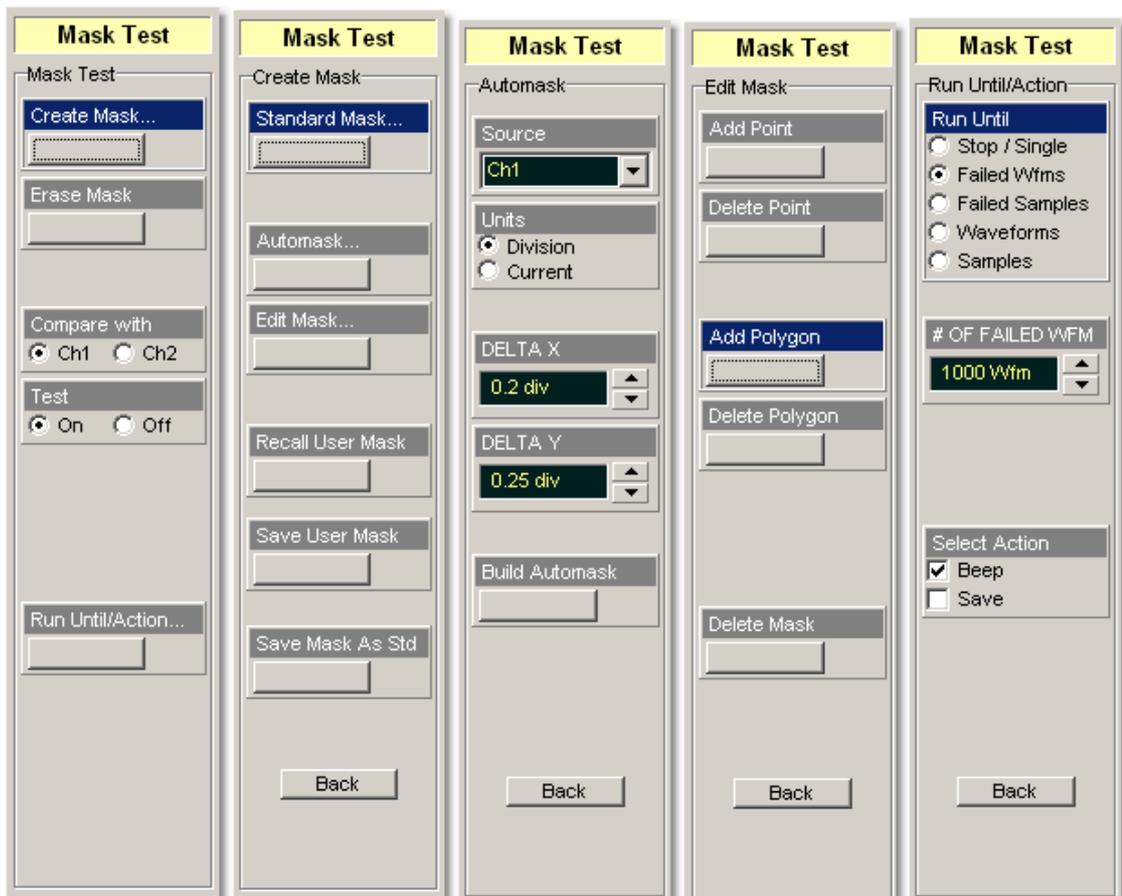
5.10 Mask Test

Mask Test

There are industry standards that define the parameters for electrical and optical waveforms. Mask testing is a process you can use to verify that the displayed waveform complies with an industry standard waveform shape.

A mask is a template that consists of numbered, shaded regions on the instrument display screen. The input waveform must then remain outside these regions in order to comply with the industry standard. Any acquired data point that falls inside a mask margin appears in red.

The instrument has been designed to perform communication industry mask testing to a variety of test standards. Mask testing may be performed by a following simple procedure. This procedure loads one of several mask templates, automatically aligns the mask to the present waveform, and then determines the waveform's compliance to the mask. The size of the mask or the portion of the mask can be increased or decreased in a linear fashion to determine the waveform's margin of compliance. Both the user defined and standard (factory-installed) masks can be stored to disk for rapid switching between instrument setups. Mask testing can also activate a variety of actions upon determining a test failure.



5.10.1 Create Mask



Clicking the Create Mask... button opens the mask selection menu. You can select from:

- industry-standard electrical masks
- industry-standard optical masks
- automasks
- new user-defined masks
- stored user-defined mask

Also you can edit any mask, and save it to a memory.

5.10.1.1 Standard Mask



Standard Masks... allows you to select from a variety of standard telecommunication masks. Clicking the Standard Masks... button opens the Standard Masks Dialog.

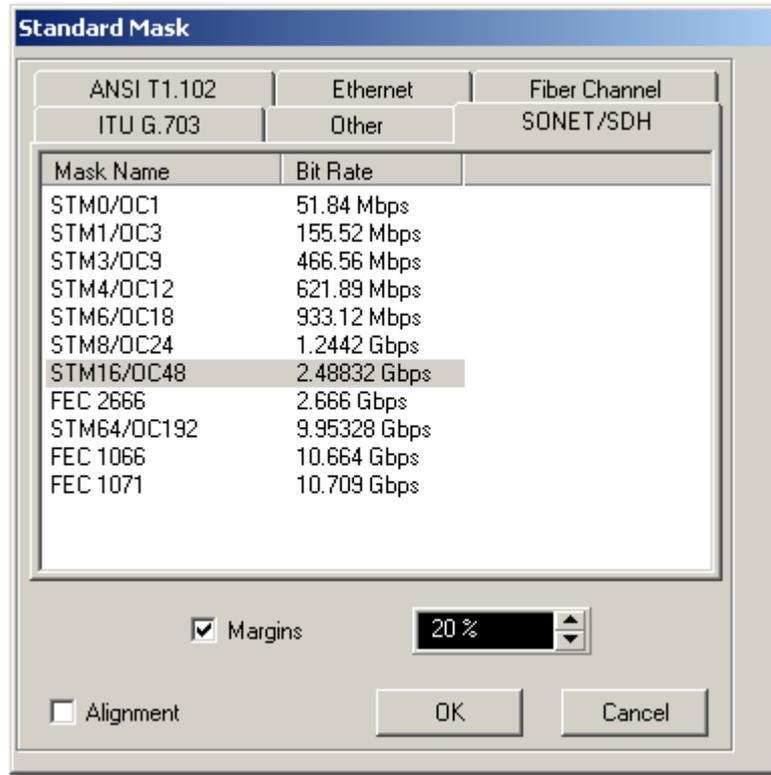
Choose a standard to access a list of masks used for optical or electrical waveforms. The PicoScope 9000A supports several standards for datacomms and telecomms masks. They are:

- SONET/SDH
- Fiber Channel
- Ethernet
- ITU G.703
- Rapid IO
- G.984.2
- PCI-Express
- ANSI T1.102
- Infini Band
- Serial ATA
- XAUI

5.10.1.1.1 SONET/SDH Masks

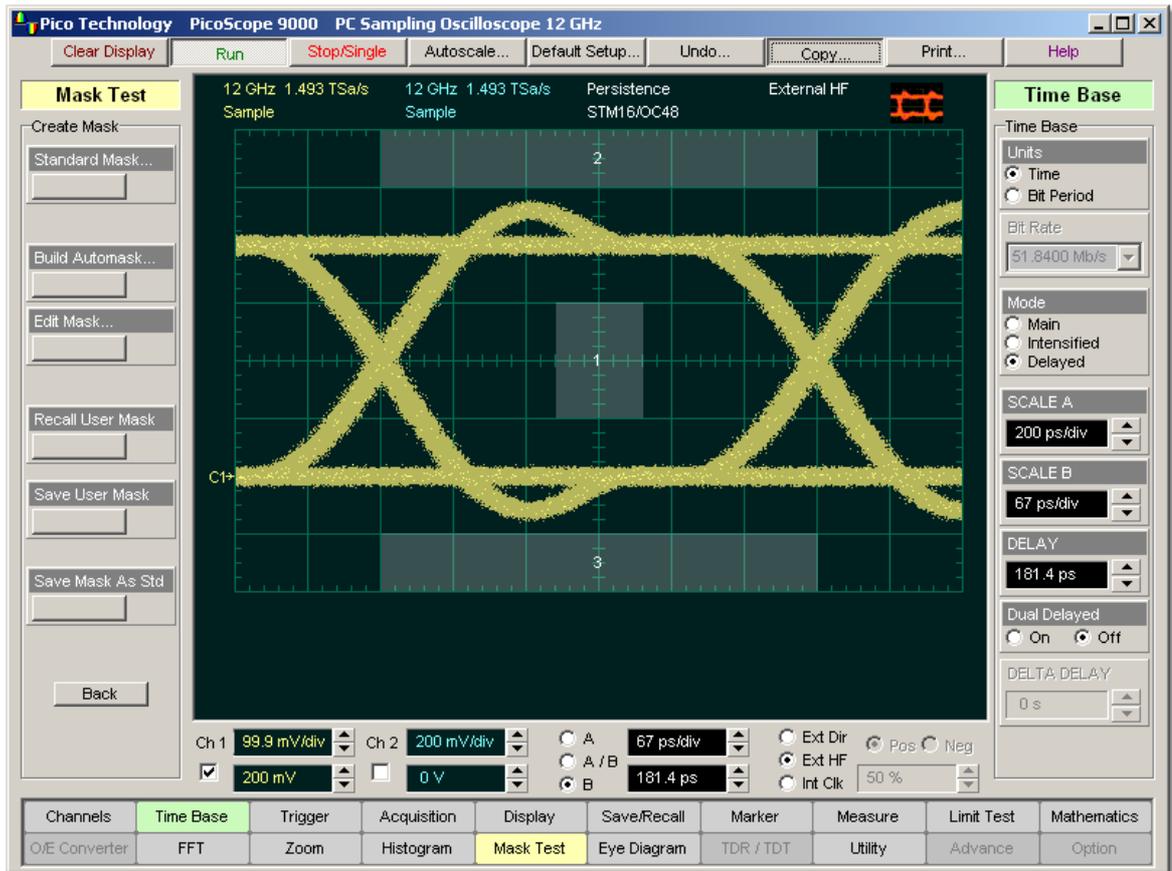
SONET/SDH

Clicking the SONET/SDH tab opens the list of industry-standard masks.



The list of industry-standard SONET/SDH masks

Any of these masks may be recalled from memory and used to test a waveform to a specific industry standard listed above. An example eye-diagram with the OS48/STM16 industry-standard mask is shown below.



An example of eye-diagram with the OS48/STM16 SONET/SDH mask

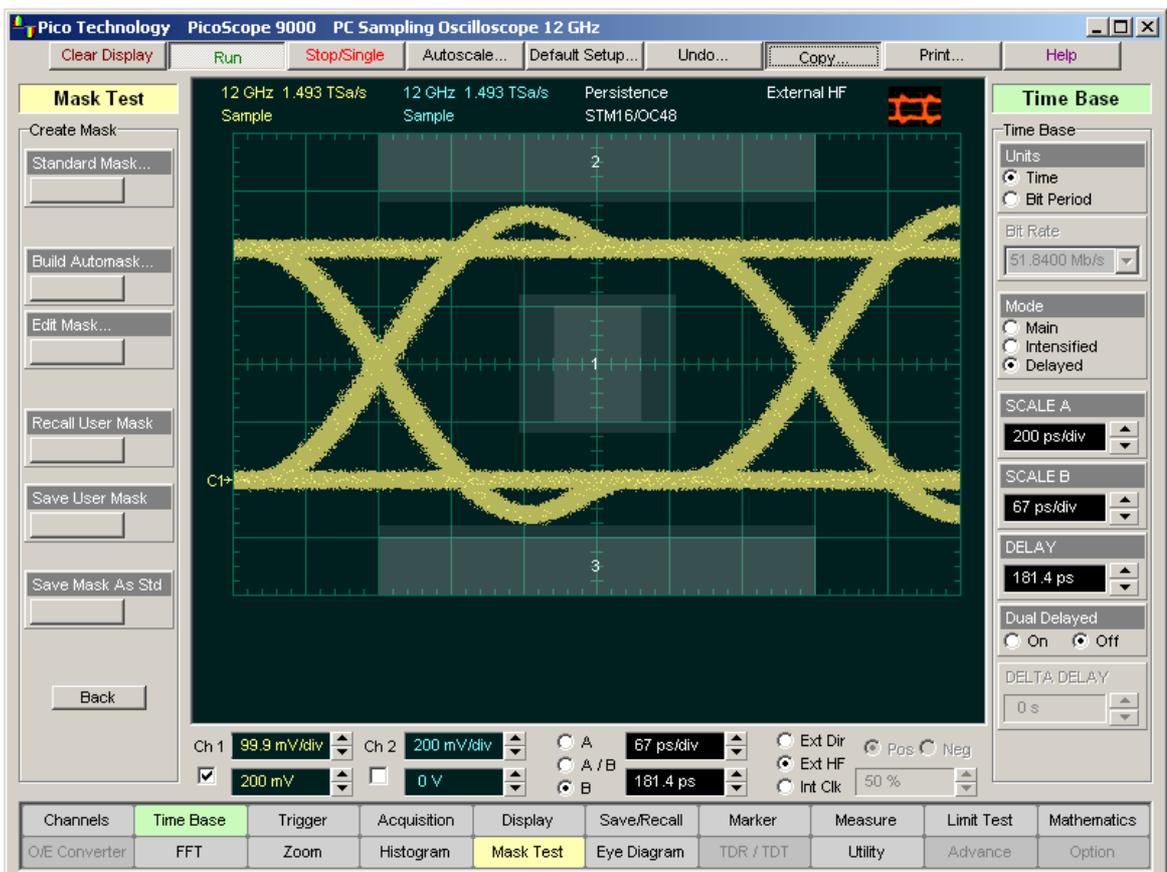
5.10.1.1.2 Mask Margins



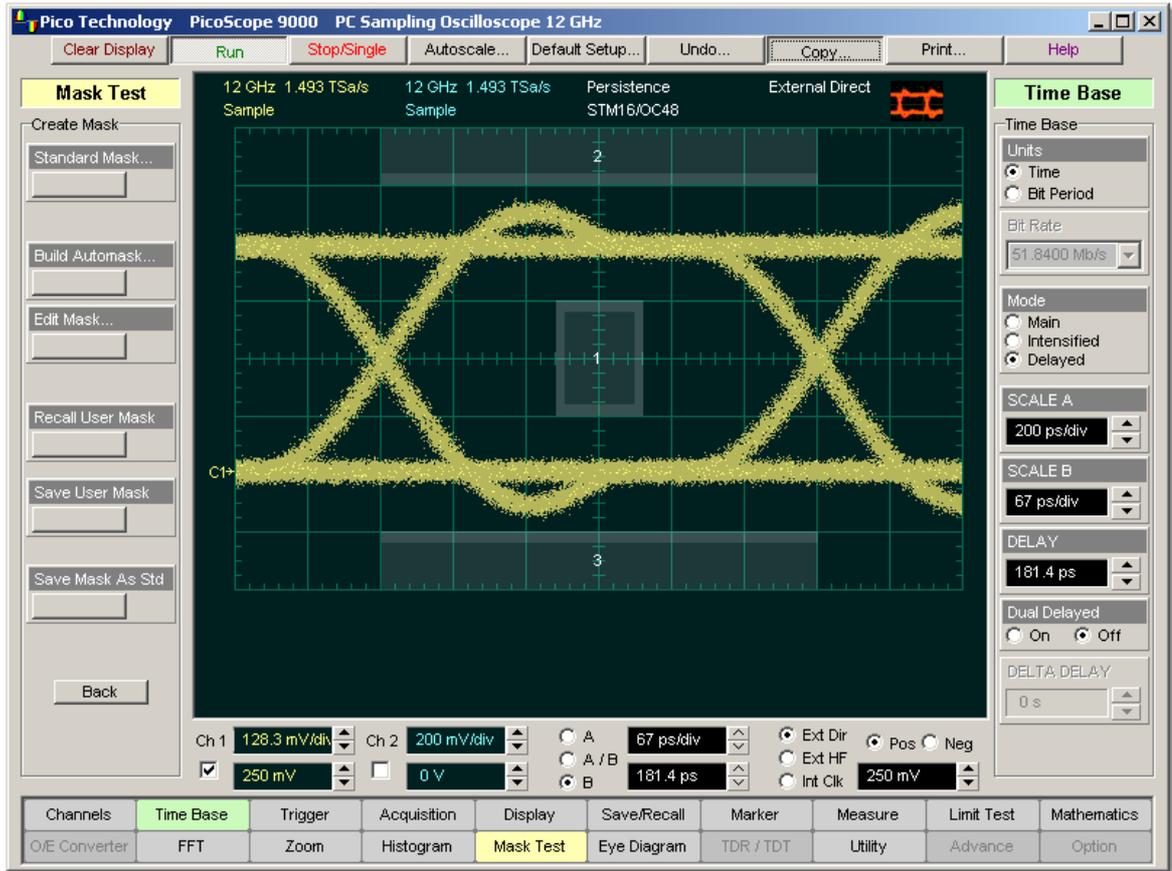
The Margins option is a part of each opened list of industry-standard masks. Mask margins are used to determine the margin of compliance for a standard mask. The operator can use both positive mask margins and negative mask margins. Positive mask margins determine how much larger you will be able to make the mask before violations will occur, while negative mask margins determine how much smaller you have to make the mask before violations no longer occur. You can then use this information to determine by what margin the waveform begins to fail to comply with industry standards.

To turn on the mask margins, check the Margins check box located on each opened list of industry-standard masks. After mask margins are enabled, use the arrows to adjust the percentage of margin you want, or use the [Pop-up Keypad](#)^[42] for quickly entering numeric data. You can enter a value between -99% and +99%. For example, if you want to verify that the waveform can comply with a standard mask with a 20% margin, set the margin value to 20%. You can then increase the size of the margin by increasing the percentage until violations occur.

The instrument displays the mask margins in a different color than the mask. As with a mask, any acquired data point that falls inside a mask margin appears in red. Two examples of positive and negative margins are shown on figures below. Notice that positive margins appear outside the mask regions, while negative margins appear inside the mask regions.



An example of eye-diagram with positive mask margins (+20%)



An example of eye-diagram with negative mask margins (-20%)

5.10.1.1.3 Alignment

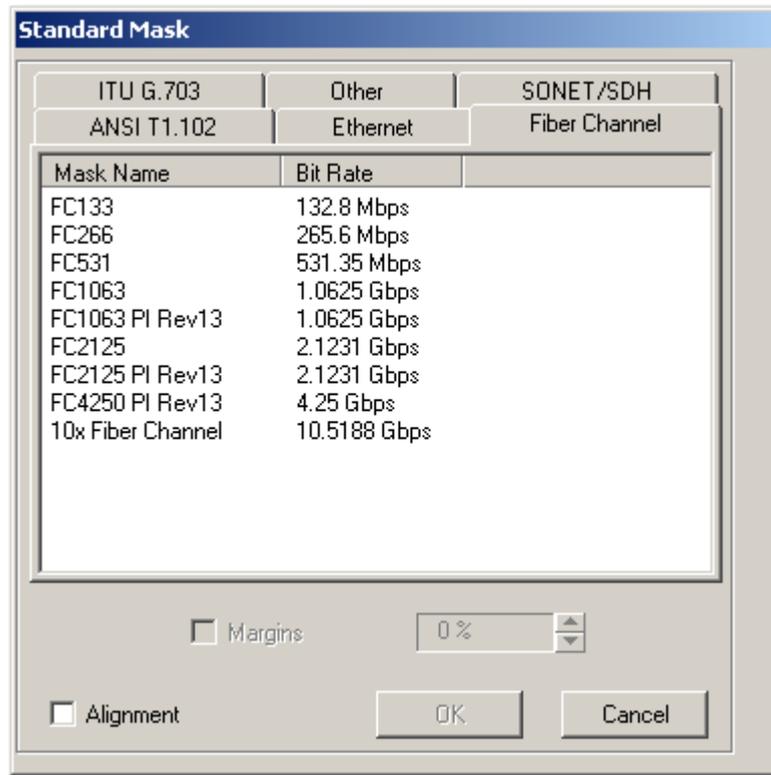


The instrument can align the Time Base Scale to a selected industry-standard mask. To turn on the alignment option, check the Alignment check box located on each opened list of industry-standard masks.

5.10.1.1.4 Fiber Channel Masks

Fiber Channel

Clicking the Fiber Channel tab opens the list of industry-standard masks. Any of these masks may be recalled from memory and used to test a waveform to a specific industry standard listed above.

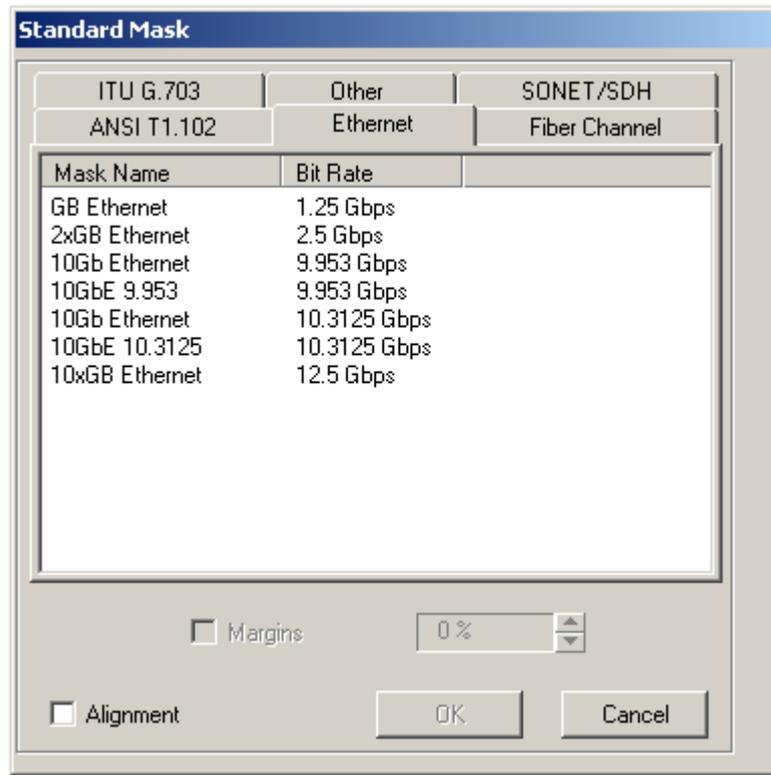


The list of industry-standard Fiber Channel masks

5.10.1.1.5 Ethernet Masks

Ethernet

Clicking the Ethernet tab opens the list of industry-standard masks. Any of these masks may be recalled from memory and used to test a waveform to a specific industry standard listed above.

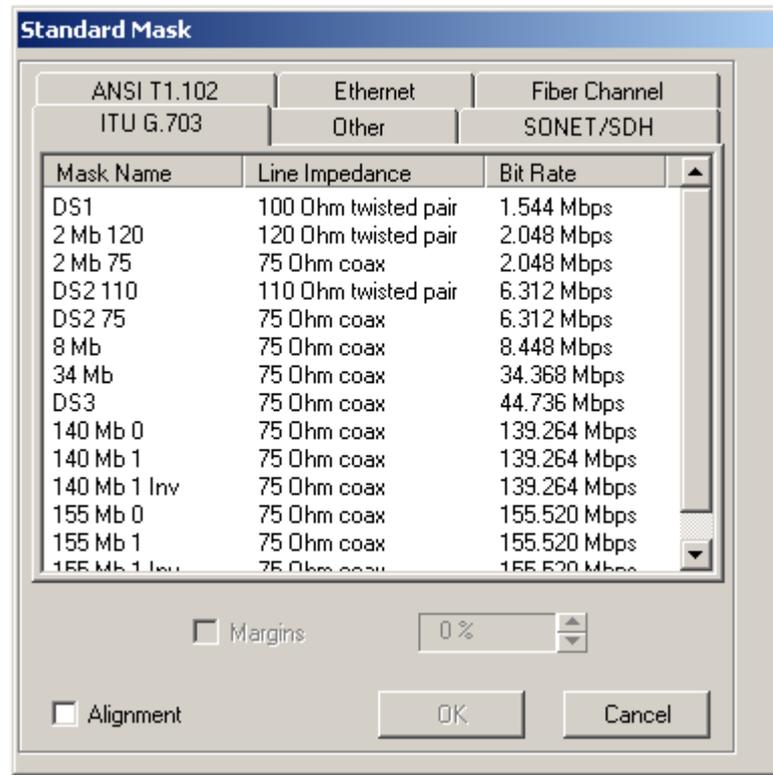


The list of industry-standard Ethernet masks

5.10.1.1.6 ITU G.703 Masks

ITU G.703

Clicking the ITU G.703 tab opens the list of industry-standard electrical masks. Any of these masks may be recalled from memory and used to test a waveform to a specific industry standard listed above.

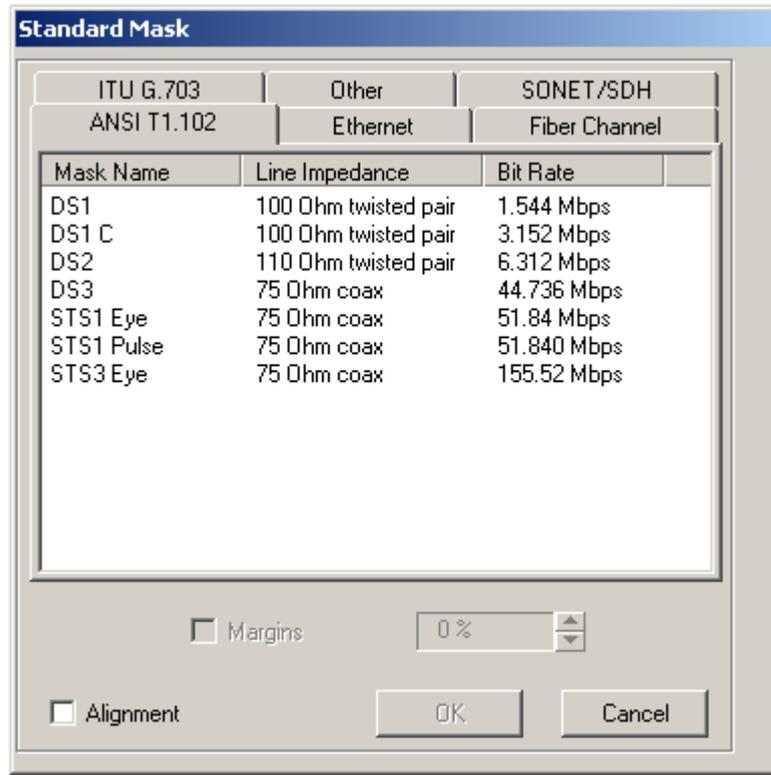


The list of industry-standard electrical ITU G.703 masks

5.10.1.1.7 ANSI T1.102 Masks

ANSI T1.102

Clicking the ANSI T1.102 tab opens the list of industry-standard electrical masks. Any of these masks may be recalled from memory and used to test a waveform to a specific industry standard listed above.

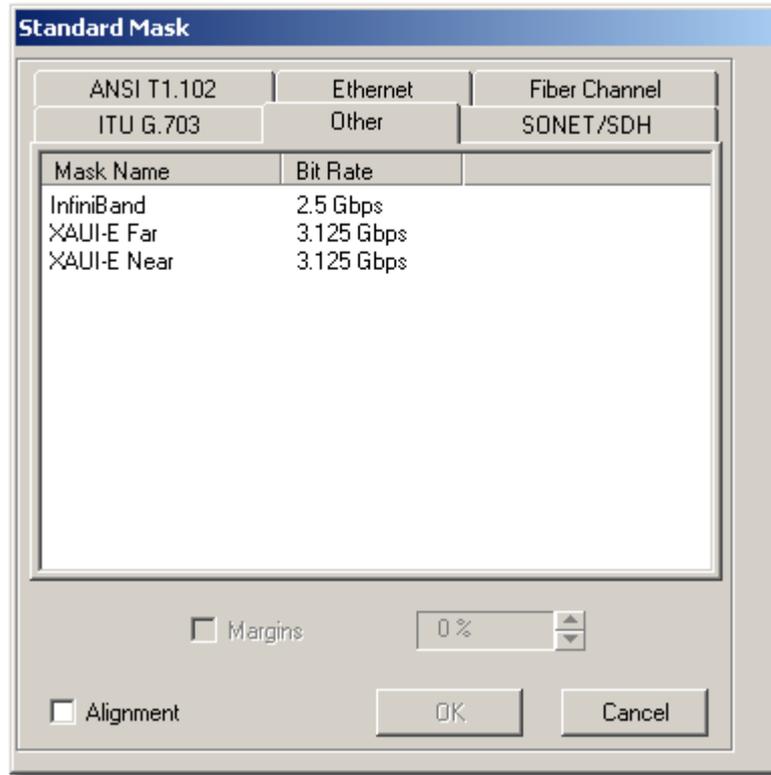


The list of industry-standard electrical ANSI T1.102 masks.

5.10.1.1.8 Other Masks

Other

Clicking Other opens the list of two additional industry-standard. Any of these masks may be recalled from memory and used to test a waveform to a specific industry standard listed above.



The list of other industry-standard masks

5.10.1.2 User-defined Masks

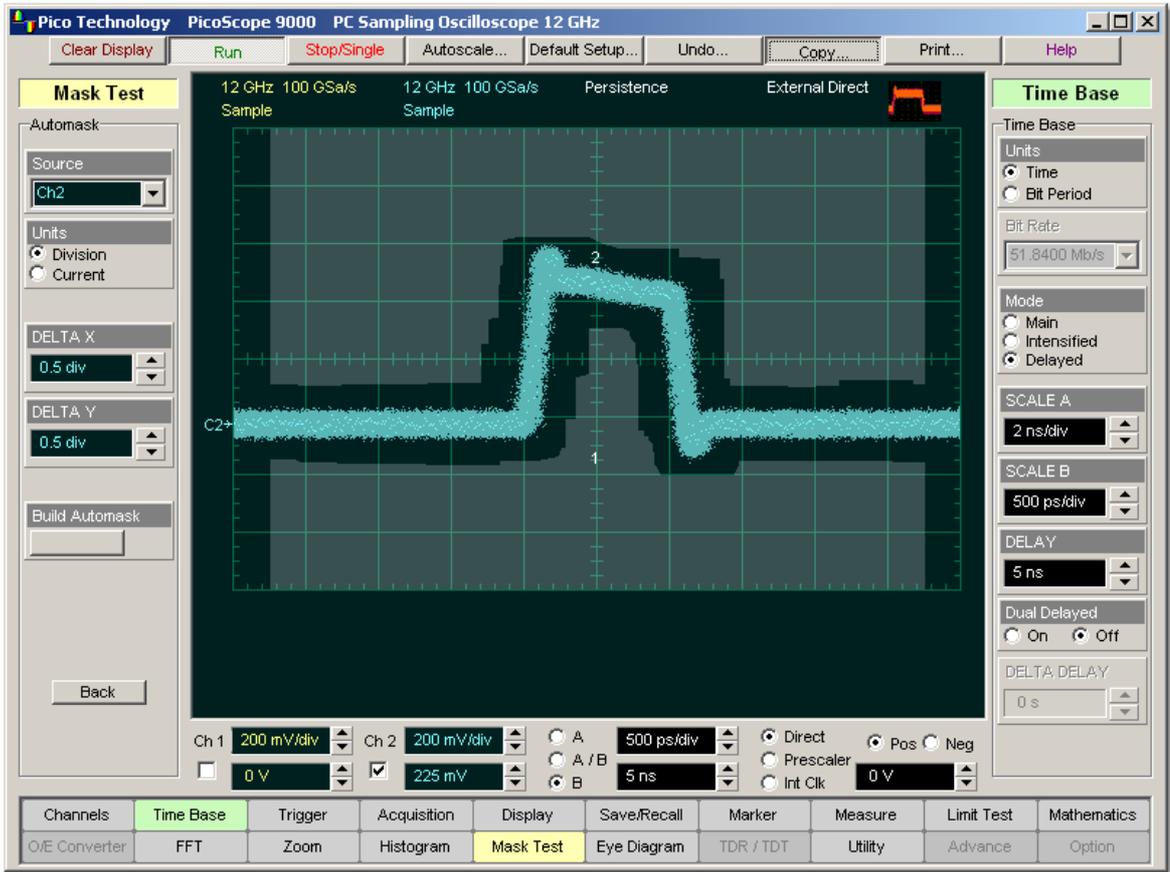
The Mask Test menu contains a mask-editing feature that allows you to create your own masks. These masks may be created using one of three methods:

- By using a reference waveform method (Automask). Masks are constructed by adding a DELTA X and DELTA Y tolerance around a reference waveform. This method is simple to use, though not as flexible as the polygon method.
- By using a polygon method for creating a unique new mask. Using this method, polygons are created to mask off failure regions of the graticule. Up to eight polygons can be positioned in the graticule area, each with 3 to 512 sides. Very complex masks can be constructed by placing polygons within polygons. Similar to margin testing discussed above, this method allows testing of waveform failure rates to varying tolerances, because failures are listed individually for each polygon.
- By using a polygon method for modifying an existing mask. This method involves the use of a reference waveform.

5.10.1.3 Automask



Clicking the Automask... button opens a menu for using the reference waveform method. An example of the method for a noisy impulse is shown in the figure below.



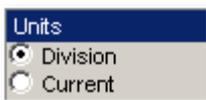
An example of Automask for a noisy impulse

5.10.1.3.1 Source



The Source function selects the channel, function, memory, or spectrum that the mask is scaled to.

5.10.1.3.2 Units



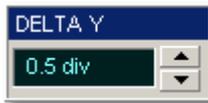
The Units function allows you to define DELTA X and DELTA Y in divisions or current source settings. Current is typically in volts and seconds or other appropriate units for the source.

5.10.1.3.3 DELTA X



The DELTA X variable defines the horizontal tolerance around the edges of the reference waveform.

5.10.1.3.4 DELTA Y



The DELTA Y variable defines the vertical tolerance around the edges of the reference waveform.

5.10.1.3.5 Build Automask



Clicking the Build Automask button builds a mask with the new values of the [DELTA X](#)^[217] and [DELTA Y](#)^[217] variables.

5.10.1.4 Edit Mask



The Edit Mask... function gives you access to a second-level menu that allows you to construct a new mask, or edit an existing one, using the polygon method. The procedure of editing a mask function brings up a set of brief instructions on how to construct a mask.

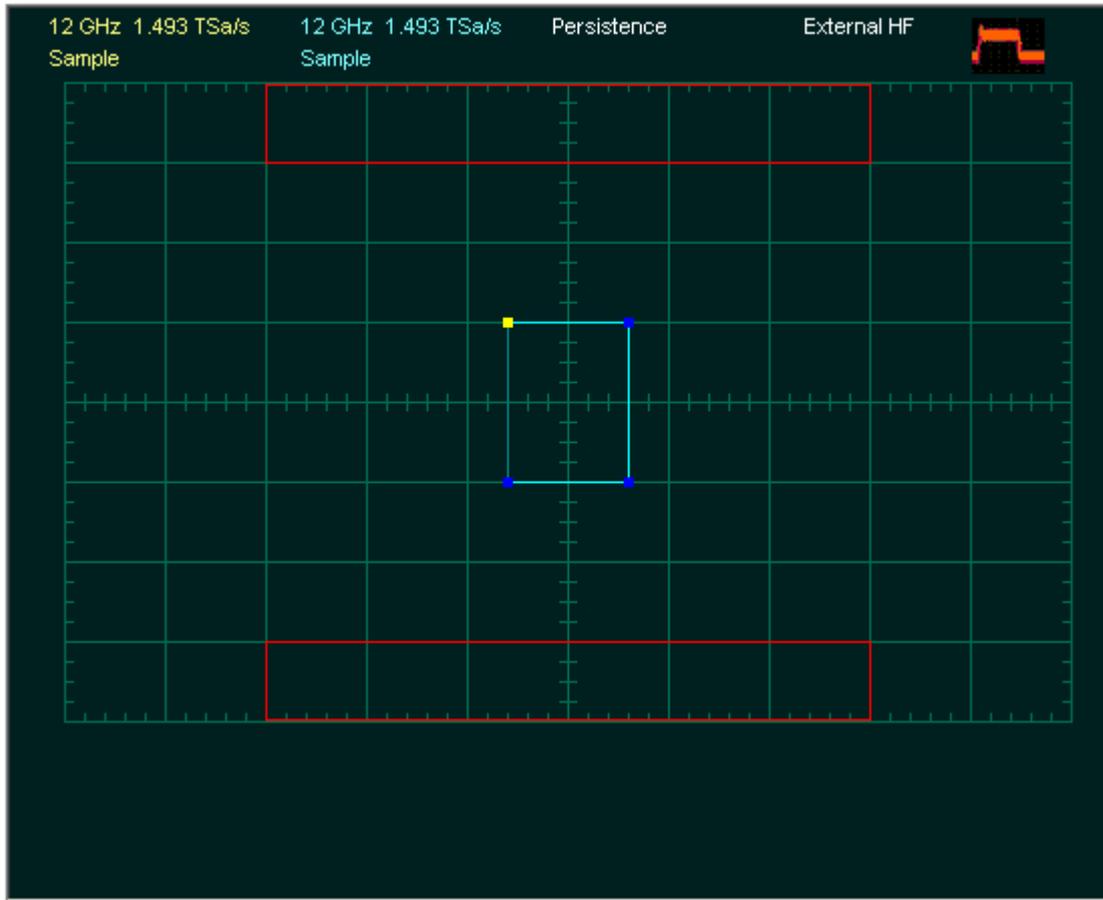
Mask editing procedure

The following is a simple editing procedure of editing the OC48/STM16 standard mask into a user-defined mask.

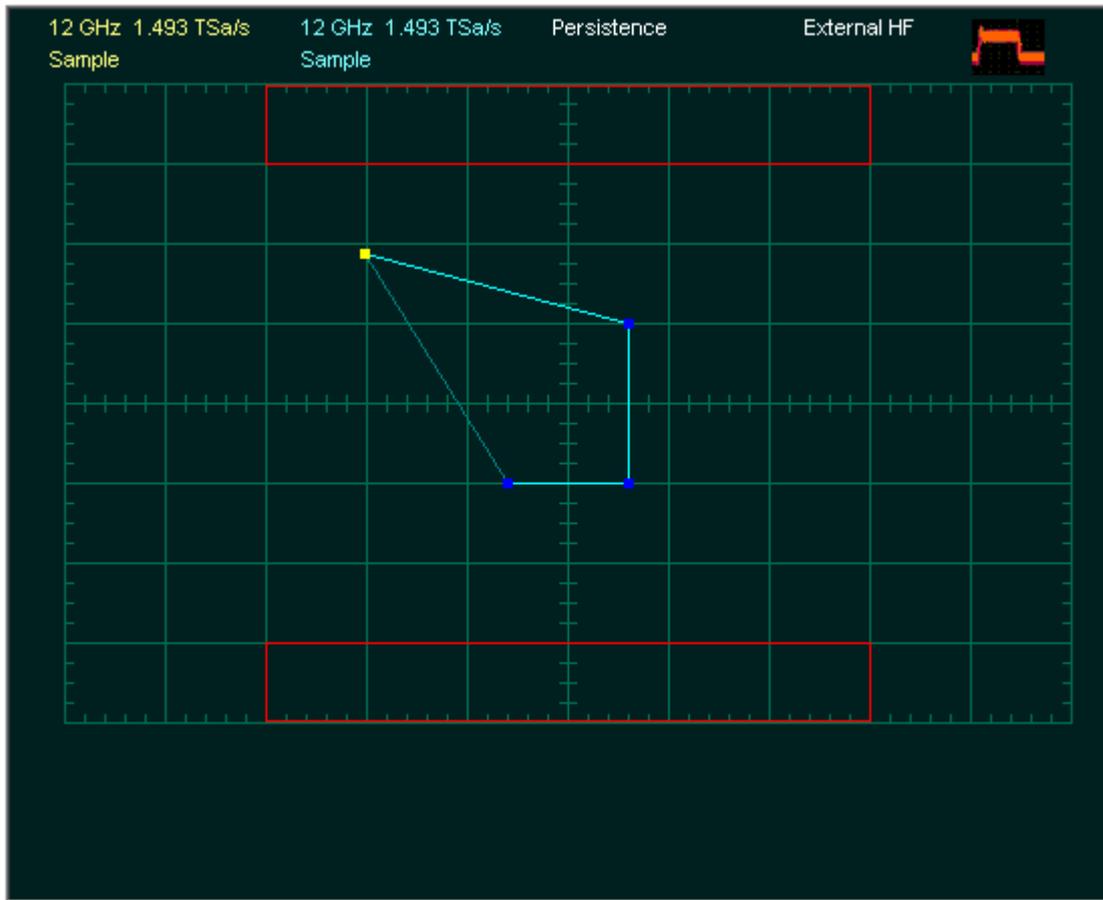
1. Select the OC48/STM16 standard mask from Mask Test / Create Mask... / Standard Mask / SONET/SDH / OC48/STM16.



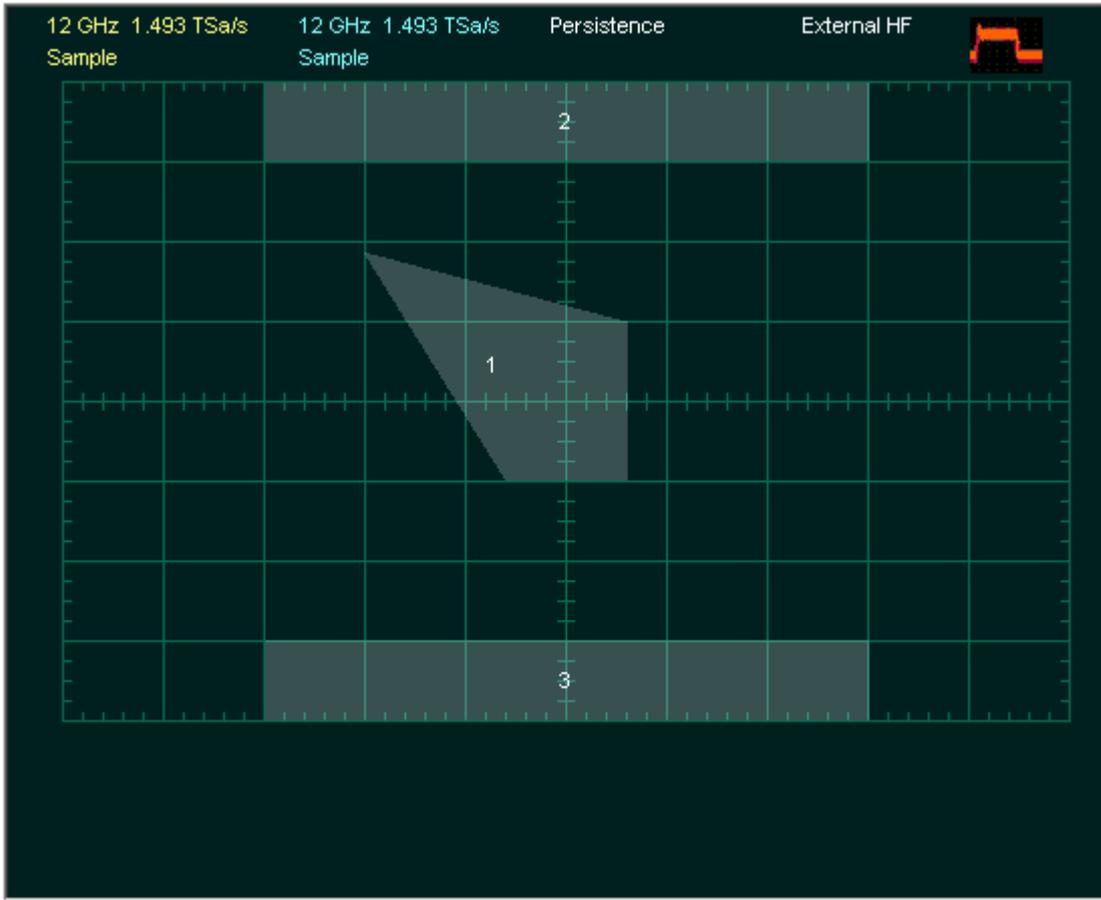
2. Click Edit Mask... Click a polygon to select it, and click again on a vertex of the polygon. Note the square points on the selected polygon, which are yellow when selected, otherwise blue. The vertical and horizontal coordinates of the selected point will appear in the Status Area of the GUI.



3. Click and hold the left mouse button on the selected point, then drag the mouse to move the point to the desired position. Release the mouse button when finished.



4. Click the Back button. The scope returns to the high-level menu, and mask gets a new shape.

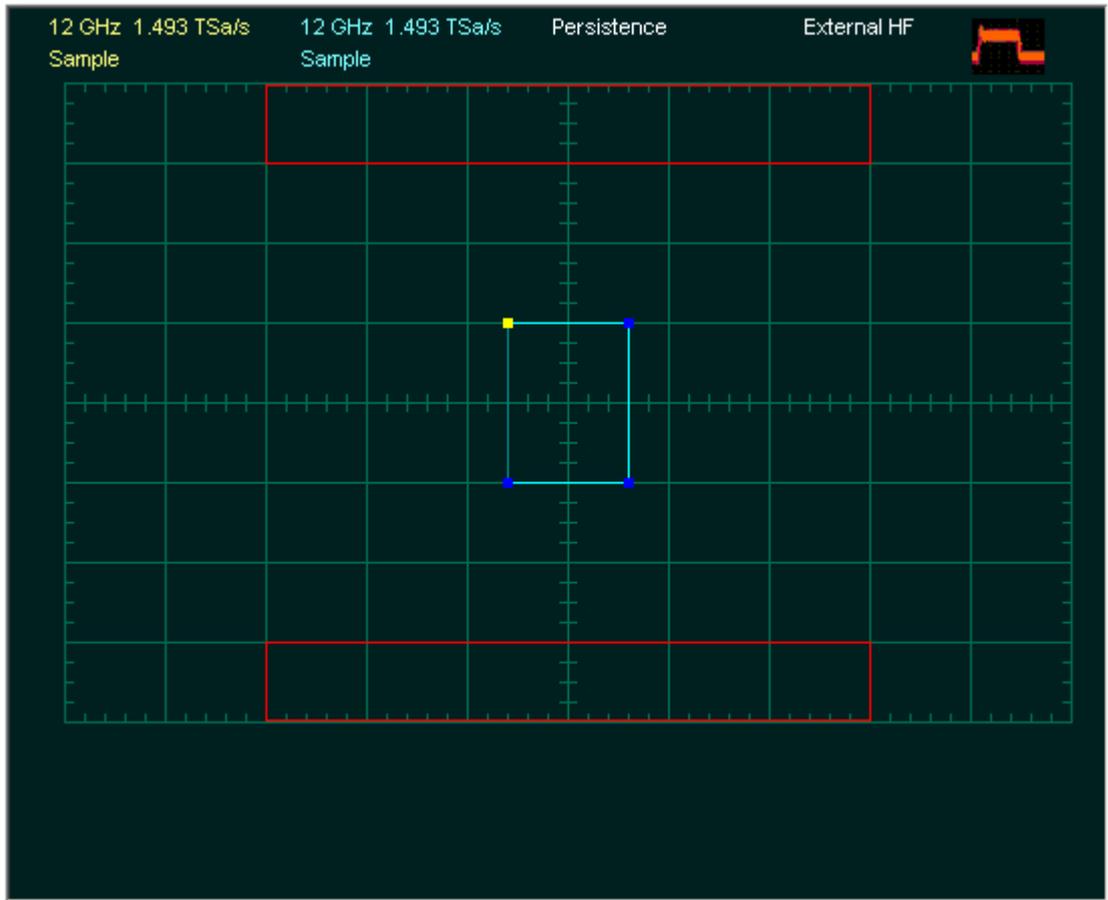


5.10.1.4.1 Add Point

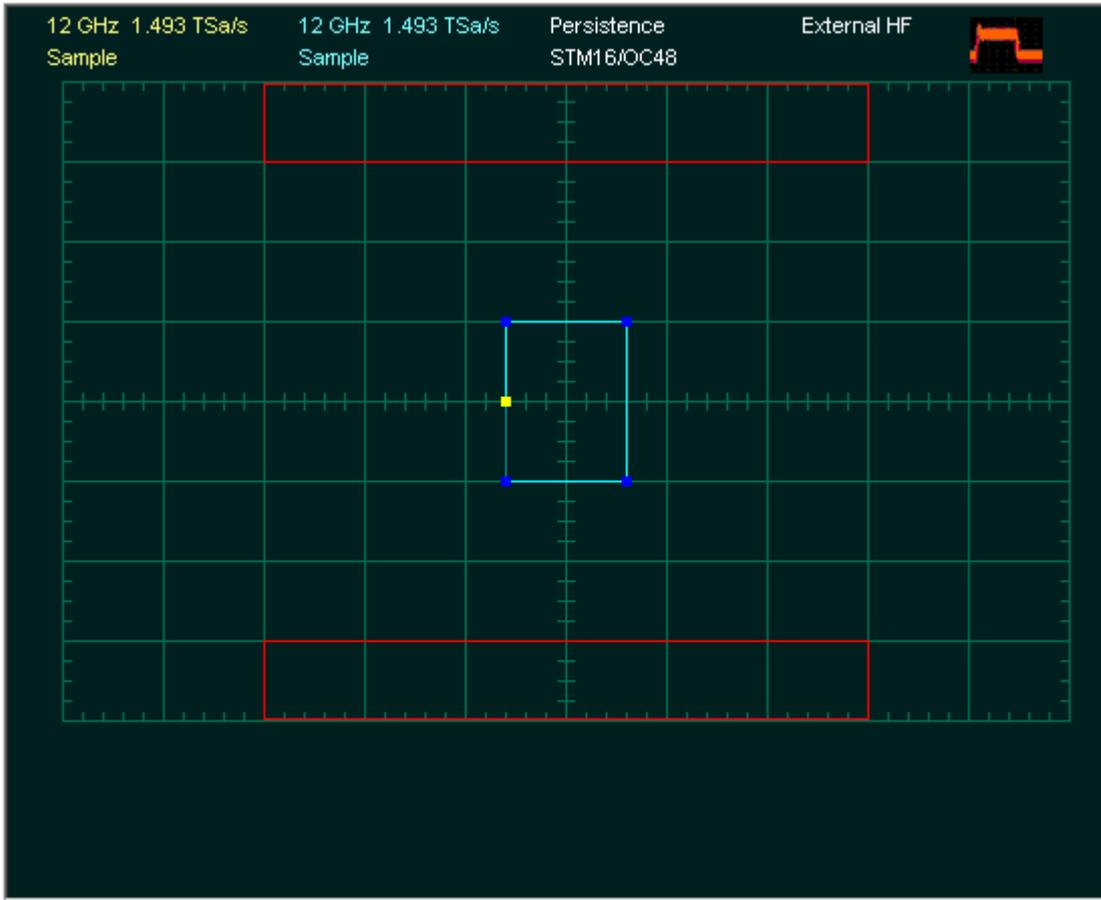


The Add Point function adds a point on the selected polygon in a Mask.

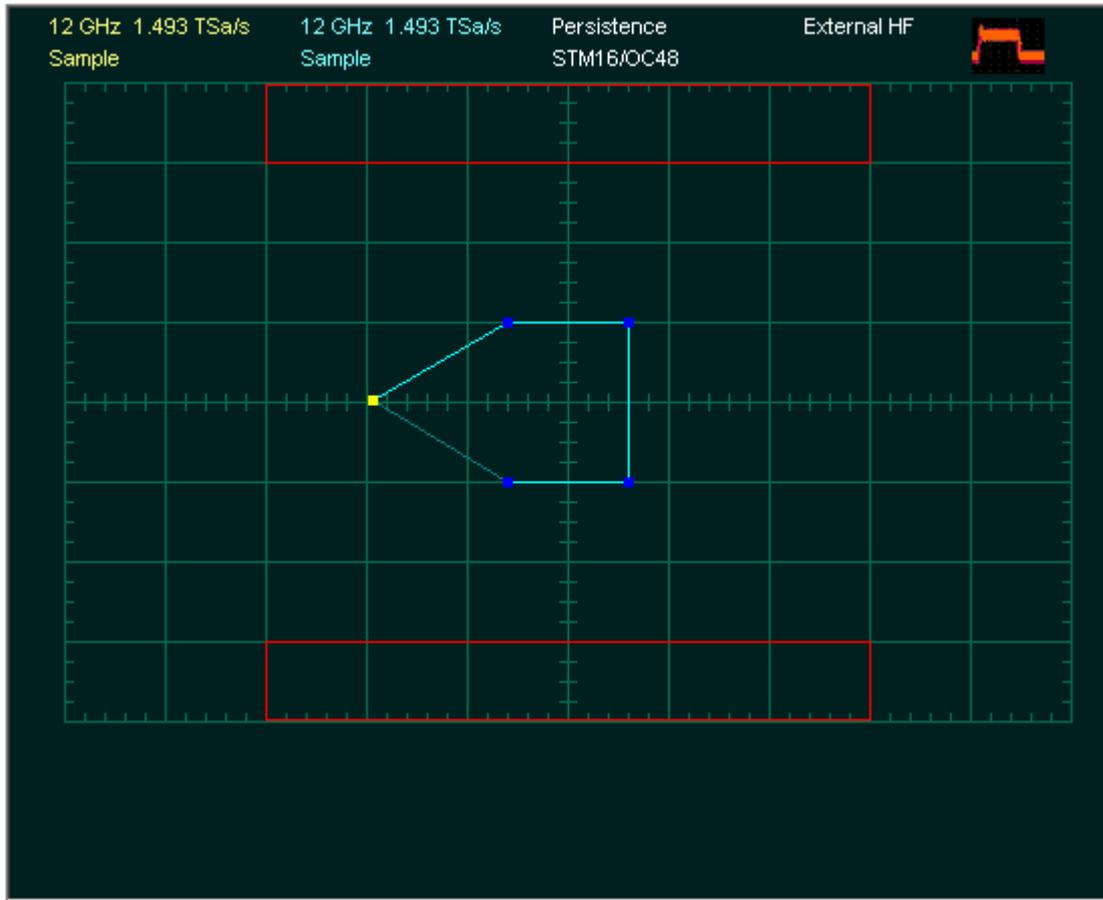
1. Click Edit Mask. Click on the polygon that you want to edit, and then click on a vertex of the polygon.



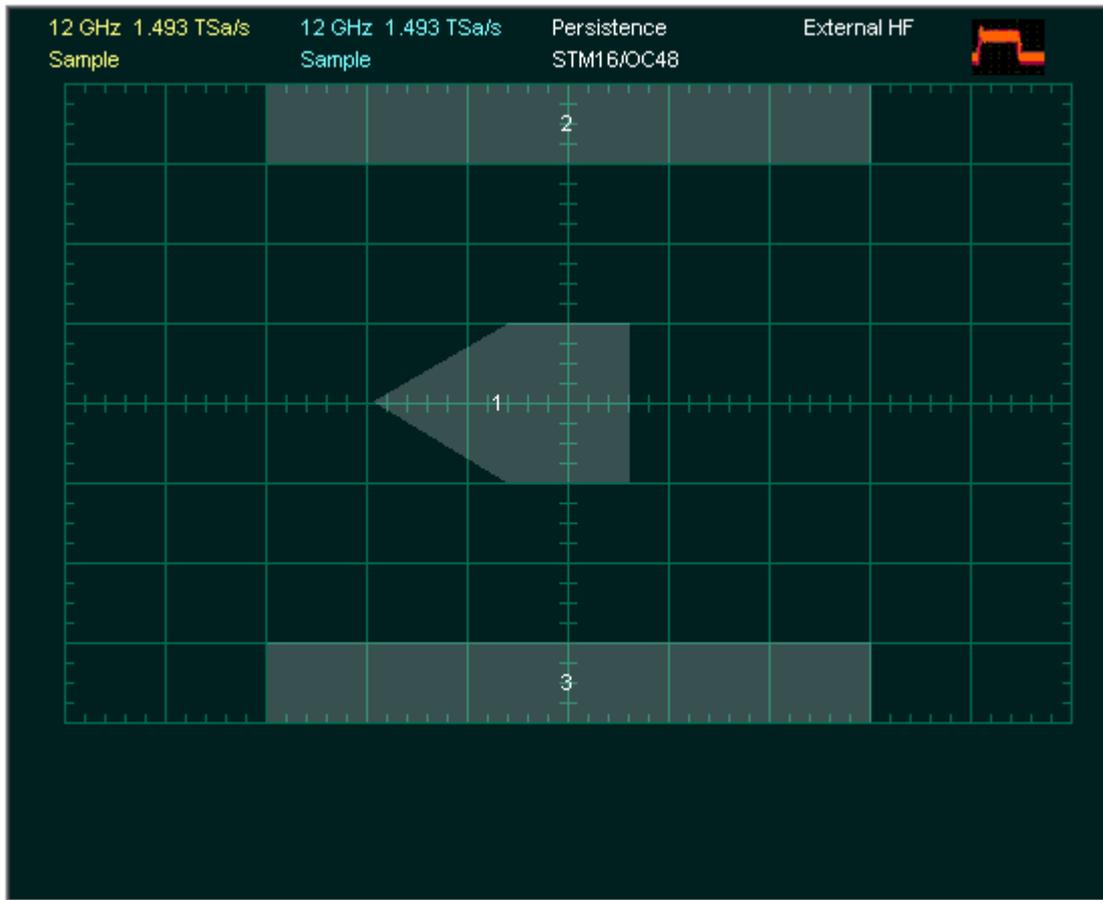
2. Click Add Point. A new point, highlighted in yellow, will appear counter-clockwise of the selected point. You can continue to edit this point.



3. Click and hold the left mouse button on the new point, then drag the mouse to move it to the desired position. The vertical and horizontal coordinates of the new point change in the Status Area of the GUI when moving. Release the mouse button when finished.



- Click the Back button. The scope returns to the high-level menu, and mask gets a new point.



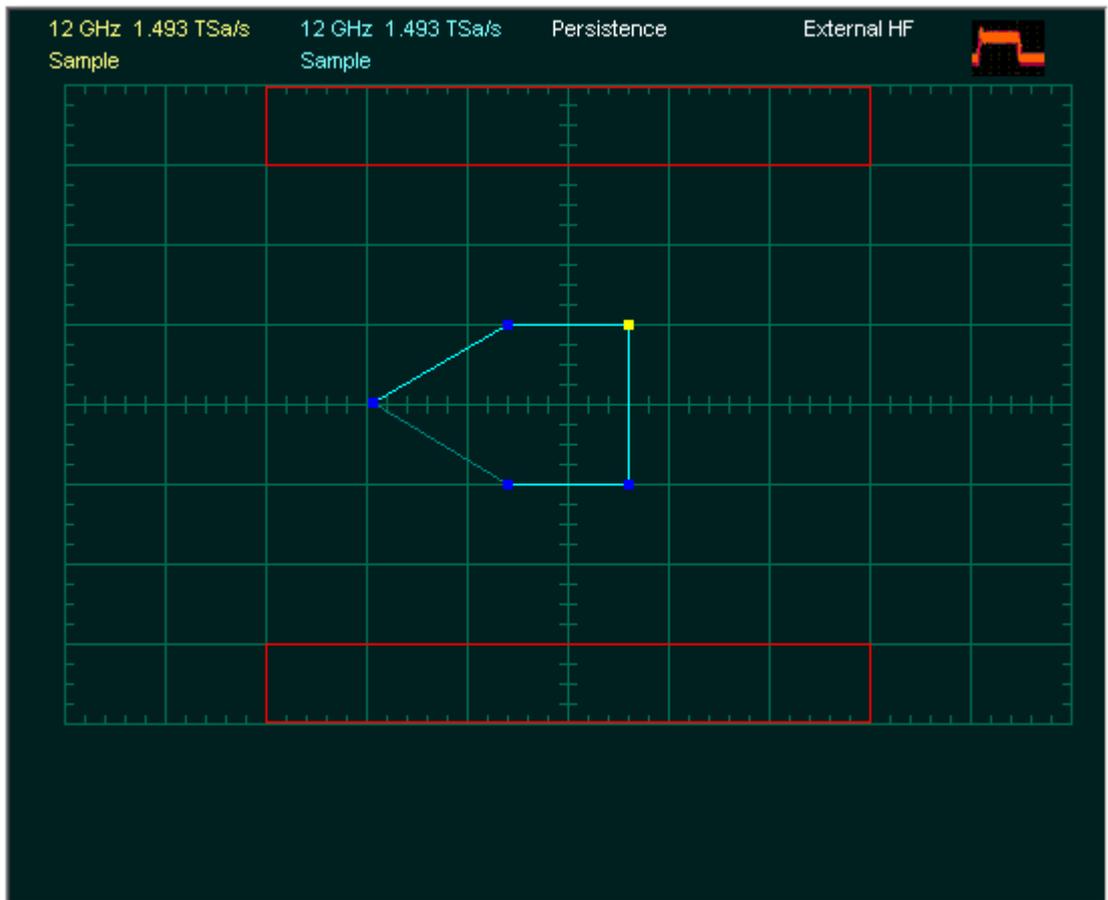
5.10.1.4.2 Delete Point



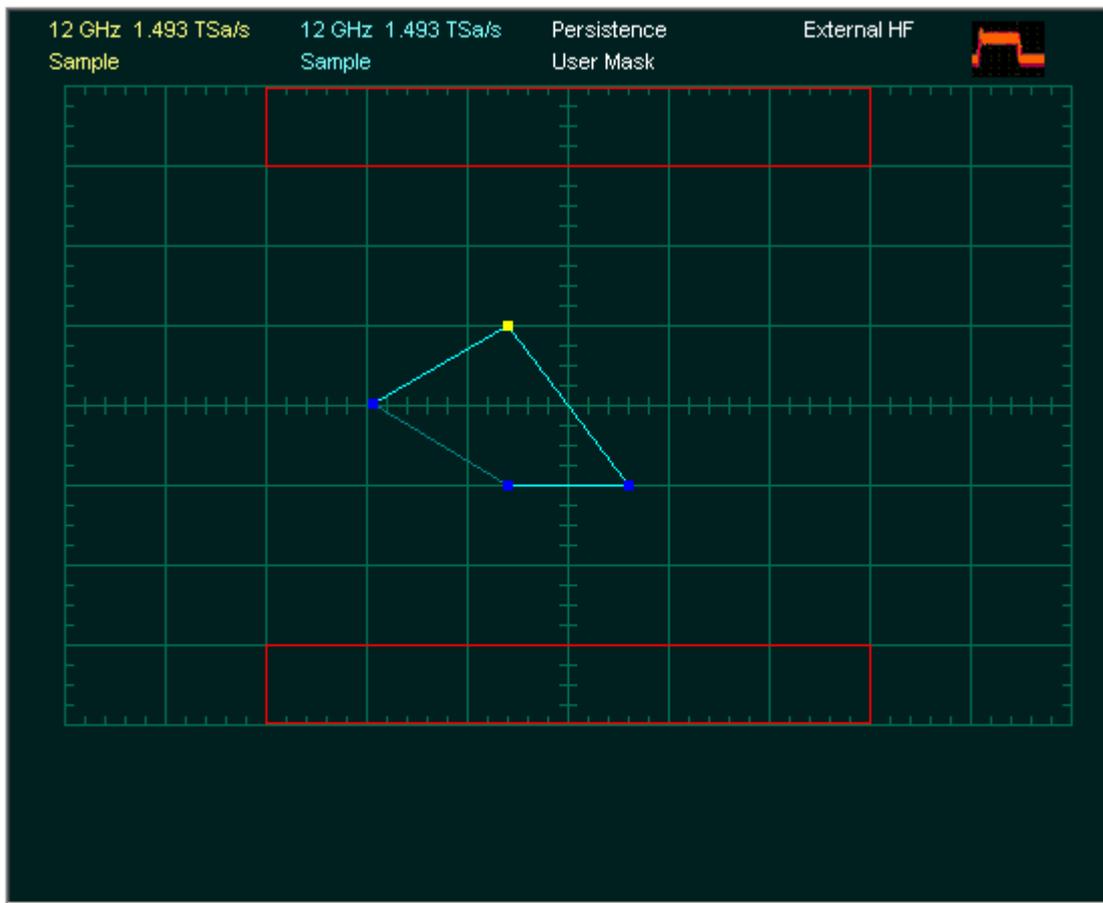
The Delete Point function deletes a point on a polygon of a Mask.

To delete a point:

1. Click Edit Mask. Click on the polygon you want to use, and then click on the vertex you want delete. The selected point is highlighted in yellow. The vertical and horizontal coordinates of the selected point appear on the Status Area of the GUI.



2. Click the Delete Point button. The point will be deleted.



3. Click the Back button. The scope returns to high-level menu, and the mask gets a new shape without the deleted point.



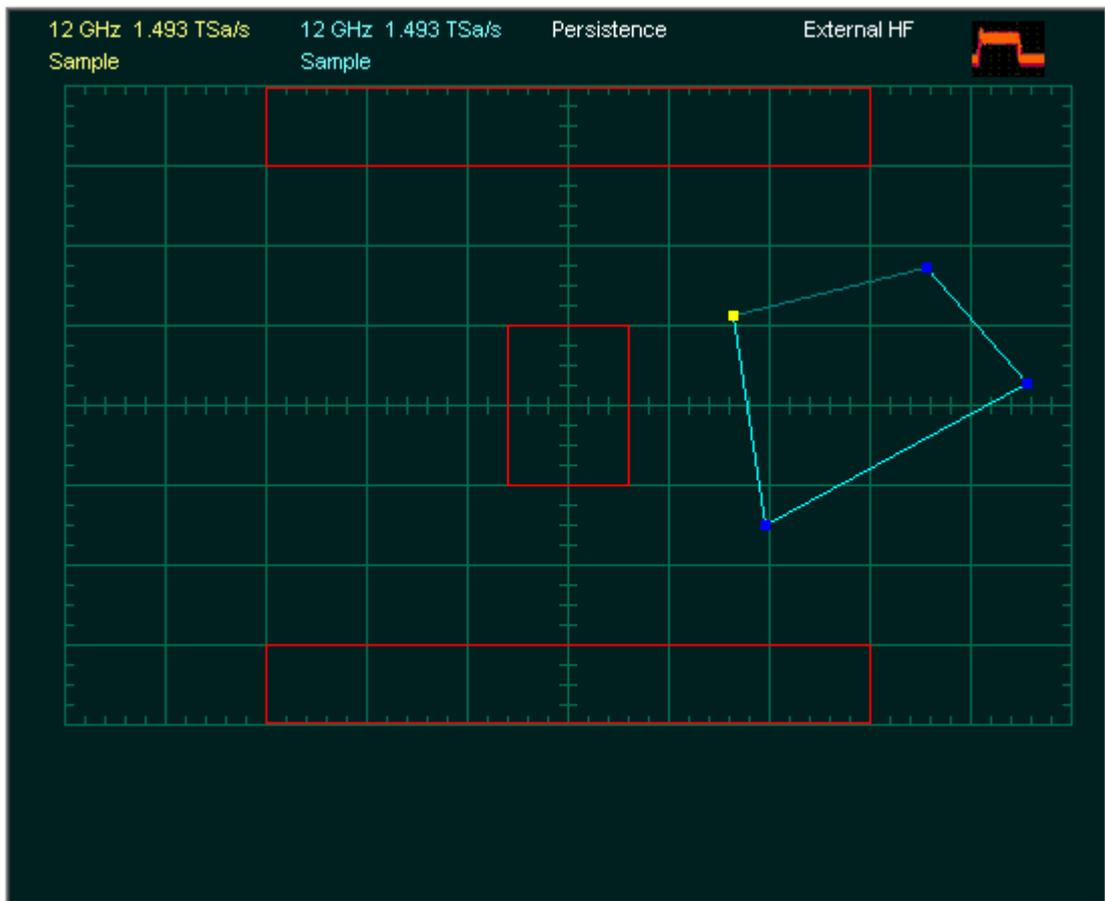
5.10.1.4.3 Add Polygon



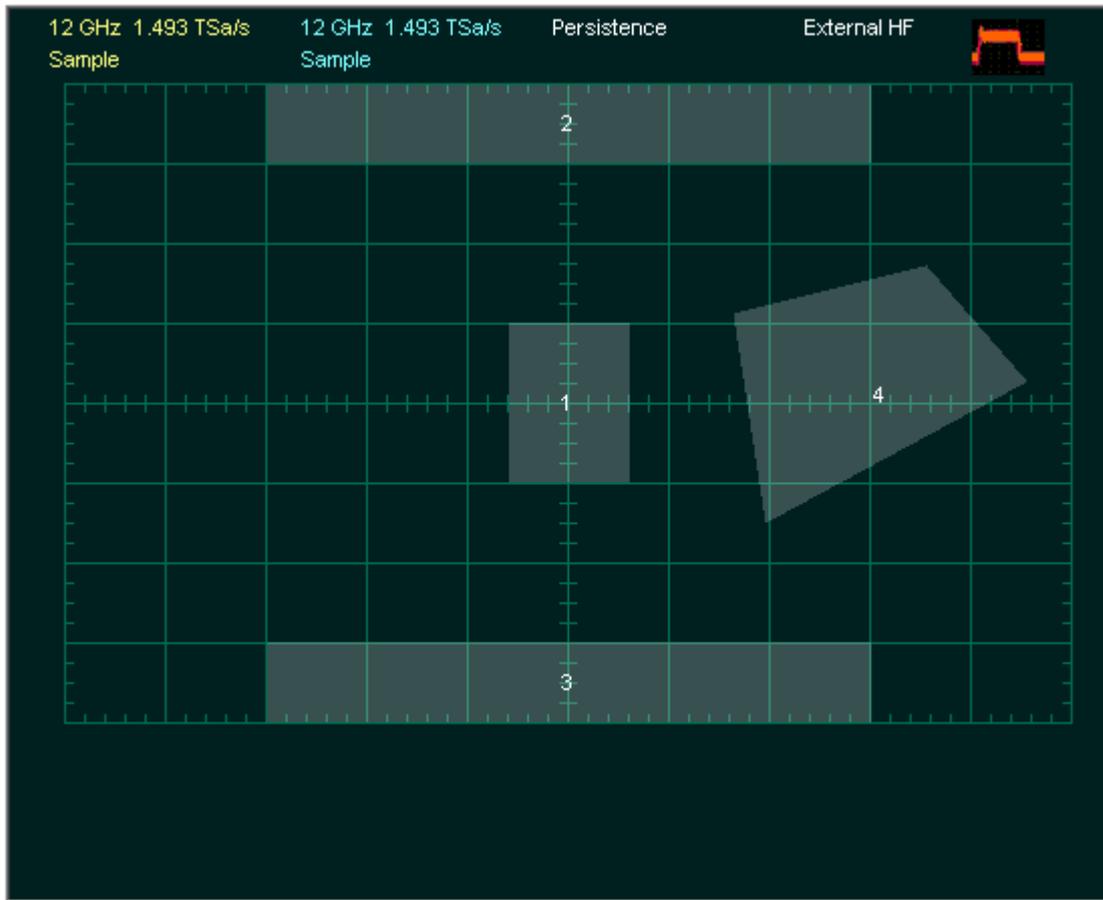
The Add Polygon function allows you to select one of the eight polygons that you want to create.

To add a polygon

1. Click the Edit Mask button, and then the Add Polygon button. To create the first point of the new polygon, click on the waveform area of the screen. Move the mouse to the second point of the new polygon, then click again. Continue for all new points. You will see lines connecting all the points of the polygon. To finish the construction, right-click anywhere on the display. The polygon is now built, and the mouse is free.



2. Click the Back button. The scope returns to the high-level menu, and the mask gets a new polygon.



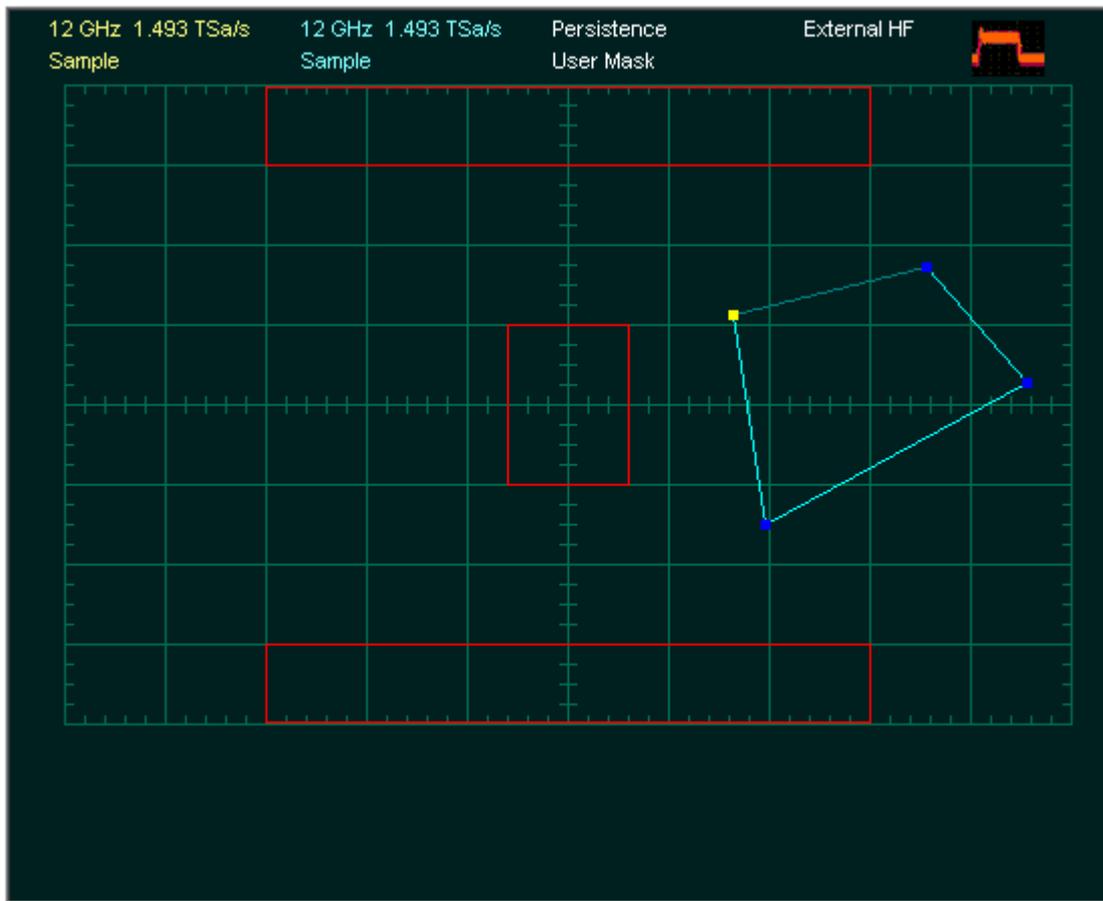
5.10.1.4.4 Delete Polygon



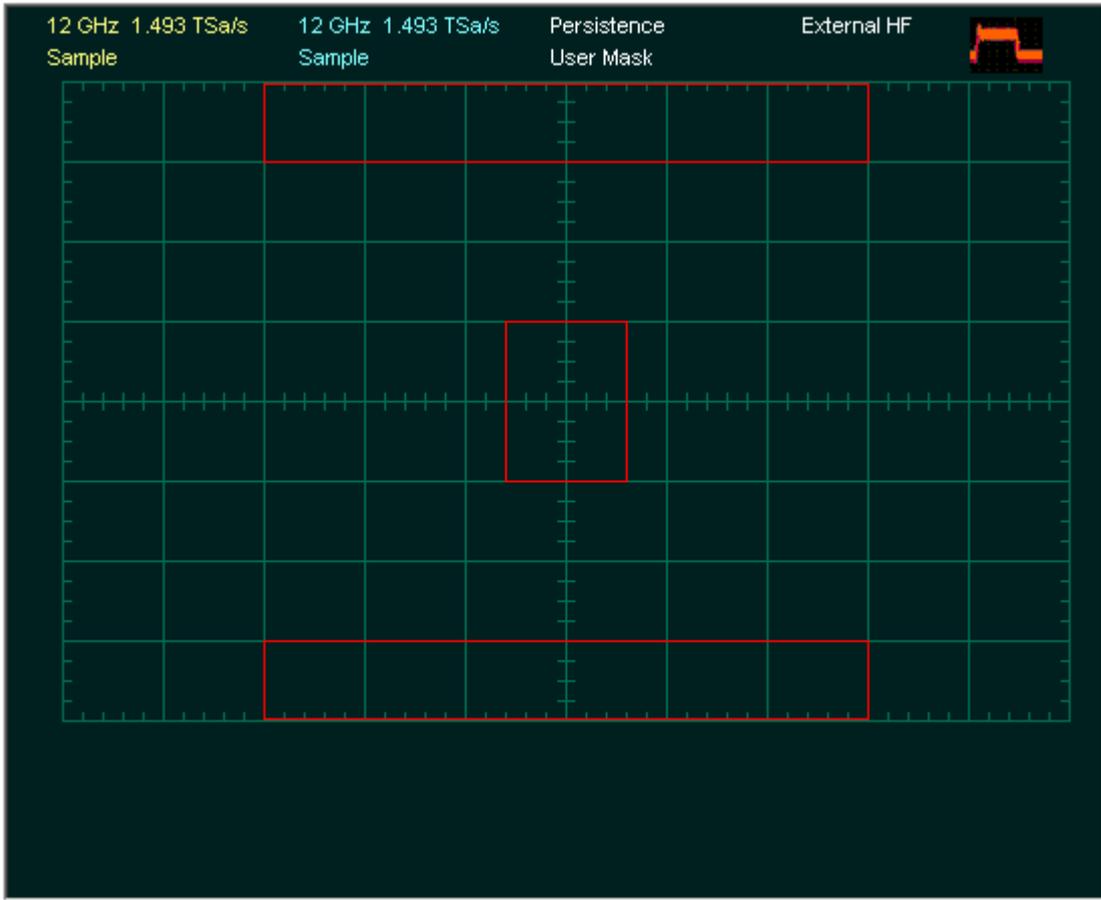
The Delete Polygon function allows you to delete one of the eight polygons.

To delete the polygon

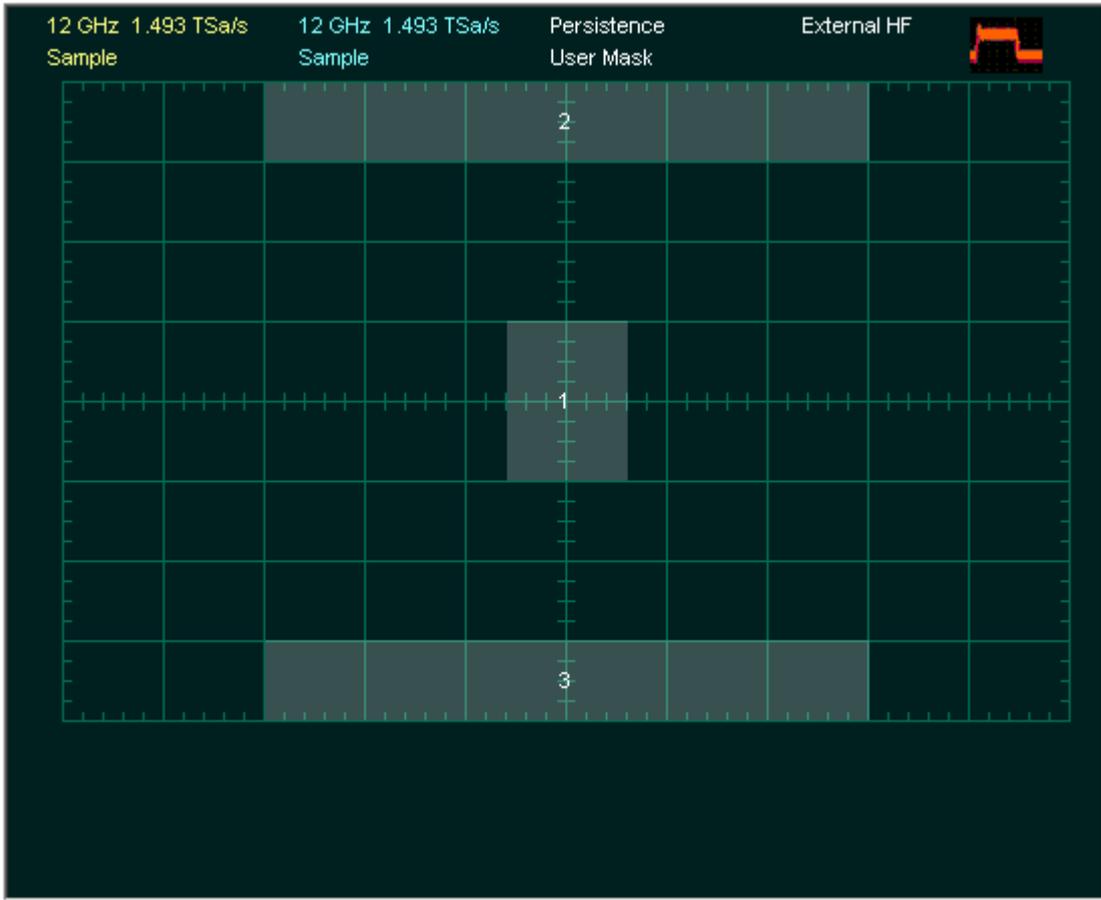
1. Click the Edit Mask button. Click on any vertex of the polygon you want to delete.



2. Click the Delete Polygon button. You will see the mask without the deleted polygon.



3. Click the Back button. The scope returns to high-level menu, and mask gets a new form without deleted polygon.



5.10.1.4.5 Delete Mask



The Delete Mask function allows you to delete the mask that you are editing.

To delete a mask

1. Click the Edit Mask button.
2. Click the Delete Mask button. You will see the screen without the deleted mask.

5.10.1.5 Recall User Mask



Clicking the Recall User Mask button recalls the Windows Recall Mask Dialog. You can recall a saved mask from any drive on the computer. Saved masks have the extension .pcm.

5.10.1.6 Save User Mask

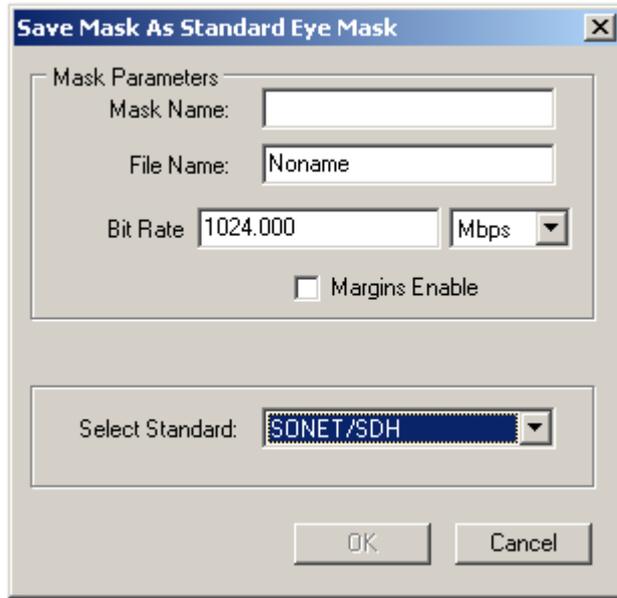


Clicking the Save User Mask button recalls the Windows Save Mask As Dialog. You can save the mask to any drive on the computer. Saved masks have the extension .pcm.

5.10.1.7 Save Mask as Std



Clicking the Save Mask as Std button recalls the Windows Save Mask As Standard Eye Mask dialog.



Windows Save Mask As Standard Eye Mask Dialog

To save the mask as a standard mask, enter all needed information in the dialog, then click OK.

5.10.2 Erase Mask



The Erase Mask function located on the first page of the Mask Test menu allows you to erase the mask that is under test.

To erase the mask click the Erase Mask button. You will see the screen without the deleted mask.

5.10.3 Compare with



The Compare with menu determines which waveform the masks are compared against. You can select from channel 1 or channel 2.

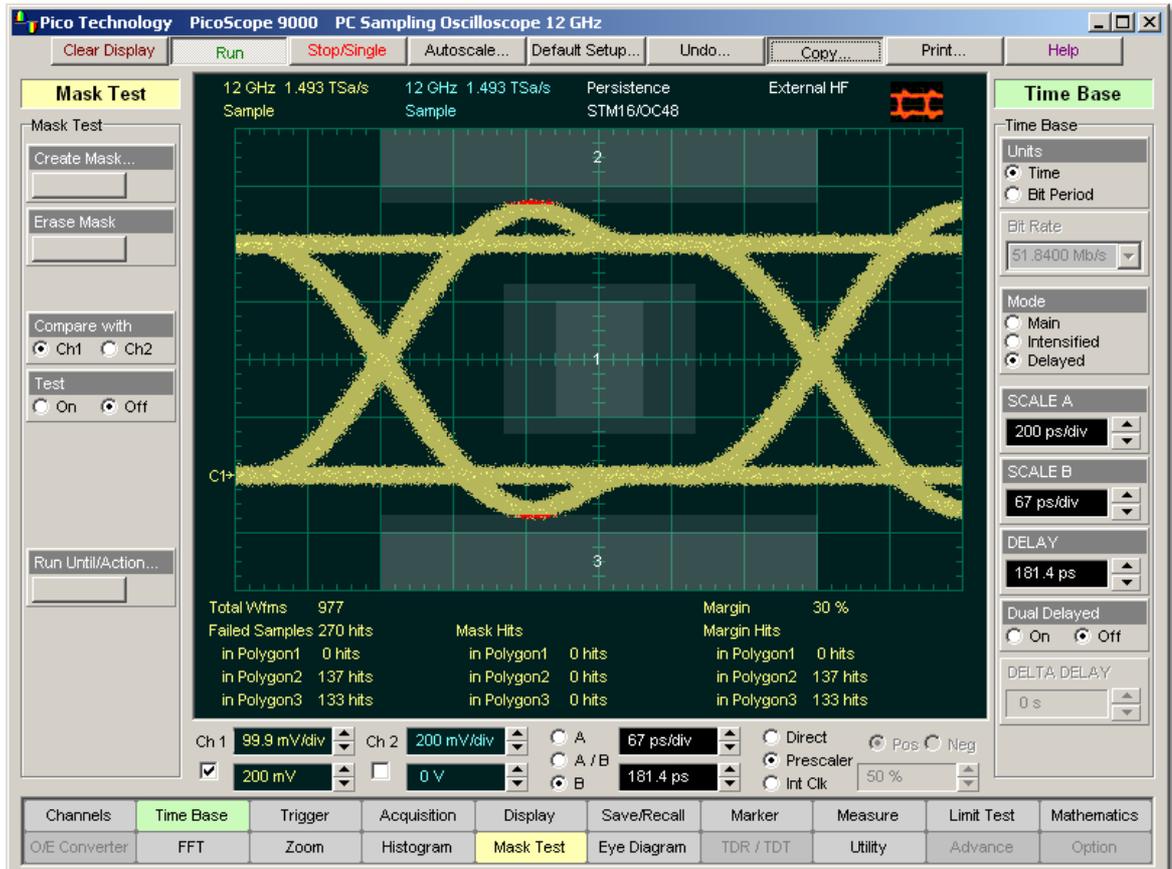
5.10.4 Test



After selecting a mask, you can enable mask counting and see the results of the count. To enable mask counting, click the On button in the Test menu.

If mask testing is on, you can read the results listed in the Measurement Area of the GUI. These values are displayed on tabs. Notice that any acquired data point that falls inside a mask or a mask margin appears in red.

The Mask Test tab displays the relevant test results.



An example of Mask Test

5.10.5 Run Until/Action



The Run Until/Action... button gives you access to a second-level menu that allows you to specify the following functions:

- When the instrument should stop running the mask test
- What the instrument does with the test data after each failure of the mask test, or after the mask test is complete

5.10.5.1 Run Until



The five choices are:

- Run the test until the Stop/Single button is pressed
- Run until a set number of failed waveforms occur
- Run until a set number of failed samples occur
- Run until a set number of waveforms occur
- Run until a set number of samples occur

Stop/Single

The Stop/Single function runs a mask test until the Stop/Single button is pressed. Use the Stop/Single mode when you want the mask test to run continually and not stop after a fixed number of failures or acquisitions. For example, you may want the mask test to run overnight and not be limited by a number of failures or acquisitions.

Failed Wfms

The Failed Wfms function runs the mask test until a set number of failed waveforms are acquired. When the Failed Wfm is selected you can set the number of failures from the [# OF FAILED WFM](#) ^[238] variable.

Failed Samples

The Failed Samples function runs the mask test until a set number of failed samples are acquired. When the Failed Samples is selected you can set the number of failed samples from the [# OF FAILED SMPL](#) ^[238] variable.

Waveforms

The Waveforms function runs the mask test until a set number of waveforms are acquired. When the Waveforms is selected you can set the number of waveforms from the [# OF WAVEFORMS](#) ^[238] variable.

Samples

The Samples function runs the mask test until a set number of samples are acquired. When the Samples is selected you can set the number of samples from the [# OF SAMPLES](#) ^[238] variable.

5.10.5.2 # OF FAILED WFM, # OF FAILED SMPL, # OF WAVEFORMS and # OF SAMPLES



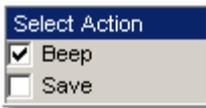
When the Failed Wfms option on the Run Until menu is selected, the # OF FAILED WFM variable sets the number of failed waveforms. After this number is reached, acquisition stops.

When the Failed Samples option on the Run Until menu is selected, the # OF FAILED SMPL variable sets the number of failed samples. After this number is reached, acquisition stops.

When the Waveforms option on the Run Until menu is selected, the # OF WAVEFORMS variable sets the number of waveforms. After this number is reached, acquisition stops.

When the Samples option of the Run Until menu is selected, the # OF SAMPLES variable sets the number of samples. After this number is reached, acquisition stops.

5.10.5.3 Select Action



One of two actions can be selected.

Beep

Beep produces an audio tone when any failure occurs.

Save

Save recalls the Windows Save Waveform As Dialog that allows you to select the type of format you want to save the waveform as. You can select one of three types of waveform formats:

- Binary format with .wfm extension
- Text format with .txt extension
- Both formats with .wfm, and .txt extensions

When a mask test is started, all waveforms that have data points sampled in the mask regions and margin regions (failures) are stored into the memory in the directory Mask Test Files.

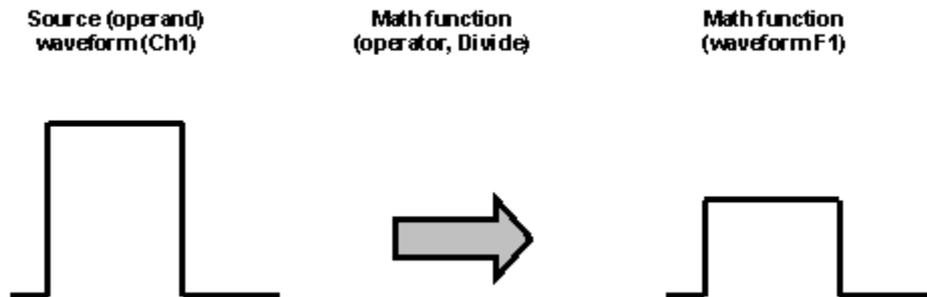
5.11 Mathematics Menu



Waveform analysis

Once you have acquired or taken measurements on waveforms, the oscilloscope can mathematically combine them to create a waveform that supports your data-analysis task. For example, you can define math waveforms mathematically (+, -, x, /). You can also differentiate or integrate a single waveform.

The PicoScope 9000 supports mathematical combination and functional transformation of the waveforms that it acquires. The figure below shows this concept.



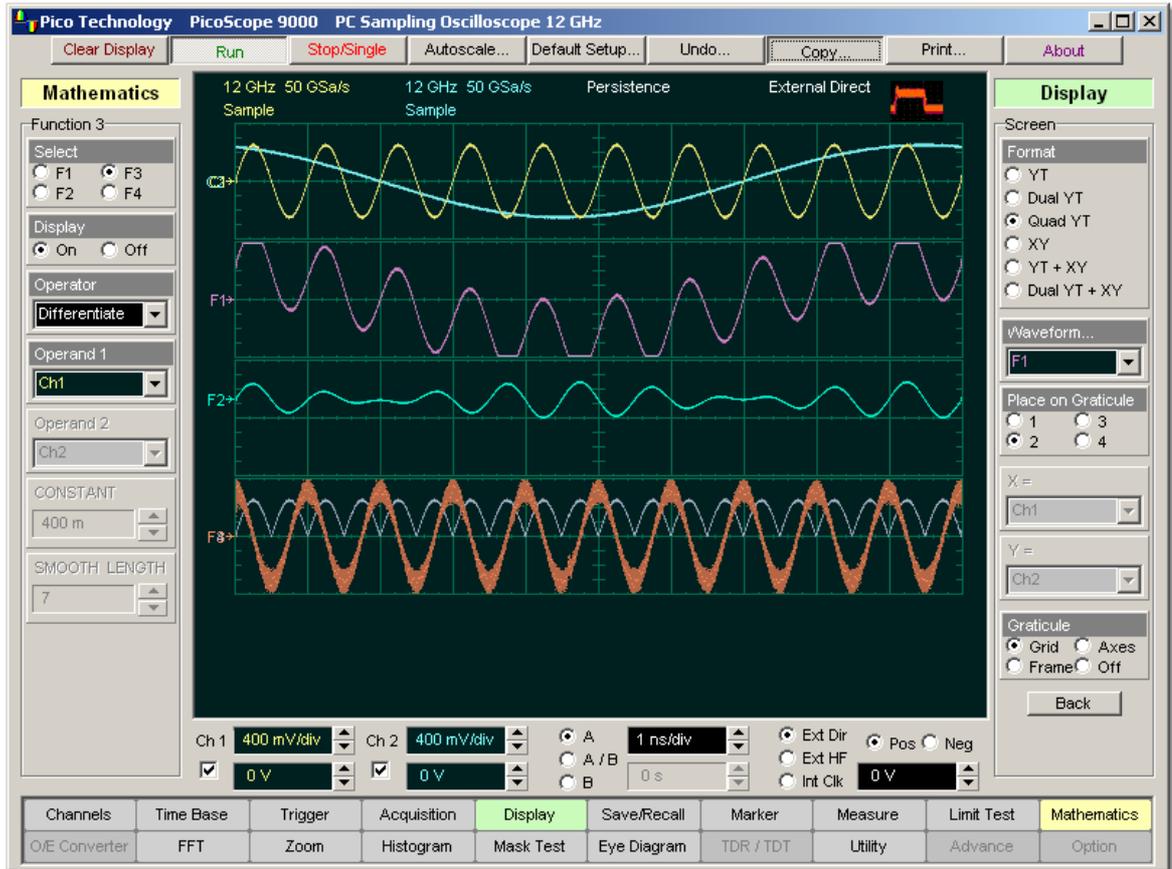
Functional transformation of an acquired waveform

Create math waveforms to support the analysis of your channel and reference waveforms. By combining and transforming source waveforms and other data into math waveforms, you can derive the data view that your application requires.



The Mathematics Menu

The Mathematics menu allows you to define up to four functions. Each function consists of a math operator and either one or two operands. A function is calculated on data adjusted by the calibration factor from a selected source(s), and a new waveform (called a function) is generated by the computation. You can place markers on functions, make measurements on functions, or store functions to waveform memories.



An example of GUI with two channel waveforms and four Math Functions: Ch1: 1-GHz sine-wave; Ch2: 100-MHz sine-wave; F1: Addition (Ch1+Ch2); F2: Multiplication (Ch1xCh2); F3: Differentiate (F1); F4: Absolute (Ch1).

You can use the waveform math function capabilities to perform math operations on one or two source waveforms. For example, you can subtract channel two from channel one to make a differential measurement. Or, if one channel is measuring current and another channel is measuring voltage, you can use a function to multiply the two channels together and display the instantaneous power as a third waveform. This new waveform can then be measured with markers, or automatic measurements, such as Peak-Peak or AC RMS.

You can define up to four functions and, in most cases, a function HF may be used as a source for another function, so the PicoScope 9000 can perform more complex math operations. Select the function you want to define: F1 to F4. Select the operator and source(s) you want to use in the function. If the sources you have selected are active, the scope is triggered, and you will see the display update as you configure the function.

When a function is calculated, it can be displayed on the screen, evaluated with the PicoScope 9000 measurement features, stored in memory or to disk, or used as the source for another function. All math operators, such as invert, subtract, multiply, and divide, are post-processing algorithms so functions are calculated only after their sources have been acquired. All waveform math functions operate on waveform data, which is on the display.



Math operators allow vertical and horizontal scaling of the displayed function. See the [Zoom](#) ^[114] menu for details.

5.11.1 Select



The Select menu allows you to select function F1 to F4.

Clicking the F1 - F4 options:

- selects one of the functions
- assigns the function soft keys to the selected function

5.11.2 Display



Clicking the On / Off options:

- turns the display for the selection on or off
- changes the label from on to off or vice versa



You can display all four functions on the screen at the same time.

5.11.3 Operator



You can select any of the math functions as a math operator to act on the operand or operands. To see the resultant waveform click the Operator drop-down list box and then select a function.

A waveform math operator is a math function that requires either one or two sources. The operators that involve two waveform sources are: Add, Subtract, Multiply, and Divide.

The operators that involve one waveform source are: Invert, Absolute, Exponent (e), Exponent (10), Logarithm (e), Logarithm (10), Differentiate, Integrate, Inverse FFT, Int(erpolation) Linear, Int(erpolation) Sin(x)/x, Smoothing and Trend.

Descriptions of all the math operators

Add

Adds, point by point, operand 1 and operand 2 voltage values. You can use Add to look at the common-mode component of differential waveforms.

Subtract

Subtracts, point by point, operand 2 from operand 1. You can use Subtract to make a differential measurement or to compare two waveforms.

Multiply

Multiplies, point by point, operand 1 and operand 2. Use Multiply to make electrical power measurements.

Divide

Divides, point by point, operand 1 by operand 2 voltage values. You can use Divide to measure the ratio of any two signals, for example the output voltage divided by the input voltage of an amplifier circuit.

Invert

Inverts the voltage values, point by point, of the waveform on operand 1. You can use Invert to compare the input and output of an inverting amplifier.

Absolute

The Absolute value function makes positive all vertical values of the waveform data points on operand 1. The results provide the vertical plot data for a waveform. The horizontal scale is not changed.

Exponent (e)

The natural logarithm base e is raised to an exponent equal to the vertical value of a waveform data point of operand 1. Exponent (e) exponentiates each point of the waveform. The results provide the vertical plot data for a waveform. The horizontal scale is not changed.

Exponent (10)

The base 10 is raised to an exponent equal to the vertical value of a waveform data point of operand 1. Exponent (10) exponentiates each point of the waveform. The results provide the vertical plot data for a waveform. The horizontal scale is not changed.

Logarithm (e)

Takes the natural logarithm (base e) of the vertical value of each waveform data points of operand 1. The natural logarithm results provide the vertical plot data for a waveform. The horizontal scale is not changed.

Logarithm (10)

The Logarithm (10) function converts the absolute vertical values in the waveform record to common logarithms of base 10 of operand 1. The results provide the vertical plot data for a waveform. The horizontal scale is not changed.

Differentiate

Calculates the discrete derivative of the vertical value of the waveform data points of operand 1. You can use Differentiate to measure the instantaneous slope of a waveform. The horizontal scale is not changed. This may be used to measure, for example, the slew rate of an operational amplifier.

Integrate

Calculates the integral of the vertical values of the waveform data points of operand 1. The results provide the vertical plot data for a waveform. The horizontal scale is not changed. This function can be used to calculate the energy of a pulse in volt-seconds or measure the area under a waveform.

Inverse FFT

Calculates the time-domain function from its frequency-domain data (spectrum).

Linear Interpolation

Draws a line between consecutive waveform data points. It gives an analog look to a digitized waveform. For example, you can see steep edges on waveforms, such as square waves.

Sin(x)/x Interpolation

Uses a sin(x)/x digital filter that improves the reconstruction of the waveform. The reconstruction is done by adding data points between the acquired data points. This function improves accuracy of measurements. It is important for waveforms that can be bandlimited to $\frac{1}{4}$ of the current equivalent sample rate.

Smoothing

This allows reduction of unwanted noise and jitter on the signal with a simple, moving-average filter. N-point smoothing can be done with up to a 51-point filter. The number of points N can be selected by the [SMOOTH LENGTH](#)^[245] variable.

Trend

Trend represents the evolution of timing parameters as line graphs whose vertical axes are the value of the parameter, and horizontal axes the order in which the values were acquired. The information obtained from applying timing parameters can then be analysed using the trend.

5.11.4 Operand 1 & Operand 2



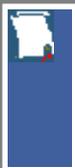
The instrument performs math functions on the source(s) (operands) you select. The math operator is performed either on operand 1, or on operand 1 and operand 2. The number of operands used depends on the math operator you select. For example, Add requires two operands while Invert requires only one operand.

The Operand 1 or Operand 2 menus let you select from:

- channels
- functions
- waveform memories
- spectrums
- constants

You should be aware of some conditions of the math function menu:

- If the operand waveforms have different record length, the function uses the shortest record length. The instrument finds the nearest point in the longer waveform record that corresponds to the current point in the shorter record. It then performs math functions on those points and skips non-corresponding points in the longer record.
- If two operands have the same timebase scale, the resulting function has the same timebase scale, which results in the proper time scale for the function.
- If two operands have different horizontal scale settings (possibly when using a waveform memory as a operand) the resulting function has the same horizontal scale as operand 1.
- Constant operands have the same time scale as the associated waveform operand.
- You can use each function as an operand for another function. This allows you to construct equations with a large number of operators and operands.



If you select a math operator that uses more than one operand, select the source 2 from the Operand 2 drop down list box. When the Constant option is selected in the Operand 2 drop-down list box the [CONSTANT](#) variable becomes active.

5.11.5 Constant



You can use the CONSTANT variable to control the value of operand 2 from -100 million to 100 million.

5.11.6 SMOOTH LENGTH



The SMOOTH LENGTH variable defines the number of points N in the moving-average filter used for the smoothing operator. N-point smoothing can be selected from 3 up to 51 points.

5.12 Measure Menu

A rectangular button with a light gray background and a thin black border. The word "Measure" is centered on the button in a dark gray, sans-serif font.

With automatic measurements, you just press a few buttons and the sampling oscilloscope does the calculations for you. Because these measurements use the waveform record points directly, they are more accurate than markers or graticules.

Measurements cover voltage, timing, and FFT. Amplitude measurements are made on vertical parameters, typically voltage. They include such parameters as Maximum, Peak-Peak, Middle, and RMS. Timing measurements are made on horizontal parameters, typically seconds or hertz. They include such parameters as Period, Width and Rise Time. FFT measurements are made on both vertical and horizontal parameters, typically volts and hertz. They include such parameters as FFT Magnitude and FFT Frequency. Measurements made on two channels can include amplitude and timing parameters.

Each measurement relates to the source that was active when you selected that measurement. It remains displayed until you remove it. If you turn off the source that was selected for a measurement, only the last measured result will be displayed.

The PicoScope 9000 makes measurements after every trigger event, always maintaining continuity between the measurement results and the display. This makes sure that no aberration in the waveform under observation is missed.

You can set measurement markers (thresholds and margins) on the display as defined parameters to track the measurement results. This helps you verify that the oscilloscope is measuring the correct phenomena and to aid in windowing the waveform properly for measurement.

<p>Measure</p> <p>Measure</p> <p>Display</p> <p><input type="radio"/> Off</p> <p><input type="radio"/> Parameters</p> <p><input checked="" type="radio"/> Statistics</p> <p>Source</p> <p>Ch1</p> <p>X Parameters...</p> <p>Y Parameters...</p> <p>Dual-Chan Param...</p> <p>Define Param...</p> <p>View Define Param</p> <p><input checked="" type="radio"/> On <input type="radio"/> Off</p> <p>Mode</p> <p><input type="radio"/> Repetitive</p> <p><input checked="" type="radio"/> Single-shot</p> <p>Single</p>	<p>Measure</p> <p>X Parameters</p> <p>Timing Parameters</p> <p><input type="checkbox"/> Period</p> <p><input type="checkbox"/> Frequency</p> <p><input type="checkbox"/> Pos Width</p> <p><input type="checkbox"/> Neg Width</p> <p><input type="checkbox"/> Rise Time</p> <p><input type="checkbox"/> Fall Time</p> <p><input type="checkbox"/> Pos Duty Cycle</p> <p><input type="checkbox"/> Neg Duty Cycle</p> <p><input type="checkbox"/> Pos Crossing</p> <p><input type="checkbox"/> Neg Crossing</p> <p><input type="checkbox"/> Burst Width</p> <p><input type="checkbox"/> Cycles</p> <p><input type="checkbox"/> Time@Maximum</p> <p><input type="checkbox"/> Time@Minimum</p> <p><input type="checkbox"/> Pos Jitter p-p</p> <p><input type="checkbox"/> Pos Jitter RMS</p> <p><input type="checkbox"/> Neg Jitter p-p</p> <p><input type="checkbox"/> Neg Jitter RMS</p> <p>Back</p>	<p>Measure</p> <p>Y Parameters</p> <p>Amplitude Paramete</p> <p><input type="checkbox"/> Maximum</p> <p><input type="checkbox"/> Minimum</p> <p><input type="checkbox"/> Peak-Peak</p> <p><input type="checkbox"/> Top</p> <p><input type="checkbox"/> Base</p> <p><input type="checkbox"/> Amplitude</p> <p><input type="checkbox"/> Middle</p> <p><input type="checkbox"/> Mean</p> <p><input type="checkbox"/> dc RMS</p> <p><input type="checkbox"/> ac RMS</p> <p><input type="checkbox"/> Area</p> <p><input type="checkbox"/> Cycle Mean</p> <p><input type="checkbox"/> Cycle dc RMS</p> <p><input type="checkbox"/> Cycle ac RMS</p> <p><input type="checkbox"/> Cycle Area</p> <p><input type="checkbox"/> Pos Overshoot</p> <p><input type="checkbox"/> Neg Overshoot</p> <p>Back</p>	<p>Measure</p> <p>Dual-Chan Parameter:</p> <p>Source 2</p> <p>Ch2</p> <p>Timing Parameters</p> <p><input checked="" type="checkbox"/> Delay 1R-1R</p> <p><input type="checkbox"/> Delay 1R-1F</p> <p><input type="checkbox"/> Delay 1F-1R</p> <p><input type="checkbox"/> Delay 1F-1F</p> <p><input type="checkbox"/> Delay 1R-nR</p> <p><input type="checkbox"/> Delay 1R-nF</p> <p><input type="checkbox"/> Delay 1F-nR</p> <p><input type="checkbox"/> Delay 1F-nF</p> <p><input type="checkbox"/> Phase Deg</p> <p><input type="checkbox"/> Phase Rad</p> <p><input type="checkbox"/> Phase %</p> <p>Amplitude Paramete</p> <p><input checked="" type="checkbox"/> Gain</p> <p><input type="checkbox"/> Gain dB</p> <p>Back</p>	<p>Measure</p> <p>FFT Parameters</p> <p>FFT Freq Parameter</p> <p><input type="checkbox"/> FFT Freq</p> <p><input type="checkbox"/> FFT dFreq</p> <p>FFT Magnitude Para</p> <p><input type="checkbox"/> FFT Magnit</p> <p><input type="checkbox"/> FFT dMagnit</p> <p><input type="checkbox"/> THD</p> <p>PEAK LEFT</p> <p>1</p> <p>PEAK RIGHT</p> <p>3</p> <p>Back</p>
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<p>Measure</p> <p>Define Param.</p> <p>Statistics...</p> <p>Method</p> <p><input checked="" type="radio"/> Histogram</p> <p><input type="radio"/> Min / Max</p> <p><input type="radio"/> User Defined</p> <p>TOP</p> <p>400 mV</p> <p>BASE</p> <p>-400 mV</p> <p>Thresholds</p> <p><input checked="" type="radio"/> 10%-50%-90%</p> <p><input type="radio"/> 20%-50%-80%</p> <p><input type="radio"/> User Defined</p> <p>Defined Thresholds</p> <p>Margins...</p> <p>Back</p>	<p>Measure</p> <p>Define Thresholds</p> <p>Units</p> <p><input checked="" type="radio"/> Percent</p> <p><input type="radio"/> Vertical Unit</p> <p><input type="radio"/> Division</p> <p>UPPER THRESHOLD</p> <p>90 %</p> <p>MIDDLE THRESHOLD</p> <p>50 %</p> <p>LOWER THRESHOLD</p> <p>10 %</p> <p>Back</p>	<p>Measure</p> <p>Statistics</p> <p>Mode</p> <p><input type="radio"/> Normal</p> <p><input checked="" type="radio"/> /Window</p> <p><input type="radio"/> Exponential</p> <p>WAVEFORMS</p> <p>8</p> <p>Back</p>	<p>Measure</p> <p>Margins</p> <p>Mode</p> <p><input type="radio"/> Waveform</p> <p><input checked="" type="radio"/> Marker</p> <p>LEFT MARGIN</p> <p>0 s</p> <p>Left Threshold</p> <p><input type="radio"/> Upper</p> <p><input checked="" type="radio"/> Middle</p> <p><input type="radio"/> Lower</p> <p>RIGHT MARGIN</p> <p>50 ns</p> <p>Right Threshold</p> <p><input type="radio"/> Upper</p> <p><input checked="" type="radio"/> Middle</p> <p><input type="radio"/> Lower</p> <p>Back</p>	<p>Measure</p> <p>FFT Define Param.</p> <p>Method</p> <p><input checked="" type="radio"/> Harmonic</p> <p><input type="radio"/> Peak</p> <p>LEFT MARGIN</p> <p>122.07 kHz</p> <p>RIGHT MARGIN</p> <p>488.28 MHz</p> <p>PEAK LEVEL</p> <p>-20 dB</p> <p>PEAK LEFT</p> <p>1</p> <p>PEAK RIGHT</p> <p>3</p> <p>Back</p>
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Measurement Results

The measurement readouts appear in the Measurement Area of the screen. These values are displayed on tabs. The readouts are continuously updated as the oscilloscope acquires new data or as you change settings. You can display as many as ten measurements of parameters, continuously updated, and as many as four statistics measurements at any one time.

Frequency (Ch1)	100.1 MHz	Period (Ch2)	1.997 ns
Rise Time (Ch1)	2.907 ns	Pos Width (Ch2)	996.5 ps
Amplitude (Ch1)	988 mV	Cycles (Ch2)	24
Peak-Peak (Ch1)	1.003 V	Amplitude (Ch2)	999.3 mV
Top (Ch1)	493.5 mV	Base (Ch2)	5.718 mV

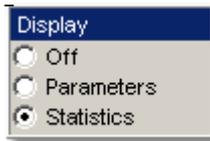
Measure tab with the results of ten automated parameter measurements

	Current	Total Wfms	Minimum	Maximum	Mean	Std Deviation
Frequency (Ch1)	100.1 MHz	58578	100.1 MHz	100.2 MHz	100.1 MHz	9.178 kHz
Peak-Peak (Ch1)	1.002 V	58578	999.9 mV	1.006 V	1.003 V	834.5 μ V
Amplitude (Ch2)	998.7 mV	4322	998.1 mV	999.9 mV	999 mV	245.3 μ V
Pos Width (Ch2)	996.4 ps	4074	996.2 ps	996.6 ps	996.4 ps	51.85 fs

Measure tab with the results of four statistics measurements

When the instrument cannot make the requested measurement, an error message "Undefined" is displayed instead of measurement results. Usually, this is because there are not enough sample points, there is no edge on the display, or the specified channel is turned off.

5.12.1 Display



Two types of measurements are used in the PicoScope 9000:

- Measurements of parameters (Parameters)
- Statistics measurements (Statistics)

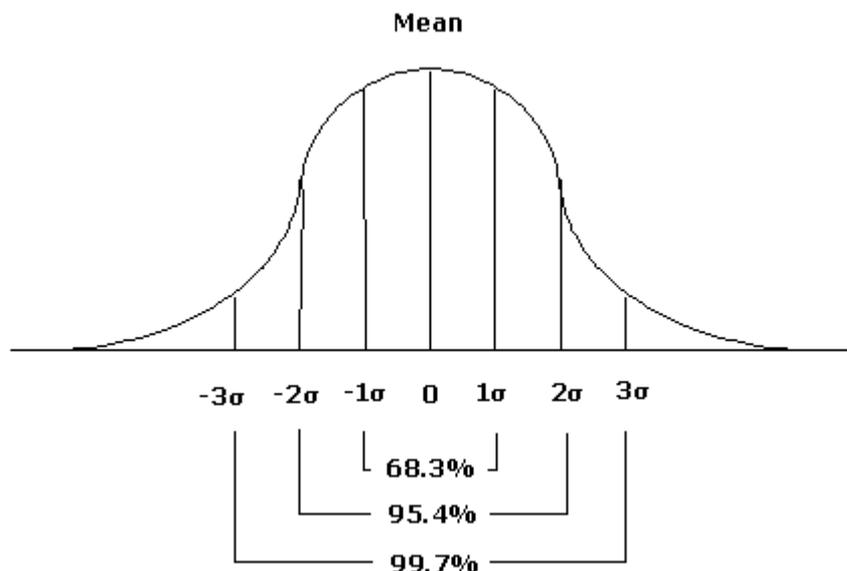
Click on the option for the type of measurement that you require. Off removes the measurement results and markers from the display.

Statistics

The Statistics function calculates the minimum, maximum, mean and standard deviation of the automatic measurement results. The current value and amount of measurements are also displayed.

When you turn Statistics on, the minimum, maximum, mean and standard deviation values start to accumulate at the same time. All results are continuously updated; the mean, standard deviation results are also calculated and continuously updated. Minimum and maximum are the absolute extremes of the automatic measurements. Mean and standard deviation calculate the mean and standard deviation of the automatic measurement results. Mean is the statistical average of all results for a particular measurement. Standard deviation measures the dispersion of those measurement results.

The figure below shows the mean and standard deviation more graphically. Standard deviation is represented by the Greek letter sigma (σ). For a Gaussian distribution, two sigma (± 1 from the mean) is where 68.3 percent of the data points reside. Four sigma (± 2 from the mean) is where 95.4 percent of the data points reside. Six sigma (± 3 from the mean) is where 99.7 percent of the data points reside.



Standard deviation of a Gaussian distribution

The mean is calculated as follows:

$$\sigma = \frac{\sum_{i=1}^N (X_i - \bar{X})^2}{N-1}$$

where: μ - mean, N – the number of taken measurements, X_i - measurement i -th result.

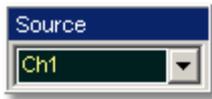
The standard deviation is calculated as follows:

$$\mu = \frac{\sum_{i=1}^N X_i}{N}$$

where: σ - mean, N – the number of taken measurements, X_i - measurement i -th result, \bar{X} - the mean.

Click the Define Param... button and open the Statistics... menu for some statistics options.

5.12.2 Source



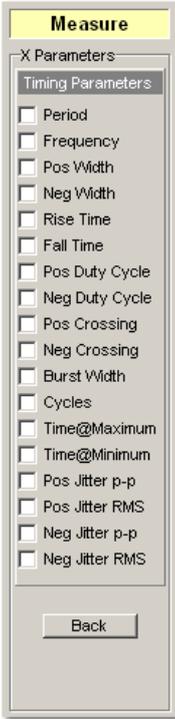
The Source drop-down list box selects the source you are measuring.

You can select as the source:

- channels 1 and 2
- functions 1 through 4
- waveform memories 1 through 4
- spectrums 1 and 2

The measurement readouts of each parameter will have the same color as the selected source.

5.12.3 X Parameters...



Clicking the X Parameters... button opens the list of timing parameters. The list includes eighteen timing parameters used for pulse measurements. Once the Top and Base calculation area is completed, most of the amplitude measurements can be made.



You can continuously update as many as ten parameter measurements, and as many as four statistics measurements at any one time.

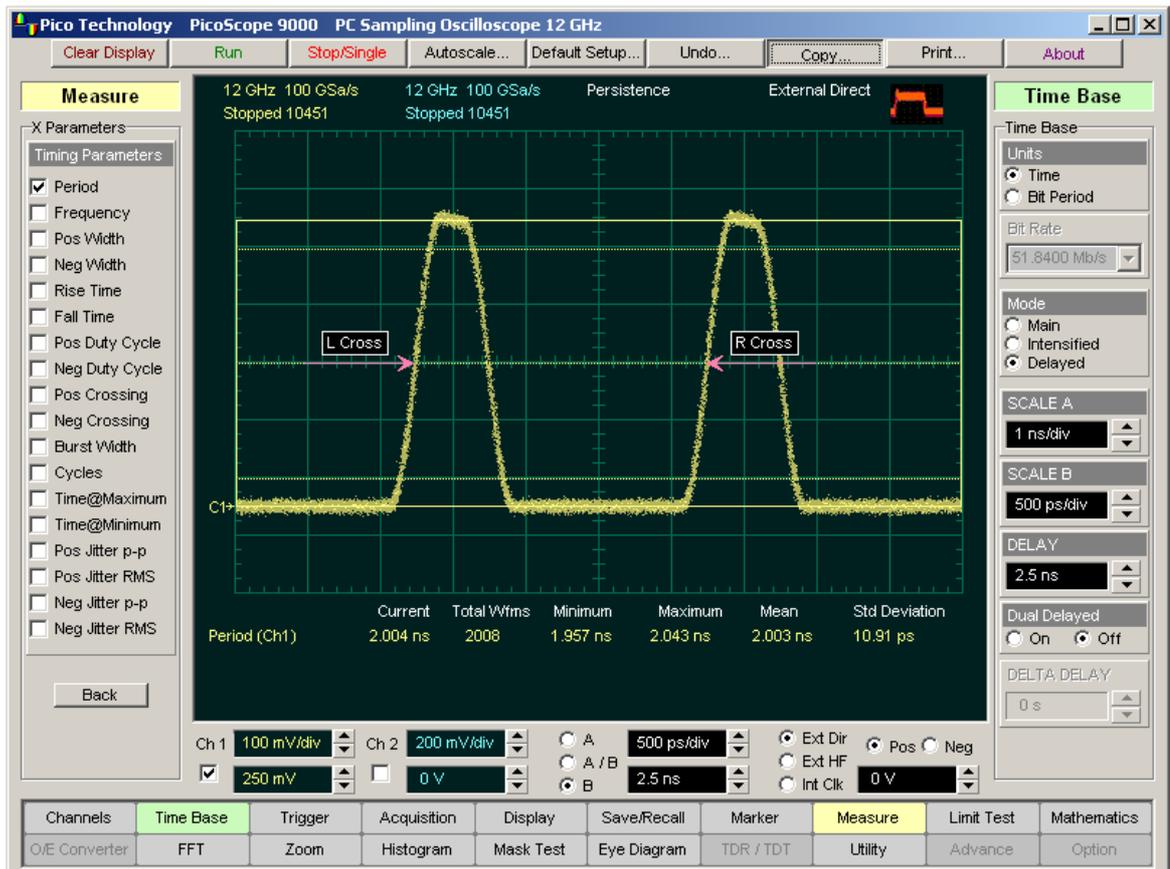


The pulse measurement algorithms for X Parameters will only work when a single-valued signal is used, and no NRZ eye diagram or RZ eye diagram is present on the screen. Measurements made on both NRZ and RZ eye diagrams will fail.

5.12.3.1 Period



Period is a measure of the time between the mid-threshold crossings of two consecutive edges of the same polarity. The PicoScope 9000 starts the measurement on the first edge on the left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the measurement region (right margin).



Period definition

Because the detected edges can be either rising or falling, the period is determined as follows:

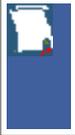
$$\text{Period} = T_{\text{cross3}} - T_{\text{cross1}}$$

where T_{cross3} and T_{cross1} are the times of the first two consecutive crossings on the same slope at the mid-reference level.

If more than one period/div can be found within the margins, the scope measures the average period.

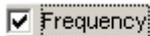


The [Margins...](#) menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of period value will be performed only inside these margins.

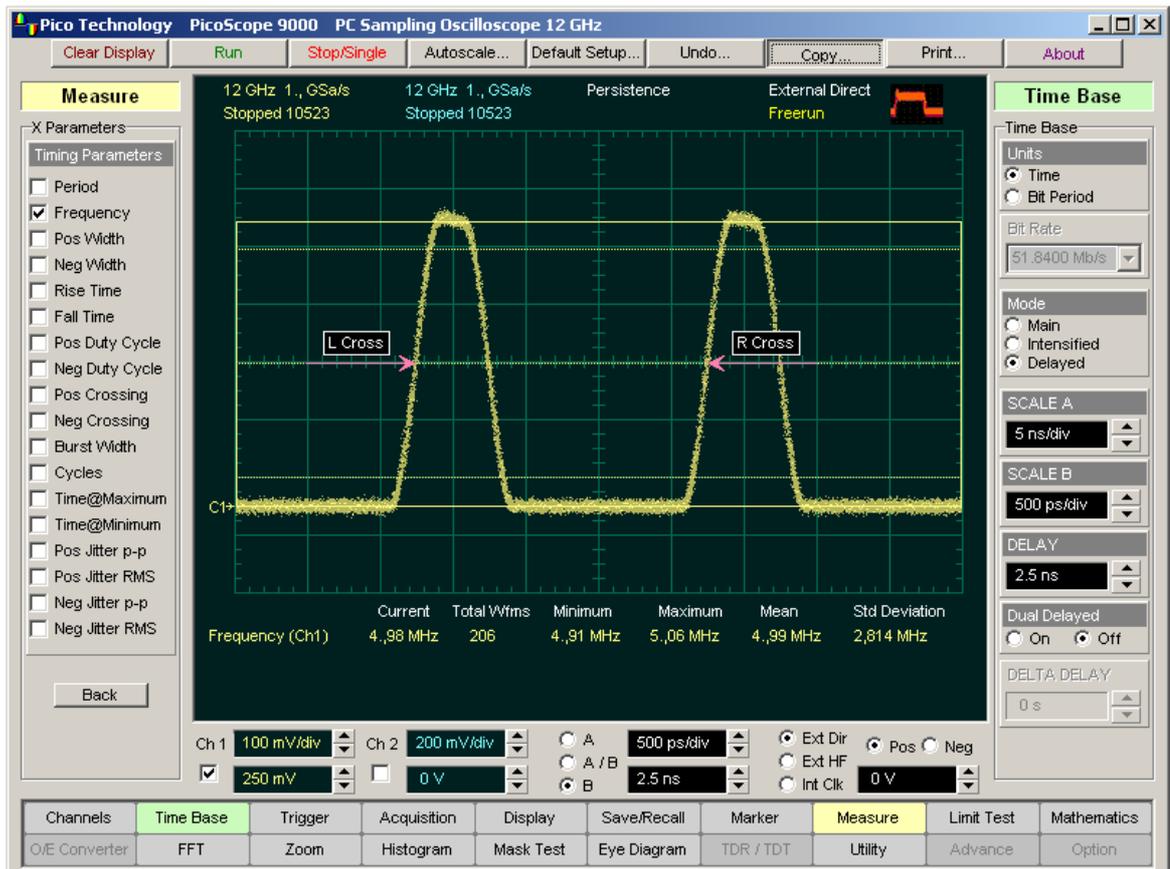


Period value is affected by the [Define Param...](#)³⁰⁵ menu. In the [Defined Thresholds](#)³¹⁰ menu you can redefine the mid-threshold setting from 50% to any other level you want.

5.12.3.2 Frequency



Frequency is defined as the inverse of the period (1/period). Period is a measure of the time between the mid-threshold crossings of two consecutive edges of the same polarity. The PicoScope 9000 starts the measurement on the first edge on the left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the measurement region (right margin).



Frequency definition

Because the detected edges can be either rising or falling, the frequency is determined as follows:

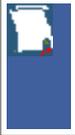
$$\text{Frequency} = 1/\text{Period} = 1/(T_{\text{cross3}} - T_{\text{cross1}})$$

where T_{cross3} and T_{cross1} are the times of the first two consecutive crossings on the same slope at the mid-reference level.

If more than one period/div can be found within the margins, the scope measures the average frequency value.



The [Margins...](#) menu sets the margin markers to see where scope is making the automatic measurement. All calculations of frequency value will be performed only inside these margins.

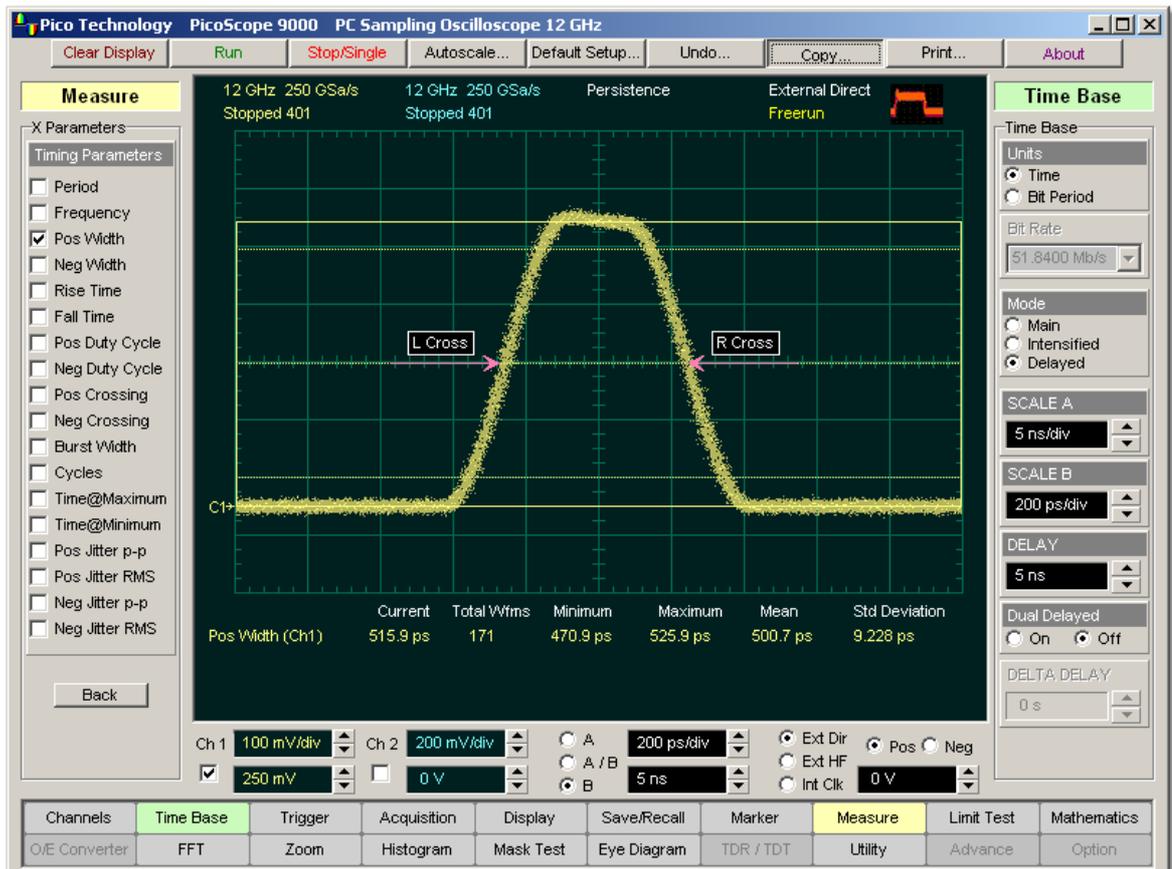


Frequency value is affected by the [Define Param...](#)^[305] menu. In the [Defined Thresholds](#)^[310] menu you can redefine the mid-threshold setting from 50% to any other level you want.

5.12.3.3 Positive Width



Positive Width is a measure of the time from the mid-threshold of the first rising edge to the mid- threshold of the next falling edge. The PicoScope 9000 starts the measurement on the first edge on the left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the measurement region (right margin).



Positive Width definition

Positive pulse width is determined as follows:

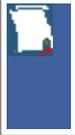
$$Positive\ Width = T_{cross2} - T_{cross1}$$

where T_{cross1} and T_{cross2} are the two consecutive horizontal crossings on the first positive pulse.

If more than one positive pulse width can be found within the margins, the scope measures the average value of the positive pulse width.



The [Margins...](#) menu sets the margin markers to see where scope is making the automatic measurement. All calculations of positive pulse width value will be performed only inside these margins.

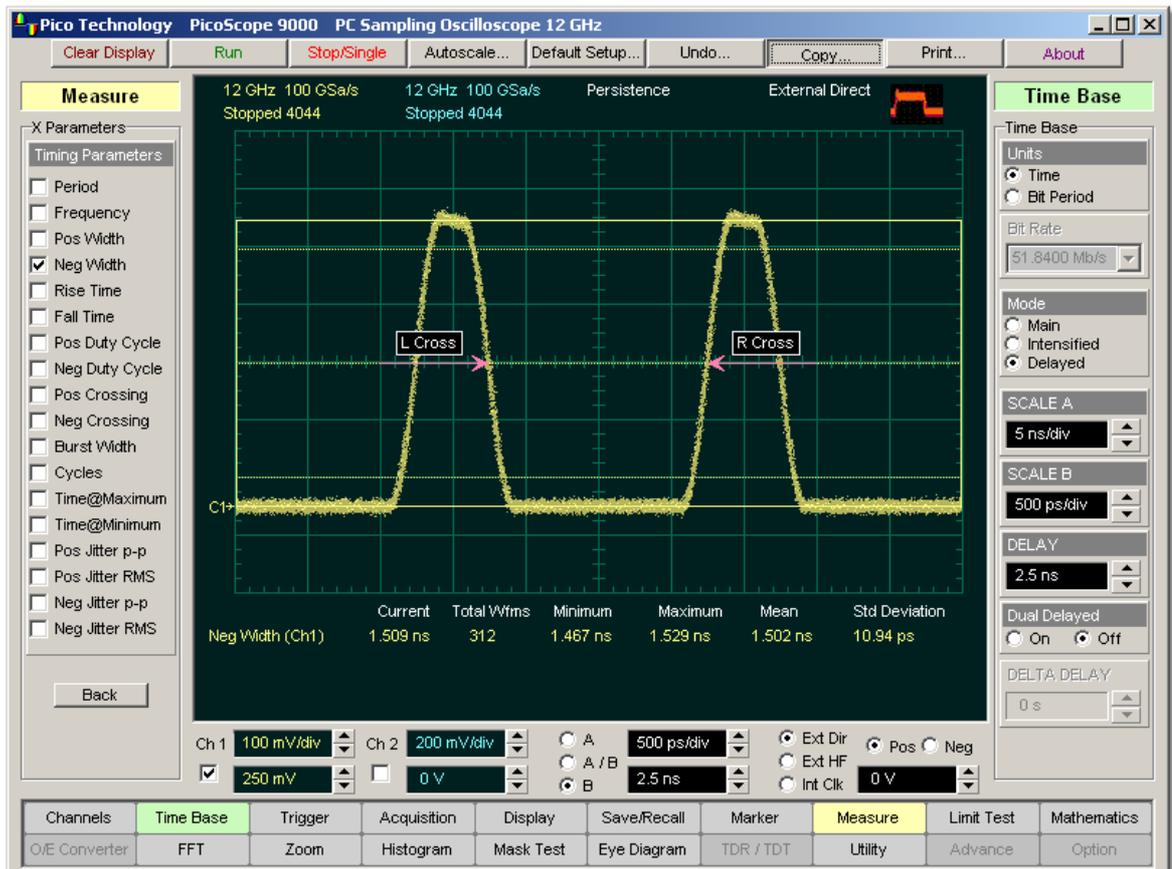


Positive pulse width value is affected by the [Define Param...](#) menu. In the [Defined Thresholds](#) menu you can redefine the mid-threshold setting from 50% to any other level you want.

5.12.3.4 Negative Width



Neg Width (Negative Pulse Width) is a measure of the time from the mid-threshold of the first falling edge to the mid-threshold of the next rising edge. The PicoScope 9000 starts the measurement on the first edge on the left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the measurement region (right margin).



Negative Width definition

Negative pulse width is determined as follows:

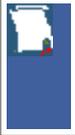
$$\text{Negative Width} = T_{\text{cross2}} - T_{\text{cross1}}$$

where T_{cross1} and T_{cross2} are the two consecutive horizontal crossings on the first negative pulse.

If more than one negative pulse width can be found within the margins, the scope measures the average value of the negative pulse width.



The [Margins...](#) menu sets the margin markers to see where scope is making the automatic measurement. All calculations of negative pulse width value will be performed only inside these margins.

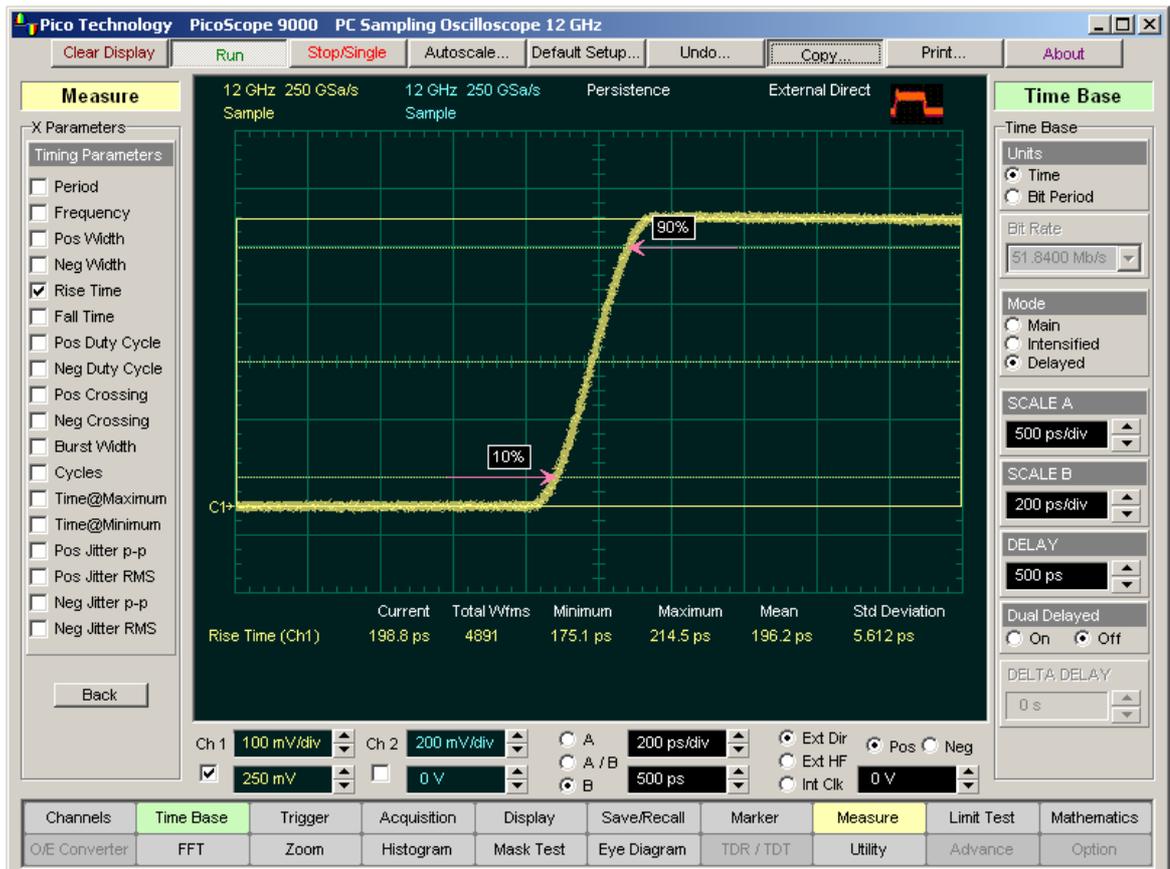


Negative pulse width value is affected by the [Define Param...](#)³⁰⁵ menu. In the [Defined Thresholds](#)³¹⁰ menu you can redefine the mid-threshold setting from 50% to any other level you want.

5.12.3.5 Rise Time



Rise Time is a measure of the time at the upper threshold minus the time at the lower threshold on the edge you are measuring on. It is a measure of the transition time of the data on the positive (rising) edge of a waveform. The PicoScope 9000 starts the measurement on the first edge on the left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the measurement region (right margin).



Rise Time definition

Rise Time is determined as follows:

$$\text{Rise Time} = T_{\text{crossUT}} - T_{\text{crossLT}}$$

where T_{crossUT} is the time of crossing with the upper threshold, and T_{crossLT} is the time of crossing with the lower threshold.

If more than one rise time can be found within the margins, the scope measures the average value of rise time.

The rise time will not be measured until the rising edge completes the transition through all three levels.



The [Margins...](#)^[312] menu sets the margin markers to see where scope is making the automatic measurement. All calculations of rise time value will be performed only inside these margins.

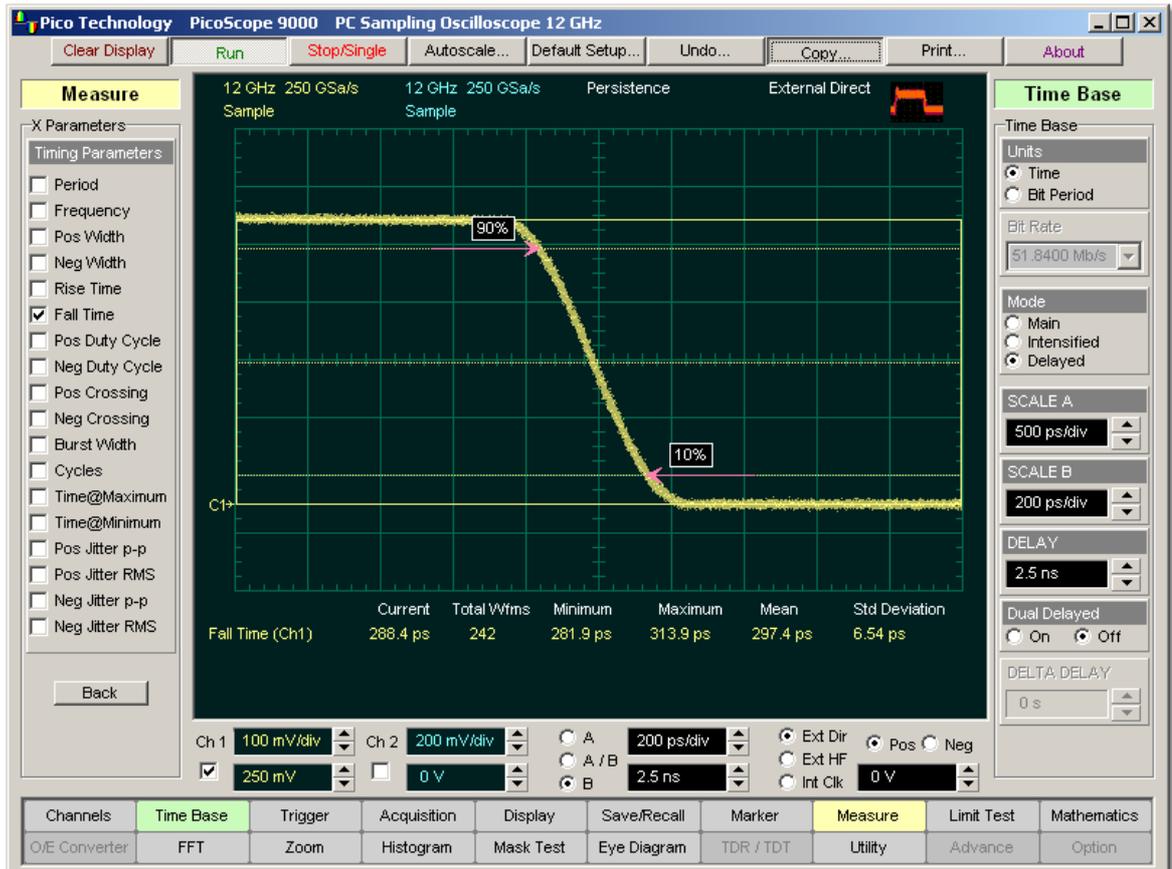


Rise time value is affected by the [Define Param...](#)^[305] menu. In the [Defined Thresholds](#)^[310] menu you can redefine the mid-threshold setting from 50% to any other level you want.

5.12.3.6 Fall Time



Fall time is a measure of the time at the lower threshold minus the time at the upper threshold on the edge you are measuring on. It is a measure of the transition time of the data on the negative (falling) edge of a waveform. The PicoScope 9000 starts the measurement on the first edge on the left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the measurement region (right margin).



Fall Time definition

Fall Time is determined as follows:

$$Fall\ Time = T_{crossLT} - T_{crossUT}$$

where $T_{crossUT}$ is the time of crossing with the upper threshold, and $T_{crossLT}$ is the time of crossing with the lower threshold.

If more than one fall time can be found within the margins, the scope measures the average value of rise time.

The fall time will not be measured until the falling edge completes the transition through all three levels.

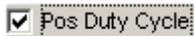


The [Margins...](#)³¹² menu sets the margin markers to see where scope is making the automatic measurement. All calculations of fall time value will be performed only inside these margins.

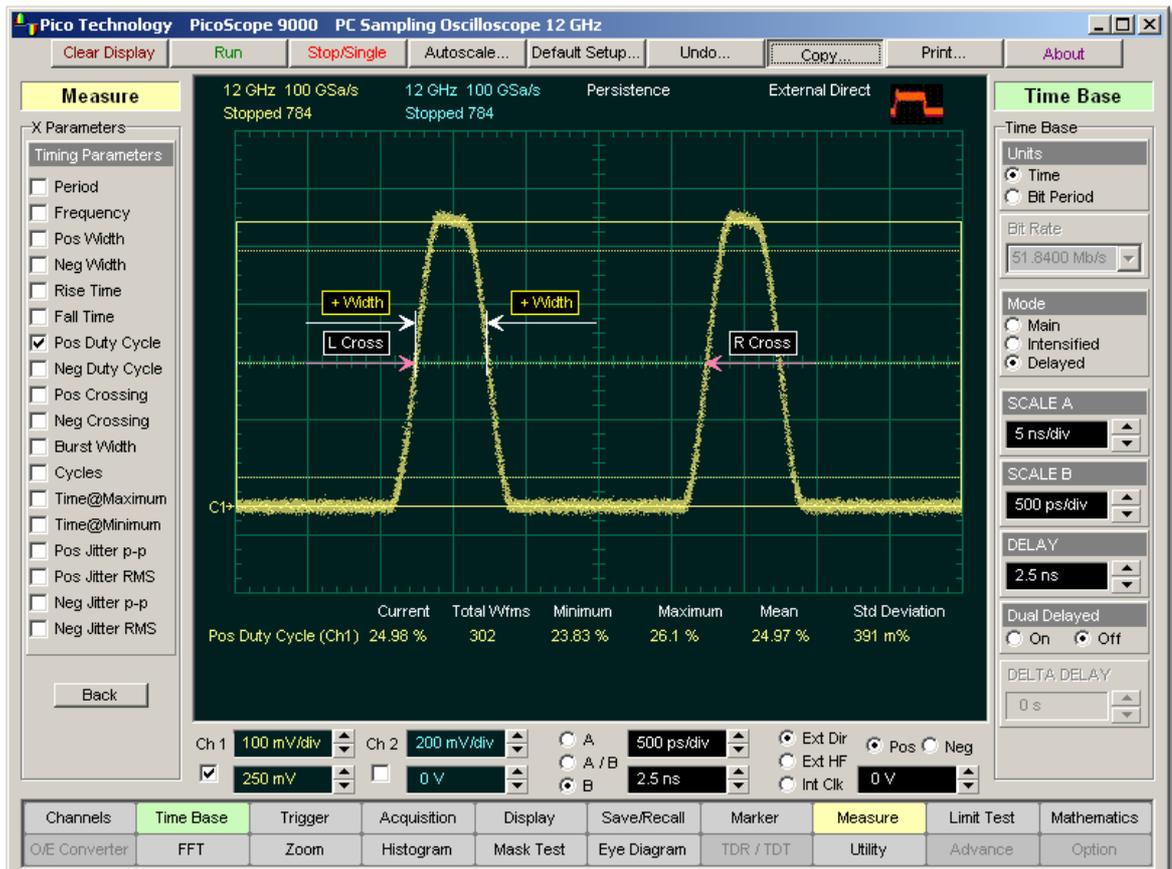


Fall time value is affected by the [Define Param...](#)³⁰⁵ menu. In the [Defined Thresholds](#)³¹⁰ menu you can redefine the mid-threshold setting from 50% to any other level you want.

5.12.3.7 Positive Duty Cycle



Positive Duty Cycle is defined as the ratio of the positive pulse width to the period. This is the percentage of the period that the positive pulse width occupies. The PicoScope 9000 starts the measurement on the first edge on the left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the measurement region (right margin).



Positive Duty Cycle definition

Positive Duty Cycle is determined as follows:

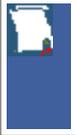
$$\text{Positive Duty Cycle} = (\text{Positive Width} / \text{Period}) * (100\%)$$

If more than one positive duty cycle can be found within the margins, the scope measures the average value of all positive duty cycles.

The positive duty cycle will not be measured until the period and positive pulse width complete the transition through all three levels.



The [Margins...](#) menu sets the margin markers to see where scope is making the automatic measurement. All calculations of positive duty cycle value will be performed only inside these margins.

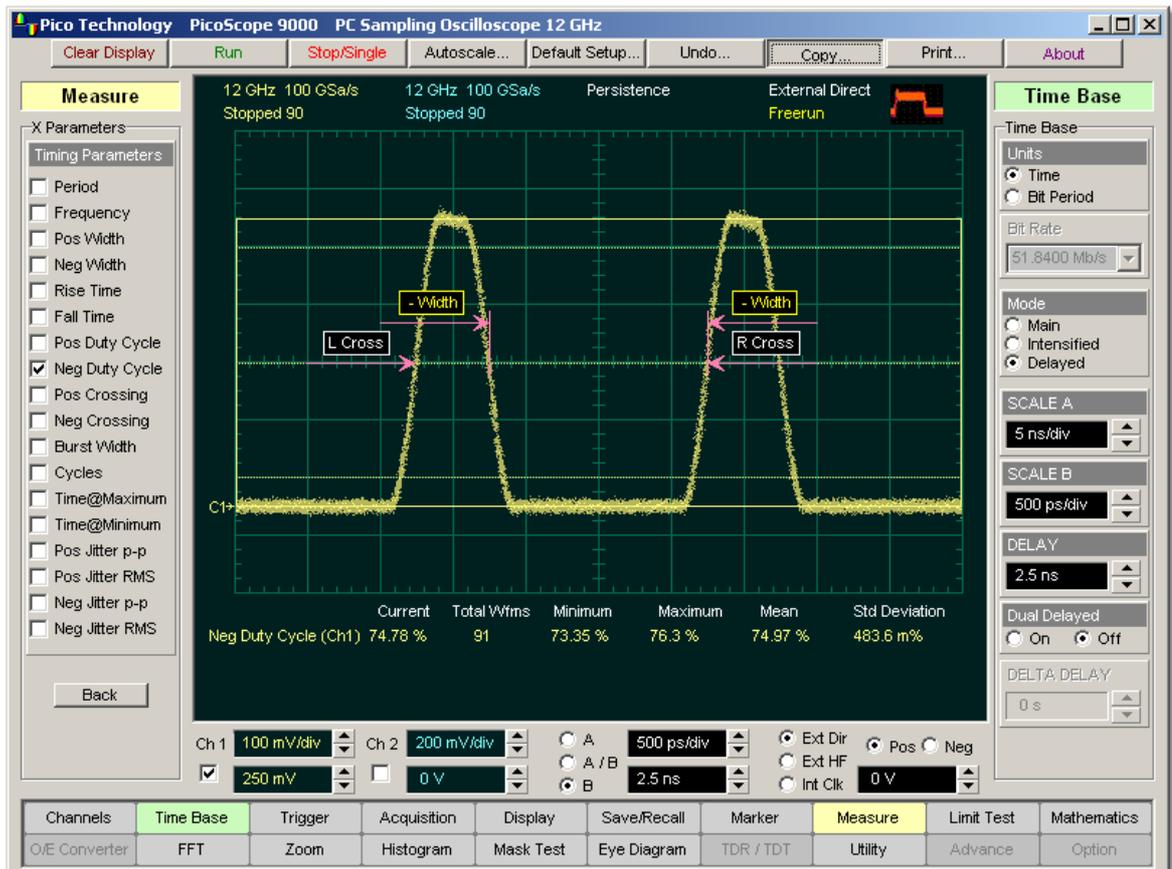


Positive duty cycle value is affected by the [Define Param...](#)³⁰⁵ menu. In the [Defined Thresholds](#)³¹⁰ menu you can redefine the mid-threshold setting from 50% to any other level you want.

5.12.3.8 Negative Duty Cycle



Negative Duty Cycle is defined as the ratio of the negative pulse width to the period. This is the percentage of the period that the negative pulse width occupies. The PicoScope 9000 starts the measurement on the first edge on the left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the measurement region (right margin).



Negative Duty Cycle definition

Negative Duty Cycle is determined as follows:

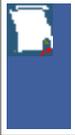
$$\text{Negative Duty Cycle} = (\text{Negative Width} / \text{Period}) * (100\%)$$

If more than one negative duty cycle can be found within the margins, the scope measures the average value of all negative duty cycles.

The negative duty cycle will not be measured until the period and negative pulse width completes the transition through all three levels.



The [Margins...](#) menu sets the margin markers to see where scope is making the automatic measurement. All calculations of negative duty cycle value will be performed only inside these margins.

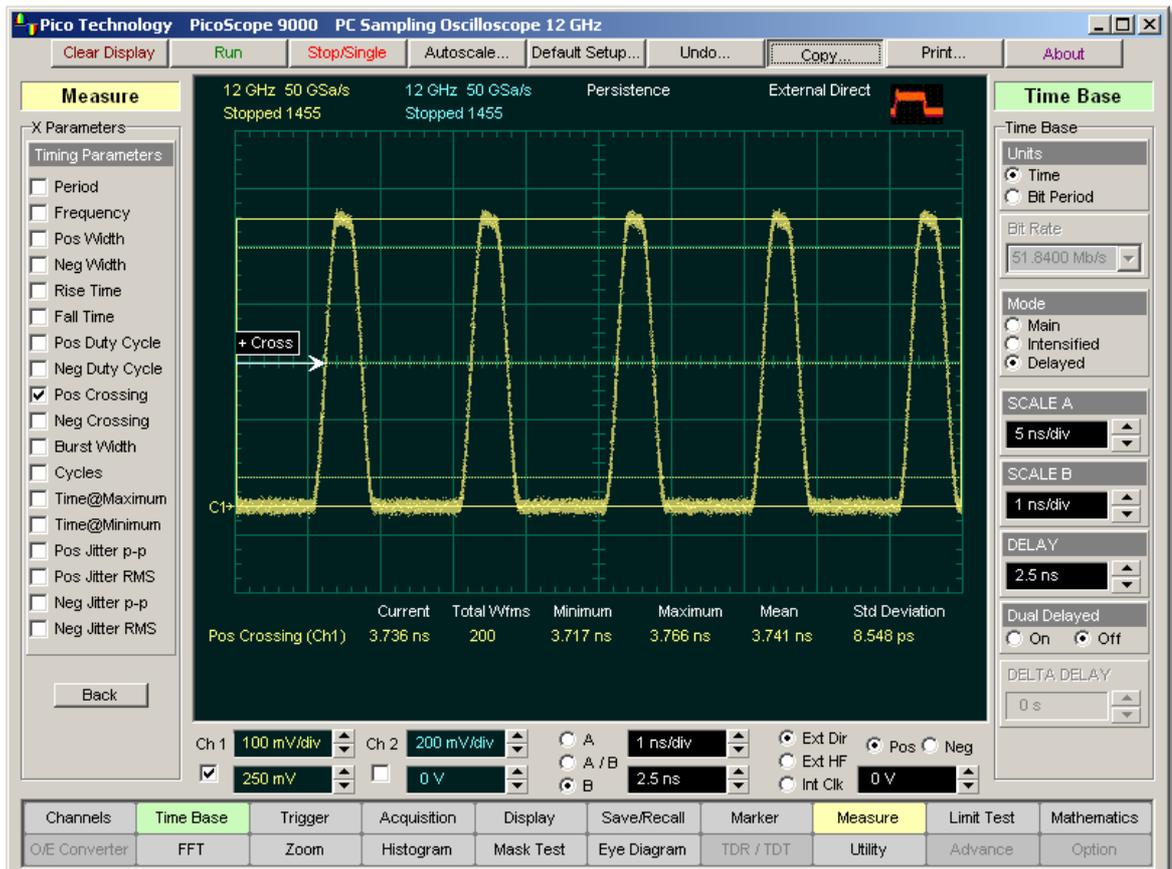


Negative duty cycle value is affected by the [Define Param...](#)³⁰⁵ menu. In the [Defined Thresholds](#)³¹⁰ menu you can redefine the mid-threshold setting from 50% to any other level you want.

5.12.3.9 Positive Crossing



Positive Crossing is defined as the time of the first positive crossing of the data sampled at the mid-reference level in the measurement region. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin).



Positive Crossing definition

Positive crossing is determined as follows:

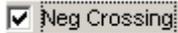
$$Positive\ Crossing = T_{cross}$$

where T_{cross} is the horizontal coordinate of the first positive crossing.

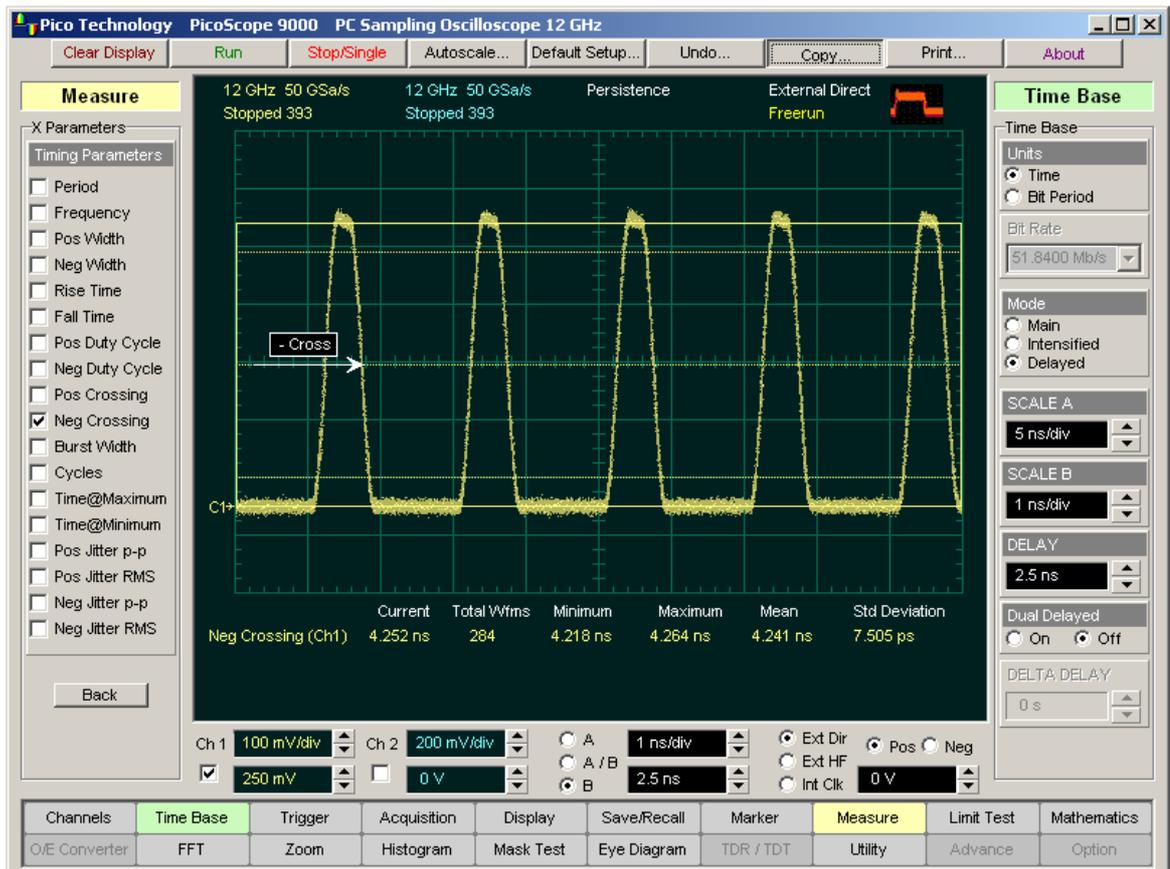
The [Margins...](#) ^[312] menu sets the margin markers to see where scope is making the automatic measurement. All calculations of positive crossing value will be performed only inside these margins.

Positive crossing value is affected by the [Define Param...](#) ^[305] menu. In the [Defined Thresholds](#) ^[310] menu you can redefine the mid-threshold setting from 50% to any other level you want.

5.12.3.10 Negative Crossing



Negative Crossing is defined as the time of the first negative crossing of the data sampled at the mid-reference level in the measurement region. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the display (right margin).



Negative Crossing definition

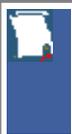
Negative crossing is determined as follows:

$$\text{Negative Crossing} = T_{\text{cross}}$$

where T_{cross} is the horizontal coordinate of the first negative crossing.



The [Margins...](#) ^[312] menu sets the margin markers to see where scope is making the automatic measurement. All calculations of negative crossing value will be performed only inside these margins.

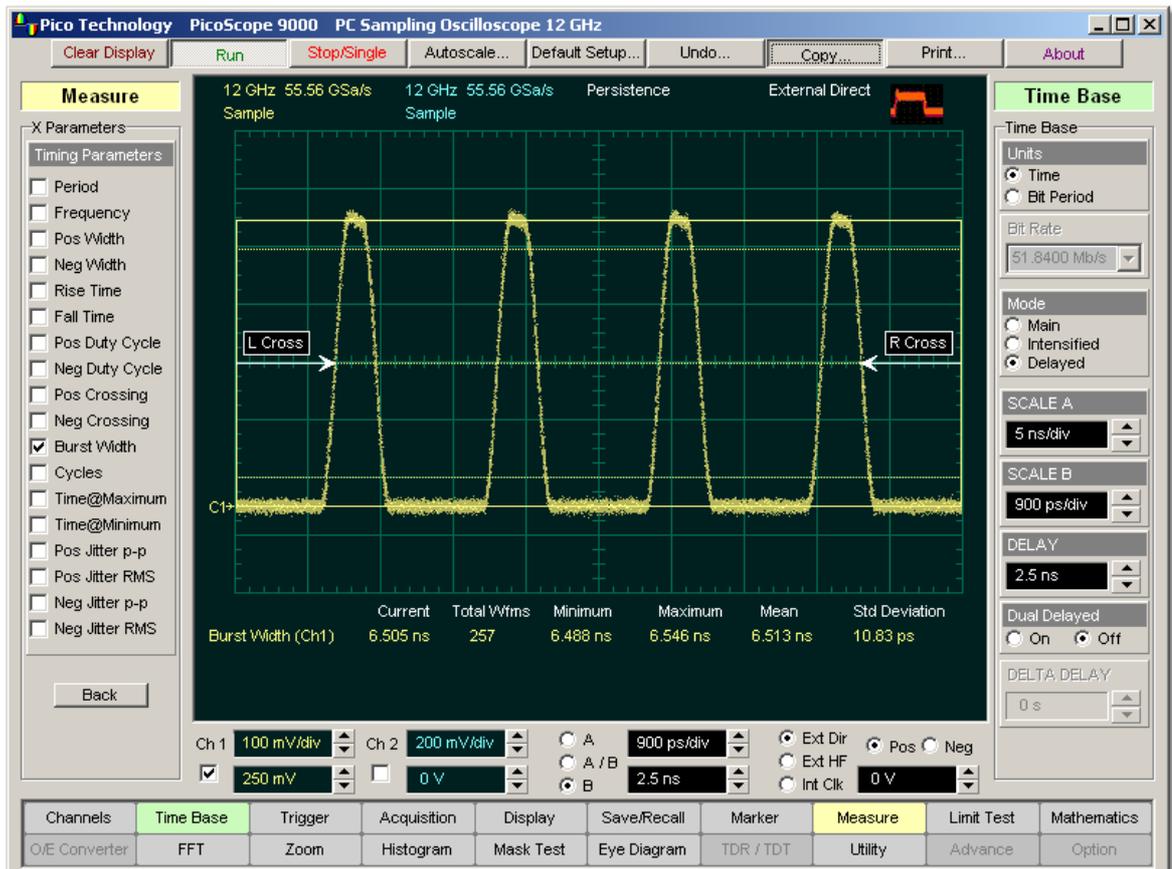


Negative crossing value is affected by the [Define Param...](#) ^[305] menu. In the [Defined Thresholds](#) ^[310] menu you can redefine the mid-threshold setting from 50% to any other level you want.

5.12.3.11 Burst Width



Burst Width is defined as the time between the first and last crossings, either positive or negative, of the waveform at the mid-reference level in the measurement region. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the display (right margin).



Burst Width definition

Burst width is determined as follows:

$$Positive\ Width = T_{crossL} - T_{crossF}$$

where T_{crossL} is the horizontal coordinate of the last crossing, and T_{crossF} is the horizontal coordinate of the first crossing.

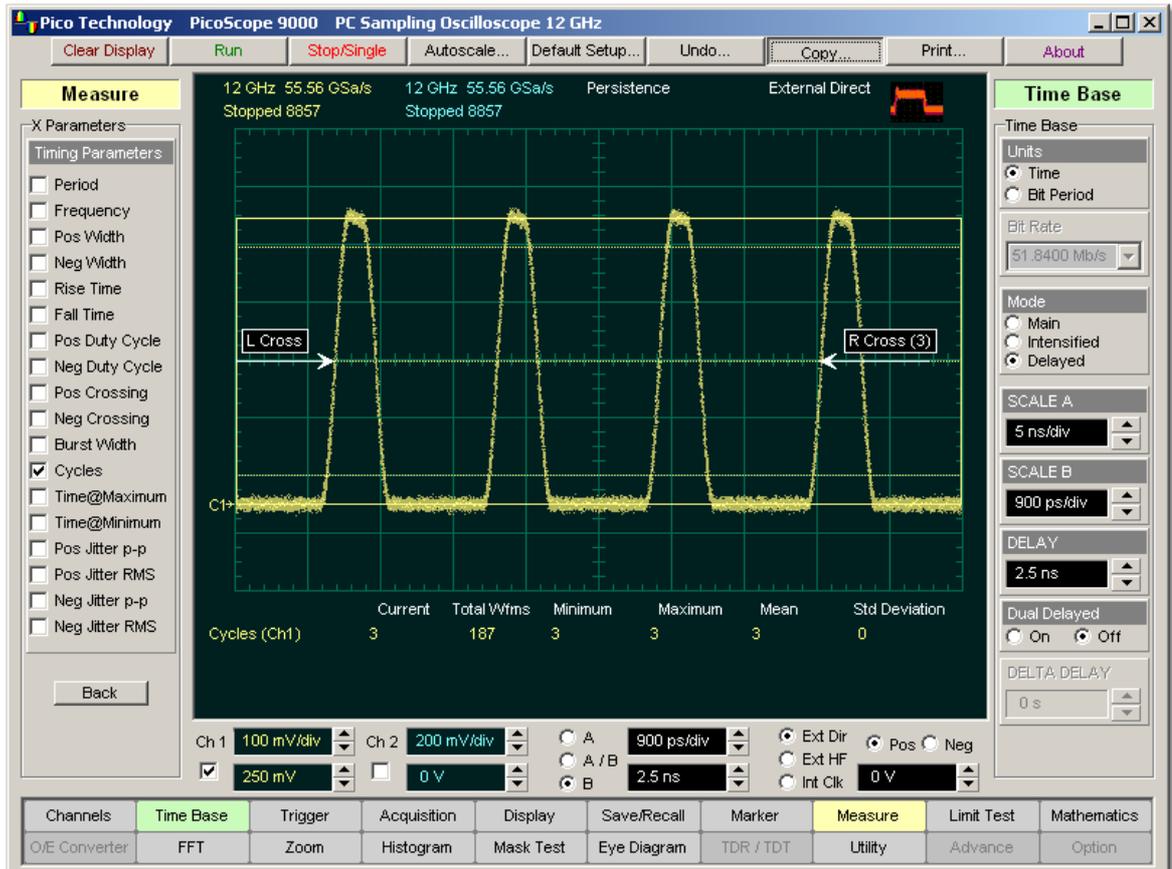
The [Margins...](#) ^[312] menu sets the margin markers to see where scope is making the automatic measurement. All calculations of burst width value will be performed only inside these margins.

Burst width value is affected by the [Define Param...](#) ^[305] menu. In the [Defined Thresholds](#) ^[310] menu you can redefine the mid-threshold setting from 50% to any other level you want.

5.12.3.12 Cycle



Cycles is defined as the number of cycles of a periodic waveform between the mid-threshold crossings of two consecutive first and last edges of the same polarity. The PicoScope 9000 starts the measurement on the first edge on the left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the measurement region (right margin). The detected edges can be either rising or falling.



Cycle definition



The [Margins...](#)^[312] menu sets the margin markers to see where scope is making the automatic measurement. All calculations of cycles value will be performed only inside these margins.



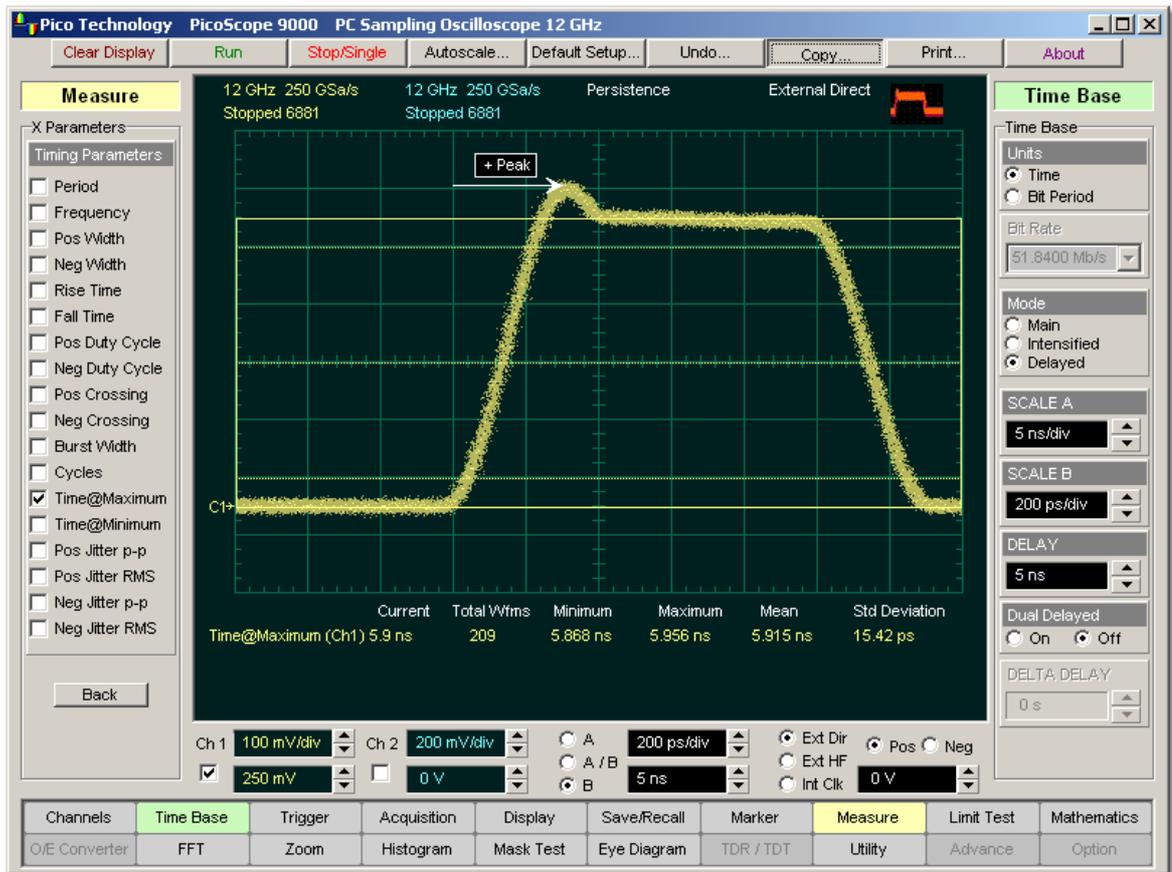
Cycles value is affected by the [Define Param...](#)^[305] menu. In the [Defined Thresholds](#)^[310] menu you can redefine the mid-threshold setting from 50% to any other level you want.

5.12.3.13 Time@Maximum

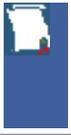


Time@Maximum is a measure of the time of the first occurrence of the first data sample with the maximum signal level. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the display (right margin).

Time@Maximum is position-independent. Therefore, the instrument uses the entire waveform on the display graticule to determine the maximum signal level.



Time&Maximum definition



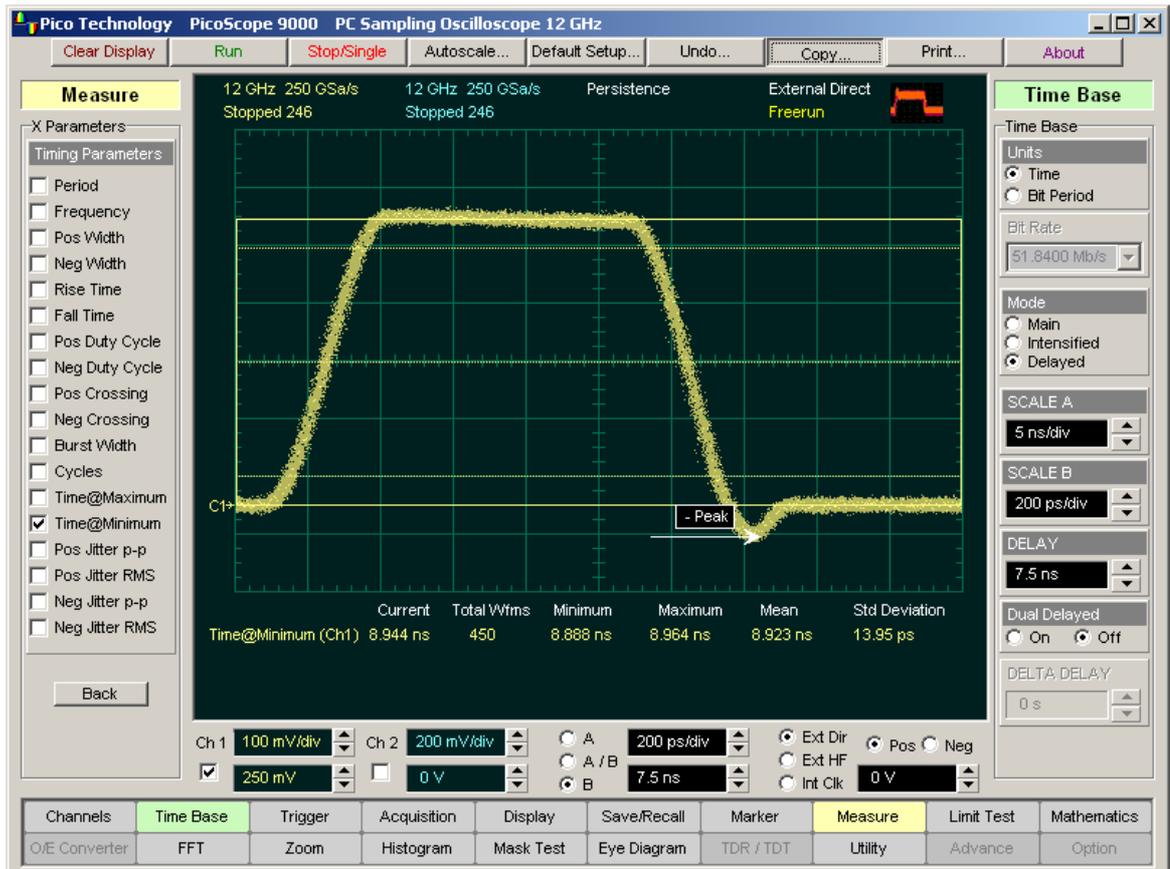
The [Margins...](#) menu sets the margin markers to see where scope is making the automatic measurement. All calculations of Time@Maximum value will be performed only inside these margins.

5.12.3.14 Time@Minimum

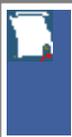


Time@Minimum is a measure of the time of the first occurrence of the first data sample with the minimum signal level. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the display (right margin).

Time@Minimum is position-independent. Therefore, the instrument uses the entire waveform on the display graticule to determine the minimum signal level.



Time@Minimum definition



The [Margins...](#) ^[12] menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of the Time@Minimum value will be performed only inside these margins.

5.12.3.15 Positive Jitter p-p



Positive Jitter p-p is a measure of peak-peak time variations of the rising edges of a pulse waveform at the middle threshold.



Positive Jitter p-p definition

Positive Jitter p-p is determined as follows:

Positive Jitter p-p = Full width of the Horizontal Histogram in the Middle Threshold



The [Margins...](#) menu sets the margin markers to see where the scope is making the automatic measurement. All calculations of Positive jitter p-p will be performed only inside these margins.

5.12.3.16 Positive Jitter RMS



Positive Jitter RMS is a measure of rms time variations of the rising edges of a pulse waveform at the middle threshold.



Positive Jitter RMS definition

Positive Jitter RMS is determined as follows:

$$\text{Positive Jitter RMS} = 1 \text{ (standard deviation) of the Horizontal Histogram in the Middle Threshold}$$



The [Margins...](#) menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of Positive jitter RMS will be performed only inside these margins.

5.12.3.17 Negative Jitter p-p



Negative Jitter p-p is a measure of the peak-peak time variations of the falling edges of a pulse waveform at the middle threshold.



Negative Jitter p-p definition

Negative Jitter p-p is determined as follows:

Negative Jitter p-p = Full width of the Horizontal Histogram in the Middle Threshold

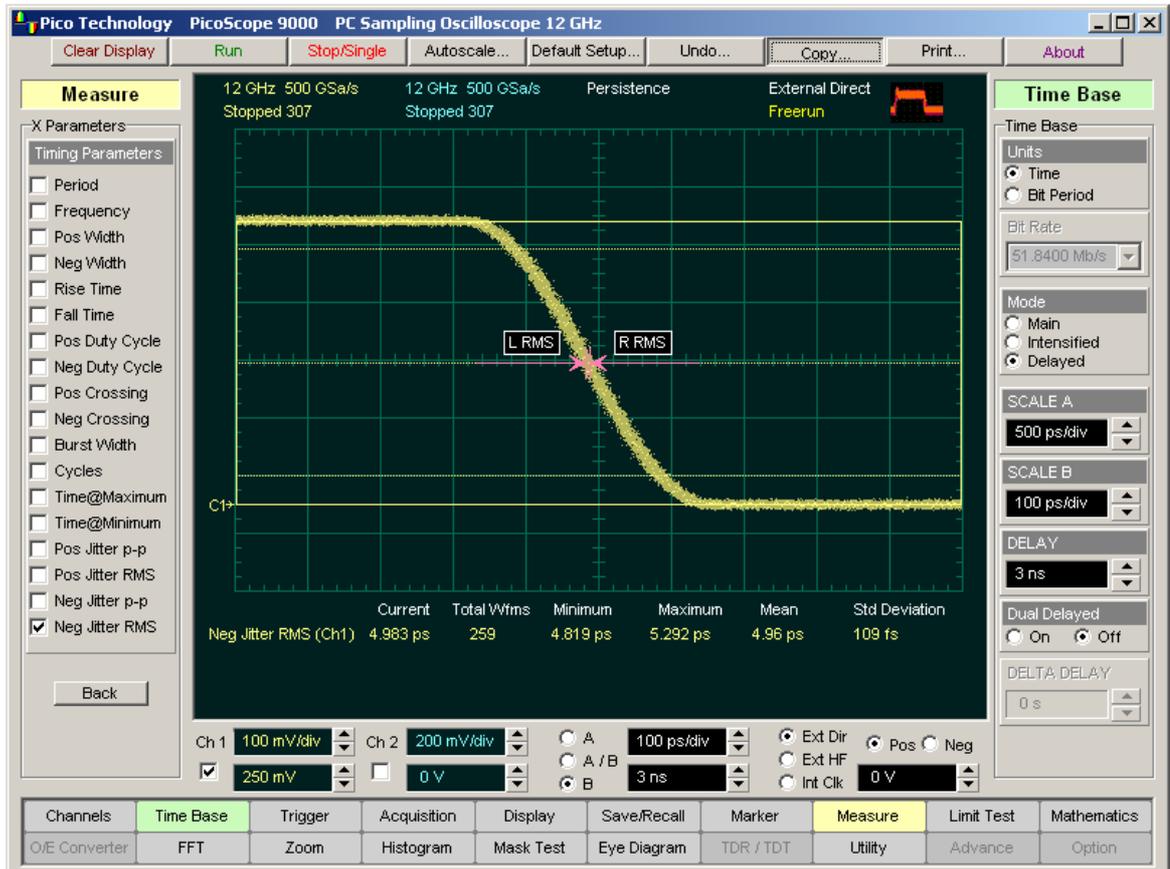


The [Margins...](#) menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of Negative jitter p-p will be performed only inside these margins.

5.12.3.18 Negative Jitter RMS



Negative Jitter RMS is a measure of the rms time variations of the falling edges of a pulse waveform at the middle threshold.



Negative Jitter RMS definition

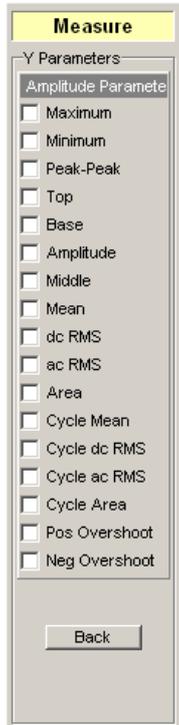
Negative Jitter RMS is determined as follows:

Negative Jitter RMS = 1 (standard deviation) of the Horizontal Histogram in the Middle Threshold



The [Margins...](#) menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of Negative jitter RMS will be performed only inside these margins.

5.12.4 Y Parameters...



Clicking the Y Parameters... button opens the list of amplitude parameters. The list includes seventeen amplitude parameters for pulse measurements. Once the Top and Base calculation area is completed, most of the amplitude measurements can be made.



You can continuously update as many as ten measurement parameters, and as many as four statistics measurements at any one time.



The pulse measurement algorithms for X Parameters will only work when a single-valued signal is used, and no NRZ eye diagram or RZ eye diagram is present on the screen. Measurements made on both NRZ and RZ eye diagrams will fail.

5.12.4.1 Maximum



Maximum is the voltage (or power) of the absolute maximum level of the measurement region. The maximum level is taken directly from the histogram data. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin).



Maximum definition

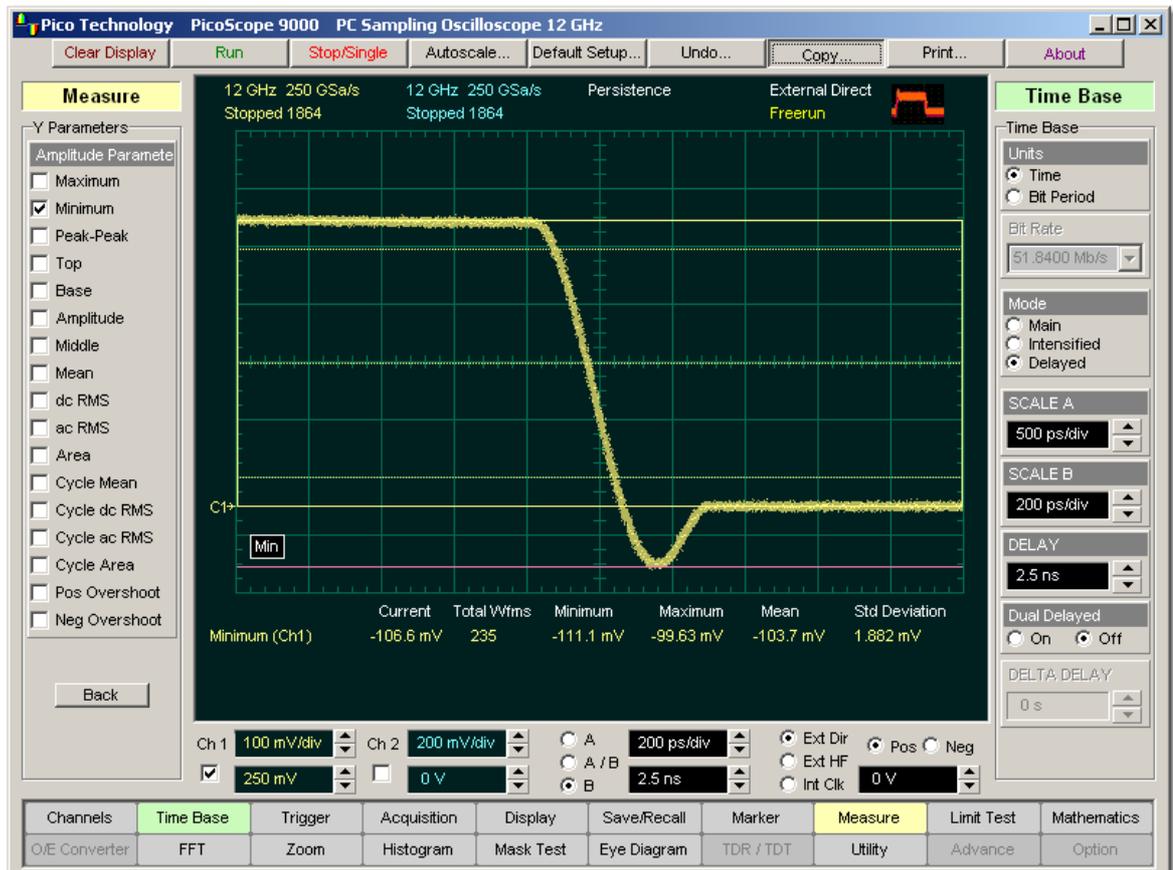


The [Margins...](#) menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of maximum value will be performed only inside these margins.

5.12.4.2 Minimum



Minimum is the voltage (or power) of the absolute minimum level of the measurement region. The minimum level is taken directly from the histogram data. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin).



Minimum definition



The [Margins...](#) menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of minimum value will be performed only inside these margins.

5.12.4.3 Peak-Peak



Peak-Peak is a measure of the difference between Maximum and Minimum of a displayed waveform. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin).



Peak-Peak definition

Peak-Peak is determined as follows:

$$\text{Peak-Peak} = \text{Maximum} - \text{Minimum}$$

where *Maximum* is the voltage (or power) of the absolute maximum value of the waveform, and *Minimum* is the voltage (or power) of the absolute minimum value of the waveform.

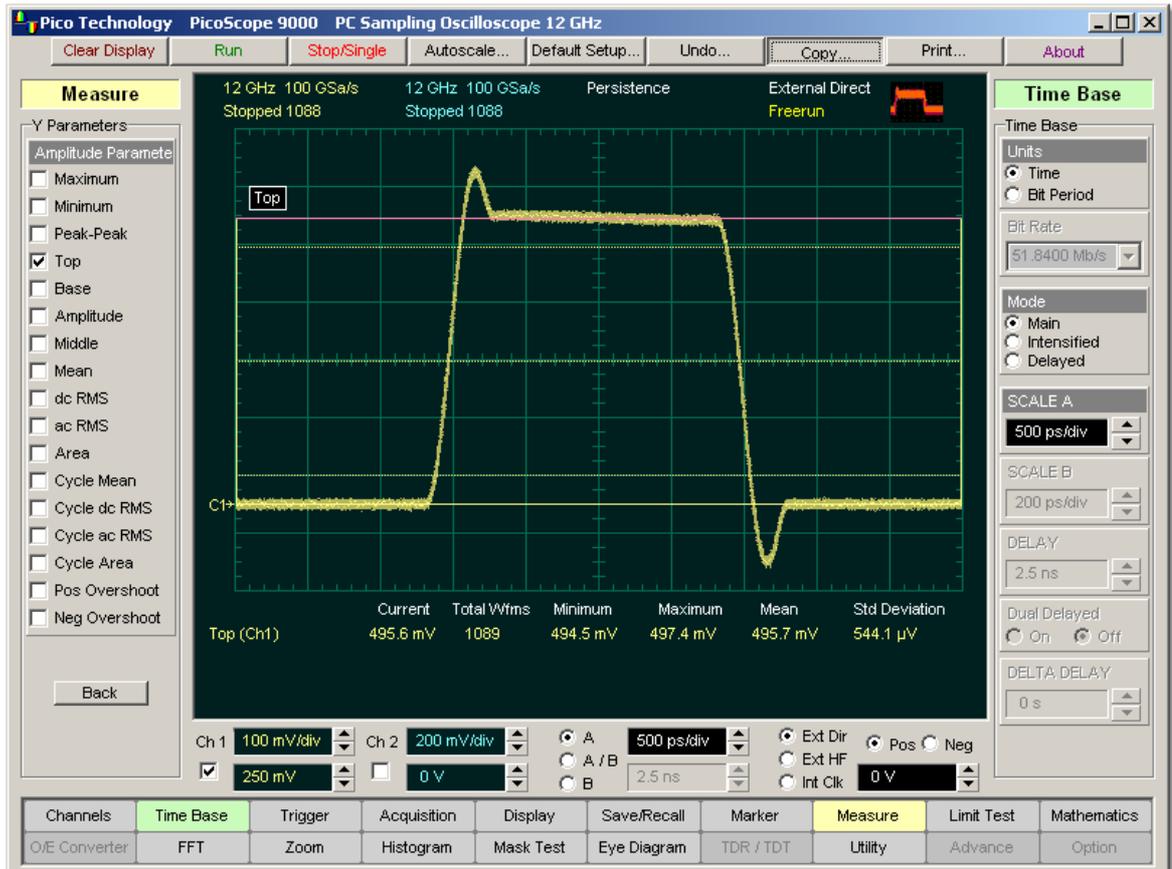


The [Margins...](#) menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of peak-peak value will be performed only inside these margins.

5.12.4.4 Top



Top is the voltage of the statistical maximum level. Use the [Method](#)^[308] and [Thresholds](#)^[309] menus to customize the measurement threshold levels. Top may be equal to Maximum for many waveforms, such as triangle waveforms. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin).

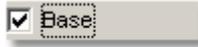


Top definition

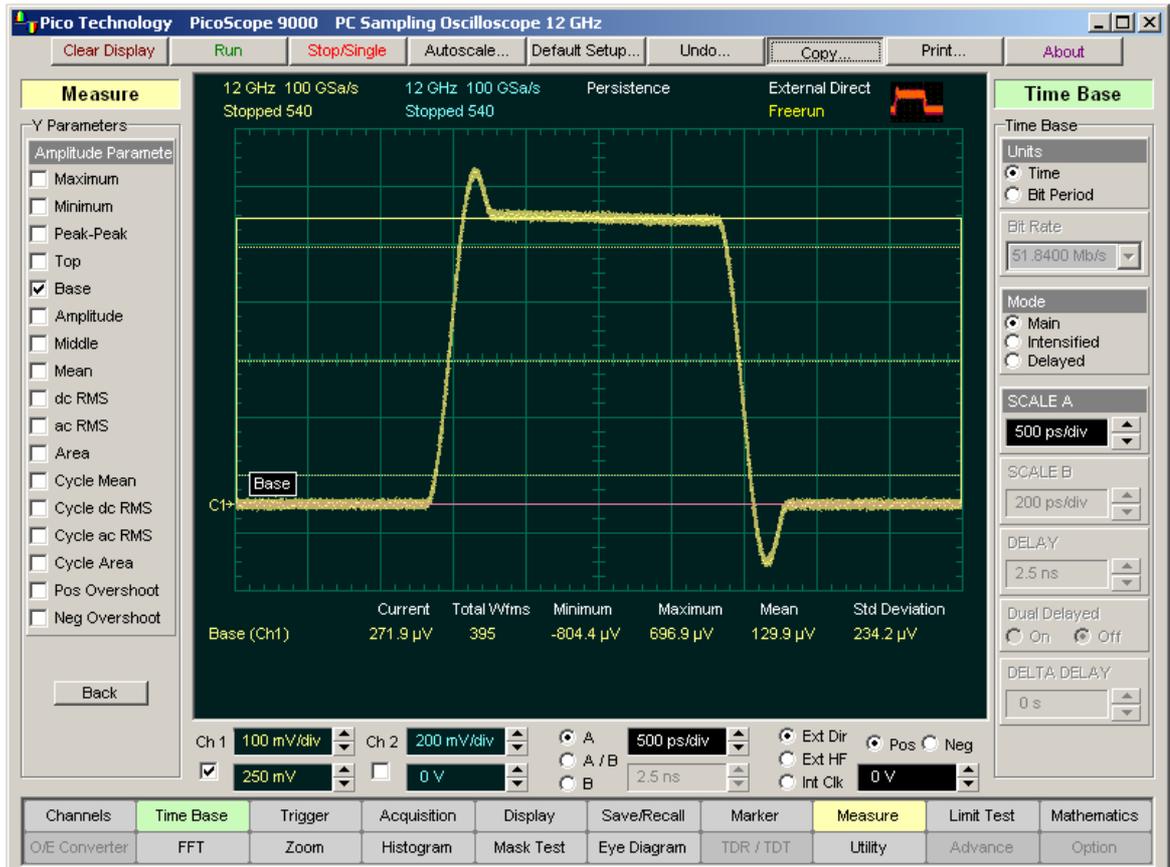


The [Margins...](#)^[312] menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of the Top value will be performed only inside these margins.

5.12.4.5 Base



Base is the voltage of the statistical minimum level. Use the [Method](#)^[808] and [Thresholds](#)^[309] menus to customise the measurement threshold levels. Base may be equal to Minimum for many waveforms, such as triangle waveforms. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin).



Base definition



The [Margins...](#)^[312] menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of the Base value will be performed only inside these margins.

5.12.4.6 Amplitude



Amplitude is a measure of the difference between the Top and Base of a displayed pulse waveform. Use the [Method](#) ^[308] and [Thresholds](#) ^[309] menus to customize the measurement threshold levels. Amplitude may be equal to Peak-Peak for many waveforms, such as triangle waveforms. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin).



Amplitude definition

Amplitude is determined as follows:

$$\text{Amplitude} = \text{Top} - \text{Base}$$

where *Top* is the statistical maximum level, and *Base* is the statistical minimum level.



Top may be less than or equal to the maximum value of the waveform, while Base may be greater than or equal to the minimum value of the waveform.



The [Margins...](#) ^[312] menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of amplitude value will be performed only inside these margins.

5.12.4.7 Middle



Middle is the computation of the middle point between the maximum and minimum amplitude peaks of the waveform over the measurement region. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin).

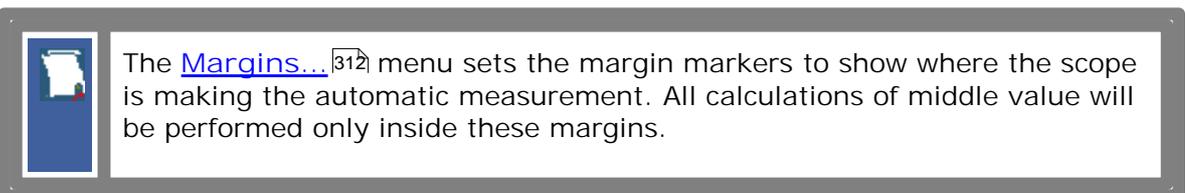


Middle definition

Middle is determined as follows:

$$\text{Middle} = (\text{Maximum} - \text{Minimum}) / 2$$

where *Maximum* is the voltage (or power) of the absolute maximum value of the waveform, and *Minimum* the voltage (or power) of the absolute minimum value of the waveform.



5.12.4.8 Mean



Mean is the average mean of all the waveform data over the measurement region. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin).



Mean definition

Mean is determined as follows:

$$Mean = \frac{1}{n} \sum_{i=1}^N V(i)$$

where n is the number of waveform points on screen and not the memory depth, $V(i)$ is the voltage at the i -th point on screen.

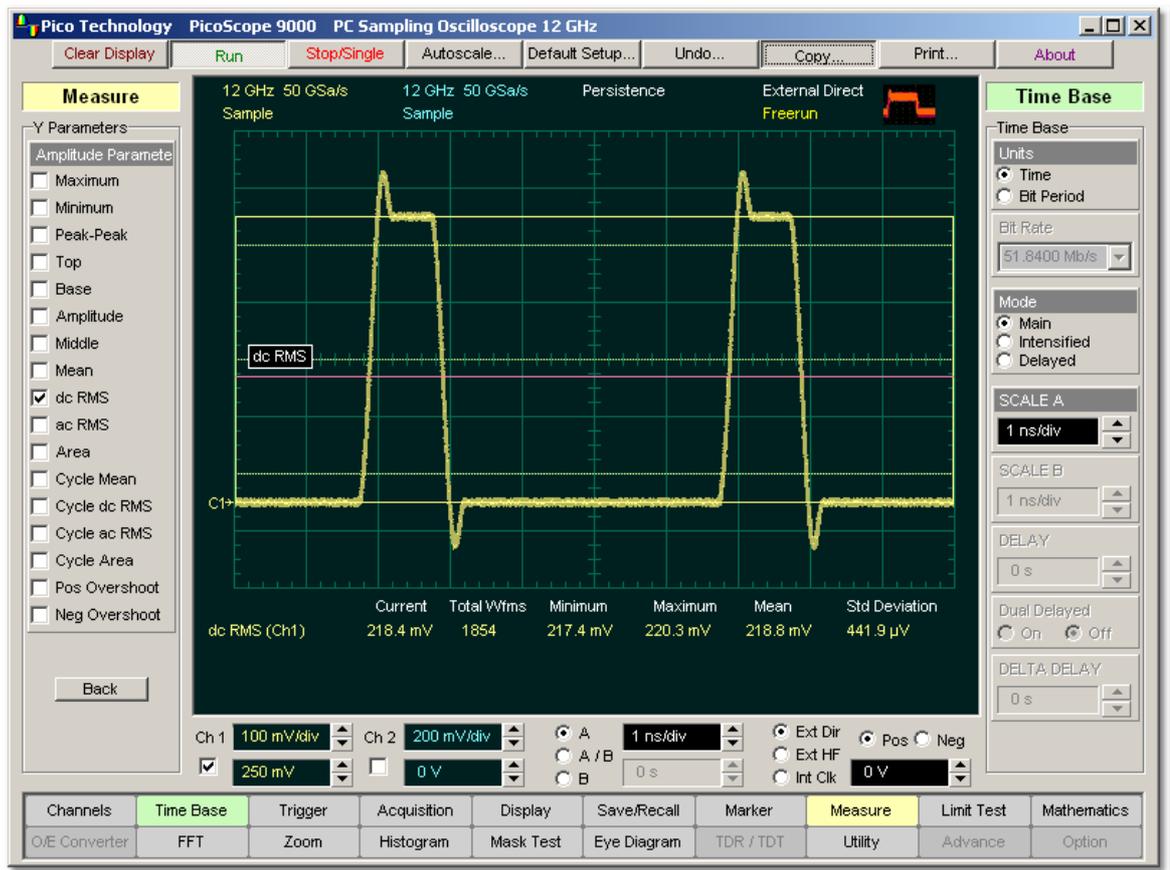


The [Margins...](#) menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of mean value will be performed only inside these margins.

5.12.4.9 dc RMS



dc RMS is the root-mean-square voltage of the waveform over the measurement region. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin). The instrument can make either ac or dc RMS measurements.



dc RMS definition

dc RMS measurement is determined as follows:

$$dcRMS = \sqrt{\frac{\sum_{i=1}^n [V(i)]^2}{n}}$$

where: n is the number of waveform points on screen and not the memory depth, and $V(i)$ is the voltage at the i -th point on screen.

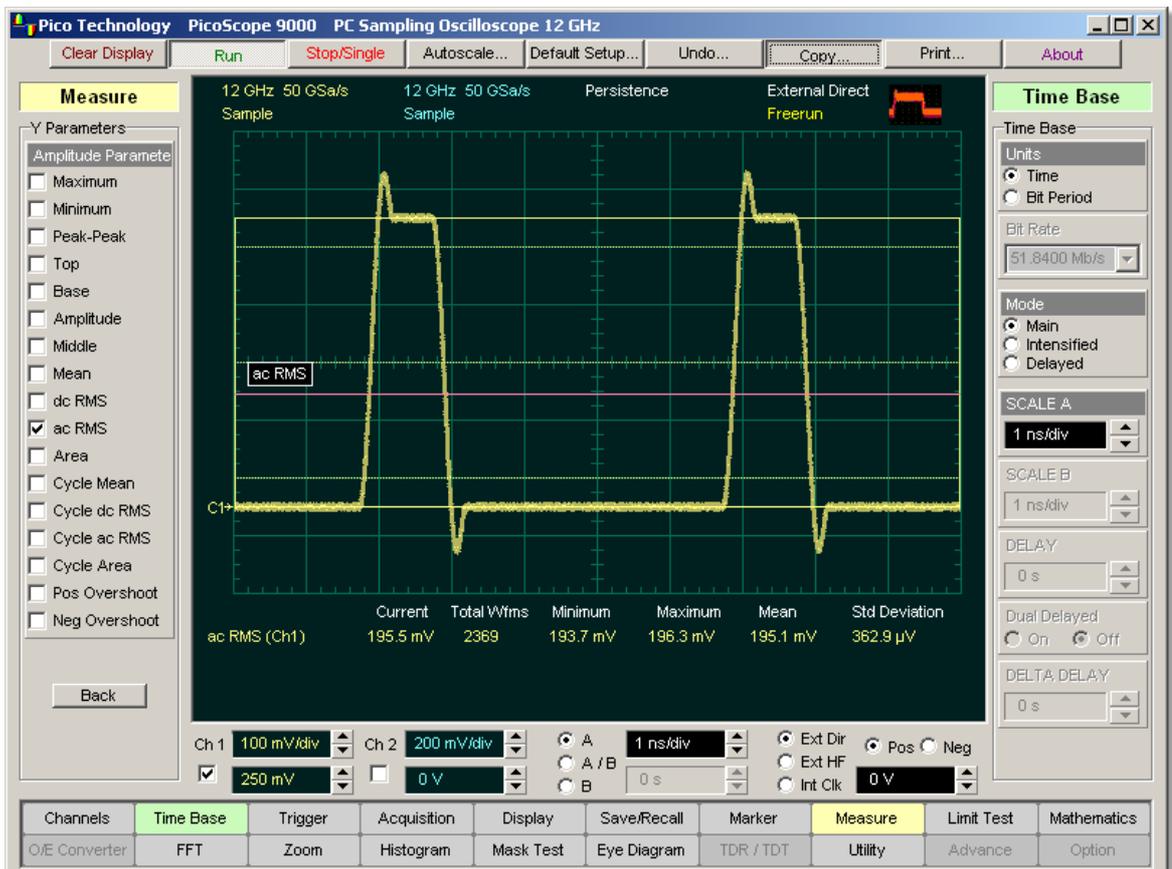


The [Margins...](#) [312] menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of the dc RMS value will be performed only inside these margins.

5.12.4.10 ac RMS



ac RMS is the root-mean-square voltage of the waveform less the mean value over the measurement region. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin). The instrument can make either ac or dc RMS measurements.



ac RMS definition.

The ac RMS measurement is determined as follows:

$$acRMS = \sqrt{\frac{\sum_{i=1}^n [V(i) - Mean]^2}{n}}$$

where: n is the number of waveform points on screen and not the memory depth, $V(i)$ is the voltage at the i -th point on screen, and $Mean$ is an average mean voltage.

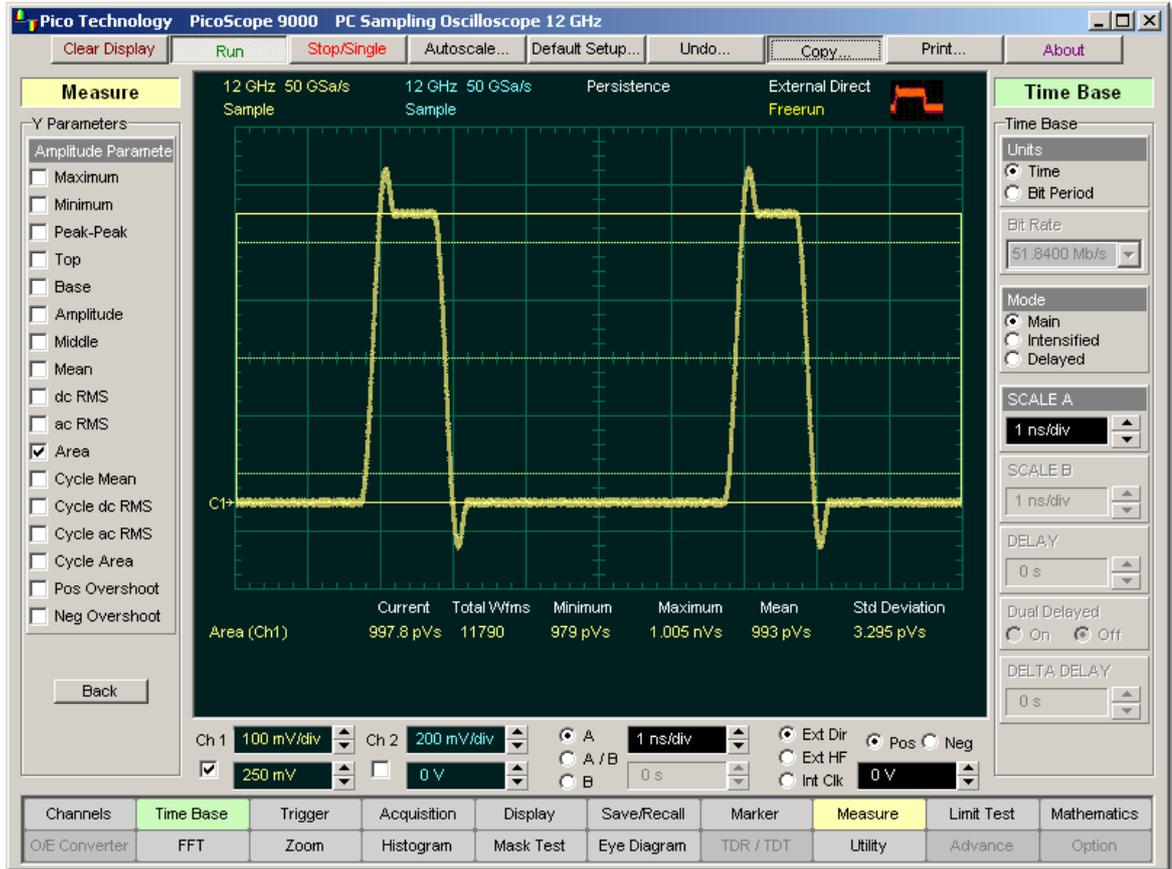


The [Margins...](#) [312] menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of the ac RMS value will be performed only inside these margins.

5.12.4.11 Area



Area is the area under the curve of the waveform within the measurement region in vertical units multiplied by horizontal units, such as volt-seconds or watt-seconds. Area measured above ground is positive; area measured below ground is negative.



Area definition

Area is determined as followed:

If $Start = End$ then return the (interpolated) value at $Start$.

Otherwise,

$$Area = \int_{Start}^{End} Waveform(t) dt$$

In practice the PicoScope 9000 uses the following algorithm:

$$Area = \frac{\Delta t}{N} \sum_{i=1}^N V(i)$$

where: N is the number of waveform points on screen and not the memory depth, $V(i)$ is the voltage at the i -th point on screen, and Δt is the measured region duration.



The [Margins...](#)^[312] menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of area value will be performed only inside these margins.

5.12.4.12 Cycle Mean



Cycle Mean is the averaged mean of all the waveform data of one cycle of the signal over the measurement region. The average of the data values is taken of an integral number of periods. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin). See also Mean.



Cycle Mean definition



You can customize this measurement to be made either on one waveform cycle or across all data on the display. The [Margins...](#) ^[312] menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of the Cycle Mean value will be performed only inside these margins.

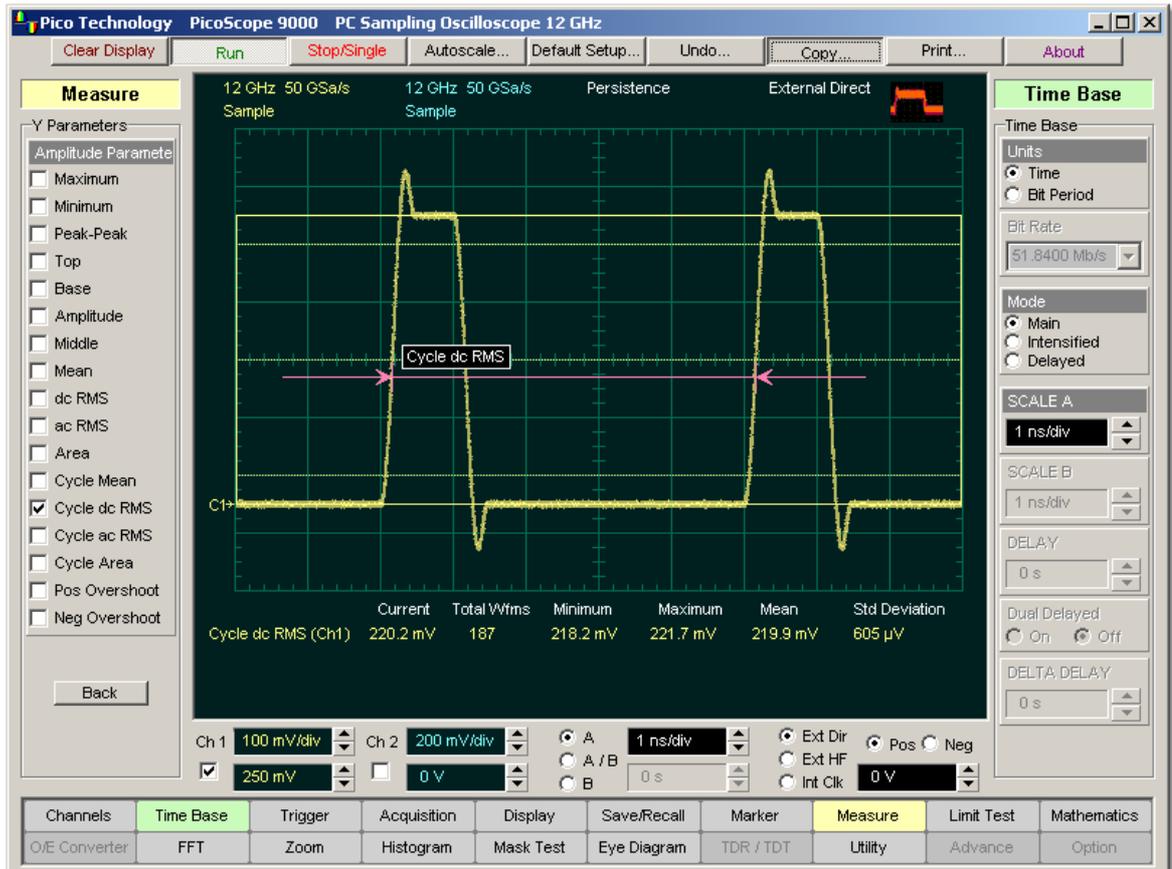


Cycle Mean value is affected by the [Define Param...](#) ^[305] menu. In the [Defined Thresholds](#) ^[310] menu you can redefine the mid-threshold setting from 50% to any other level you want.

5.12.4.13 Cycle dc RMS



Cycle dc RMS is the averaged root-mean-square voltage of one cycle of the waveform value over the measurement region. The average of the data values is taken of an integral number of periods. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin). The instrument can make either cycle ac or dc RMS measurements. See also [dc RMS](#)^[288].



Cycle dc RMS definition

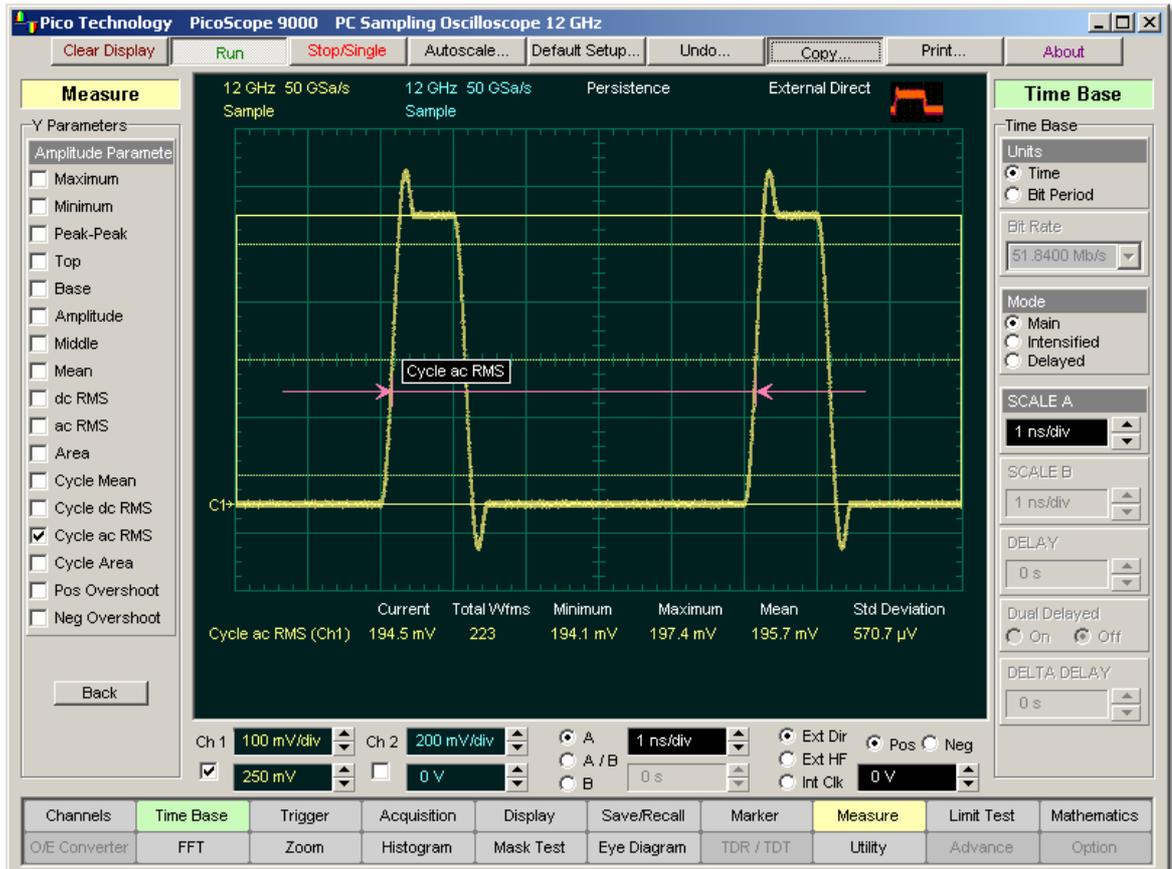


You can customize this measurement to be made either on one waveform cycle or across all data on the display. The [Margins...](#)^[312] menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of the Cycle dc RMS value will be performed only inside these margins.

5.12.4.14 Cycle ac RMS



Cycle ac RMS is the averaged root-mean-square voltage of one cycle of the waveform less the cycle mean value over the measurement region. The average of the data values is taken of an integral number of periods. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin). The instrument can make either ac or dc RMS measurements. See also [ac RMS](#)^[289].



Cycle as RMS definition



You can customize this measurement to be made either on one waveform cycle or across all data on the display. The [Margins...](#)^[312] menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of the Cycle ac RMS value will be performed only inside these margins.

5.12.4.15 Cycle Area



Cycle Area is the averaged area under the curve for one cycle the waveform within the measurement region in vertical units multiplied by horizontal units, such as volt-seconds or watt-seconds. The average of the data values is taken over an integral number of periods. Area measured above ground is positive; area measured below ground is negative. See also [Area](#)^[290].

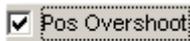


Cycle Area definition



The [Margins...](#)^[312] menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of cycle area value will be performed only inside these margins.

5.12.4.16 Positive Overshoot



Positive Overshoot is defined as a maximum distortion that follows a positive waveform edge transition. This distortion occurs after the edge crosses through the waveform threshold levels. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin). The instrument can make either positive and negative overshoot measurements.



Positive Overshoot definition

Positive Overshoot definition

Positive overshoot, determined when the waveform edge is rising (upward slope), is computed as follows:

$$\text{Positive Overshoot} = [(Maximum - Top) / Amplitude] \times 100\%$$

where: *Maximum* is the signal maximum, *Top* is the signal top value, and *Amplitude* is the signal amplitude.



The [Margins...](#) menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of the Positive Overshoot value will be performed only inside these margins.

5.12.4.17 Negative Overshoot



Negative Overshoot is defined as a maximum distortion that follows a negative waveform edge transition. This distortion occurs after the edge crosses through the waveform threshold levels. The PicoScope 9000 starts the measurement on the first left-most portion of the measurement region (left margin) and stops the measurement on the right-most portion of the display (right margin). The instrument can make either positive and negative overshoot measurements.



Negative Overshoot definition

Negative Overshoot, determined if the waveform edge is falling, is computed as follows:

$$\text{Negative Overshoot} = [(Base - Minimum) / Amplitude] \times 100\%$$

where: *Minimum* is the signal minimum, *Base* is the signal base value, and *Amplitude* is the signal amplitude.



The [Margins...](#) ^[312] menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of the Negative Overshoot value will be performed only inside these margins.

5.12.5 Dual-Channel Parameters



Clicking the Dual Channel Parameters... button opens the list of parameters that can be measured with two sources.

You can select as one of the sources:

- channels 1 and 2
- functions 1 through 4
- waveform memories 1 through 4
- spectrums 1 and 2

The list includes eight delay parameters, three phase parameters, and two gain parameters.



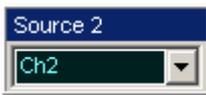
You can continuously update as many as ten measurement parameters, and as many as four statistics measurements at any one time.



The pulse measurement algorithms for X Parameters will only work when a single-valued signal is used, and no NRZ eye diagram or RZ eye diagram is present on the screen. Measurements made on NRZ and RZ eye diagrams will fail.

When the Dual Channel Parameters... menu is selected, the Source drop-down list box located on the first page of the [Measure](#) ^[246] menu selects the reference source, while the Source 2 drop-down list box located on the Dual Channel Parameters menu page selects the second source.

5.12.5.1 Source 2



When the Dual-Chan Parameters... menu is selected, the Source drop-down list box located on the first page of the [Measure](#) ^[246] menu selects the reference source, while the Source 2 drop-down list box located on the Dual-Chan Parameters menu page selects the second source.

5.12.5.2 Delay

- Delay 1R-1R
- Delay 1R-1F
- Delay 1F-1R
- Delay 1F-1F
- Delay 1R-nR
- Delay 1R-nF
- Delay 1F-nR
- Delay 1F-nF

Delay is defined as a time interval between the crossings of the two mid-reference levels on the two sources of the measurement. The PicoScope 9000 starts the measurement on the first edge on the left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the measurement region (right margin).

Delay is determined as follows:

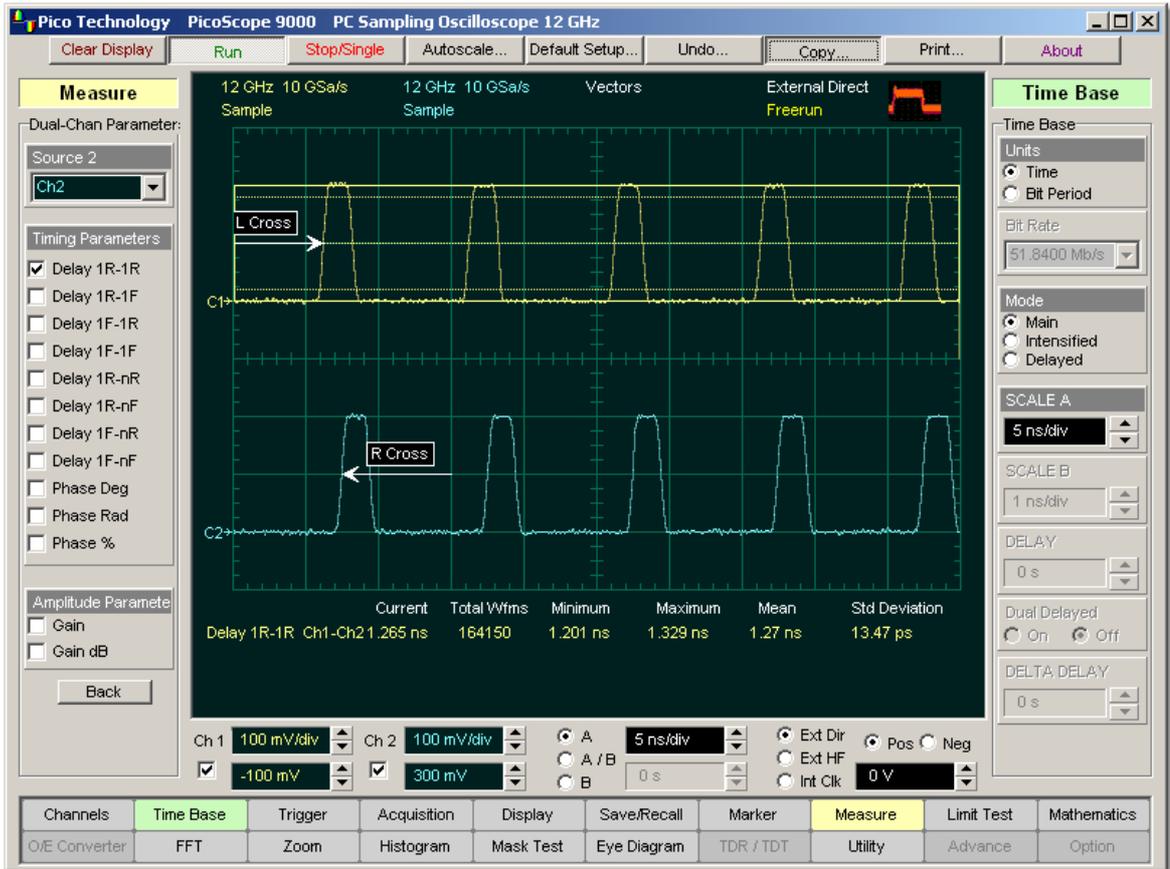
$$Delay = T_{cross2} - T_{cross1}$$

where: T_{cross2} is a horizontal crossing on the rising or falling edge of the second source, and T_{cross1} is a horizontal crossing on the rising or falling edge of the first (reference) source.

The delay will not be measured until the rising and falling edges on both sources complete the transition through all three levels.

You can select one of the eight delay options:

- Delay 1R-1R Delay 1R-1R is the delay between the first rising edge on the reference source and the first rising edge on the second source.
- Delay 1R-1F Delay 1R-1F is the delay between the first rising edge on the reference source and the first falling edge on the second source.
- Delay 1F-1R Delay 1F-1R is the delay between the first falling edge on the reference source and the first rising edge on the second source.
- Delay 1F-1F Delay 1F-1F is the delay between the first falling edge on the reference source and the first falling edge on the second source.
- Delay 1R-nR Delay 1R-nR is the delay between the first rising edge on the reference source and the last rising edge on the second source.
- Delay 1R-nF Delay 1R-nF is the delay between the first rising edge on the reference source and the last falling edge on the second source.
- Delay 1F-nR Delay 1F-nR is the delay between the first falling edge on the reference source and the last rising edge on the second source.
- Delay 1F-nF Delay 1F-nF is the delay between the first falling edge on the reference source and the last falling edge on the second source.



Example of Delay measurement between the first rising edge on the reference source and the first rising edge on the second source

The [Margins...](#) ^[312] menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of the Delay value will be performed only inside these margins.

The Delay value is affected by the [Define Param...](#) ^[305] menu. In the [Defined Thresholds](#) ^[310] menu you can redefine the mid-threshold setting from 50% to any other level you want.

5.12.5.3 Phase



Phase is the amount by which a waveform leads or lags another in time. It is defined between the first rising edge on the reference source and the first rising edge on the second source. The PicoScope 9000 starts the measurement on the first edge on the left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the measurement region (right margin).

Phase is determined as follows:

$$PhaseDeg = \frac{T_{cross2} - T_{cross1}}{Period} * 360^\circ$$

$$PhaseRad = \frac{T_{cross2} - T_{cross1}}{Period} * 2\pi$$

$$PhaseRad = \frac{T_{cross2} - T_{cross1}}{Period} * 100\%$$

where: T_{cross2} - is a horizontal crossing on the first rising edge of the second source, T_{cross1} is a horizontal crossing on the first rising edge of the first (reference) source, and $Period$ is a period value.

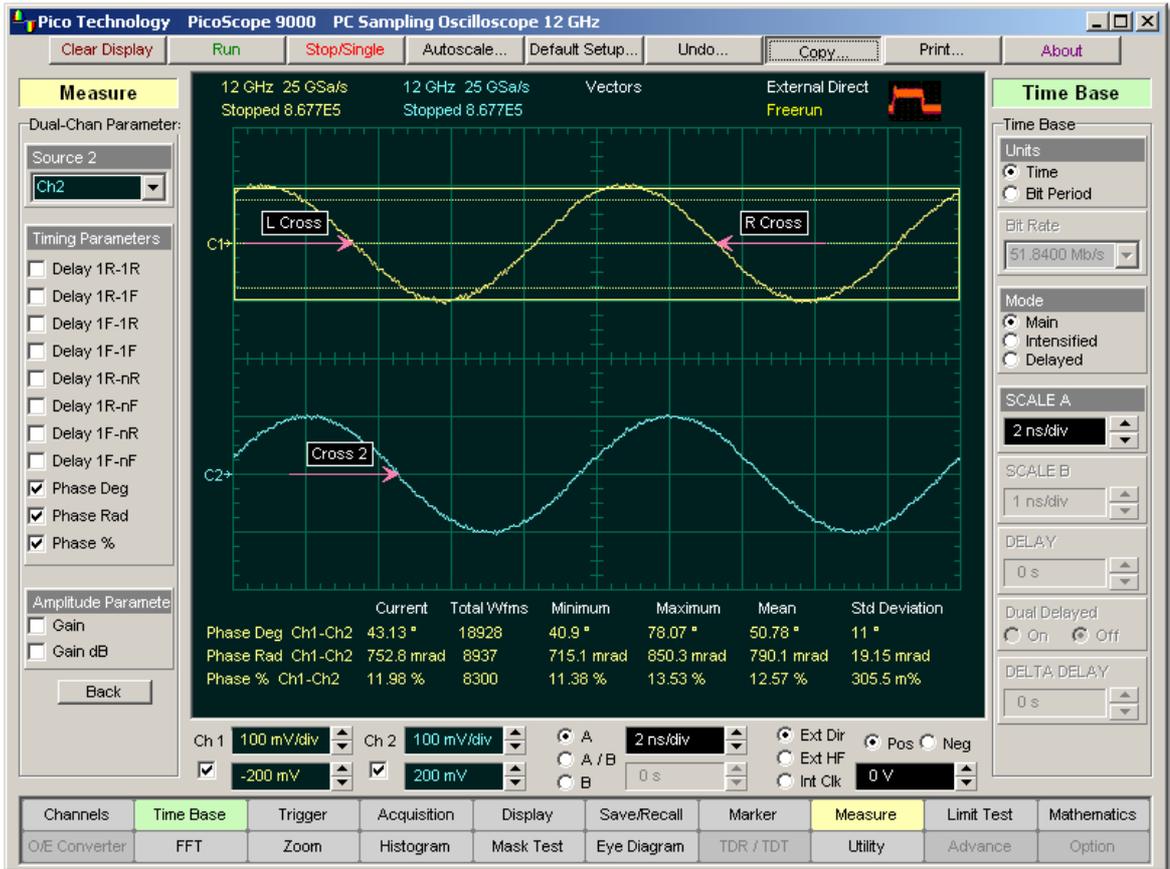
You can select one of three phase options:

- Phase Deg

Phase Deg is a phase expressed in degrees, where 360° constitutes one waveform cycle
- Phase Rad

Phase Rad is a phase expressed in radians, where one waveform cycle (360°) corresponds to 2π radians
- Phase %

Phase % is a phase expressed as a percentage of one waveform cycle



Example of phase measurement between two sine-wave signals



Both the first (reference) and the second sources should have an equal period value when the phase measurements are performed.

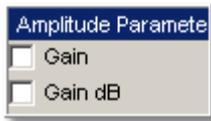


The [Margins...](#)³¹² menu sets the margin markers to see where scope is making the automatic measurement. All calculations of the Phase value will be performed only inside these margins.



Phase value is affected by the [Define Param...](#)³⁰⁵ menu. In the [Defined Thresholds](#)³¹⁰ menu you can redefine the mid-threshold setting from 50% to any other level you want.

5.12.5.4 Gain



Gain is the amplitude gain between two selected waveforms. The PicoScope 9000 starts the measurement on the first edge on the left-most portion of the measurement region (left margin) and stops the measurement on the last edge on the right-most portion of the measurement region (right margin).

Gain is determined as follows:

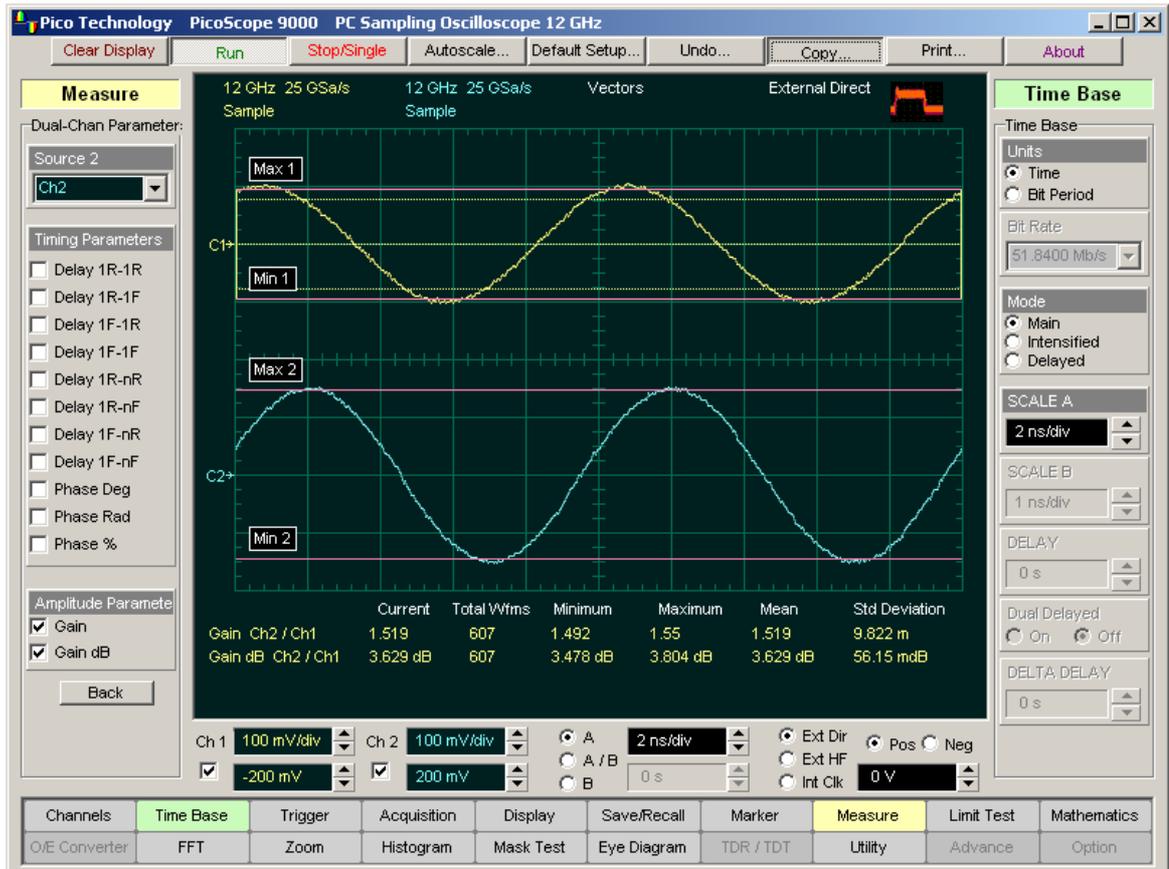
$$\text{Gain} = \frac{\text{Amplitude2}}{\text{Amplitude1}}$$

$$\text{Gain}_{dB} = 20 \log_{10} \left(\frac{\text{Amplitude2}}{\text{Amplitude1}} \right)$$

where: *Amplitude1* is the amplitude measurements of the first (reference) source, and *Amplitude2* is the amplitude measurements of the second source.

You can select one of two gain options:

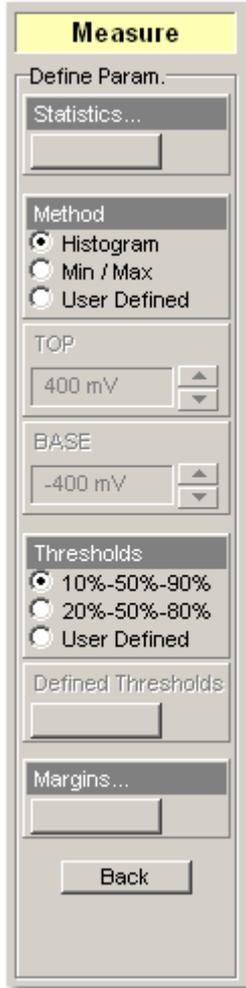
- Gain Gain is a gain expressed as an amplitude gain between the amplitudes of two waveforms.
- Gain dB Gain dB is a gain expressed in decibels.



Example of gain measurement between two sine-wave signals

The [Margins...](#) menu sets the margin markers to show where the scope is making the automatic measurement. All calculations of the Gain value will be performed only inside these margins.

5.12.6 Define Parameters

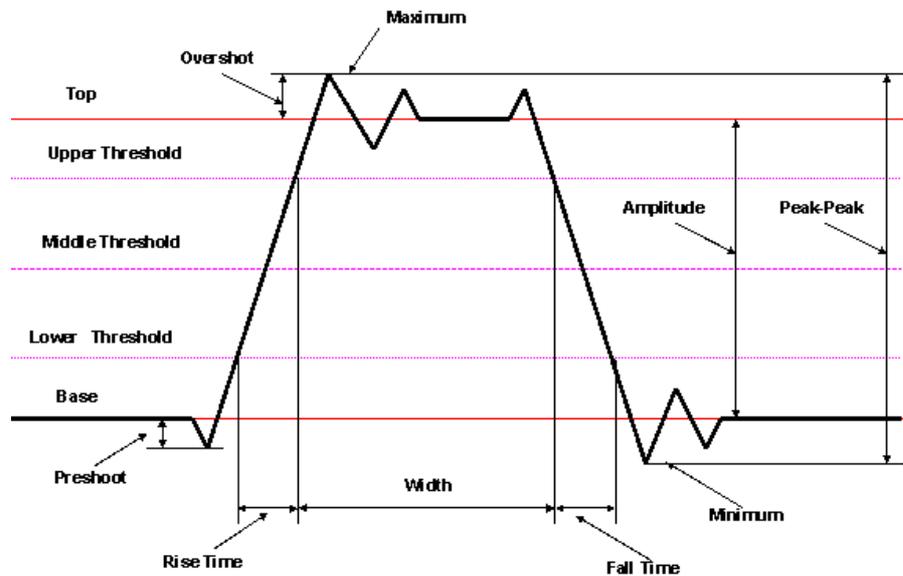


The Define Parameters menu sets the measurement points (thresholds and margins) where the automatic measurements are made. These measurement points can be set to the same points for all waveforms (channel waveforms, function waveforms, and waveform memories) or can be set differently for each individual waveform. The menu influences the measurement algorithm by allowing you to use the standard IEEE measurement points, or customize the measurements with the user-defined selections. The Define Param... menu also includes the [Statistics...](#) menu for some statistics options.

The Define Parameters menu is different when you work in time domain with signals or in the frequency domain with spectrums.

Standard IEEE measurement points

The waveform drawing below shows some of the standard measurement points, thresholds, and parameters.



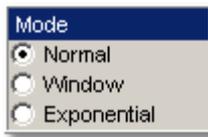
Standard IEEE measurement points

5.12.6.1 Statistics...



The Statistics... menu includes modes and variables that determine the algorithm for a statistical measurement calculation. The Statistics... menu is active only when the Statistics mode of the [Display](#)^[55] menu is selected.

5.12.6.1.1 Mode



The Mode menu defines one of three modes that determine the algorithm for statistical measurement calculations.

- Normal.** Each of the acquired waveforms has an equal influence on the result of the statistical measurement calculation. The [WAVEFORMS](#)^[307]/[WEIGHT](#)^[307] variables are not active in this mode.
- Window.** Only a limited number of the recently acquired waveforms have an equal influence on the result of statistical measurement calculations. The [WAVEFORMS](#)^[307] variable specifies the number of recently acquired waveforms used for statistical measurement calculations. Use the Window mode when measuring a waveform that is rapidly drifting.
- Exponential.** Each of the acquired waveforms has a weighted influence on the result of statistical calculations on eye diagrams. Each subsequently acquired waveform has a greater influence than the preceding acquired waveforms. The [WEIGHT](#)^[307] variable specifies the degree of this influence. Use the Exponential mode when measuring a waveform that is slowly drifting.

5.12.6.1.2 WAVEFORMS



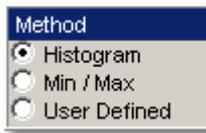
The WAVEFORMS variable specifies the number of recently acquired waveforms used for statistical measurement calculations. The variable is active when Window is selected in the [Mode](#)^[307] menu. It can be varied from 8 to 8192 in multiples of two.

5.12.6.1.3 WEIGHT



The WEIGHT variable specifies the degree of influence of each recently acquired waveform against more remote waveforms. The variable is active when Exponential is selected in the [Mode](#)^[307] menu. WEIGHT can be varied from 8 to 8192 in multiples of two.

5.12.6.2 Method



The Method menu sets the Top and Base vertical reference thresholds for amplitude measurements. It also sets the values from which the upper, middle and lower thresholds are calculated. The Top and Base variables are displayed when the User Defined method is selected. The three selections under the Method menu allow the user to choose the method for determining the Top and Base of the waveform.

Histogram. The instrument calculates the top and base using the IEEE standards with a voltage histogram of the waveform that is on the display. The instrument finds the most prevalent top and base voltage values.

Make sure there is enough of the signal displayed on the screen so that the instrument can accurately determine the top and base values of the waveform. However, if too much of the top and base of the waveform are on the display, it may reduce the number of sample points on the edge of interest, which may reduce the repeatability of your measurements. A good rule of thumb is to have two divisions of top and two divisions of base.

Min / Max. The absolute maximum (positive peak) of the targeted waveform is used as the Top, and the absolute minimum (negative peak) of the targeted waveform is used as the Base.

User Defined. This method lets you set the top and base to a specific voltage value. The upper, middle and lower thresholds are then calculated from the voltage values you select.

The User Defined simplifies the threshold detection algorithm. The result is that the measurement throughput of the instrument is increased, because the instrument does not have to calculate the top and base values. After you selected the User Defined method, the Top and Base variables becomes active.

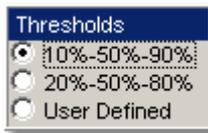
5.12.6.3 TOP and BASE



The TOP and BASE variables let you set the top and base to a specific voltage value. As an example, for a 200 mV/div vertical scale you can set the top and base voltage values from -798 mV to 798 mV in 25 mV (coarse) or 1.56 mV (fine) increments determined by the voltage range you are in.

Note that the top value cannot be less than base value.

5.12.6.4 Thresholds



The Thresholds menu sets the measurement points that the automatic measurements use for calculating the timing measurement results. The threshold points are upper, middle, and lower. For example, rise time is measured from the lower threshold to the upper threshold, while a width measurement is made between two middle thresholds.

The three threshold choices are the standard IEEE measurement points:

- 10% -50% -90%
- 20% -50% -80%
- User Defined

By default, the PicoScope 9000 uses the IEEE thresholds of 10, 50 and 90 percent for pulse measurements. A rising or falling edge is only recognized after passing through all three thresholds. You can specify your own thresholds rather than using the IEEE standard 10, 50, and 90 percent levels, but this can dramatically change measurement results. Note how the rise and fall times will be faster for the same waveform using the 80%, 20% criteria instead of the 90%, 10% criteria. You may rely on the scope to automatically set top and base or redefine those levels yourself and use units of voltage instead of percent.

The UPPER THRESHOLD, MIDDLE THRESHOLD, and LOWER THRESHOLD variables are displayed only when the User Defined is selected in the Thresholds menu.

10% -50% -90% and 20% -50% -80%

These are two IEEE standard pulse measurement thresholds for all measurements. These standard thresholds are calculated as a percentage of the top-base values, and the top-base values are calculated from the waveform that is on the display.

10% -50% -90% means: Lower threshold = 10 %, Middle threshold = 50 %, Upper threshold = 90 %.

20% -50% -80% means: Lower threshold = 20 %, Middle threshold = 50 %, Upper threshold = 80 %.

Make sure that the waveform is expanded vertically and horizontally so that the instrument can accurately determine the top and base values of the waveform. However, if too much of the top and base of the waveform is on the display, it may reduce the repeatability of you measurements. A good rule of thumb is to have two divisions of top and two divisions of base.

User Defined

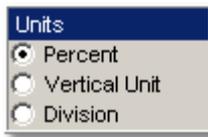
For waveform records or portions of waveform records on which you want to make custom measurements or define thresholds in units of volts, percents or divisions, you can use the User Defined setting. By using units of Volts, you can fix the thresholds and compare different waveform records using exactly the same, fixed threshold points.

5.12.6.5 Defined Thresholds...

A vertical dialog box titled "Measure" with a yellow header. It contains a "Define Thresholds" section with three radio buttons: "Percent" (selected), "Vertical Unit", and "Division". Below this are three threshold settings: "UPPER THRESHOLD" set to "90 %", "MIDDLE THRESHOLD" set to "50 %", and "LOWER THRESHOLD" set to "10 %". Each setting has a dark green display box and up/down arrow controls. At the bottom is a "Back" button.

Clicking the Defined Thresholds... button opens the second-level menu that allows you select defined threshold options.

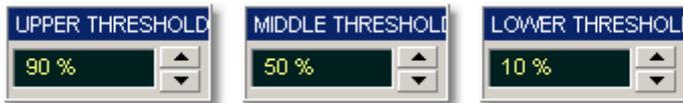
5.12.6.5.1 Units



You can set the unit of measure for upper, middle, and lower thresholds to Percent, Vertical Unit or Division.

- Percent.** This is calculated from the top-base values, and you can set the maximum percentage up to 200% in 1% (coarse) or 0.1% (fine) increments.
- Volt.** This lets you set the thresholds to particular voltage values regardless of the top-base values. For example, for a vertical scale of 200 mV/div you can set the voltage values from -797 mV to 797 mV in approximately 25 mV (coarse) or 1.56 mV (fine) increments determined by the voltage range you are in. Setting Units to Volt simplifies the threshold detection algorithm. The result is that the measurement throughput of the instrument is increased, because the instrument does not have to calculate the voltage thresholds.
- Division.** This lets you set the thresholds to particular voltage values regardless of the top-base values. For example, you can set the voltage values from -3.97 to 3.97 divisions in 125 milli-divisions (coarse) or 7.8 milli-divisions (fine) increments.

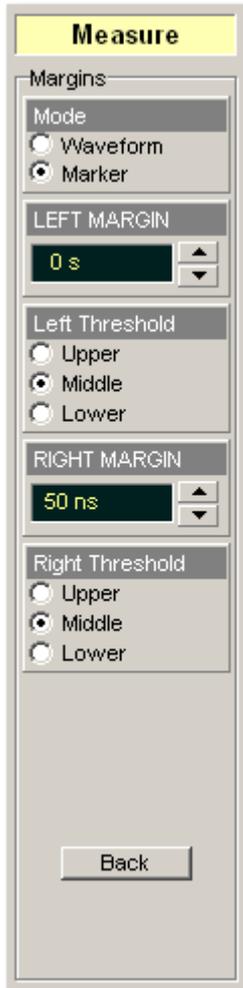
5.12.6.5.2 UPPER, MIDDLE and LOWER THRESHOLD



The UPPER THRESHOLD, MIDDLE THRESHOLD, and LOWER THRESHOLD variables are displayed only when User Defined is selected in the [Thresholds](#) menu. All variables can be selected for the either Percent, Volt or Division.

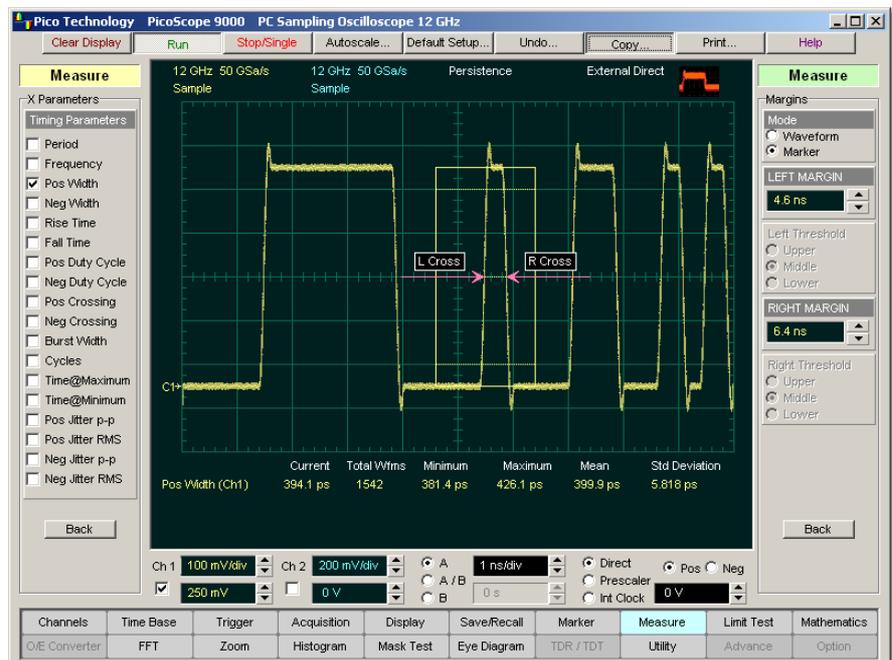
The upper threshold value is always greater than the value of the middle threshold, and the middle threshold value is always greater than the value of the lower threshold. The instrument will not allow a threshold to cross over the adjacent threshold.

5.12.6.6 Margins...



The Margins... menu sets left and right horizontal margins that the automatic measurements use for calculating measurement results. All calculations of measuring parameters can be performed only inside these margins.

The figure below demonstrates how correctly positioned margins can provide enough complicated user-defined horizontal measurements.



Correct position of both margins provides width measurement of second short pulse

5.12.6.6.1 Mode



Two modes are used to set the margins:

- Waveform
- Marker

Waveform. Provides automatic setting of the left and right margins on any of the rising or falling edges of the selected waveform. The LEFT MARGIN and RIGHT MARGIN variables provide positioning of both margins into any upper, middle or lower threshold with any rising or falling edge of the waveform.

Marker. Provides manual setting of the left and right margins with the LEFT MARGIN and RIGHT MARGIN variables.

5.12.6.6.2 LEFT MARGIN and RIGHT MARGIN

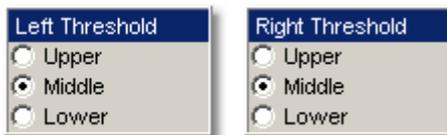


You can set the left and right margins with the [LEFT MARGIN](#)^[313] and [RIGHT MARGIN](#)^[313] variables.

When the Waveform is selected in the Mode menu, both variables automatically set margins on any rising or falling edge of selected waveform. With the [LEFT MARGIN](#)^[313] marker or [RIGHT MARGIN](#)^[313] marker you can move the left and right margins from the 1st rising (edge) up to the 256th falling (edge).

Both variables set the margins at any point of the display manually when Marker is selected in the [Mode](#)^[312] menu.

5.12.6.6.3 Left Threshold and Right Threshold



The LEFT THRESHOLD and RIGHT THRESHOLD variables select crossing points on the edge of the selected waveform. Both variables can be used only when Waveform is selected in the [Mode](#)^[312] menu.

Upper. A margin will be placed on the upper threshold.

Lower. A margin will be placed on the lower threshold.

Middle. A margin will be placed on the middle threshold.

You can change values of upper, lower, and middle thresholds from the [Defined Thresholds...](#)^[310] menu.

5.12.7 FFT Parameters

You can use automated measurements to measure FFT waveforms. To take automated measurements with FFT waveforms, select one of the spectrums in the Source on the first page of the [Measure](#) ²⁴⁶ menu.

After one of the spectrum waveforms is selected you can perform up to five FFT measurements. They are:

- FFT Frequency
- FFT delta Frequency
- FFT Magnitude
- FFT delta Magnitude
- Total Harmonic Distortion



You can continuously update as many as ten measurement parameters, and as many as four statistics measurements at any one time.



The algorithms for FFT measurements will only work when a spectrum waveform is used. Measurements made on a single-valued signal, NRZ or RZ eye diagrams, will fail.



Aliasing. When using FFTs, make sure you avoid signal aliasing. Aliasing occurs when there are insufficient samples on each cycle of the input signal to reconstruct the signal. It occurs whenever the frequency of the input signal is greater than the Nyquist frequency, which is the sample frequency divided by 2. When a signal is aliased, it shows up in the FFT spectrum as a signal of a lower frequency. Because the frequency span goes from 0 to the Nyquist frequency, the best way to prevent aliasing is to make sure that the frequency span is greater than all the frequencies present in the input signal. Keep in mind that most periodic signals that are not sine waves have frequency components much higher than the fundamental frequency of the signal. Those components may also cause aliasing.

5.12.7.1 FFT Frequency



The FFT Frequency measures the frequency value of a peak in the FFT spectrum as defined by the [Define param...](#) menu.

When Harmonic is selected in the [Method](#) menu a peak 1 is defined as a peak having maximum amplitude among other peaks and located within the margins limited by the [LEFT MARGIN](#) and [RIGHT MARGIN](#) variables.

When the Peak is selected in the [Method](#) menu a peak 1 is defined as a peak having maximum amplitude among all peaks exceeding the value of the [PEAK LEVEL](#) variable.

You can choose a peak by using the PEAK 1 variable in the [Define param...](#) menu.

5.12.7.2 FFT Delta Frequency



The FFT Delta Frequency measures the frequency difference between two peaks in the FFT spectrum as defined by peak numbers the [Define param...](#) menu.

When the Harmonic is selected in the [Method](#) menu a peak 1 is defined as a peak having maximum amplitude among other peaks and located within the margins limited by the [LEFT MARGIN](#) and [RIGHT MARGIN](#) variables.

When the Peak is selected in the [Method](#) menu a peak 1 is defined as a peak having maximum amplitude among all peaks exceeding the value of the [PEAK LEVEL](#) variable.

You can choose a peak by using the PEAK 1 and PEAK 2 variables in the [Define param...](#) menu.

5.12.7.3 FFT Magnitude



The FFT Magnitude measures the magnitude value of a peak in the FFT spectrum as defined by the [Define param...](#) menu.

When the Harmonic is selected in the [Method](#) menu a peak 1 is defined as a peak having maximum amplitude among other peaks and located within the margins limited by the [LEFT MARGIN](#) and [RIGHT MARGIN](#) variables.

When the Peak is selected in the [Method](#) menu a peak 1 is defined as a peak having maximum amplitude among all peaks exceeding the value of the [PEAK LEVEL](#) variable.

You can choose a peak by using the PEAK 1 variable in the [Define param...](#) menu.

5.12.7.4 FFT Delta Magnitude



The FFT Delta Magnitude measures the magnitude difference between two peaks in the FFT spectrum as defined by peak numbers the [Define param...](#) menu.

When the Harmonic is selected in the [Method](#) menu a peak 1 is defined as a peak having maximum amplitude among another peaks and located within the margins limited by the [LEFT MARGIN](#) and [RIGHT MARGIN](#) variables.

When the Peak is selected in the [Method](#) menu a peak 1 is defined as a peak having maximum amplitude among all peaks exceeding the value of the [PEAK LEVEL](#) variable.

You can choose a peak by using the PEAK 1 and PEAK 2 variables in the [Define param...](#) menu.

5.12.7.5 Total Harmonic Distortion



THD is a ratio, expressed as a percentage, of the rms level of the measured signal, with the fundamental harmonic removed, to the rms level of the the fundamental harmonic.

Total harmonic distortion is determined as follows:

$$THD = \sqrt{\frac{\sum_{n=2}^N U_n^2}{U_1^2}} \cdot 100\%$$

where: U_n - is an amplitude of the n -th harmonic, and U_1 - is an amplitude of the fundamental harmonic.

THD is a measure of signal purity, used to characterize linearity in electronic circuits and components. A high-purity sine wave, one with low harmonic content, is input to the device under test. An analysis of the frequency content of the output from that device will reveal non-linear operation in the form of increased harmonic levels.

5.12.8 FFT Define Parameters

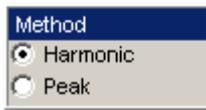


The [Define Param...](#)^[305] menu is changed when the spectrum waveform for FFT measurement is selected.

To select defined parameters for FFT measurements do as follows:

- Select one of the spectrums in the Source on the first page of the [Measure](#)^[246] menu.
- Click [Define Param...](#)^[305]

5.12.8.1 Method



Two modes are used to define FFT peaks:

- Harmonic
- Peak

Harmonic. A peak 1 is defined as a peak having maximum amplitude among other peaks and located within the margins limited by the [LEFT MARGIN](#)^[313] and [RIGHT MARGIN](#)^[313] variables. F_1 is a fundamental frequency of a peak 1.

A frequency of n -th harmonics is calculated as follows:

$$F_n = n * F_1$$

Peak. A peak 1 is defined as a peak having maximum amplitude among all peaks exceeding the value of the [PEAK LEVEL](#)^[318] variable.

5.12.8.2 LEFT MARGIN and RIGHT MARGIN



LEFT MARGIN and RIGHT MARGIN variables limit a horizontal (spectrum) window used for a peak 1 definition. When Harmonic is selected in the [Method](#)^[318] menu a peak 1 is defined as a peak having maximum amplitude among other peaks and located within the margins limited by the LEFT MARGIN and RIGHT MARGIN variables.

5.12.8.3 PEAK LEVEL



The PEAK LEVEL defines the threshold that an FFT peak must cross to be considered a peak. The default peak level is -20 dBmV.

5.12.8.4 PEAK LEFT and PEAK RIGHT



PEAK LEFT defines which of the peaks, counting from the left of the display, you want to start making FFT measurements on. When Harmonic is selected in the [Method](#)^[318] menu a peak 1 is defined as a peak having maximum amplitude among other peaks and located within the margins limited by the [LEFT MARGIN](#)^[318] and [RIGHT MARGIN](#)^[318] variables. When Peak is selected in the [Method](#)^[318] menu, a peak 1 is defined as a peak having maximum amplitude among all peaks exceeding the value of the [PEAK LEVEL](#)^[318] variable.

PEAK RIGHT defines the second peak used for the FFT measurements.

5.12.9 View Define Parameters



The markers can be used to give you a visual indicator of where you are manually setting the thresholds and margins. To use the markers to show the settings, use the View Define Param menu.

Clicking the On / Off options turns the display for the selection on or off.

5.12.10 Mode



Two modes are available for extracting parameters:

- Repetitive
- Single-shot

Repetitive. This mode dynamically extracts the same number of parameters, based on successive acquisition sequences, and updates the measurements approximately every 100 ms (except at very slow repetition rates).

Single-shot. Extracts up to ten measuring parameters and up to four statistical parameters, based on the last acquisition, and displays the result.

5.12.11 Single



Clicking the Single button provides single-shot measurement of selected parameters.

5.13 O/E Converter

O/E Converter

The PicoScope 9221A/9231A optical/electrical oscilloscopes incorporate the following configurations:

- Two electrical channels and independent O/E Converter,
or
- One electrical channel and one optical channel.

The typical unfiltered optical channel bandwidth is 8 GHz. The equipment connection for measurements with unfiltered optical bandwidth is shown in Figure 1.

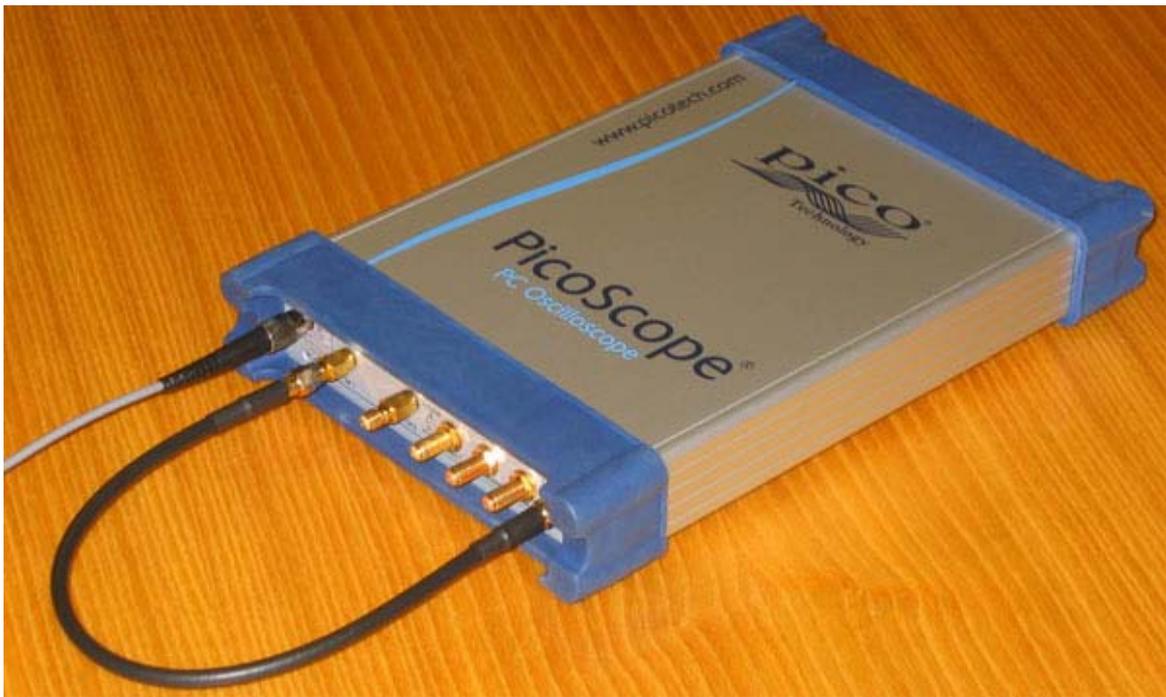


Figure 1

Depending on the remote optional filter, the optical channel provides an optical reference receiver from 51.8 Mb/s to 2.5 Gb/s. The equipment connection for measurements with a filter is shown in Figure 2.

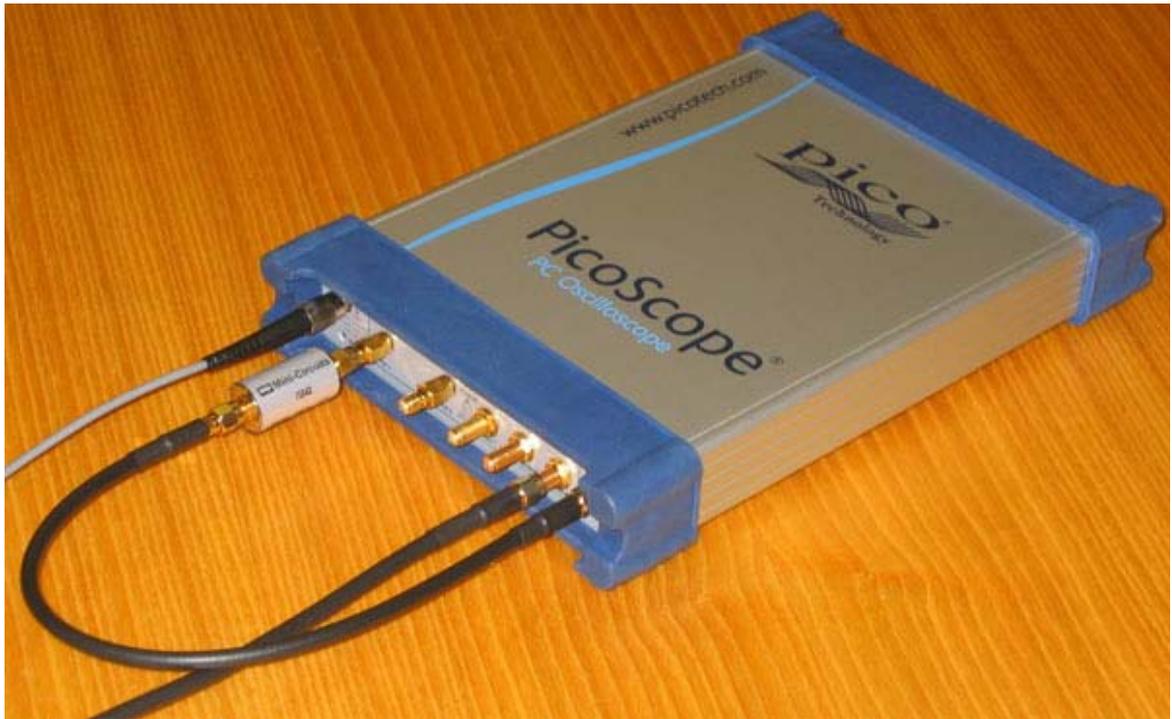
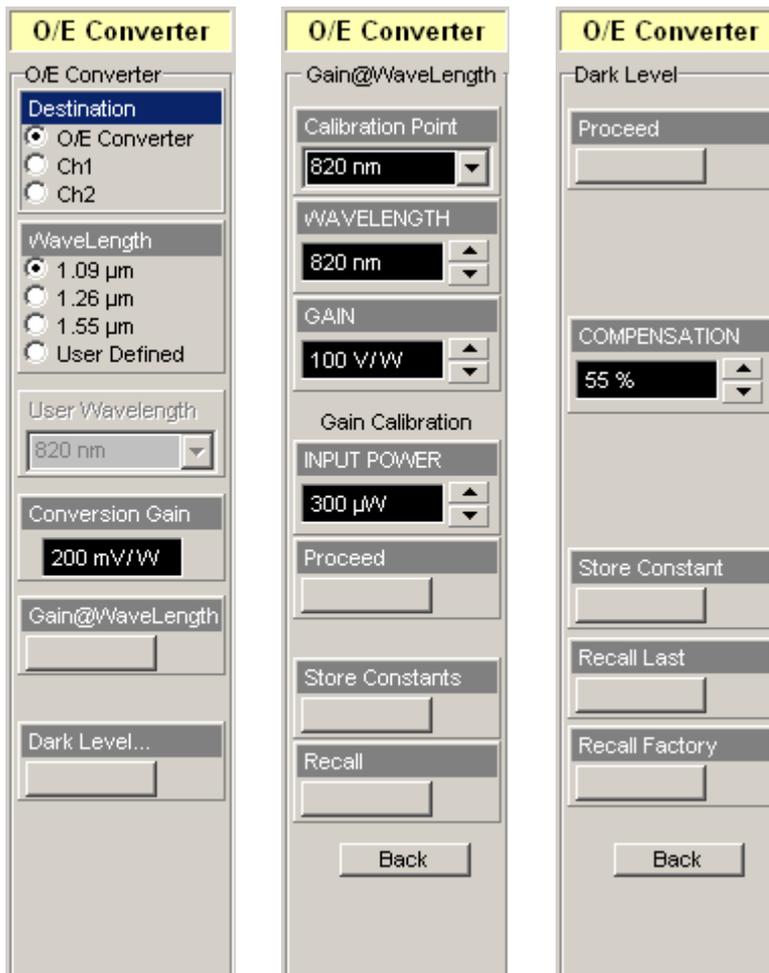


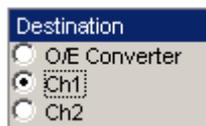
Figure 2

The optical channel is calibrated at 850 nm, 1310 nm, and 1550 nm to provide accurate display of the received optical waveform in optical power units. In addition, the optical channel calibration can be used to provide an additional user-defined wavelength for consistent accuracy at any wavelength between 750 nm and 1650 nm using an optical source and a precision optical power meter.

Menu



5.13.1 Destination



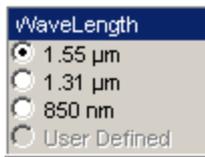
The Destination menu defines the optical configuration of the PicoScope 9000A.

There are three types of configuration:

- **O/E Converter:** The O/E Converter works as an independent module having both input and output. The output of the converter can be used with remote electrical instrument, for example with another oscilloscope. Two electrical channels of the PicoScope 9000A can be used at the same time.
- **Ch1:** The output of the O/E Converter should be connected to the input of the channel 1 by a 30-cm SMA(m) - SMA(m) coaxial cable. With this configuration channel 1 is an optical channel, while channel 2 is an electrical channel.
- **Ch2:** The output of the O/E Converter should be connected to the input of the channel 2 by a 30-cm SMA(m) - SMA(m) coaxial cable. With this configuration channel 2 is an optical channel, while channel 1 is an electrical channel.

To provide specified unfiltered optical bandwidth, use the 30-cm precision SMA(m) - SMA(m) coaxial cable. See "[What's in the box?](#)"

5.13.2 Wavelength



To select the optical wavelength, use the WaveLength menu.

Three options (1.55 μm , 1.31 μm and 850 μm) are concerned with calibrated wavelengths, while the fourth option (User Defined) is concerned with user-defined wavelength points. These points are defined from the Gain@WaveLength... menu.

When the wavelength is defined you can monitor the information about conversion gain from the Conversion Gain window.

When User Defined is selected, the User Wavelength drop-down list box becomes active, so you can select any from user-defined wavelength points. Selecting any of the user-defined wavelength points also opens the information about conversion gain from the Conversion Gain menu.

Wavelength bands

Below are shown the wavelength bands and regions commonly used in the optical communications industry. The band and region ranges are listed for classification purposes, and do not necessarily imply specification of a given range.

Single-mode Systems

- Region II: 1260 nm to 1360 nm
- Region IIe: 1360 nm to 1480 nm
- S-band: 1530 nm to 1565 nm
- L-band: 1565 nm to 1625 nm
- M-band: 1625 nm to 1675 nm

Multimode Systems

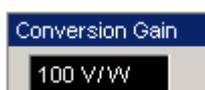
- Region Im: 770 nm to 910 nm
- Region II m: 1260 nm to 1380 nm

5.13.3 User Wavelength



When User Defined is selected from the [Wavelength](#)^[323] menu, the User Wavelength drop-down list box becomes active, so you can select any from user-defined wavelength points. Selecting any of the user-defined wavelength points also opens the information about conversion gain from the [Conversion Gain](#)^[323] window.

5.13.4 Conversion Gain



Conversion Gain is an information window showing the conversion gain of the user-defined wavelength points selected from the [User Wavelength](#)^[323] drop-down list box. The value of conversion gain is defined from the [Gain@WaveLength...](#)^[324] menu.

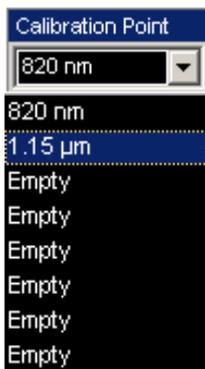
5.13.5 Gain@WaveLength...



The optical channel is calibrated at 850 nm, 1310 nm, and 1550 nm to provide accurate display of the received optical waveform in optical power units. In addition, the optical channel calibration can be used to provide an additional user-defined wavelength for consistent accuracy at any wavelength between 750 nm and 1650 nm using an optical source and a precision optical power meter.

The Gain@WaveLength... menu provides the optical channel calibration for user-defined wavelengths.

5.13.5.1 Calibration Point



To create a new user-defined wavelength, click Empty in the [Calibration Point](#)^[324] drop-down list box.

To recalibrate the optical channel for the existing user-defined wavelength, click the necessary wavelength in the Calibration Point drop-down list box.

5.13.5.2 WAVELENGTH



When an existing user-defined wavelength is selected from the [Calibration Point](#)^[324] drop-down list box, the WAVELENGTH control allows modification of the wavelength value.

When a new user-defined wavelength is selected from the Calibration Point drop-down list box, the WAVELENGTH control shows Undefined, and then the user may enter a new value of wavelength.

5.13.5.3 GAIN



When an existing user-defined wavelength is selected in the [Calibration Point](#)^[324] drop-down list box, the GAIN control allows modification of the gain value.

When a new user-defined wavelength is selected from the Calibration Point drop-down list box, the WAVELENGTH control shows Undefined, and then the user may enter a new value of gain.

The optical channel calibration is used to provide an additional user-defined wavelength for consistent accuracy at any wavelength between 750 nm and 1650 nm using an optical source and a precision optical power meter.

5.13.5.4 INPUT POWER



The INPUT POWER control shows the calibration source power.

For user calibrations from 750 nm to 1000 nm, the calibration source power must be between 175 µW and 225 µW.

For user calibrations from 1000 nm to 1650 nm, the calibration source power must be between 375 µW and 425 µW.

5.13.5.5 Proceed



The Proceed command button performs user-defined wavelength calibration.

5.13.5.6 Store Constants



The Store Constants command button stores all user-defined wavelength calibration constants.

5.13.5.7 Recall



The Recall command button recalls stored user-defined wavelength calibration constants.

5.13.6 Dark Level...



The Dark Level... button opens the dark level calibration menu.

Performing a dark-level calibration will maximize the accuracy of the extinction ratio and other optical automatic measurements you take.

5.13.6.1 Proceed



The Proceed command button opens the dark-level calibration menu.

1. Disconnect all cables from the front panel.
2. Perform calibration of the electrical channels and timebase.
3. Connect the output of the O/E Converter to the input of selected channel with a 30-cm SMA(m) - SMA(m) coaxial cable.
4. Click the Proceed button. After calibration is performed, the line should be on the second major division from the bottom of the graticule.

5.13.6.2 COMPENSATION



The COMPENSATION control shows the result of dark-level calibration. It may also be used for manual control of dark level.

5.13.6.3 Store Constant



The Store Constants command button stores the dark-level calibration value.

5.13.6.4 Recall Last



The Recall Last command button recalls the last stored dark-level calibration value.

5.13.6.5 Recall Factory



The Recall Factory command button recalls the factory dark-level calibration value.

5.13.7 Filters

Filters are used with optical channels for compliance testing. For example, SONET/SDH, Gigabit Ethernet, and Fibre Channel standards have defined the compliance tests for consistency in standard measurements. These tests must be performed in a specific bandwidth. This bandwidth is achieved using the filters in the optical channels.

The compliance tests then verify the performance of the input signal in that bandwidth.

The filters concur with specific SONET/SDH, Fiber Channel, or Gigabit Ethernet data rates. The filters available for the optical channel in the PicoScope 9000A are remote and optional. They should be placed between the output of the O/E converter and the input of the selected electrical channel (see Figure 1 below).

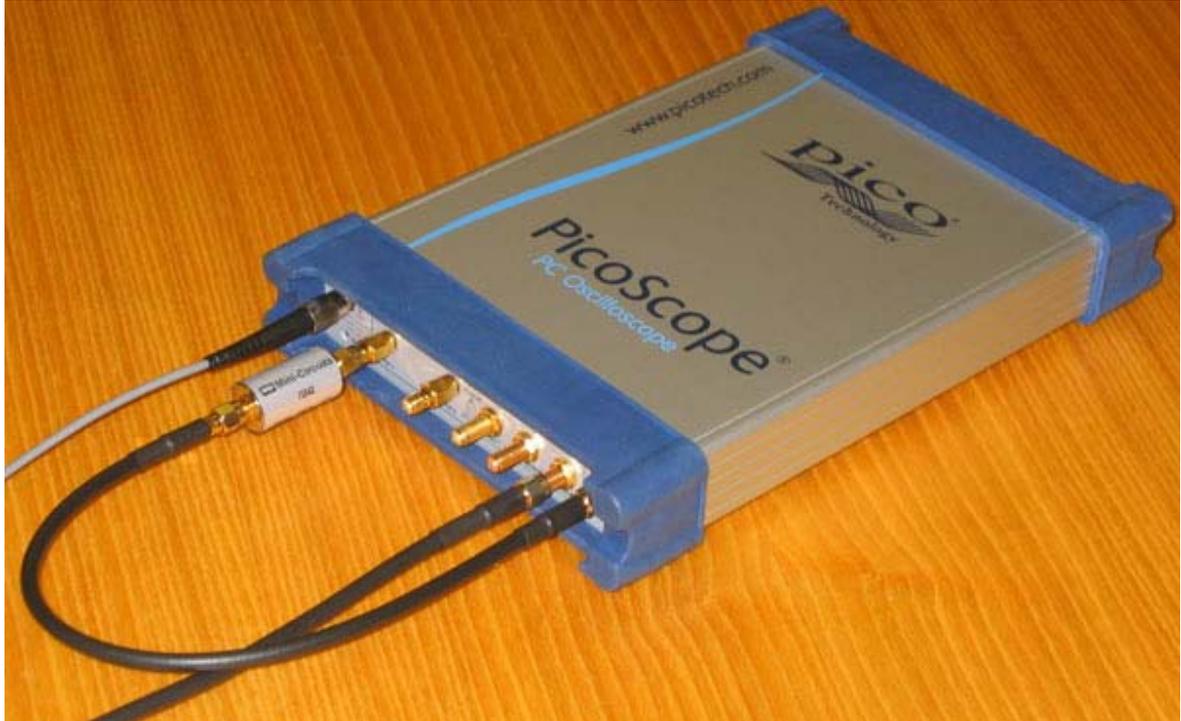


Figure 1

5.13.8 Clock Recovery

Use the clock recovery trigger when the trigger signal is a NRZ data pattern with any data rate between 12.3 Mb/s and 2.7 Gb/s. See the equipment connection in Figure 1 below.

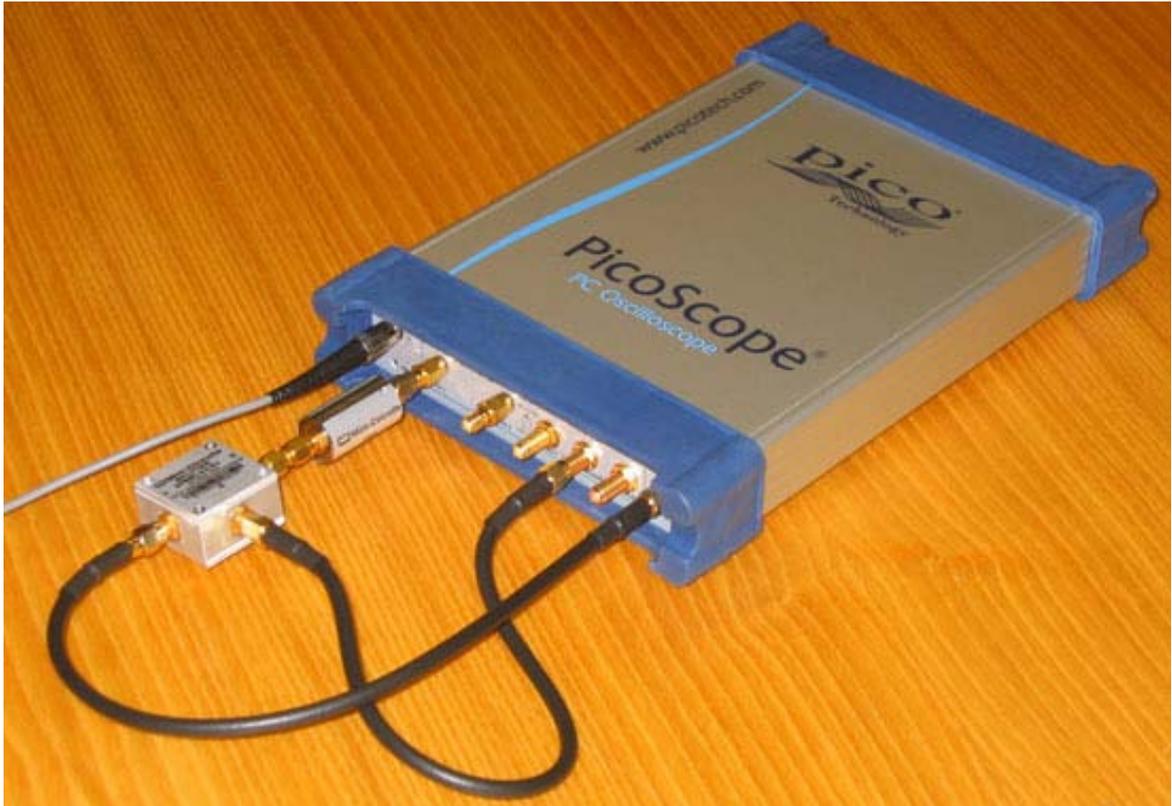


Figure 1

5.14 Permanent Controls



The Permanent Controls are located at the bottom of the display area. They are permanent because they are the most common functions that affect the waveform display. They include the channel, time base and trigger toolbars.

The Permanent Controls are:

- The Channel 1 and Channel 2 on/off check boxes, scale, and offset settings
- The time base modes, the A and B time base scales, and delay settings
- Trigger source, slope, and level settings

Clicking the right mouse button on a selected variable displays a [pop-up numeric keypad](#) ^[427] allowing you to set a precise value.

Each channel has a check box allowing you to turn that channel on or off, and a set of controls allowing you to change the vertical scaling or offset. Only channels that are on are shown in matching colors.

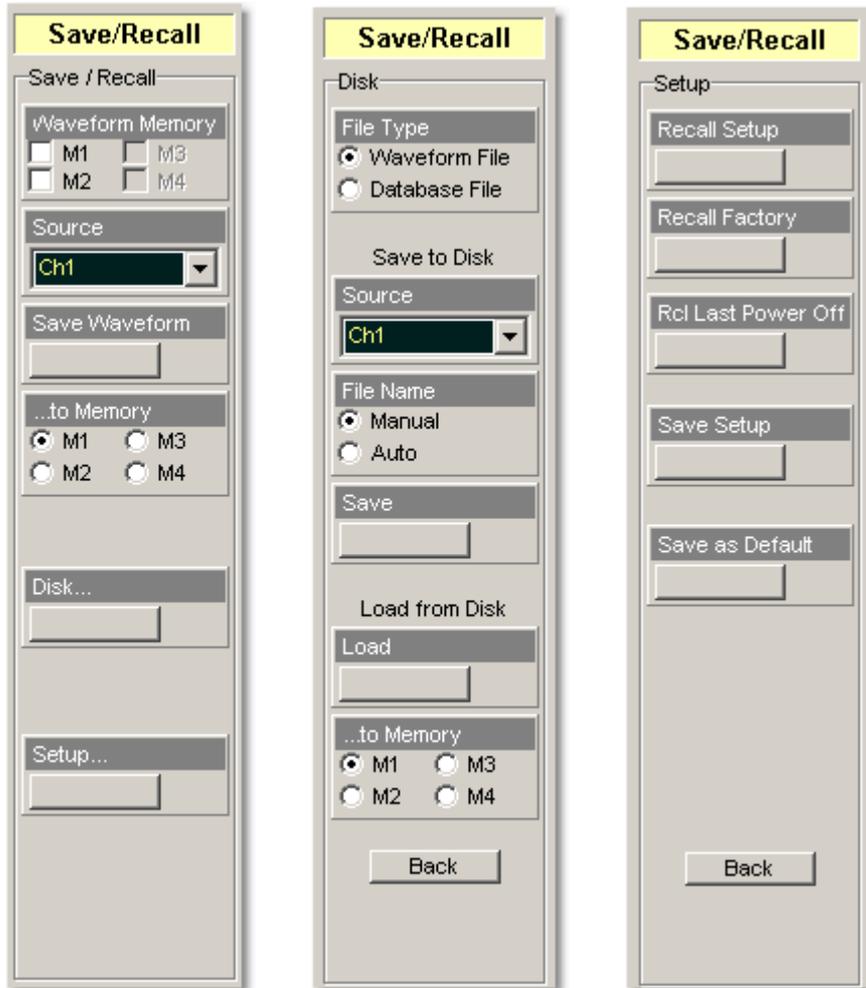
The right-hand side of the permanent controls contains a selection of trigger controls. You can choose between Direct, Prescaler, Int Clk and Clock Recovery source, and between Positive and Negative trigger slope. You can set a particular trigger level.

5.15 Save/Recall Menu



You can use any drive on the PicoScope 9000's PC for the following save/recall tasks:

- To save or recall your acquired waveforms to or from the M1 - M4 waveform memories
- To save your acquired waveforms to a drive
- To load your saved waveforms from a drive to the M1 - M4 display memories
- To save current front-panel setups for later recall



5.15.1 Waveform Memory



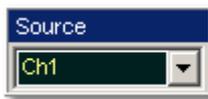
The instrument allows you to save your acquired waveforms to any of the instrument's internal drives. You can recall these waveforms at a later time and display them on the instrument's display screen.

The Waveform Memory allows you to save or recall a waveform into one of the waveform memories (M1 – M4), intended for display. When you recall a waveform from memory, it is displayed in the default color for that memory number. However, you can change the default color in the [Display/Color](#) menu. The default colors are:

- M1: red
- M2: yellow-gray
- M3: violet
- M4: gray

The waveform memories are non-volatile so the data is not lost if you turn off the power, or set the instrument to the default settings. The M1 - M4 memories contain a single waveform record, including the horizontal and vertical scaling parameters. Therefore you can make parametric measurements on stored waveforms or use them as operands in a function. You can also recall the waveform for future comparison or analysis, save it to disk, or load it from a disk.

5.15.2 Source (Waveform Memory)



The Source menu allows you to choose the source of the waveform you intend to save into one of the waveform memories (M1 – M4). You can choose between channels, functions, spectrums, and memories as the waveform sources.

5.15.3 Save Waveform



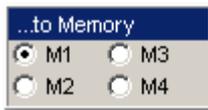
Clicking the Save Waveform button copies the selected waveform to one of the selected waveform memories (M1 – M4).

Save Waveform saves only the current acquired data from the signal. Therefore, the recalled waveform will be displayed as a single trace. This method of saving the waveform is not the preferred process if you want to save a waveform that is using the measurement database (for example, saving a persistence or color-graded trace, or an eye diagram), and you want to recall the entire waveform.



Make sure the waveform to be saved exists; that is, your source must be a channel, an active math waveform, or an active waveform memory. Display the waveform in the timebase with which you want to save it.

5.15.4 ...to Memory



Clicking ...to Memory selects which of the available waveform memory locations the instrument saves the waveform to. When a waveform is saved to a memory, it overwrites any data that was previously stored in that memory. If the Waveform Memory menu for that memory is on, then the display is also updated.

5.15.5 Disk...

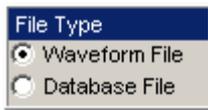


The Disk menu allows you to save your acquired waveform or database as arbitrary file to a disk, in either internal format or text format. You can load these waveforms at a later time into the waveform memory (M1 – M4), and display them on the instrument's display screen. A database also can be loaded and displayed, but not via the waveform memory (M1 – M4).

Save/recall capability is helpful when you want to:

- Recall a waveform for further evaluation or comparison with other waveforms.
- Extend the waveform-carrying capacity of the oscilloscope. The PicoScope 9000 supports two channels, four waveform memories, four math functions, and two spectrums.

5.15.5.1 File Type



The File Type menu selects how waveforms are stored to disk. Two options are available:

- Waveform File
- Database File

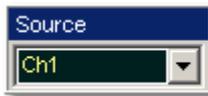
Waveform File

The Waveform File is used for storing the last record of the waveform data acquired by the instrument after the Save button was pressed. You can save acquired waveforms to a file, so that you can recall them at a later time and display them on the instrument's screen, and perform different measurements.

Database File

The Database File is used for storing the multiple-waveform database acquired by the instrument between clicking the Save button and later clicking any another control. The Database File is useful for such database signals as eye diagrams, and the pulse waveforms for noise and jitter measurements with histograms. A histogram can also be saved with this mode. You can recall saved database files at a later time, display them on the instrument's screen with different display styles, and perform histogram measurements and mask tests.

5.15.5.2 Source



The Source menu allows you to choose the source of the waveform you intend to save to disk. You can choose between channels, functions, spectrums and memories as the waveform source.

5.15.5.3 File Name



The File Name menu sets how the oscilloscope creates the name of the file. The PicoScope 9000 uses two modes:

- Manual
- Auto

Manual

You enter the file name from the keyboard of the PC.

Auto

In this mode full information the file name consists of a base name, a file number, and one underline between them. The length of file name is unlimited, while the file number must have five digits. The last digit in the file name is sequential. For example, the instrument can assign the file name abc_XXXXX.cgs where XXXXX is a number from 1 to 99999. Each time you save a waveform, the number in the file name is automatically incremented by one or by whatever is necessary to reach the next unused number. This ensures that the waveform will always be saved to a new file and protects you from inadvertently overwriting an existing file.

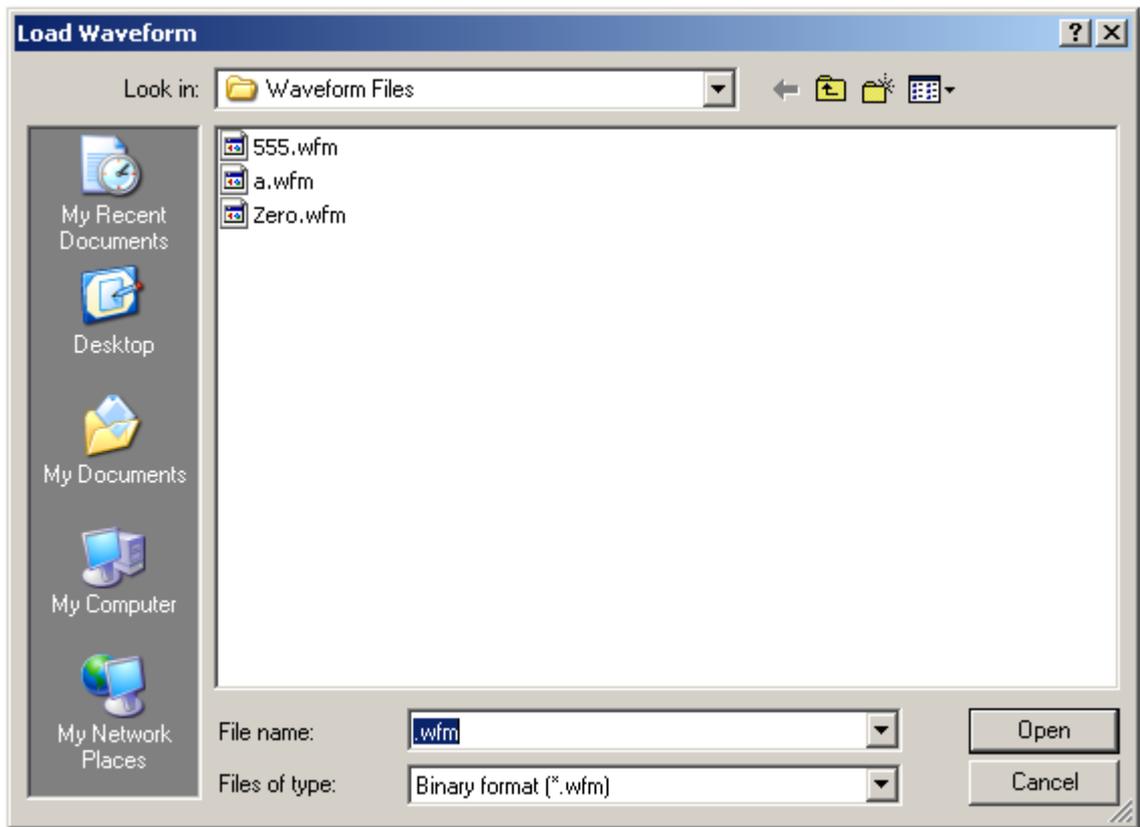
5.15.5.4 Save



The Save button stores the selected waveform to a disk. Clicking the Save button performs one of the following:

1. Waveform File is selected in the [File Type](#) ^[332] menu, while Manual is selected in the [File Name](#) ^[332] menu.

Clicking the Save button opens the Windows Load Waveform dialog box, which allows you select the type of format you want to save the waveform as.



Windows Load Waveform dialog box

You can select one of three types of waveform format:

- Binary format with .wfm extension
- Text format with .txt extension
- Both formats with .wfm, and .txt extensions

The Waveform Files dialog box also allows you to create subdirectories, rename waveform files, or overwrite existing waveform files.

The Save feature saves only the current acquired data from the signal. Therefore, the recalled waveform will be displayed as a single trace. This method of saving the waveform is not the preferred process if you want to save a waveform that is using the measurement database (for example, saving persistence or color-graded traces, or eye diagrams), and you want to recall the entire waveform.



Remember to always copy important settings and waveforms to a removable disk. If your original files are damaged or lost, you can restore the files from the backup disk.

Binary format

The binary format files (.wfm extension) stored using the internal format contain the vertical and horizontal scaling parameters of the original waveform. Therefore, when you recall a waveform into a waveform memory, you can still perform automatic measurements and use the markers. Because the internal format is binary, you cannot directly display its contents in a word processing or plotting program. However, you can convert the binary format file to a text file (.txt) for use in a spreadsheet or word processing program, by recalling a .wfm waveform and saving it in the text format.

Text format

The text format (.txt) is an ASCII text file format that uses alphanumeric characters to represent the voltage values of a waveform. This file format consists of a file header, which describes format (.txt) waveform horizontal and vertical scaling information and scope information. The header is followed by data, which consists of Y values separated by a carriage return and line feed. Text format files use 4 to 5 times more disk space than internal format files.

The text files are a convenient method for transferring waveforms to other software applications. You can import this file format into many spreadsheet or word processing programs.

Both

The Both uses both internal and text formats. Two files are needed when you save waveform in both formats.



Ensure your waveform files have the file name extension .wfm or .txt. If you specify a different extension, the instrument automatically corrects the extension.



Make sure the waveform to be saved exists; that is, your source must be a channel, an active math waveform, or an active waveform memory. Display the waveform in the timebase with which you want to save it.



Enter a useful comment in the file name about each waveform you save. Write the comment so that it explains the purpose of the saved file when that file is later accessed.

2. Waveform File is selected in the [File Type](#)^[332] menu, while Auto is selected in the [File Name](#)^[332] menu.

Clicking the Save button stores your acquired waveforms, automatically incrementing a new number in a previous file name with its selected format(s).

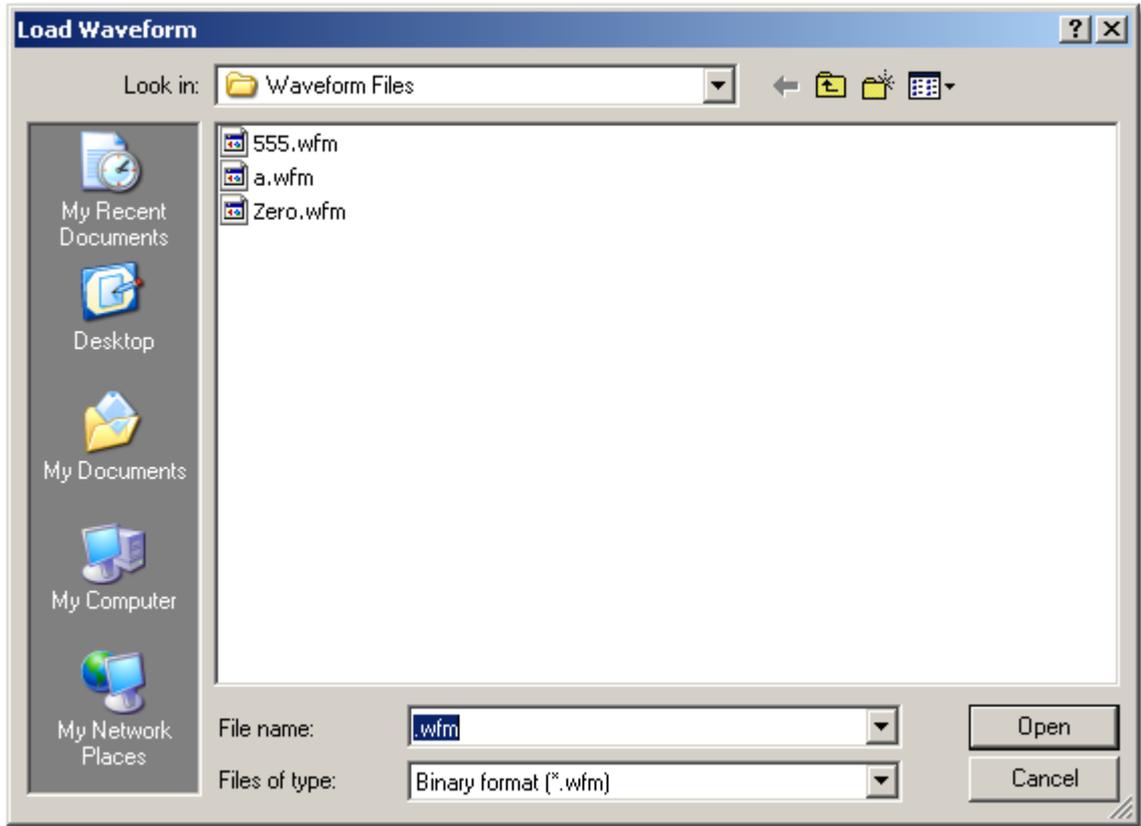
3. Database File is selected in the [File Type](#)^[332] menu.

Clicking the Save button opens Windows Load Waveform dialog box, which allows you to select a file name. Only .cgs file extension can be use in this case.

5.15.5.5 Load



The Load button loads the selected file from a disk into one of the memories M1 - M4 . Clicking the Load button opens the Windows Load Waveform dialog box and allows you to select which subdirectory, waveform, and file format you want to recall.



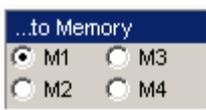
Windows Waveform Files dialog box

You can select one of three types of waveform formats:

- Binary format with .wfm extension
- Text format with .txt extension
- Both formats with .wfm, and .txt extensions

You can also specify in the ...to Memory menu to which one of the four waveform memories M1 – M4 you want to load the file.

5.15.5.6 ...to Memory



The ...to Memory menu selects which of the available memory locations the instrument loads the saved file into.

5.15.6 Setup...



To save a current setup for later use, you can use any drive available to the PicoScope 9000's PC. When you save a setup, all of PicoScope 9000's settings, including measurements, markers, horizontal and vertical control settings, trigger configuration, color scheme, and math functions, are saved.

The Setup... menu allows you to save and recall setups. You can use the setup memories when you want to:

- Save a series of setups to help automate a procedure. You can later recall a sequence of saved setups when you perform the procedure (for production test environments).
- Save and recall a setup that optimises the instrument for displaying and analysing certain signals.
- Compare waveforms by using more than one setup.
- Set the instrument to its default settings. These settings set the instrument to a known operating condition.
- Export a setup for sharing with a second instrument.

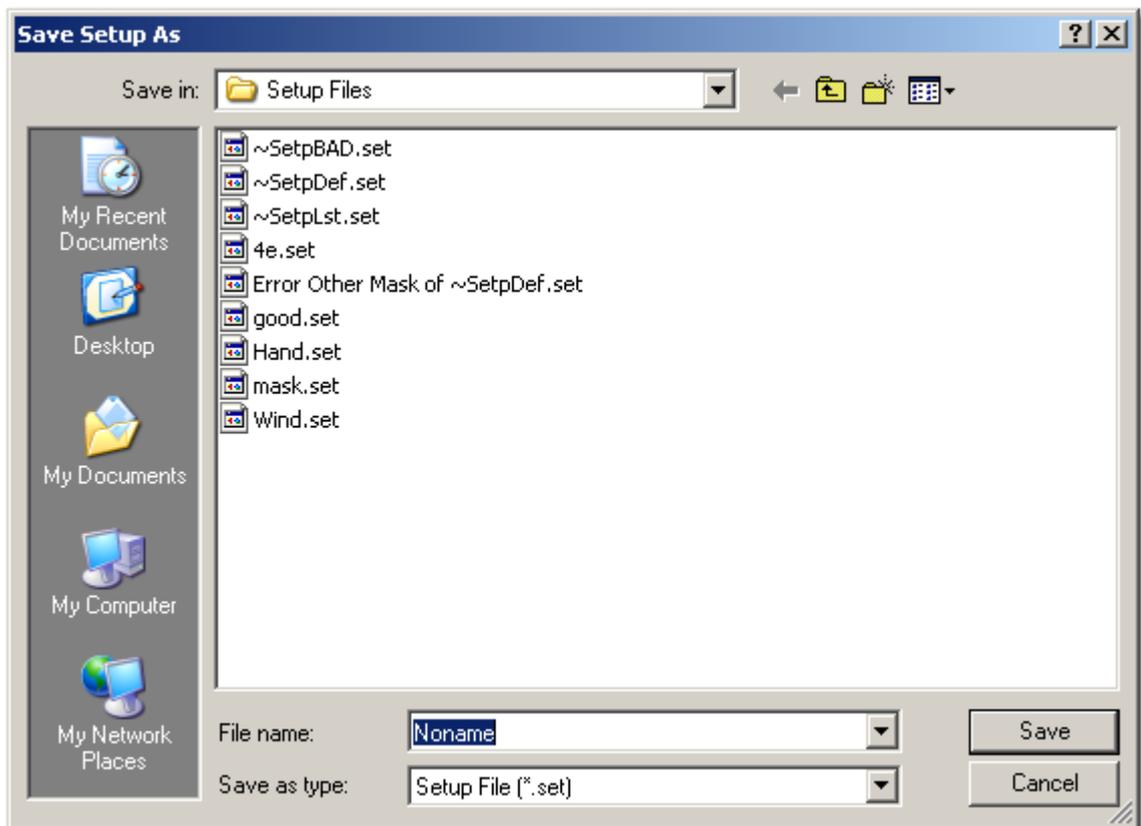
The number of setups you can save is limited only by the available space on the selected drive. Each setup uses approximately 30 kbytes of disk space.

5.15.6.1 Recall Setup



You can recall a setup that you have previously saved on any drive of your PC.

The Recall Setup button sets up the front panel by recalling a front-panel setup from a selected setup memory. Use the standard Windows Save Setup As dialog box. The dialog box opens and allows you to select which subdirectory and setup you want to recall. Because recalling a setup will overwrite the instrument's existing configuration, you may want to save the existing setup first.



Windows Setup Files dialog box



Remember that the PicoScope 9000 uses the file extension .set for setup files.

Recalling a setup replaces the current setup with the recalled setup. If you do not want to lose your current setup, save it to its own setup file for later recall before you recall the new setup.



Remember to always copy important settings and waveforms to an external drive. If your original files are damaged or lost, you can restore the files from the backup drive.

5.15.6.2 Initialization

Initialization allows you to return the instrument to one of its default settings. The default settings place the instrument in a known operating condition. This known operating condition is used as a starting point in the service procedures. You may find it helpful to use this known operating condition when someone else has used the scope before you, or as a starting point when setting up the instrument to view signals.

Three initialization settings are:

- Factory
- Last Power Off
- Default

5.15.6.3 Recall Factory



Clicking the Recall Factory button returns the instrument to the manufacturer's default setting. This places the oscilloscope in a known operating condition. You may find it helpful to use the default factory settings when initially setting up the instrument to view signals, or someone else has used the scope before you. You may also use the default settings to troubleshoot unexpected instrument behaviour.

Default Factory Setup

Channels

Select	Ch1
Display	On (for both channels)
SCALE	200mV/div (for both channels)
OFFSET	0 V (for both channels)
Bandwidth	Full (for both channels)
DESKEW	0 s (for both channels)
Attenuation Units	Off (for both channels)

Timebase

Units	Time
Mode	Main
SCALE A	10 ns/div

TRIGGER

Source	External Direct
Mode	Freerun
LEVEL	0 V
Slope	Positive
HOLDOFF	10 us
Hysteresis	Normal
Attenuation Units	Off

ACQUISITION

Fit Acquisition To...	Single-valued signal
Sampling Mode	Simultaneous
Mode	Sample
RECORD LENGTH	512 points (for both channels)

DISPLAY

Trace Mode	All Locked
Style	Variable Persistence
PERSISTENCE TIME	2 s
Format	YT
Graticule	Grid
Default Colors	Default colors legend

SAVE/RECALL

...to Memory	M1
Disk	
File Type	Waveform File
File Name	Manual
...to Memory	M1

MARKER

Type	Off
------	-----

MEASURE

Display	Off
Define Parameter	
Method	Histogram
Thresholds	10%-50%-90%
Margins	
Mode	Marker
LEFT MARGIN	0 s
RIGHT MARGIN	100 s
Left Threshold	Middle
Right Threshold	Middle

LIMIT TEST

Off

MATHEMATICS

Select	F1
Display	Off
Operator	Add
Operand 1	Ch1
Operand 2	Ch2

FFT

Select	S1
Display	Off
Source	Ch1
Window	Rectangular

ZOOM

Off

HISTOGRAM

Axis	Off
Source	Ch1

MASK TEST

Compare with	Ch1
--------------	-----

EYE DIAGRAM

Measure	Off
Source	Ch1
Define Parameter	
EYE BOUNDARY 1	40%
EYE BOUNDARY 2	60%
Thresholds	20%-80%

5.15.6.4 Recall Power Off



Clicking the Recall Power Off button returns the instrument to the last setting before the power supply was last switched off.

5.15.6.5 Save Setup



The Save Setup button stores the present front-panel setup to a selected setup memory. To save a current setup for later use, you can use any available drive. Use the standard Windows Setup Files dialog box. You can create subdirectories; new setup files, or overwrite existing setup files from this dialog box. The PicoScope 9000 uses the file extension .set for setup files.



Enter a useful comment about each setup you save. Write the comment so that it explains the purpose of the saved file when that file is later accessed.

When you save a setup, all settings, including measurements, markers, horizontal and vertical control settings, trigger configuration, color scheme, and math functions, are saved to the disk file you have selected. The number of setups you can save is limited only by the available space on the drive. Each setup uses approximately 30 kbytes of disk space.



Ensure your setup files have the extension .set.

If you do not specify an extension, the oscilloscope supplies one automatically.

If you use a different extension, the instrument may not recognize the file as a setup file, therefore you may have trouble saving or finding the setup file.

To recall a setup you have previously saved, use the Recall Setup button in the same menu.

Try to use the Save Setup button to save important setups.



Remember always to copy important settings and waveforms to an external disk. If your original files are damaged or lost, you can restore the files from the backup disk.

5.15.6.6 Save as Default



Clicking the Save as Default button stores the present front-panel setup as the default setup.

You can recall the saved default setup by clicking the Default Setup button in the [System Controls](#) ³⁴⁴ area.

5.16 System Controls



Using the System Controls, you control whether the oscilloscope is running or stopped; other buttons allow you to reset the oscilloscope to its default setup, automatically configure the oscilloscope for the current signals (Autoscale), or erase the waveforms from the display.

The System Controls are:

- The [Clear Display](#) ^[345] button
- The [Run](#) ^[346] button
- The [Stop/Single](#) ^[347] button
- The [Autoscale](#) ^[348] button
- The [Default Setup](#) ^[350] button
- The [Undo](#) ^[351] button
- The [Copy](#) ^[352] button
- The [Print](#) ^[354] button
- The [Help](#) ^[355] button

5.16.1 Clear Display

A rectangular button with a light gray background and a thin black border. The text "Clear Display" is written in a dark gray, sans-serif font, centered within the button.

Clicking the Clear Display button erases all channel waveform data from the graticule area. The following occurs when the display graticule is cleared:

- All channel waveform data is erased from the graticule area.
- Functions, spectrums and waveform memories are not erased from the display graticule when the clear display feature is executed.
- All associated measurements and measurement statistics are reset (averaging, color-grading, mask test data, limit test data, and histogram results), if enabled.

When the instrument is running

If the instrument is running and is receiving triggers, new waveform data is displayed on the next acquisition, averaging is reset; and persistence and color-grading, histograms, the mask testing database and all measurements are recalculated.

When the instrument is stopped

If the instrument is stopped, the display remains cleared of waveform data until the trigger circuit is rearmed and the instrument is triggered. Then the new data is displayed and measurements are recalculated.

5.16.2 Run



The Run button causes the instrument to resume acquiring data. If the instrument is stopped, it starts acquiring data on the next trigger event. If the instrument is already in the run mode, it continues to acquire data on successive trigger events.

If pressing the Run button does not cause waveform data to display on the screen, try the following:

- Make sure a signal is connected to one of the channel and the display for that channel is turned on.
- Make sure the offset does not have the trace clipped off the display.
- Check the trigger setup conditions to make sure the trigger conditions are valid for the signal.
- Set the trigger mode to Freerun. Freerun forces the instrument to trigger, which may allow you to see enough of the signal so that you can set up the front panel properly.
- Click the Autoscale button.

5.16.3 Stop/Single

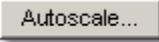


The Stop/Single button causes the oscilloscope to stop acquiring data or to perform a single waveform acquisition. You can stop acquisition if you want to freeze the displayed waveform(s) for closer analysis or measurement.

Each subsequent press of the Stop/Single button rearms the trigger circuit. A complete acquisition cycle is performed, and any measurements are recalculated.

If all of the channels are turned off or if a trigger event is not found, the instrument will not acquire any data.

5.16.4 Autoscale



Adjusting an oscilloscope to display a stable trace of usable size and amplitude can be a time-consuming process. The Autoscale feature of the PicoScope 9000 can quickly give you a stable, meaningful trace display.

The Autoscale button causes the instrument to quickly analyse any waveforms connected to the trigger and channel inputs. Then, it sets up the vertical, horizontal, and trigger controls to best display that signal.

When you click the Autocale button, you tell the PicoScope 9000 to examine the signal and adjust the following controls for optimum display:

- Vertical scale and offset
- Timebase scale and delay
- Trigger level, if appropriate to that trigger source

The PicoScope 9000 must have an available trigger source and input. For example, if you are using the DIRECT TRIGGER INPUT, and Direct is selected in the [Trigger Source](#) menu, the trigger signal must be connected to this trigger input. Autoscale can then set the trigger level. If you are using the PRESCALE TRIGGER INPUT, and the Prescaler is selected in the [Trigger Source](#) menu, the trigger signal must be connected to this trigger input.

When Direct is selected in the [Trigger Source](#) menu the Autoscale function can find repetitive signals with:

- Frequency greater than 1 kHz
- Duty cycle greater than 1%
- Vertical amplitude greater than 50 mV p-p
- Trigger amplitude as it is specified

When Prescaler is selected in the [Trigger Source](#) menu, the Autoscale function can find repetitive signals having trigger frequency and amplitude as they are specified.

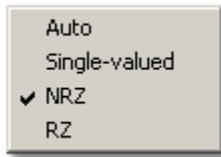
Autoscale is operative only for relatively stable input signals. Autoscale looks for signals on both channels, even if they are turned off. It also searches for a trigger signal on the trigger inputs.

If the Autoscale button is pressed unintentionally, use the Undo button to return the instrument to the settings that existed before.

When the Autoscale is selected, the following controls are set:

- Time Base Mode: Delayed (B)
- SCALE B: to best display the waveform
- Trigger.
 - If the Direct Trigger Source is selected: Freerun Mode, Positive Slope, Trigger LEVEL to 50% amplitude point of the trigger waveform, Normal Hysteresis, HOLDOFF with minimum value;
 - If the Prescaler Trigger Source is selected: to best display waveforms
- Vertical OFFSET: to best display waveforms on active channels
- Vertical SCALE: to best display waveforms on active channels

Autoscale options



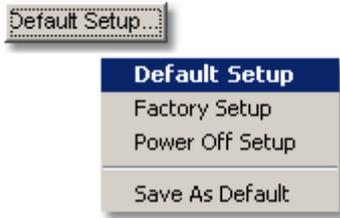
To perform autoscale, right-click the Autoscale button to get the four autoscale options. Select one of them, and then the scope will perform an optional Autoscale.

The four Autoscale options are:

- Auto
- Single-valued
- NRZ
- RZ

Auto.	Optimizes the autoscale algorithm for such waveforms as sine waves or pulses, for all main menus excluding the following cases: <ul style="list-style-type: none">● Either NRZ or RZ is selected in the Eye Diagram/Measure^[78] menu● One of the standard masks for eye-diagram waveforms is selected in the Mask Test^[204] menu
Single-valued.	Optimizes the autoscale algorithm for such waveforms as sine waves and pulses.
NRZ.	Optimizes the autoscale algorithm for such waveforms as NRZ eye-diagrams.
RZ.	Optimizes the autoscale algorithm for such waveforms as RZ eye-diagrams

5.16.5 Default Setup



The Default Setup button returns the instrument to its default settings. This places the oscilloscope in a known operating condition. You may find it helpful to use this known operating condition when someone else has used the oscilloscope before you. If you accidentally press the Default Setup button, use the Undo button to return the oscilloscope to the operating condition it was in before Default Setup was pressed.

Right-click on the button to get four options:

- Default Setup. Returns the instrument to its default settings.
- Factory Setup. Returns the instrument to default setting of the manufacturer.
- Power Off Setup. Returns the instrument to the last setting before switching off the power supply.
- Save As Default. Stores the present front-panel setup as default setup.

5.16.6 Undo



You may find situations where you have unintentionally selected an unnecessary control. When this happens, you can use the Undo button to return the oscilloscope to the previous settings. The depth of undo steps can be up to 100.

If you later decide you didn't want to undo an action, right-click the button and select Redo.

5.16.7 Copy

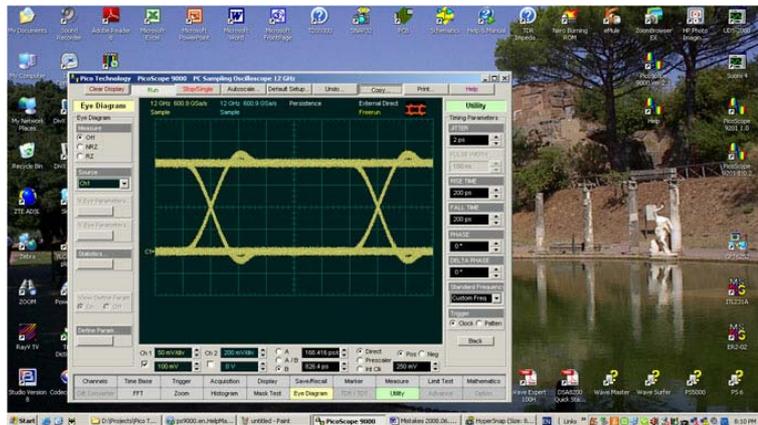


Clicking the Copy button copies different programming windows into the Windows Clipboard. From there, you can paste copied information into such Windows programs as Word, Corel Draw, Paint Brush, Photoshop and so on.

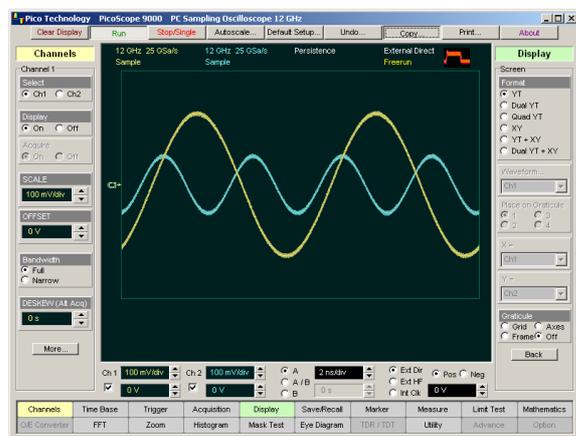
Use the Copy function when preparing documentation based on usage of the PicoScope 9000.

Right-click the button to get six options:

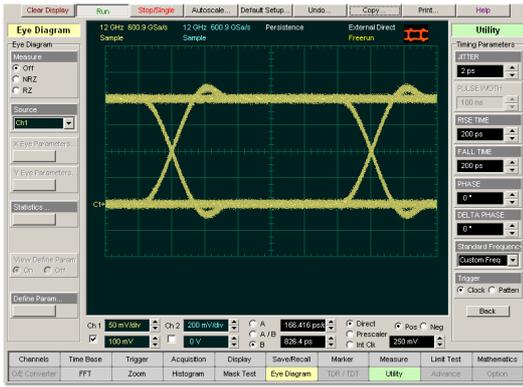
- Full Screen
- Full Window
- Client Part
- Invert Client Part
- Oscilloscope Screen
- Invert Oscilloscope Screen



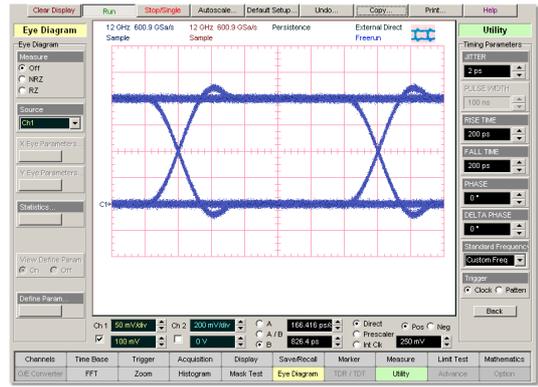
Full Screen Copy



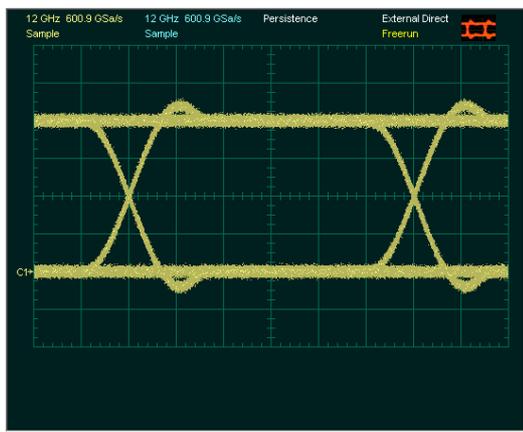
Full Window Copy



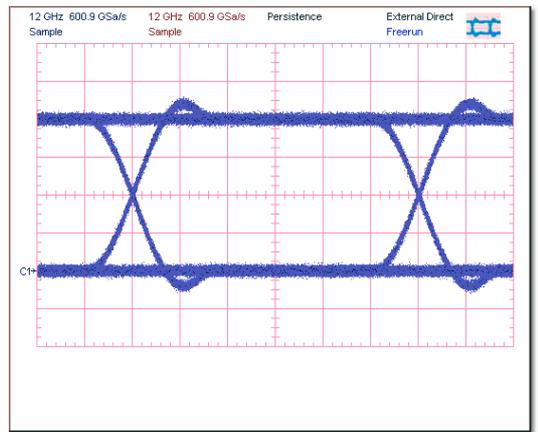
Client Part Copy



Invert Client Part Copy



Oscilloscope Screen Copy



Invert Oscilloscope Screen Copy

5.16.8 Print



To print, you must first have installed and configured a printer.

To print a hardcopy, click the Print button.

Right-click the button, and then select the Printer Setup. It opens the standard Windows Print Setup dialog box, which allows you select printer options.

5.16.9 Help



The Help button has two functions:

- Click it to activate the context-sensitive built-in information system on the instrument. This changes the pointer into a context-sensitive help icon, like this:
 . You can then click any control to open the manual at the relevant page.
- Right-click it to open the PicoScope 9000 Help manual, or the About... and Instrument Info windows.

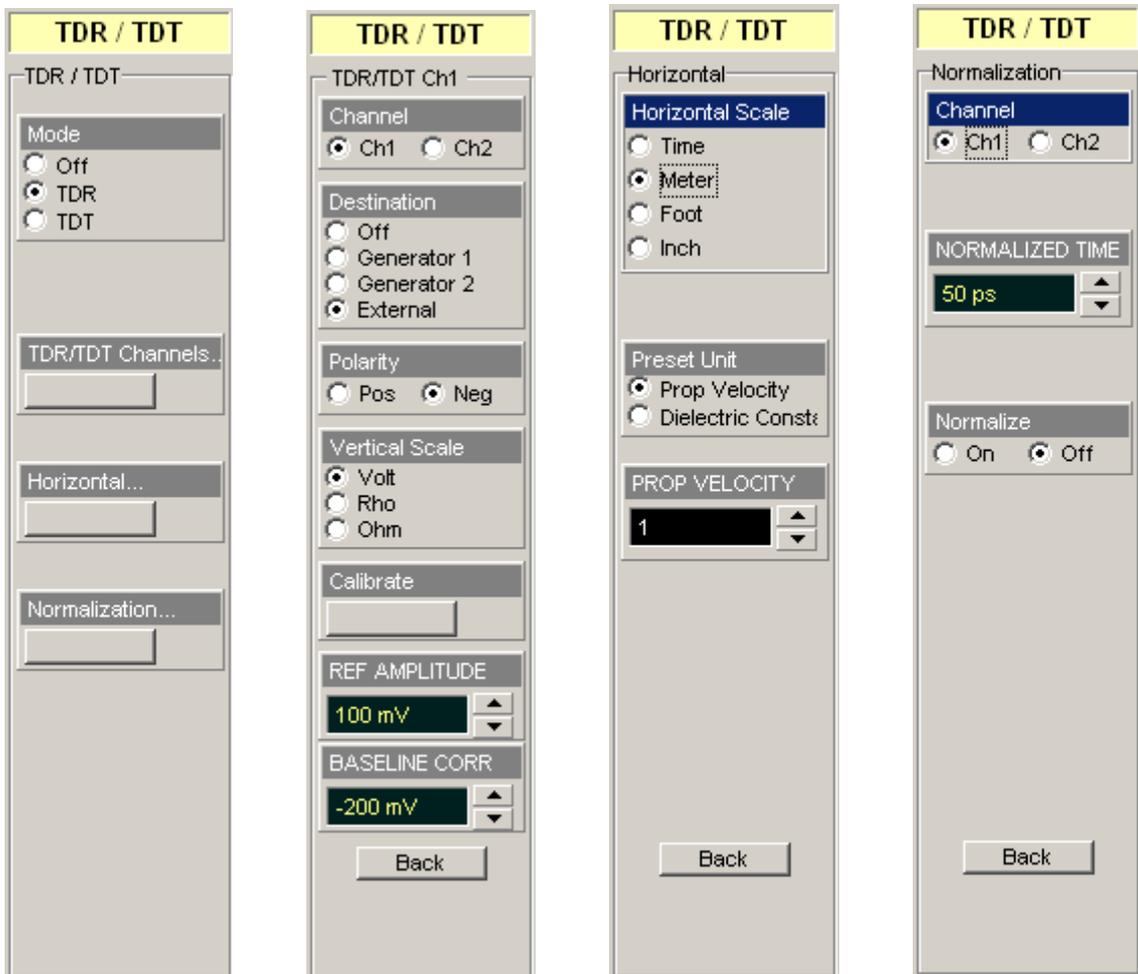
5.17 TDR / TDT

TDR / TDT

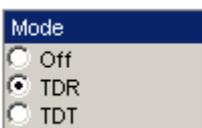
Time Domain Reflectometry, or TDR, is a method of characterizing a transmission line or network by sending a step signal into one end and monitoring the electrical reflections.

A TDR step can also be used to make Time Domain Transmission (TDT) measurements. TDT is a technique that allows you to measure the response of a system by sending steps through a device and monitoring its output. The measurements are made on signals transmitted through the device rather than reflections from the device (as in TDR).

The TDR/TDT menu provides you with automatic and manual single-ended TDR and TDT measurement capability.



5.17.1 Mode



The Mode menu lets you control the TDR/TDT functions of the PicoScope 9000A. The selector turns the features Off, or enables TDR or TDT.

5.17.2 TDR/TDT Channels...



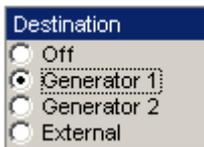
The TDR/TDT Channels... button opens the second-level menu that lets you control the vertical TDR/TDT functions of the PicoScope 9000A.

5.17.2.1 Channel



The Channel menu selects the channel that will be used for TDR/TDT. You can assign the Vertical Scale, REF AMPLITUDE and BASELINE CORR for each selected channel.

5.17.2.2 Destination



The Destination menu selects the signal to be used as a TDR/TDT step.

The four choices are:

- Off
- Generator 1
- Generator 2
- External

Off

Turns the TDR step off and disables the TDR measurement system.

Generator 1

Turns the TDR 1 step on (the OUTPUT 1 of the oscilloscope's generator) and enables the TDR/TDT 1 measurement system. This output generates a 400-mV negative-going step having typical 20-80% rise time of 100 ps.

Generator 2

Turns the TDR 2 step on (the OUTPUT 2 of the oscilloscope's generator) and enables the TDR/TDT 2 measurement system. This output generates a 400-mV negative-going step having typical 20-80% rise time of 100 ps.

External

Use an external step generator acceptable for your measurements. This setup provides control for and requires an external step generator before measurements can be made.



The external step generator should have pre-trigger output with minimum 40-ns pre-trigger time.

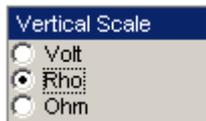
5.17.2.3 Polarity



This control should correspond to the polarity of the external step generator. The Polarity is active only when External is selected in the [Destination](#) menu.

- Pos. For positive polarity of external step generator
- Neg. For negative polarity of external step generator

5.17.2.4 Vertical Scale



The Vertical Scale menu selects the vertical units of measure commonly used in TDR/TDT. The menu applies to the selected channel.

Vertical scale for TDR

The three choices are:

- Volt
- Rho
- Ohm

Volts

The vertical axis unit is volt.

In addition to voltage, TDR can use special scalings. The vertical axis units most appropriate to TDR/TDT measurements are either reflection coefficient Rho (**P**) or impedance (ohm).

Rho

Reflection Coefficient is defined as follows:

$$Rho = Er / Eo$$

where Er is the measured reflected voltage

Eo is the reflected voltage for the opened reference plane.

For open circuit: $Er = Eo$ and $Rho = 1$

For short circuit: $Er = -Eo$ and $Rho = -1$

For 50-ohm circuit: $Er = 0$ and $Rho = 0$

Ohm

Rho values can be converted to impedance values Z or back by using the following equations:

$$Z = Zo * (1 + Rho) / (1 - Rho),$$

$$Rho = (Z - Zo) / (Z + Zo)$$

where Z is the impedance of the DUT

Z_0 is the 50-ohm impedance of the transmission line

For open circuit when $\rho = 1$, $Z = \infty$.

For short circuit when $\rho = -1$, $Z = 0$.

For a 50-ohm circuit, $\rho = 0$ and $Z = 50 \text{ ohm}$.

To use both ρ and Ohm vertical scales the oscilloscope should be calibrated.

Vertical scale for TDT

In addition to the voltage scale, TDT can also use Gain scaling.

- Volt
- Gain

Gain

Gain is defined as follows:

$$GAIN = E / A$$

where: E is the measured voltage

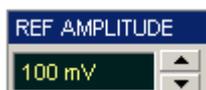
A is the amplitude of the TDT step.

5.17.2.5 Calibrate



The Calibrate button starts the calibration procedure for the TDR or TDT vertical scale. Follow the instructions when the calibration process starts.

5.17.2.6 REF AMPLITUDE



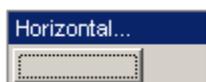
The REF AMPLITUDE control allows manual or automatic setting of the amplitude of TDR/TDT step equal to 1.00 ρ .

5.17.2.7 BASELINE CORR



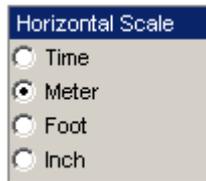
The BASELINE CORREction control changes the vertical position of the TDR/TDT step on the display. Use BASELINE CORR when ρ mode is selected in the [Vertical Scale](#) ^[358] menu. This feature is most useful in TDR/TDT measurements, because changes in transmission line impedance affect the vertical placement of the trace.

5.17.3 Horizontal...



The Horizontal... button opens a second-level menu that lets you control the horizontal TDR/TDT functions of the PicoScope 9000A.

5.17.3.1 Horizontal Scale



The Horizontal Scale menu selects one of the horizontal units of measure commonly used in TDR/TDT.

The selection is:

- Time
- Meter
- Foot
- Inch

When Meter, Foot or Inch is selected you can use the [Preset Unit](#) ^[360] menu, and also the PROPagation VELOCITY/DIELECTRIC CONSTAnt control to enter the parameters of your transmission line.

5.17.3.2 Preset Unit



The PicoScope 9000A allows you to specify the propagation delay, which is the fraction of the speed of light at which signals travel through your transmission line. If you know that the propagation velocity of your transmission line (cable) differs from the default, use the Preset Unit menu.

The two choices are:

- Propagation Velocity
- Dielectric Constant

5.17.3.3 PROPagation VELOCITY or DIELECTRIC CONSTAnt



The PROPagation VELOCITY or DIELECTRIC CONSTAnt controls let you specify the fraction of the speed of light at which the signal passes through your transmission line or network. PROP VELOCITY and DIELECTRIC CONST apply only to axis units of distance, and do not apply if your horizontal units are seconds.

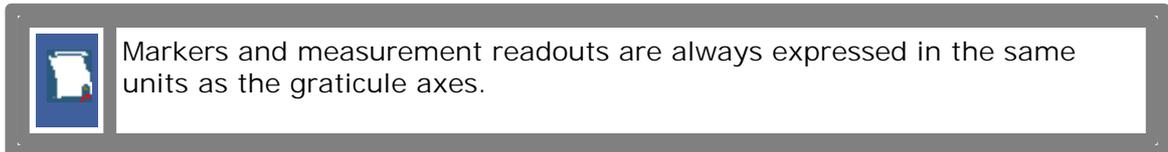
Propagation velocity is relative to an air-line transmission cable, so a setting of 1.0 indicates that your transmission line or network passes signals at the same speed as an air-insulated cable. The default value of 0.7 applies to most 50- coaxial cables with plastic dielectric.

You can change the value of propagation velocity from 0.1 to 1 in 0.005 steps, or the value of dielectric constant from 1 to 100 in 0.01 steps.

If you don't know the velocity but you know the dielectric constant of the transmission medium, you can convert its dielectric constant to a velocity using the following equation:

$$Velocity = \frac{1}{\sqrt{DielectricConstant}}$$

The horizontal axis is now calibrated in your chosen units of measurement.



5.17.4 Correction...



The Correction... menu allows you to change the rise time of the corrected step for TDR or for TDT on each of the channels, and also to turn on or off the display of the corrected TDR or TDT trace (function).

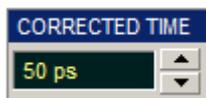
Correction compensates for sources of measurement errors concerned with TDR response. By using correction, the results become more reliable, repeatable, and accurate. In addition, performing a correction allows the instrument to simulate stimulus steps with different effective rise times. This allows you to view the effect of actual signal rise times on the magnitude of reflections from discontinuities.

5.17.4.1 Channel



This selects the channel to be used for correction.

5.17.4.2 CORRECTED TIME



The CORRECTED TIME control allows you to change the corrected step's rise time from a minimum of 100 ps or 0.1 x time/div, whichever is greater, to a maximum of 3 x time/div. This rise time value applies to both TDR and TDT corrected channels.

5.17.4.3 Correct



The Correct menu allows you to start the correction calibration procedure. After calibration is performed you'll see the corrected function together with a signal on the TDR channel. You can turn on or off the display of the corrected TDR function.

5.17.5 TDR Setup Guide

5.17.5.1 Equipment connections for TDR measurements

1. Connect the equipment as shown in Figure 1.

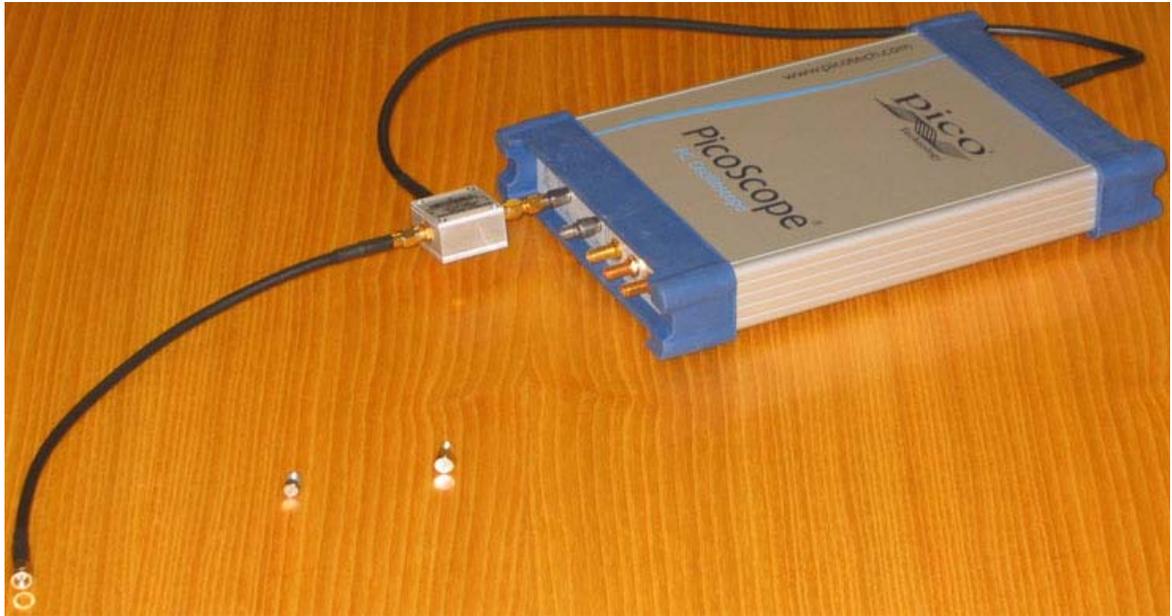


Figure 1

2. Switch on the oscilloscope and run the software.
3. Select the Vector style from the [Display](#) ^[55] menu.
4. Uncheck Ch 2.
5. Click TDR/TDT in the [Main Menu](#) ^[203].
6. Click TDR in the [Mode](#) ^[178] menu.
7. Click TDR/TDT Channels...
8. Click Generator 1 in the [Destination](#) ^[322] menu. See Figure 2. Notice that reflected step has similar slope to the incident step.

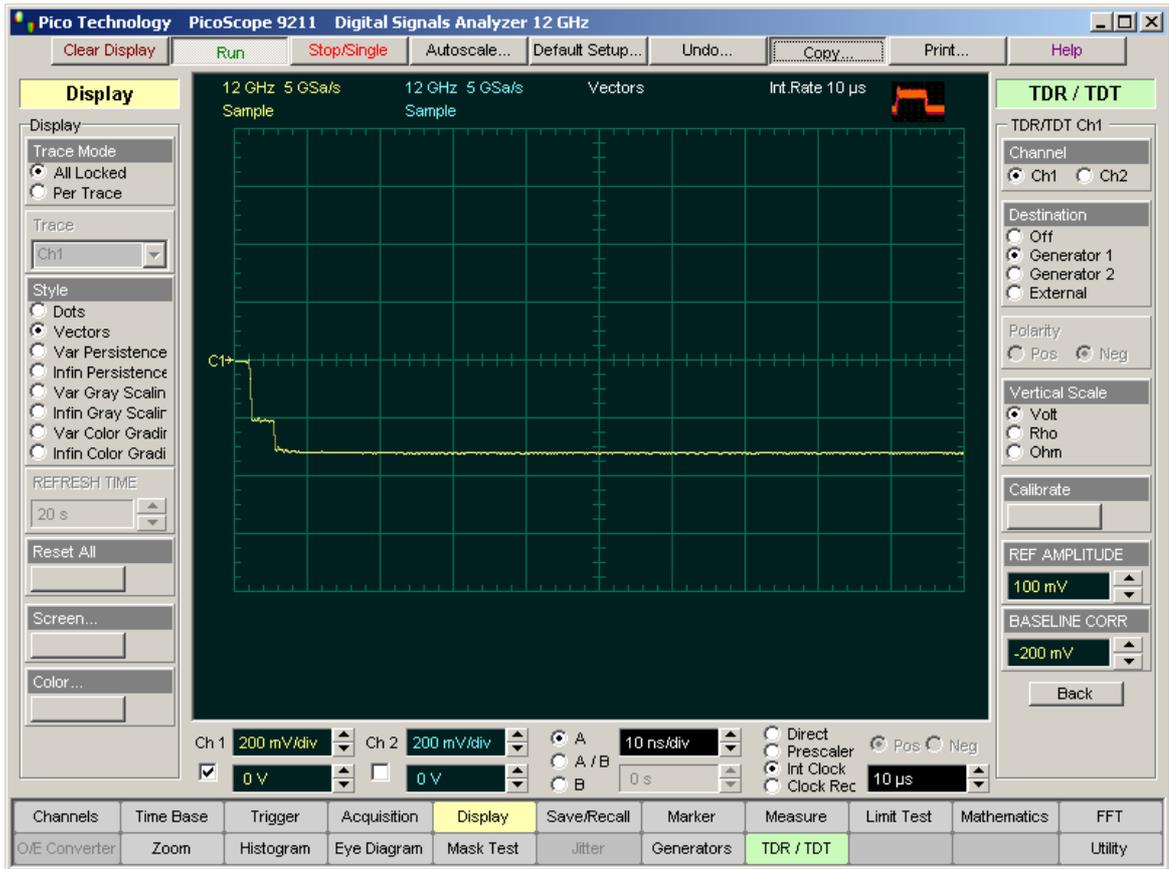


Figure 2

The internal generator generates an approximately 400-mV negative step. Going through the Resistive Power Divider its amplitude is divided by 2 on each of the outputs when terminated in 50 ohms.

The incident step (the first negative step in Figure 2) coming to the sampler from one of the outputs of the Resistive Power Divider has approximately 200-mV amplitude and is not used for TDR measurements.

The same 200-mV step coming from the second output of the Resistive Power Divider goes through the 30-cm precision cable to the transmission line and is used as a TDR step. It is a reflected step. All the reflections from transmission line return to the sampler repeatedly passing through the Resistive Power Divider. That is why step amplitude is divided by 2 once more and is approximately 100 mV (the second negative step in Figure 2).

The Reference Plane is a physical location where the transmission line is connected to the DUT. A 30-cm precision coaxial cable is used to separate the two steps: the unused incident step and the useful reflected step from the Reference Plane with DUT.

9. Connect the 50-ohm termination to the Reference Plane. See Figure 3. Notice that there is no reflection from the Reference Plane.

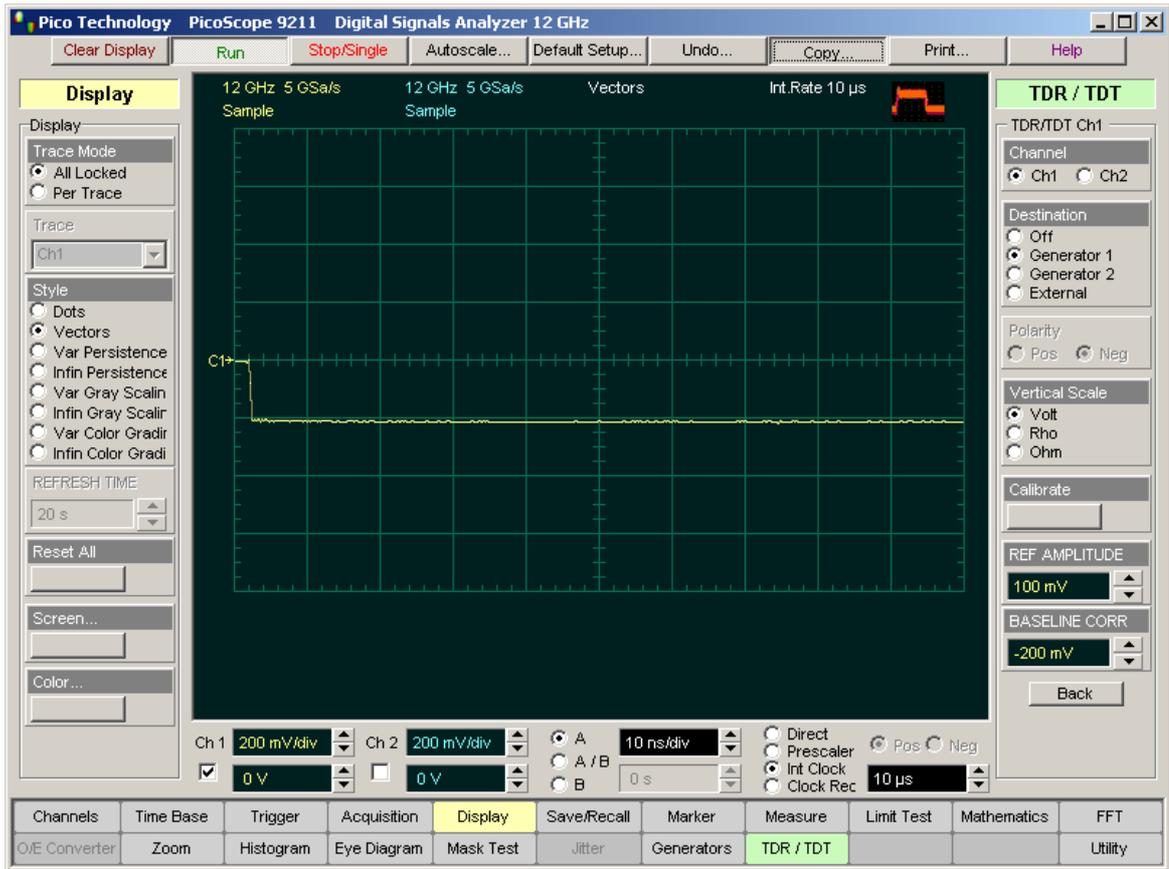


Figure 3

10. Connect the Short to the Reference Plane. You should see a picture like Figure 4. Notice that there is a reflected step having 100-mV amplitude and with the opposite (positive) polarity.



Figure 4

11. Connect a 6-dB attenuator to the Reference Plane. This attenuator should have approximately 85 ohm resistance when it is unterminated. See Figure 5. Notice that the reflected step has similar slope to the incident step, but its amplitude is much less than when it was reflected from the open Reference Plane.



Figure 5

5.17.5.2 Manual TDR Calibration

1. Connect the equipment as shown in Figure 1 in "[Equipment connections for TDR measurements](#)".
2. Get a picture as shown in Figure 2 in "[Equipment connections for TDR measurements](#)".
3. Click [Acquisition](#), then Multiple Average in the Mode menu. Select AVERAGE N = 16.
4. Click [Measure](#)/Parameters/Y Parameters...
5. Check Mean.
6. Move Left Margin to the fourth division.
7. Write the mean value V_0 equal to -322.4 mV. See Figure 1.

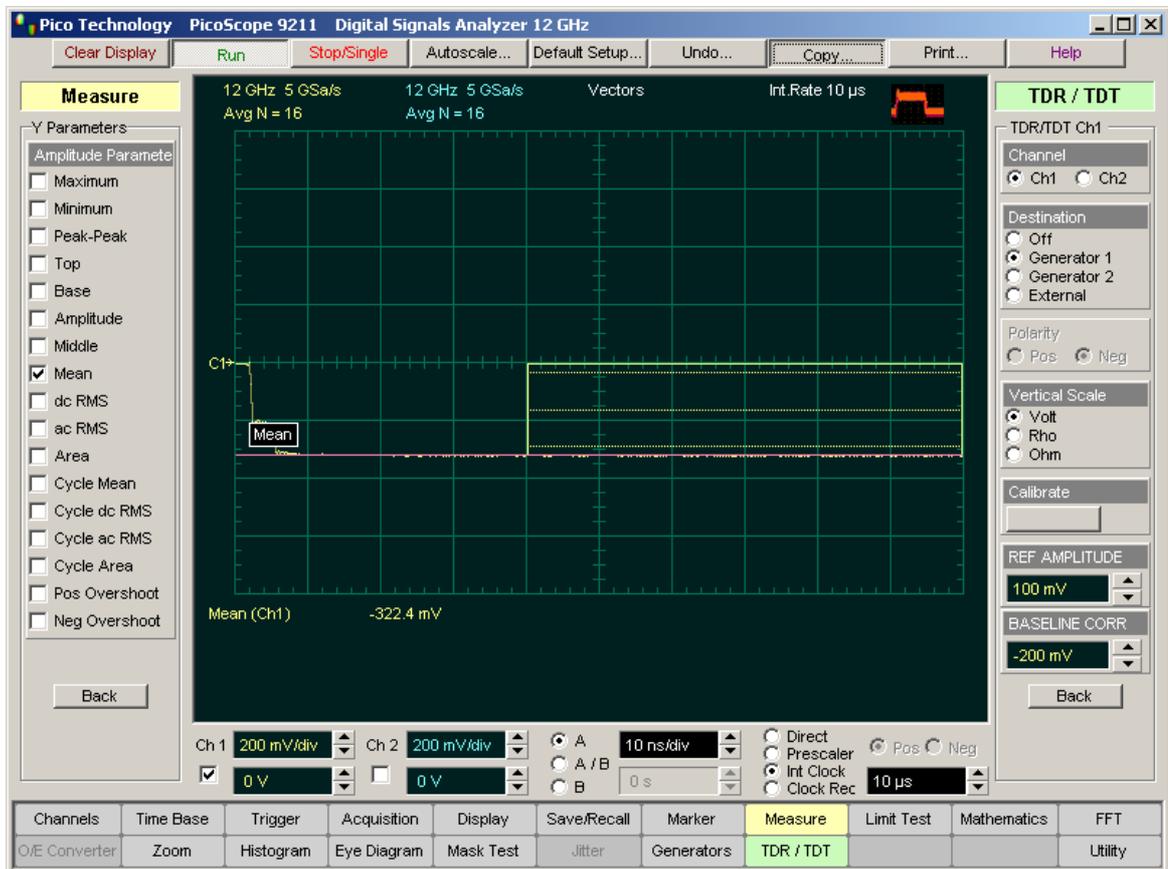


Figure 1

8. Connect the 50-ohm termination to the Reference Plane. See Figure 2. Write the mean value V_{50} . It is equal to -218.3 mV. See Figure 2.

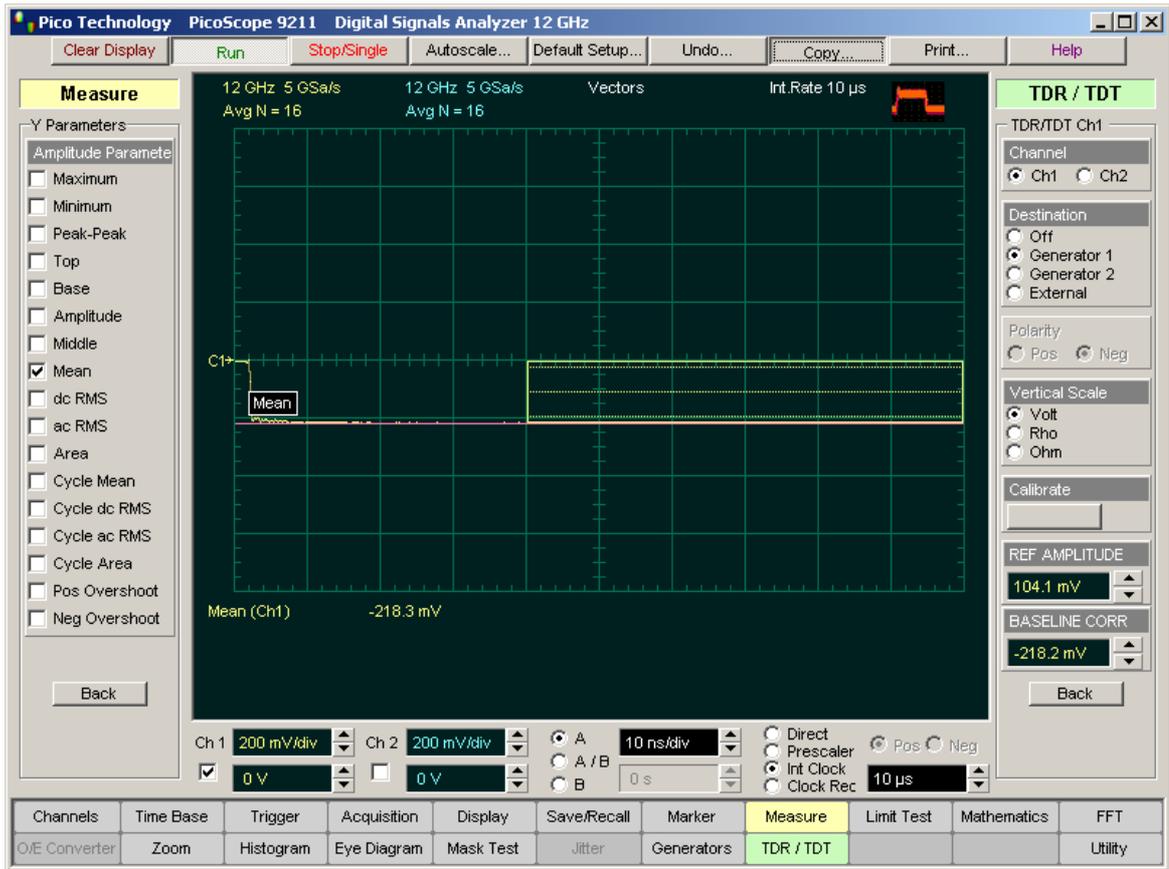


Figure 2

9. Enter the following value into the REF AMPLITUDE :

$$\text{REF AMPLITUDE} = |V_0 - V_{50}| = |-322.4 \text{ mV} - (-218.3 \text{ mV})| = 104.1 \text{ mV}$$

10. Enter the following value into the BASELINE CORR:

$$\text{BASELINE CORR} = V_{50} = -218.3 \text{ mV}$$

5.17.5.3 Rho and Ohm Vertical Scale

1. Click Rho in the [Vertical Scale](#) ³⁵⁸ menu. See Figure 1.

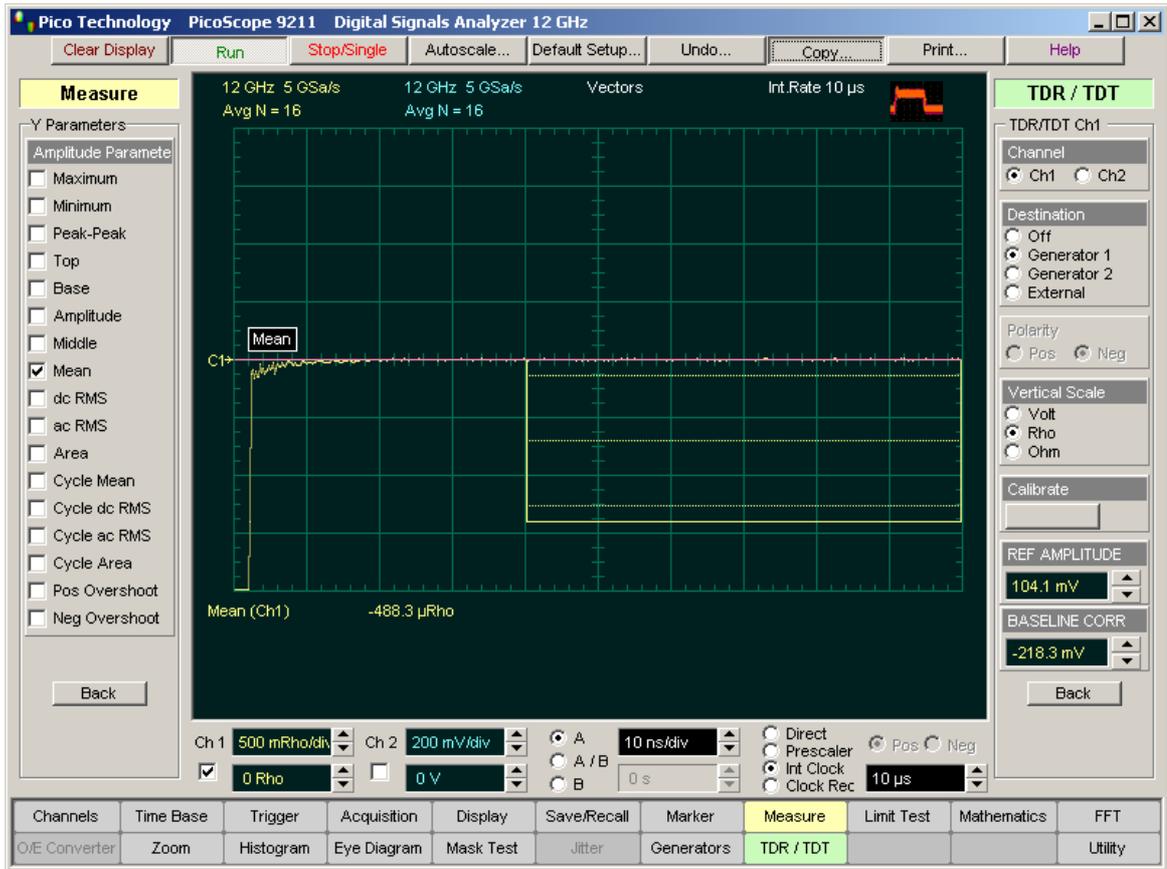


Figure 1

Figure 1 shows that the rho value is near to 0 when the transmission line is terminated in 50 ohms. The Mean measurement shows -488.3 mrho.

2. Click Ohm in the Vertical Scale menu. See Figure 2.

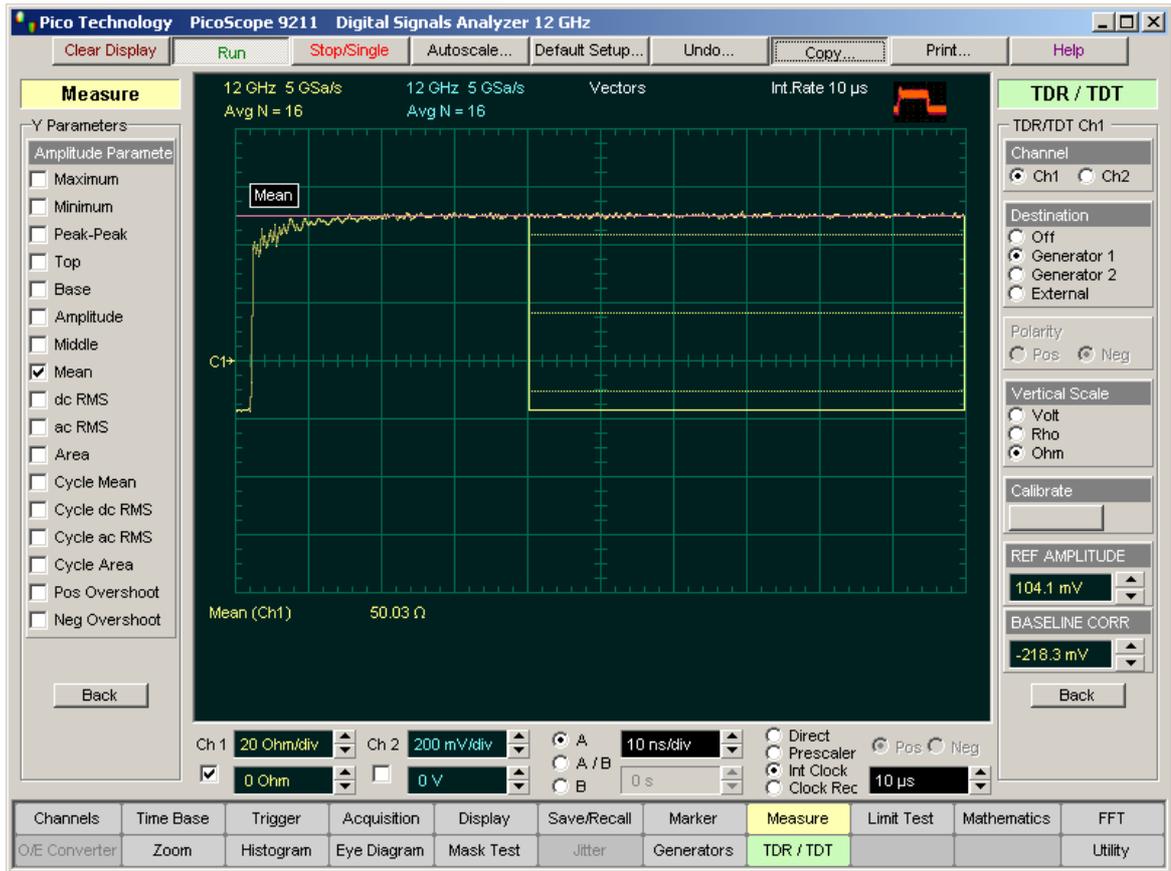


Figure 2

Fig. 2 shows that the ohm value is near 50 ohms when the transmission line is terminated in 50 ohms. The Mean measurement shows 50.03 ohm.

3. Remove the 50-ohm termination.
4. Click Rho in the Vertical Scale menu. See Figure 3.

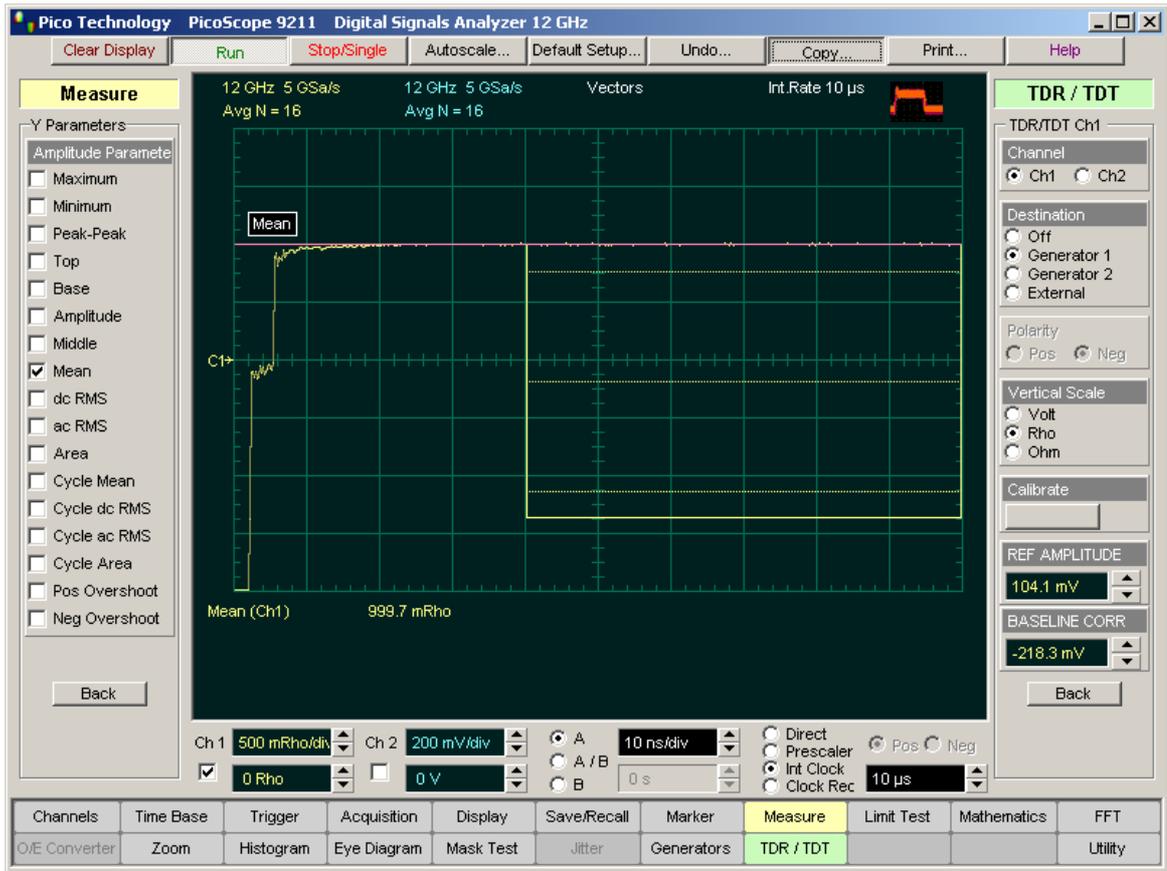


Figure 3

Figure 3 shows that the rho value is near 1 rho when the transmission line is open-circuit. The Mean measurement shows 999.7 mrho.

5. Connect a short termination. See Figure 4.

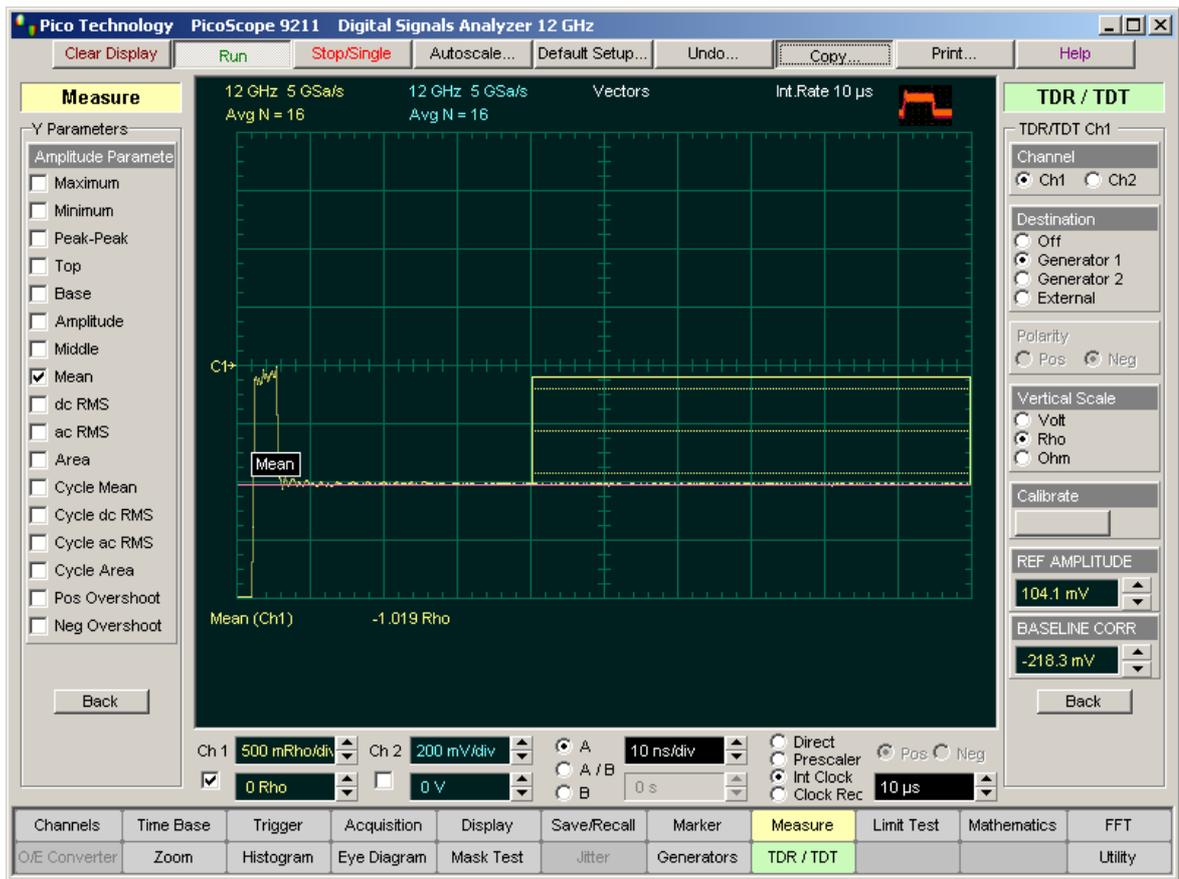


Figure 4

Fig. 4 shows that the rho value is near -1 rho when transmission line is shorted. The Mean measurement shows -1.019 rho.

6. Click Ohm in the Vertical Scale menu. See Figure 5.

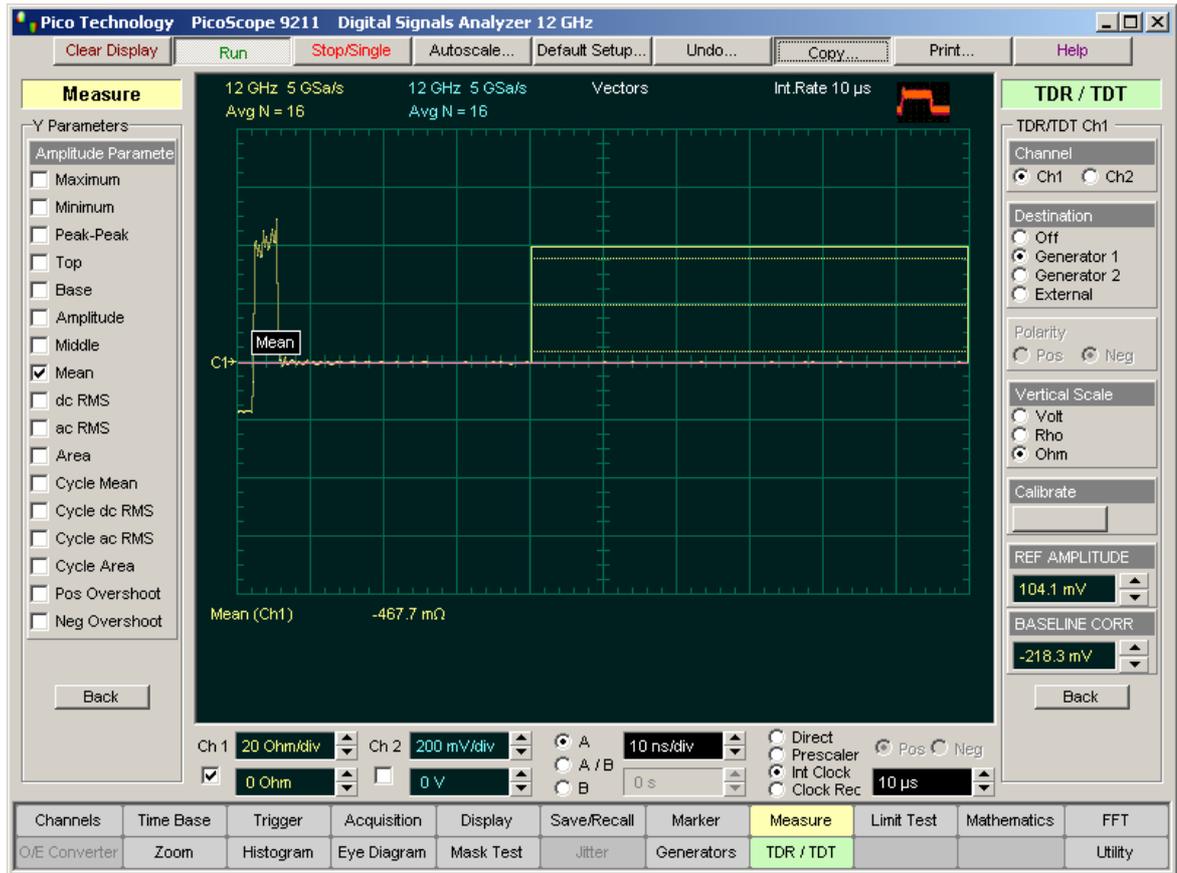


Figure 5

Fig. 5 shows that the ohm value is near 0 ohms when transmission line is shorted. The Mean measurement shows -467.7 mohm .

7. Connect a 6-dB unloaded attenuator to the Reference Plane. This attenuator should have approximately 85 ohm resistance when it is unterminated. See Figure 6.
8. Click Rho in the Vertical Scale menu. See Figure 6.

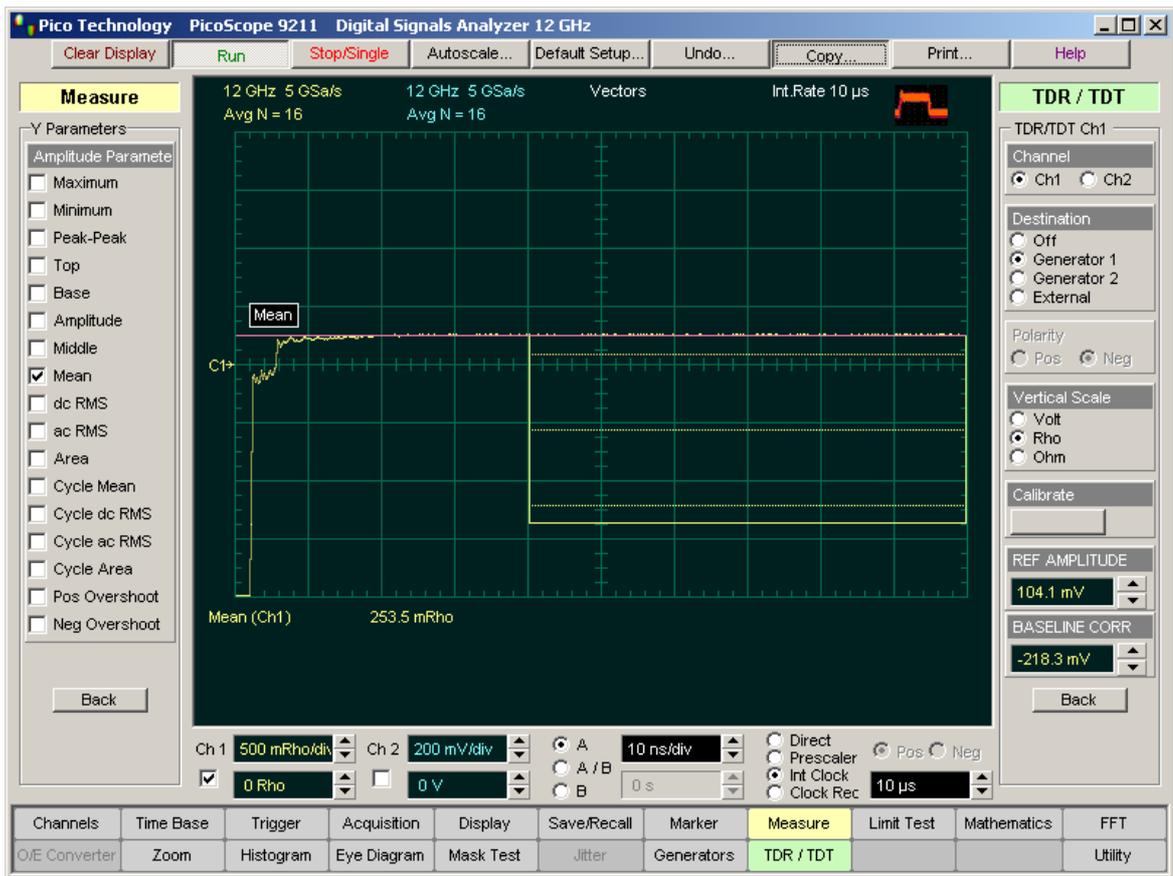


Figure 6

Fig. 6 shows mean value of 253.5 mrho.

8. Click Ohm in the Vertical Scale menu. Switch the vertical scale to 50 ohm/div. See Figure 7.



Figure 7

The Mean measurement shows 83.88 ohm.

5.17.5.4 Automatic TDR Calibration

1. Connect the equipment as shown in Figure 1 in "[Equipment connections for TDR measurements](#)^[362]".
2. Get a picture as shown in Figure 2 in "[Equipment connections for TDR measurements](#)^[362]".
3. Click Calibrate in the [TDR/TDT](#)^[356] Menu.
4. Follow the instructions.
5. After the calibration is performed, two values appear in the REF AMPLITUDE and BASELINE CORR controls.
6. Use the [Marker](#)^[192] and [Measure](#)^[246] menus for rho and ohm measurements.

5.17.5.5 Distance and Length Measurements

1. Connect the equipment as shown in Figure 1 in "[Equipment connections for TDR measurements](#)".
2. Get a picture as shown in Figure 2 in "[Equipment connections for TDR measurements](#)".
3. Click [Acquisition](#), then Multiple Average in the [Mode](#) menu. Select AVERAGE N = 16.
4. Click the [TDR/TDT](#) menu.
5. Click Horizontal.
6. Click Meter in the Horizontal Scale menu.
7. Click Dielectric (constant) in the Preset Unit menu.
8. Set the DIELECTRIC CONSTANT to 2.25 (for polyethylene cable).
9. Set Time Base Scale to 500 mm/div.
10. Click the [Marker](#) menu.
11. Click the XY marker.
12. Place marker M1 on the reflection from the open-circuit Reference Plane. See Figure 1.

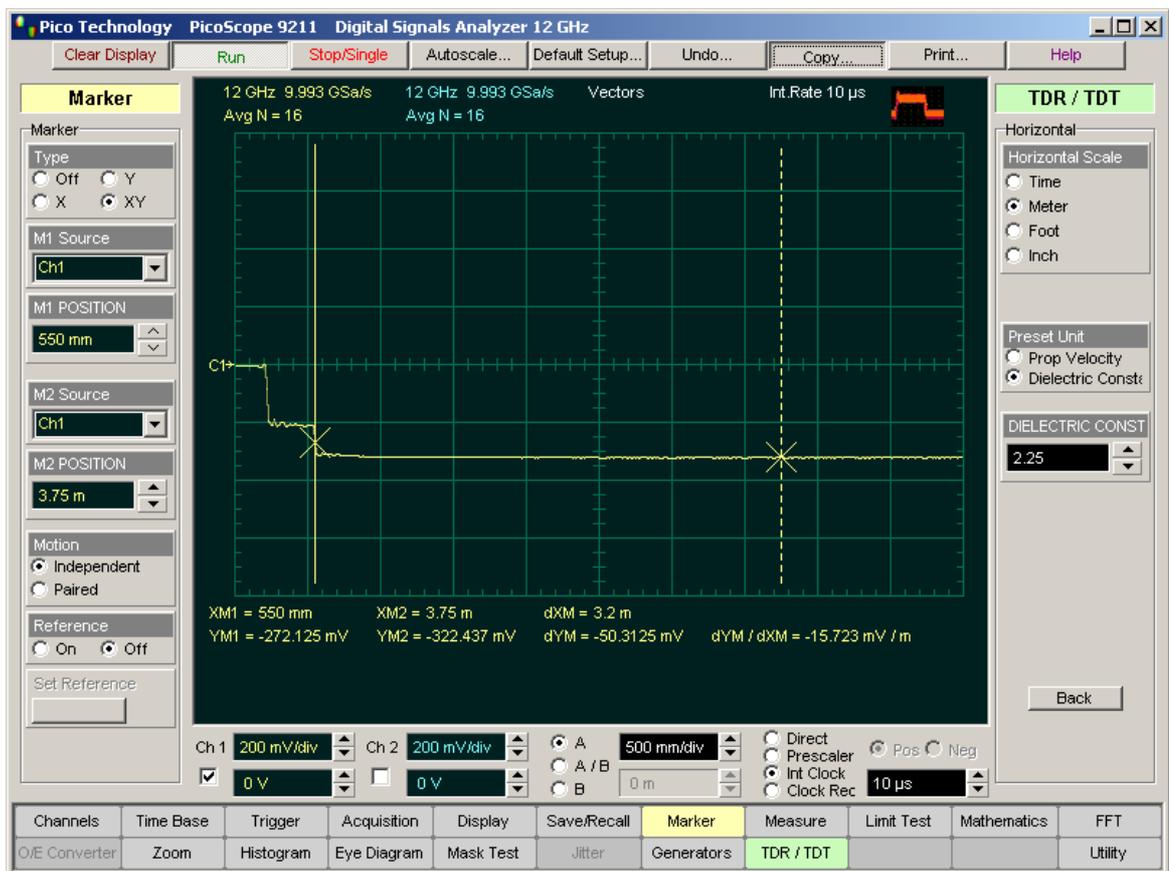


Figure 1

13. Connect a polyethylene cable to the Reference Plane. The cable must have a length of approximately 90 cm and dielectric constant of 2.25.
14. Place marker M2 on the reflection from the open end of the cable. The dXM value shows the length of the cable equal to 930 mm. See Figure 2.

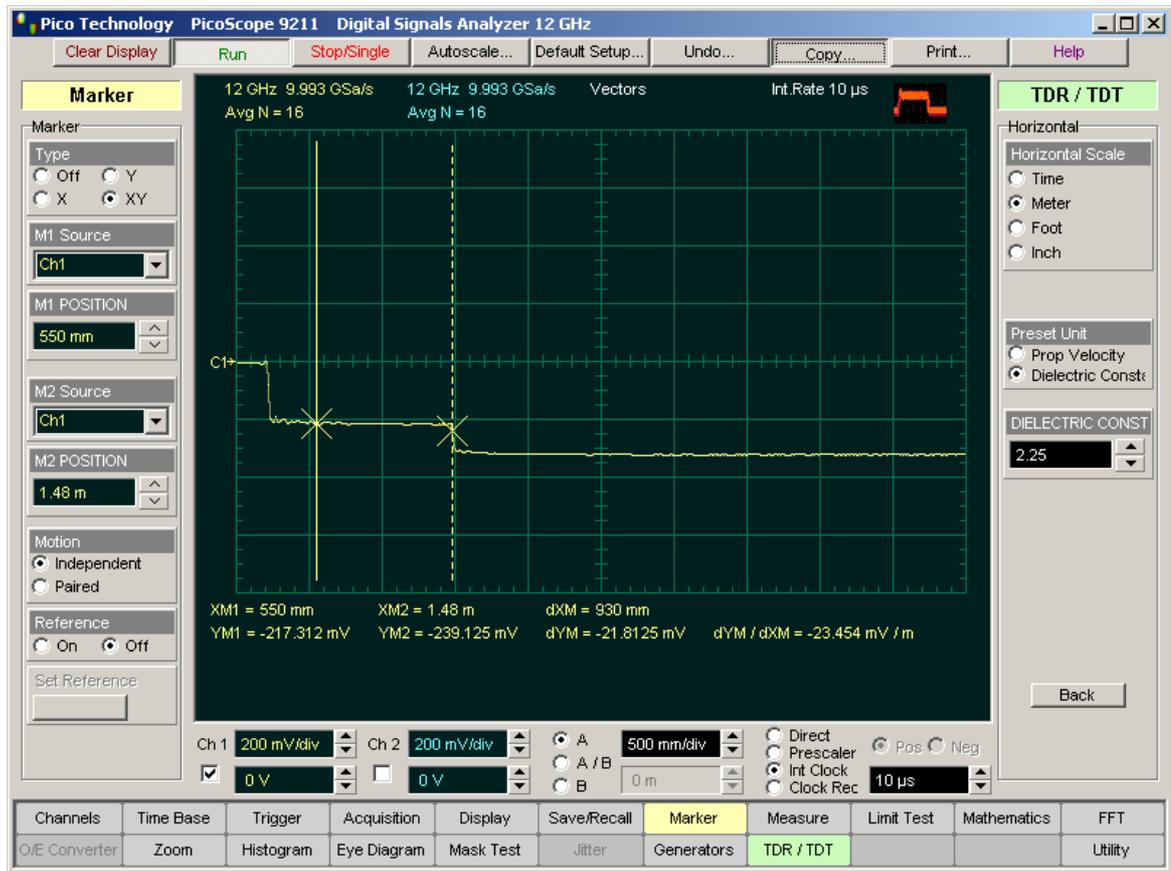


Figure 2

5.17.5.6 TDR Correction

Perform the correction procedure as follows:

1. Connect the equipment as shown in Figure 1 in "[Equipment connections for TDR measurements](#)".
2. Get a picture as shown in Figure 2 in "[Equipment connections for TDR measurements](#)".
3. Click **Acquisition**, then select Multiple Average from the **Mode** menu. Select AVERAGE N = 16.
4. Select the Time Base Scale acceptable for your test. If you change the Time Base Scale after calibration for correction you may lose all advantages of this feature and create additional signal distortions. Select 1 ns/div.
5. Click Correction... in the **TDR/TDT** menu.
6. Select the CORRECTED TIME. For better evaluation we recommend starting from 1 ns.

7. Click On in the Correct menu. This starts calibration for correction.
8. Follow the instructions. After Calibration is performed you'll see the corrected function together with a signal on the TDR channel. Notice that the calibration for correction always places the Reference Plane on the second horizontal division.
9. Uncheck Ch1.
10. Remove the 50-ohm termination, then connect a short. See Figure 1 with corrected reflection function (F1) from the short. In comparison with the uncorrected response, the corrected response has much lower distortion.

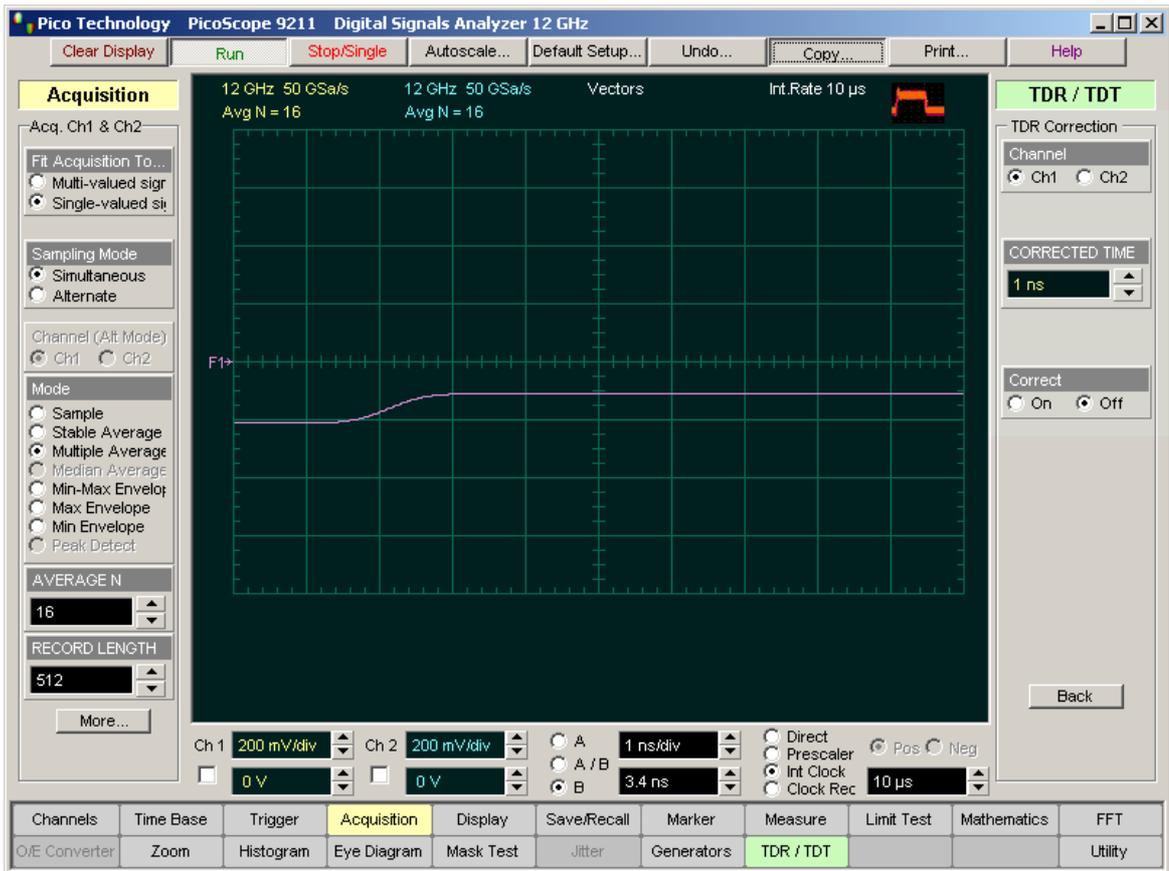


Figure 1

11. For channel 1 select 20 mV/div vertical scale and -150 mV offset.
12. Click Measure/Parameters.
13. Select F1 from the Source menu.
14. From the X Parameters... menu select Rise Time, and from the Y Parameters... menu select Pos Overshoot. See Figure 2.

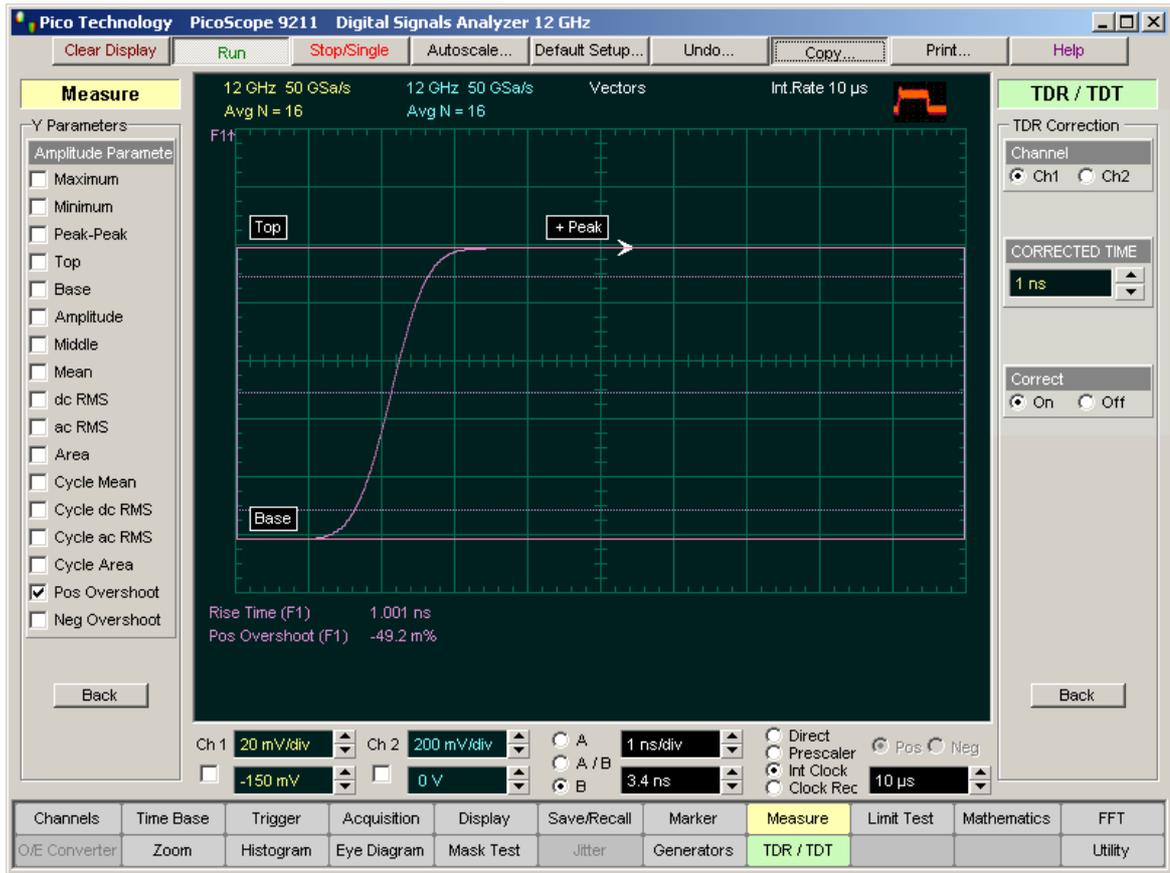


Figure 2

The measurement shows 1.001 ns corrected rise time and -0.0492% positive overshoot.

15. Set the CORRECTED TIME to 200 ps. See Figure 3.

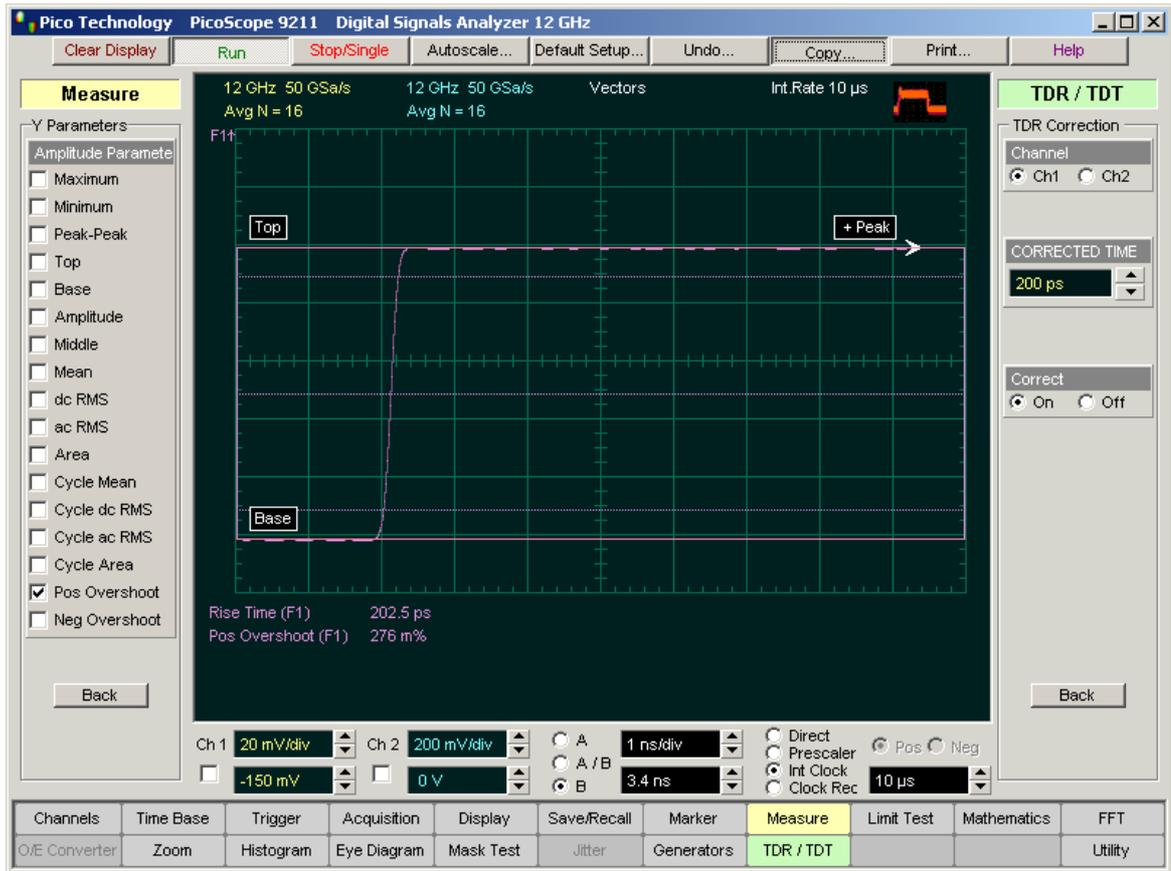


Figure 3

The measurement show 202.5 ns corrected rise time and -0.276% positive overshoot.

5.17.6 TDT Setup Guide

5.17.6.1 Equipment connections for TDT measurements

1. Connect the equipment as shown in Figure 1.

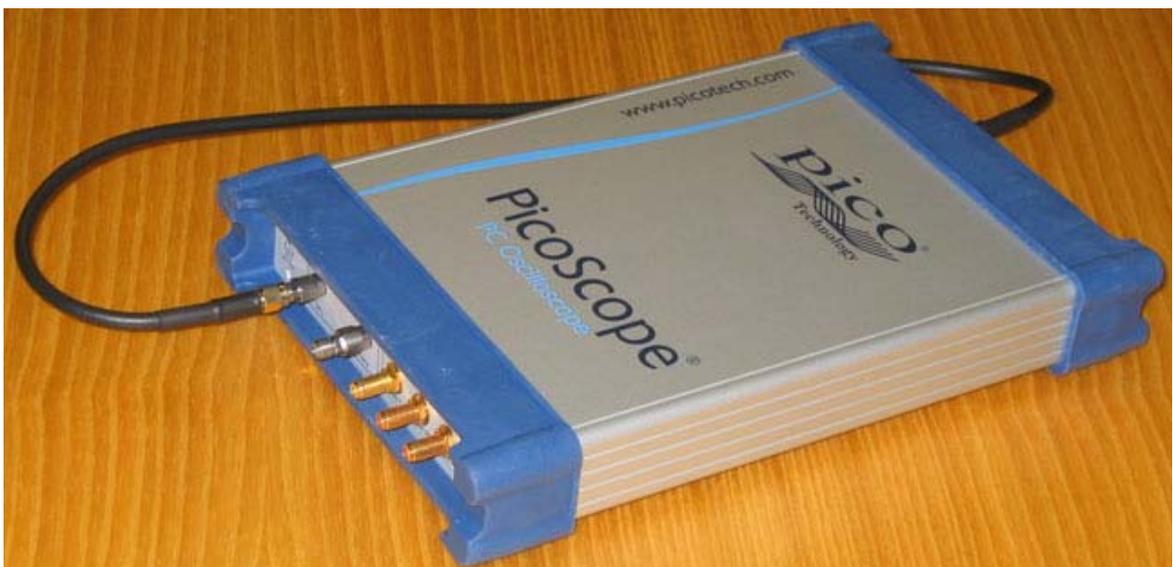


Figure 1

2. Switch on the oscilloscope and run the software.
3. Select the Vector style in the [Display](#)^[55] menu.
4. Uncheck Ch 2.
5. Click [TDR/TDT](#)^[356] in the [Main Menu](#)^[203].
6. Click TDT in the Mode menu.
7. Click TDR/TDT Channels...
8. Click Generator 1 in the Destination menu. See Figure 2.

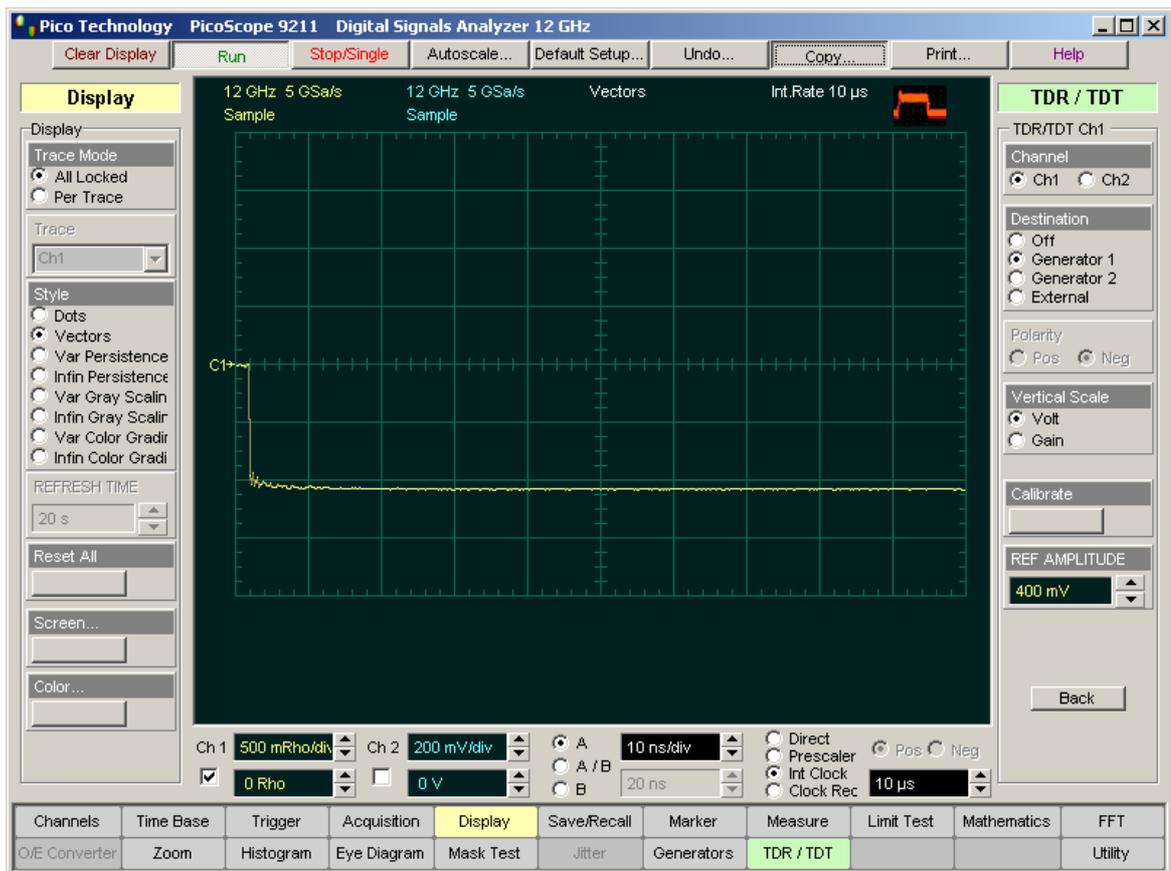


Figure 2

The internal generator generates an approximately 400-mV negative step. As in TDR the Reference Plane is a physical location where the transmission line (the end of 80-cm precision coaxial cable) is connected to the DUT.

After calibration is performed the DUT should be placed between the Reference Plane and the input of selected channel (see Figure 1).

5.17.6.2 Manual TDT Calibration

1. Connect the equipment as shown in Figure 1 "[Equipment connections for TDT measurements](#)^[38b]".
2. Get a picture as shown in Figure 2 in "[Equipment connections for TDT measurements](#)^[38b]".
3. Click [Acquisition](#)^[30], then Multiple Average in the [Mode](#)^[36] menu. Select AVERAGE N = 16.
4. Click Measure/Parameters/Y Parameters...
5. Check Amplitude. See Figure 1.

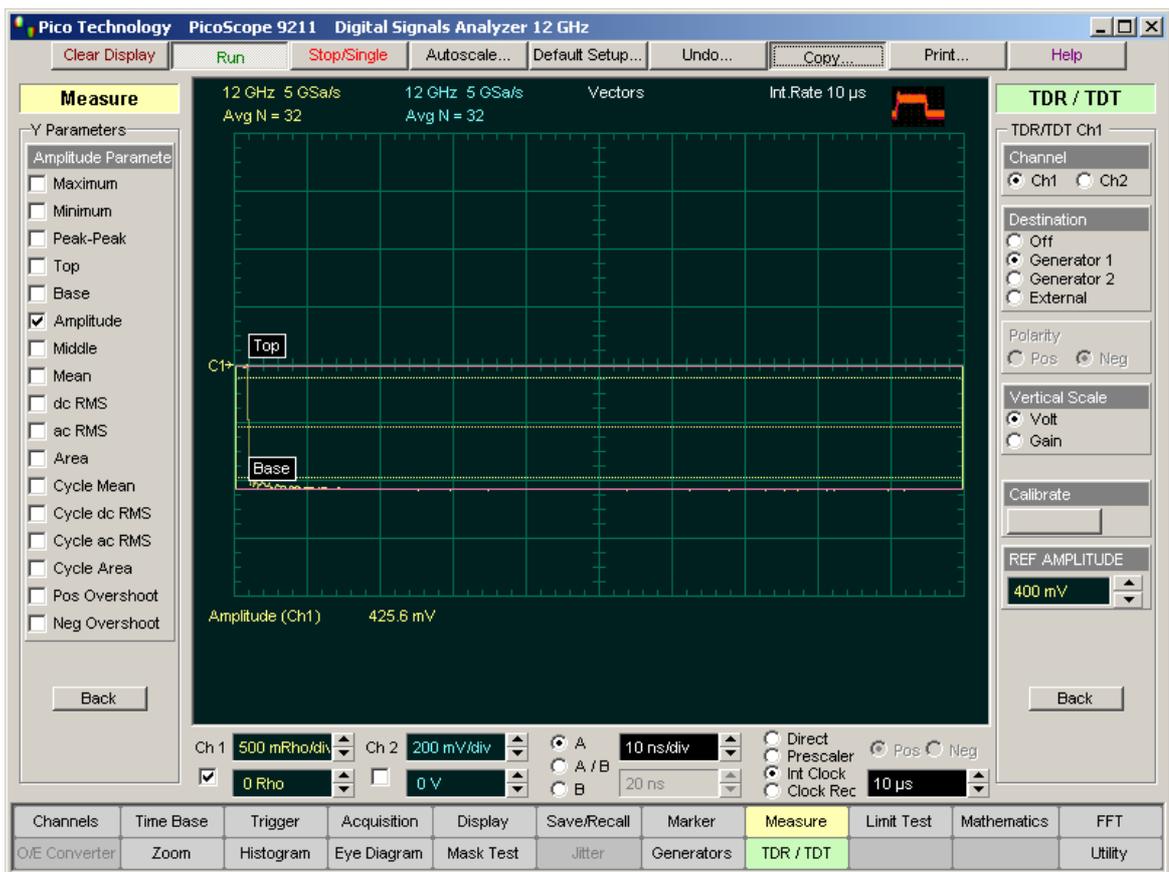


Figure 1

6. In REF AMPLITUDE enter the measured value of the amplitude. It is equal to 425.6 mV.
7. Click Gain in the Vertical Scale menu. See Figure 2.

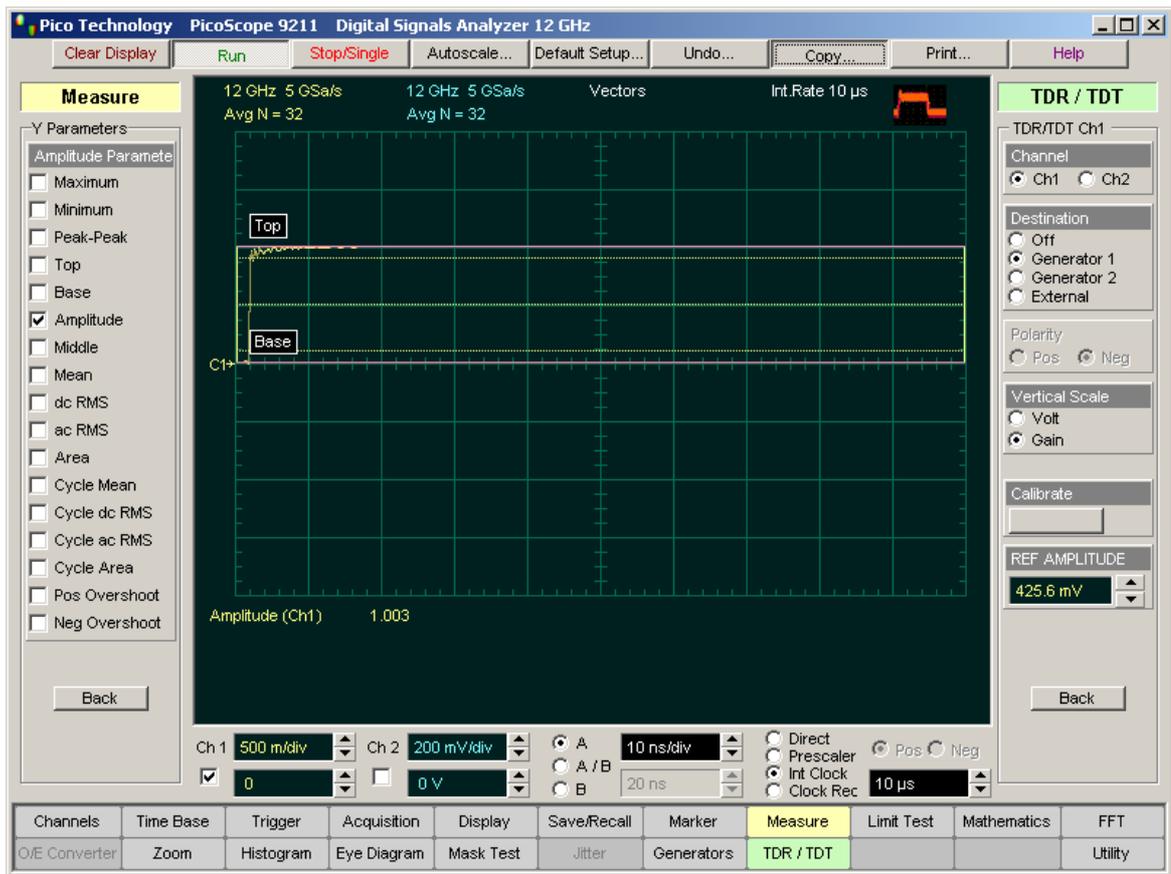


Figure 2

Figure 2 shows that the gain value is close to 1.00 when the DUT is not installed in the TDT measurement circuit.

5.17.6.3 Automatic TDT Calibration

1. Click Volts in the Vertical Scale menu.
2. Click Calibrate.
3. Follow the instructions.
4. The measured amplitude value is automatically written into the REF AMPLITUDE.
6. Click Gain in the Vertical Scale menu. This returns to the gain vertical scale.

5.17.6.4 TDT Measurements

The main TDT measurements are:

- TDT propagation delay
- TDT gain

As an example of a DUT we'll use a 90 cm polyethylene cable with a 6-dB attenuator at the end.

1. Click the [TDR/TDT](#) ^[356] menu.
2. Click Horizontal.

3. Click Meter in the Horizontal Scale menu.
4. Click Dielectric constant in the [Preset Unit](#)³⁶⁰ menu.
5. Set the DIELECTRIC CONSTANT to 2.25 (for polyethylene cable).
6. Set the Time Base Scale to 500 mm/div.
7. Click the Marker/XY marker.
8. Place marker M1 on the TDT step. See Figure 1.

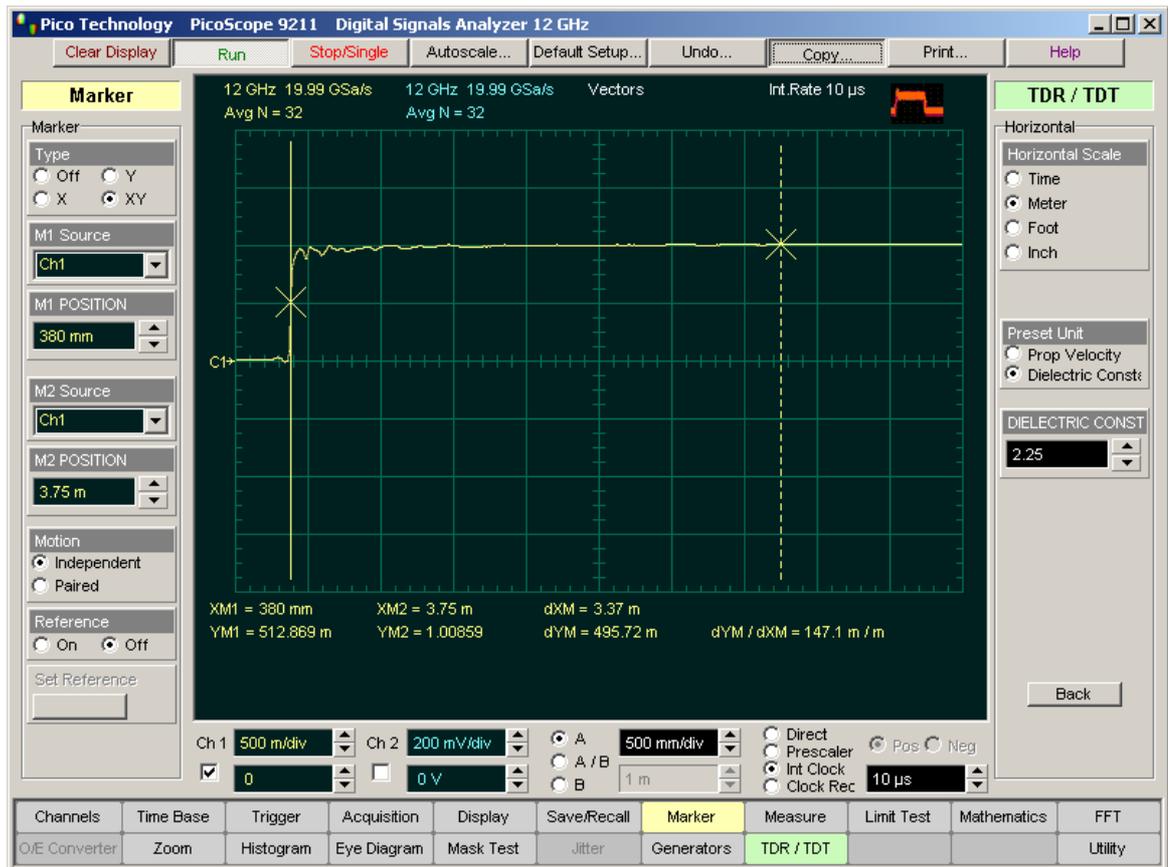


Figure 1

9. To make TDT measurements, place the DUT between the Reference Plane and the input of the sampler.
10. Place marker M2 on the TDT step. See Figure 2.



Figure 2

11. Read that $dXM = 950$ mm. This is a TDR propagation delay that corresponds to the electrical length of the DUT (cable + attenuator).

12. Place marker M2 on the top of TDR step. See Figure 3.



Figure 3

Read that $YM2 = 0.509$. This is the TDT gain that corresponds to an attenuation value of 6 dB.

5.17.6.5 TDT Correction

1. Connect the equipment as shown in Figure 1 in "[Equipment connections for TDT measurements](#)^[380]".
2. Get a picture as shown in Figure 2 in "[Equipment connections for TDT measurements](#)^[380]".
3. Click [Acquisition](#)^[30], then Multiple Average in the [Mode](#)^[36] menu. Select AVERAGE N = 16.
4. Select the Time Base Scale acceptable for your test. If you change the Time Base Scale after calibration for correction you may lose all advantages of this feature, and also create additional signal distortions. Select 1 ns/div.
5. Click Correction... in the [TDR/TDT](#)^[356] menu.
6. Select the CORRECTION TIME. For better evaluation we recommend starting from 1 ns.
7. Click On in the Correct menu. This starts calibration for correction.
8. Follow the instructions. After Calibration is performed you'll see the corrected function together with a signal on the TDT channel. Notice that the calibration for correction always places the Reference Plane on the second horizontal division.

9. Uncheck Ch1.
10. See the corrected TDT function (F1). In comparison with the uncorrected response, the corrected response has much lower distortion.
11. Click [Measure](#)²⁴⁶/Parameters.
12. Select F1 from the Source menu.
13. From the X Parameters... menu select Fall Time, and from the Y Parameters... menu select Neg Overshoot. See Figure 1.

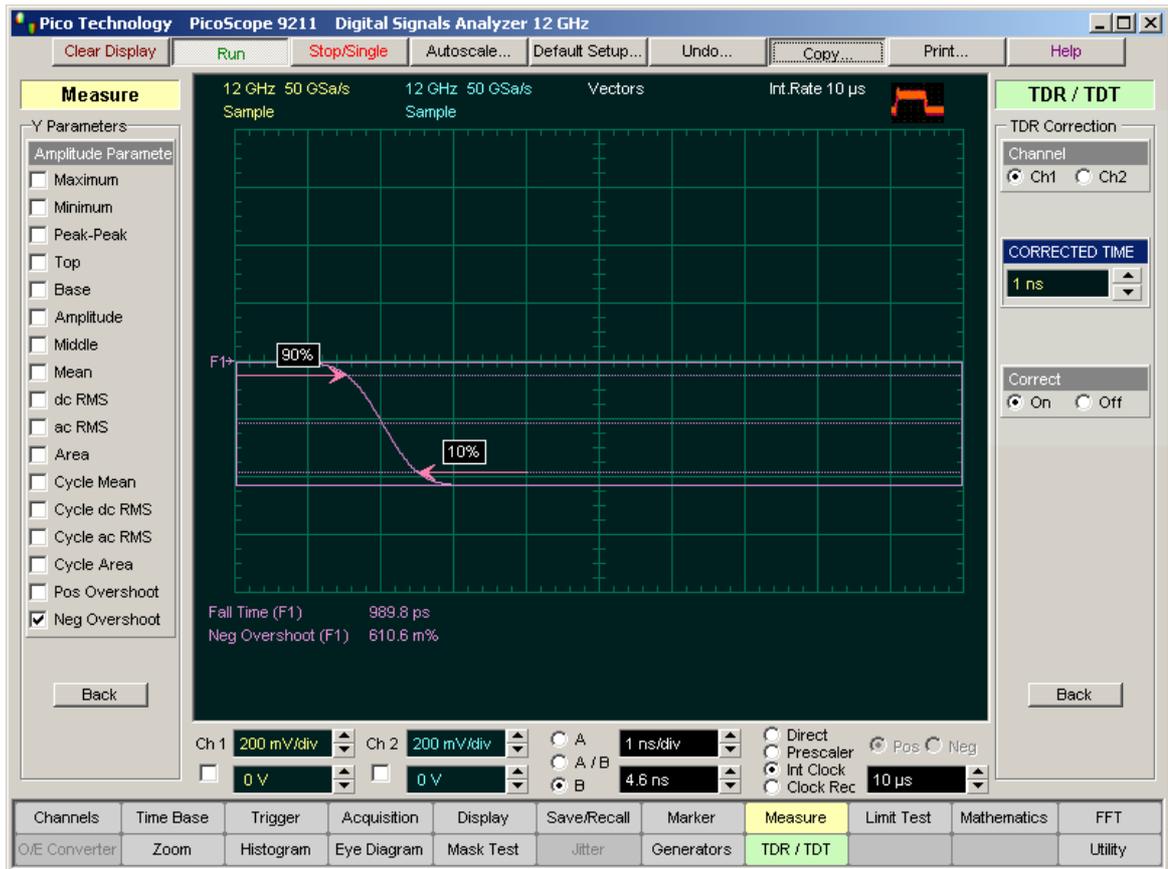


Figure 1

The measurement results show 989.8 ps corrected fall time and 0.6106 % negative overshoot.

11. Set the CORRECTED TIME to 200 ps. See Figure 2.

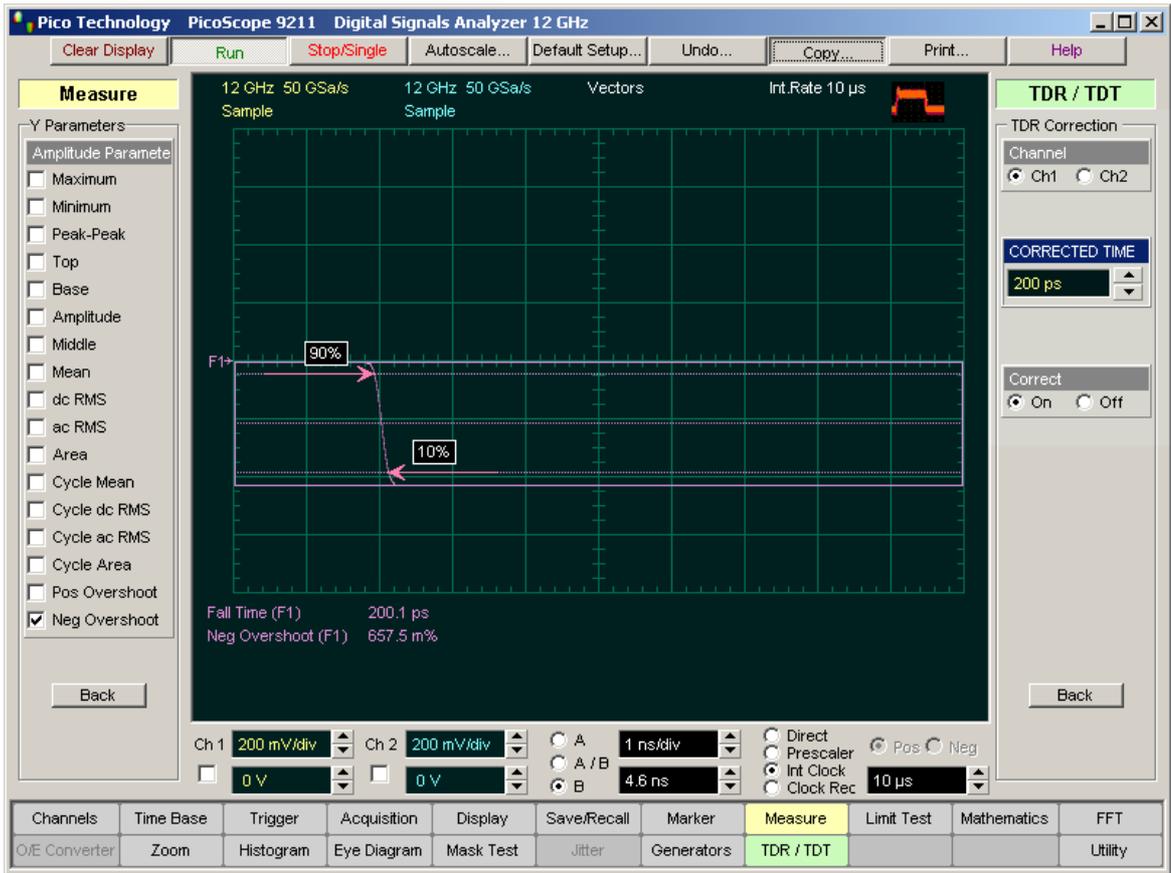


Figure 2

The measurement results show 200.1 ps corrected fall time and 0.6575 % negative overshoot.

12. Set the CORRECTED TIME to 100 ps. See Figure 3.

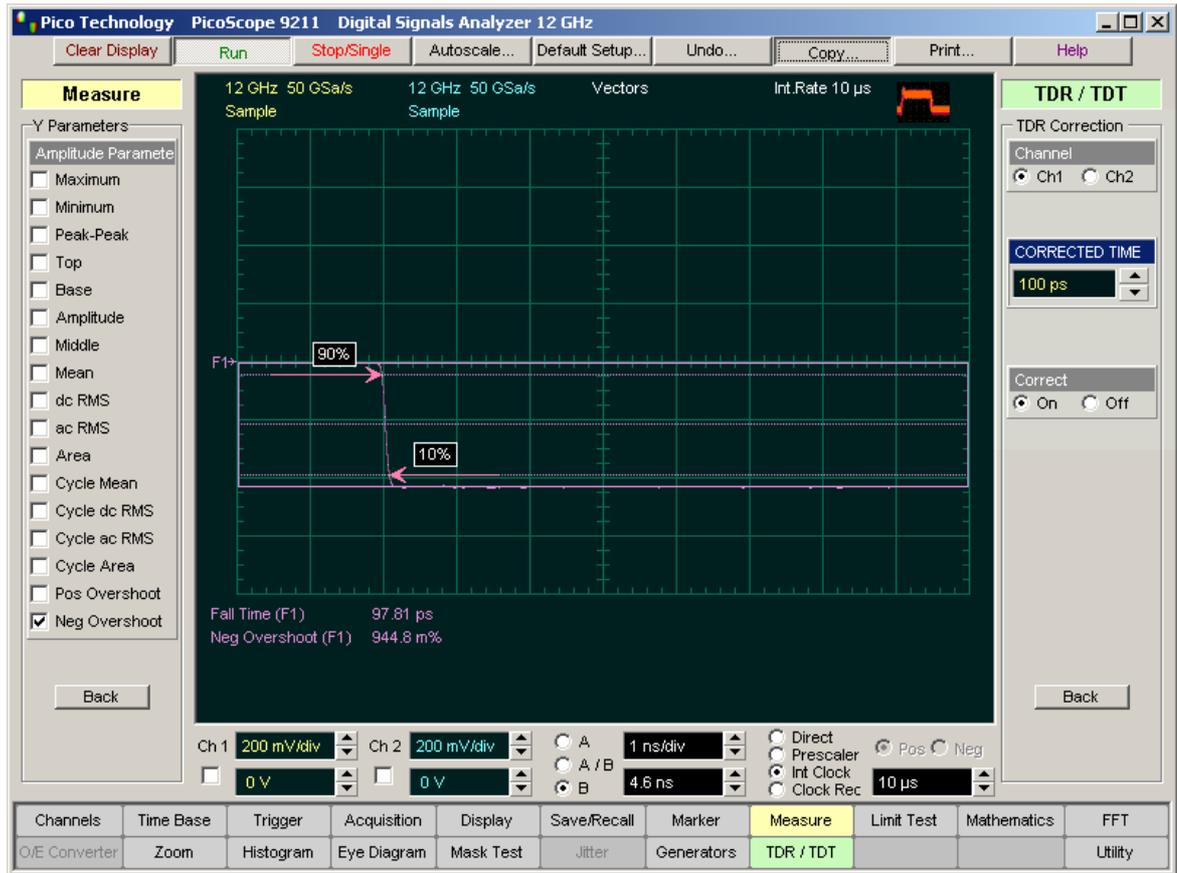


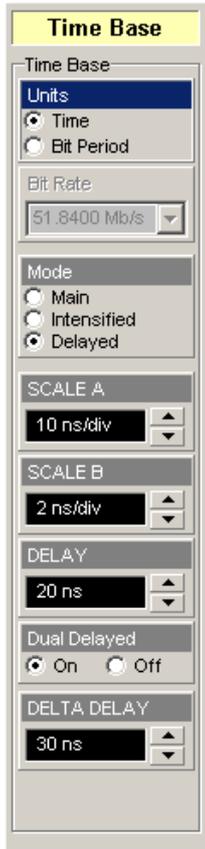
Figure 3

The measurement results show 97.81 ps corrected fall time and 0.9448% negative overshoot.

5.18 Time Base Menu



The Time Base menu allows you to control the horizontal display through the Main, Intensified, Delayed or Dual Delayed timebases and through the TIME/DIV and DELAY functions.



The common timebase parameters specify a common horizontal acquisition window that is applied to both channels in parallel. These parameters are:

- The trigger signal that you input, and set the trigger system to recognize, determines the point relative to the input waveform that triggers the oscilloscope.
- The horizontal position you set determines the horizontal delay from the trigger point to the first sample point in the acquisition window.
- The horizontal scale you set, and the requirement that all waveforms fit within the 10 horizontal-division display, determines the horizontal duration of the window relative to any waveform, allowing you to scale it to contain a waveform edge, a cycle, or several cycles.
- The record length (along with the horizontal scale) you set for the 10-division window determines the sample interval (horizontal point spacing or resolution) on the waveform.

The Time Base Scale, Record Length, Sample Interval and Resolution are related to each other and specify the horizontal acquisition window. Relations between these horizontal elements are as follows:

$$\text{Time Duration (seconds)} = 10 \text{ div (window size)} \times \text{Time Base Scale (sec/div)}$$

$$\text{Time Duration (seconds)} = \text{Sample Interval (seconds/sample)} \times \text{Record Length (samples)}$$

$$\text{Sample Interval (seconds/sample)} = \text{Resolution (sec/sample)} = 1 / \text{Sample Rate (samples/sec)}$$

These elements in the formulas behave as follows:

- If Record Length or Time Duration vary, Sample Interval varies to accommodate them, up to the highest sample rate (lower sample interval or highest resolution).
- If you set a faster Time Base Scale setting, decreasing Time Duration, and the Sample Interval reaches its lower limit, the horizontal scale becomes limited to a setting compatible with the record length and the lower limit of the sample interval.
- If you attempt to set a longer Record Length and the Sample Interval reaches its lower limit, Time Duration remains constant and the record length becomes limited. The equation becomes:

$$\text{Maximum Record Length} = \text{Time Duration} / \text{Min Sample Interval}$$

5.18.1 Units



The Units function lets you set the instrument timebase in basic time units or in bit period (data rate) units. Bit period units provide an easy and intuitive way to display digital communication signals. Instead of having to compute the time interval required to display two bits or eyes, you can simply set the scale to two bits.

Time (Basic time units)

Allows you to set the scale units to seconds per division (*s/div*) and the position units to seconds (*s*). The default value for basic time units is 10 ns/div.

Bit Period (Bit units)

Allows you to select from a list of standard optical and digital telecommunications rates. When selected, the time base scale units are set to bits per division and the delay units to bits. In this mode, the instrument internally performs the calculation to convert the number of bits displayed on the screen to the time per division. For example, if you wanted to convert *x* bits per division to time per division, you would have to compute the following:

$$Y \text{ bits/screen}$$

$$\text{Bit period} = 1 / \text{bit rate}$$

$$\text{Time/screen} = Y \text{ bits/screen} \times (\text{bit period})$$

$$\text{Time/division} = 0.1 \text{ time/screen}$$

5.18.2 Bit Rate



The Bit Rate allows the time base to be configured for a variety of standard optical and electrical telecommunications rates. If you are measuring a signal with one of these standard rates, the scale and delay functions will coincide with this rate.

The following bit rates are standard selections when you select [Bit Period](#) as the horizontal (time base) scale units.

Bit Rate	Standard	Bit Rate	Standard	Bit Rate	Standard
1.544 Mbit/s	DS1	466.5 Mbit/s	OC9	3.187 Gbit/s	FC3187
2.048 Mbit/s	PDH 2.048 Mb	531.2 Mbit/s	FC531	3.320 Gbit/s	12x Parallel Optics
3.152 Mbit/s	DS1C	622.0 Mbit/s	STM4/OC12	9.953 Gbit/s	STM64/OC192
6.312 Mbit/s	DS2	933.1 Mbit/s	OC18	10.31 Gbit/s	10Gb Ethernet
8.448 Mbit/s	PDH 8.448 Mb	1.062 Gbit/s	FC1063	10.51 Gbit/s	10GFC
34.36 Mbit/s	PDH 34.4 Mb	1.244 Gbit/s	OC24	10.66 Gbit/s	FEC 1066
44.73 Mbit/s	DS3	1.250 Gbit/s	Gb Ethernet	10.70 Gbit/s	FEC 1071
51.84 Mbit/s	STM0/OC1	1.866 Gbit/s	OC36	11.09 Gbit/s	
125.0 Mbit/s	FDDI	2.125 Gbit/s		12.24 Gbit/s	STM-64 SuperFEC
132.8 Mbit/s	FC133	2.488 Gbit/s	STM16/OC48	19.90 Gbit/s	STM-128/OC-384
139.2 Mbit/s	DS4/PDH139Mb	2.500 Gbit/s	2XGb/Infiniband	39.81 Gbit/s	STM-256/OC-768
155.5 Mbit/s	STM1/OC3	2.666 Gbit/s	FEC 2666	42.65 Gbit/s	FEC 4266
265.6 Mbit/s	FC266	3.125 Gbit/s	XAUI	43.01 Gbit/s	FEC 4302

5.18.3 Time Base Mode

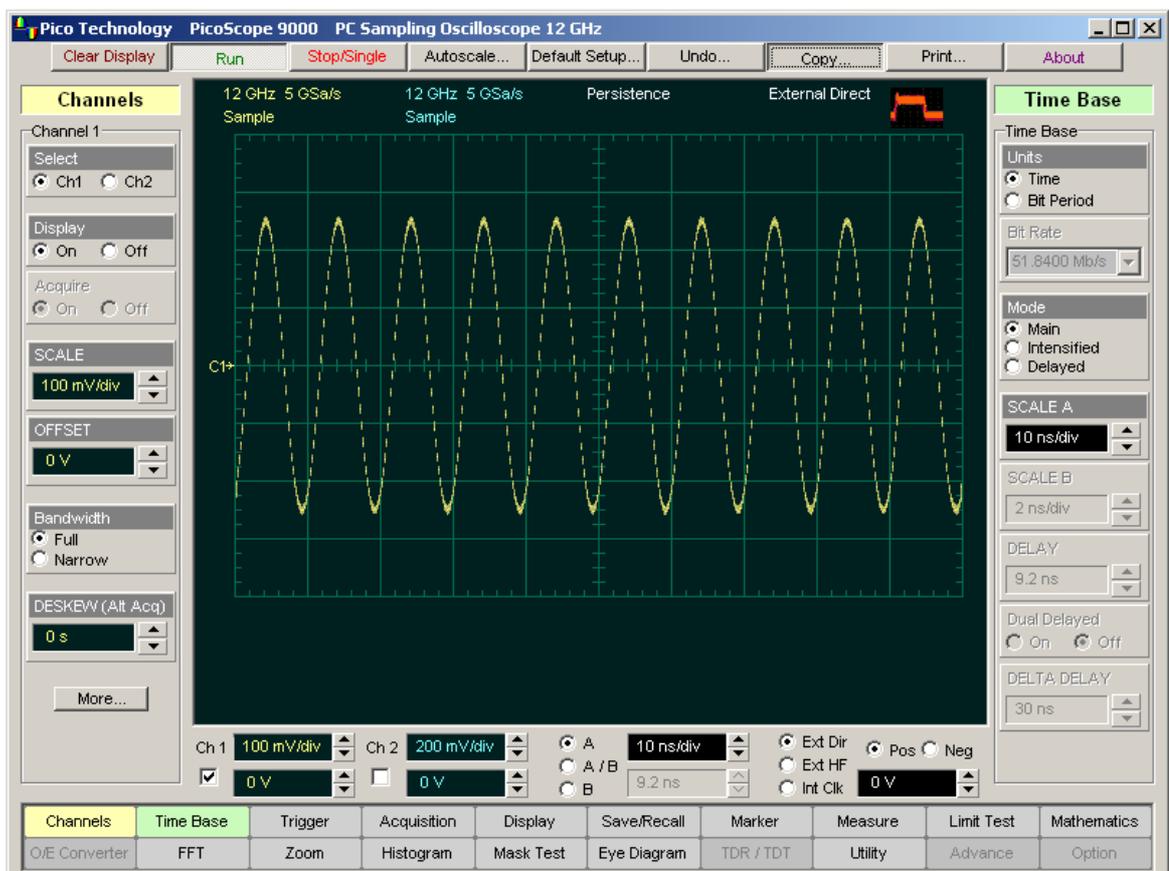


The Mode menu provides Main, Intensified, Delayed, or Dual Delayed timebase modes using time windowing.

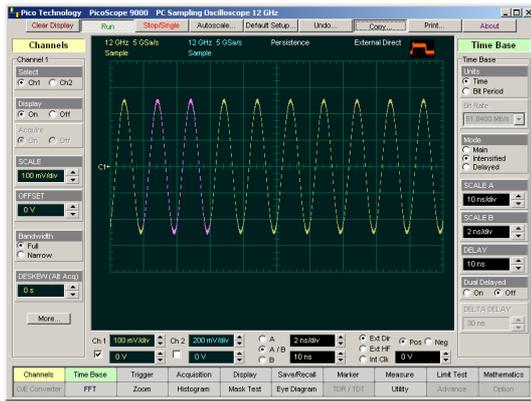
The Time Base windowing function is similar to the delayed or dual delayed sweep on traditional oscilloscopes because it turns on an expanded time base. This expanded time base allows you to pinpoint and to horizontally expand a portion (or two portions) of the signal for a more detailed or high-resolution analysis. It can also help you to make custom automatic measurements. Automatic measurements are made on the first occurrence of the event on the display. The windowing feature allows you to isolate individual events on the display for the automatic measurements.

Windowing includes several steps:

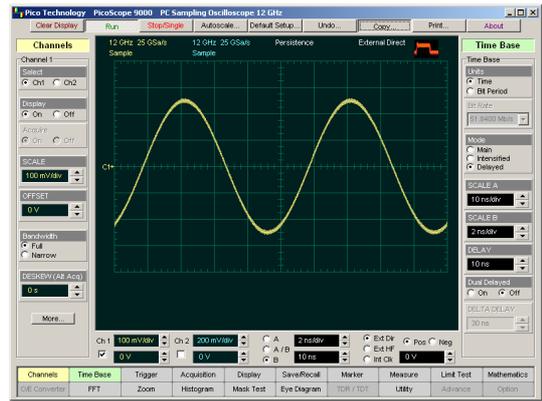
- Select main time base scale (SCALE A).
- Select one or two intensified time bases. Select the dimension (SCALE B) and position (DELAY) of the delayed time base or the Dual Delayed time base (DELTA DELAY) on the main time base trace.
- Click the Delayed or Dual Delayed timebase (Delayed or Dual Delayed/On).



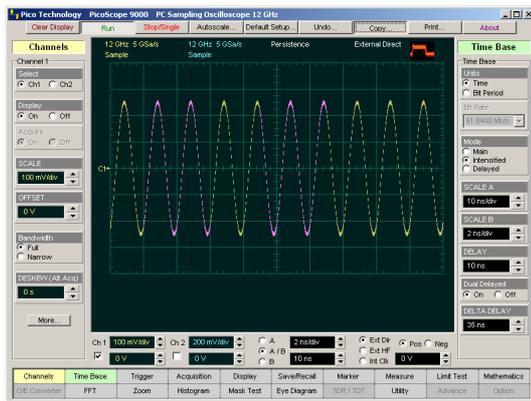
Main Time Base Mode



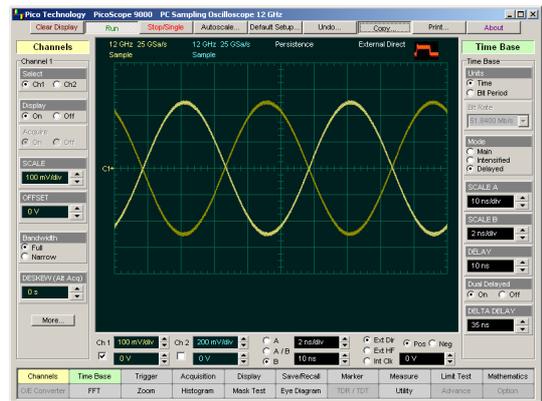
Intensified Time Base Mode



Delayed Time Base Mode



Intensified Time Base Mode



Dual Delayed Time Base Mode

5.18.4 SCALE A

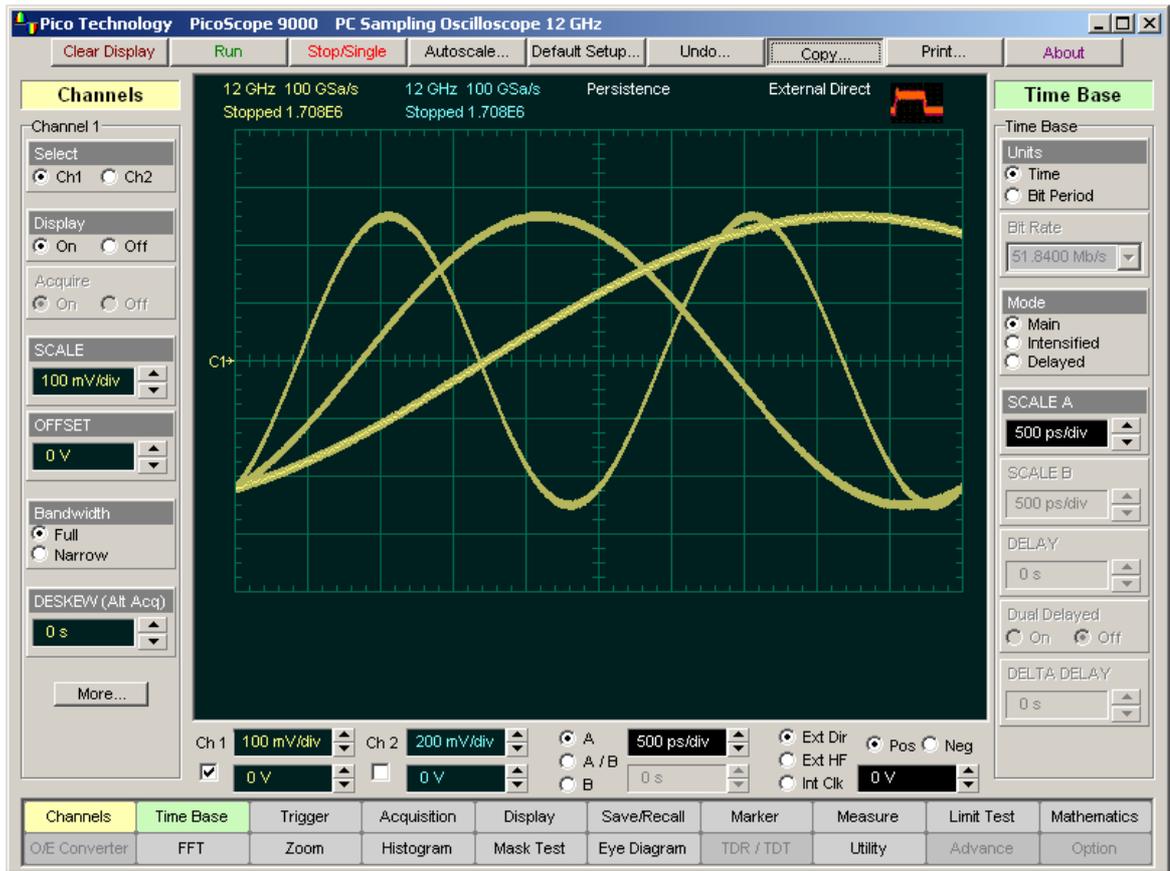


The SCALE A function is similar to the time/div knob of the main timebase on a traditional oscilloscope. (Division in this instance equals 1/10 of the horizontal axis.) Adjusting the horizontal (timebase) scale control expands and compresses the displayed waveform horizontally.

SCALE A controls horizontal scaling of the waveform. You can set the main timebase scale from 10 ps/div to 50 ms/div in one of three ways:

- By using the SCALE A spin box
- By using the corresponding spin box in the [Permanent Controls Area](#) ^[328]
- By using the [Pop-up Keypad](#) ^[427] to quickly enter numeric data for the time base scale using the mouse.

If fine mode is off, the main time base scaling is in a 1-2-5-10 sequence. When fine mode is on, you can adjust the main time base scaling in 0.1% increments or smaller.



Horizontal scaling of a waveform

5.18.5 SCALE B

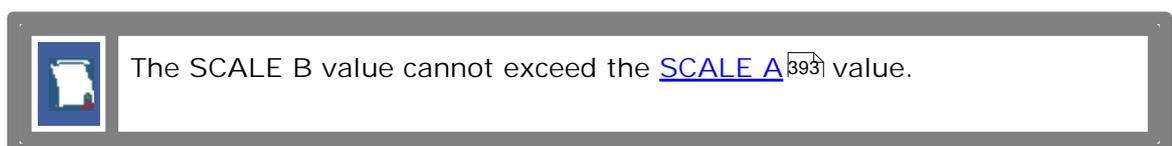


The SCALE B function is similar to the time/div knob of the delayed timebase on a traditional oscilloscope. Adjusting the delayed timebase scale control expands and compresses the displayed waveform horizontally.

SCALE B allows you to simultaneously control the time scale of both delayed timebases from 10 ps/div to 50 ms/div in one of three ways:

- By using the SCALE B spin box
- By using corresponding spin box in the [Permanent Controls Area](#)³²⁸
- By using the [Pop-up Keypad](#)⁴²⁷ to quickly enter numeric data using the mouse.

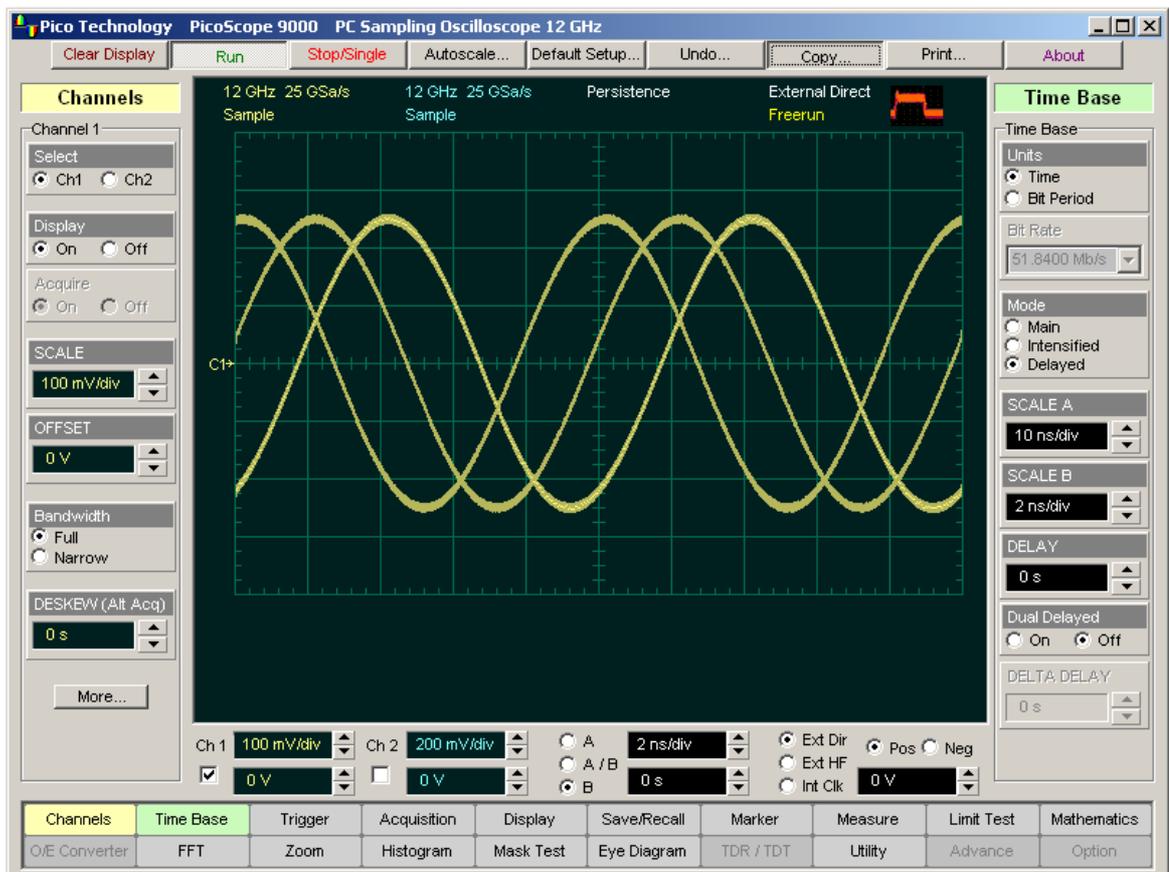
If fine mode is off, the main timebase scaling is in a 1-2-5-10 sequence. When fine mode is on, you can adjust the main timebase scaling in 0.1% increments or smaller.



5.18.6 DELAY



The DELAY function is similar to the delay knob of the delayed timebase on a traditional oscilloscope. DELAY is a post-trigger function, because it controls the delay from the trigger. The maximum post-trigger delay varies with the sweep speed, and the minimum delay (zero delay value) is limited by the propagation delay of the trigger path. The advantage of digital delay is that it is calibrated. Adjusting the delay moves the position of the input waveform horizontally. As the delay increases, the waveform moves to the left of the display graticule. As the delay decreases, the waveform moves to the right of the graticule.



Delay of a waveform

The DELAY spin-box allows you to simultaneously control the position of both delayed time bases up to maximum value of 10 divisions of main time base in one of three ways:

- By using the DELAY spin box
- By using corresponding spin box in the [Permanent Controls Area](#)³²⁸
- By using the [Pop-up Keypad](#)⁴²⁷ for some specific settings.

If fine mode is off, the delay can be changed in a sequence of 0.5 major divisions of the main time base. When fine mode is on, you can change delay in a sequence of 0.001 major divisions of main time base.

The possible maximum value of DELAY can be calculated from the following condition:

$$\text{Maximum Delay} + 10 \times \text{SCALE B} = 10 \times \text{SCALE A}$$

5.18.7 Dual Delayed



This function expands and displays the intensified portion of the waveform. The amount of expansion depends on the [SCALE B](#) ^[394] setting. The position of the first delayed timebase depends on the [DELAY](#) ^[395] setting, and the position of the second delayed timebase depends on both the [DELAY](#) ^[395] and [DELTA DELAY](#) ^[397] settings.

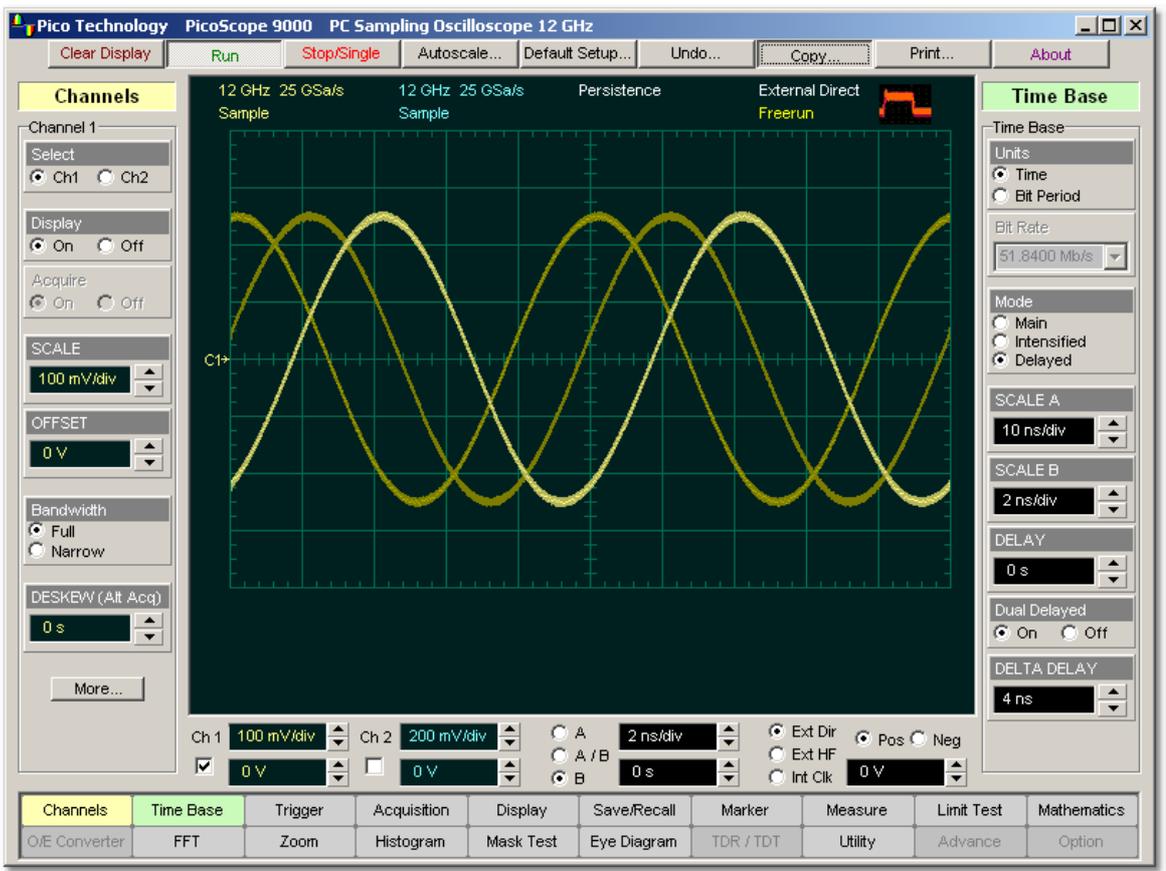
Click the On option to select the delayed time base. The following conditions are then available:

- If Off is selected, the time base is equivalent to Delayed Time Base
- If On is selected, the time base is equivalent to Dual Delayed Time Base

5.18.8 DELTA DELAY



The DELTA DELAY function is similar to the delta delay knob of the dual delayed timebase on a traditional oscilloscope.



Dual Delay of a waveform

The DELTA DELAY spin-box allows you to vary the position of the second delayed timebase relative to the position of the first delayed time base from 0 up to a maximum value of 10 divisions of the main timebase, in one of three ways:

- By using the DELTA DELAY spin box
- By using the corresponding spin box in the [Permanent Controls Area](#)^[328]
- By using the [Pop-up Keypad](#)^[427]

If fine mode is off, delta delay can be changed in a sequence of 0.5 major divisions of the main timebase. When fine mode is on, you can change the delay in a sequence of 0.001 major divisions of the main timebase.

The possible maximum value of the DELTA DELAY variable can be calculated from the following condition:

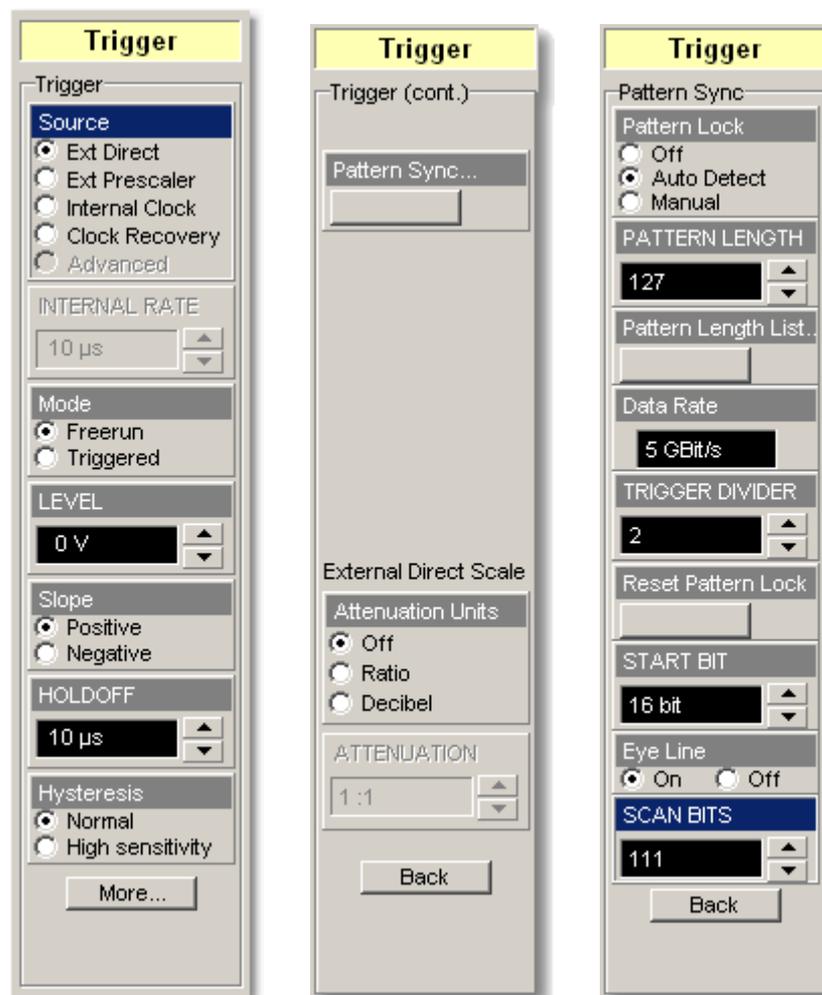
$$\text{Maximum delay} + \text{Maximum delta delay} + 10 \times \text{SCALE B} = 10 \times \text{SCALE A}$$

5.19 Trigger Menu



The scope trigger circuitry helps you locate the waveform you want to view. The oscilloscope uses a reference signal to determine precisely when to acquire data from the signal. The data can then be displayed as a function of time (relative to the reference signal). This reference signal is commonly referred to as a trigger.

The trigger event, when synchronized to the input signal, also defines the horizontal acquisition window. By choosing the trigger event and adjusting the horizontal position (delay between trigger event and the horizontal reference point) you control the location in the data stream (the input signal) from which the waveform record is taken.



Types of trigger

There are several different types of trigger used in digitizing oscilloscopes. The PicoScope 9000A uses four of them:

- Edge trigger
- Prescaled trigger
- Clock recovery trigger
- Pattern Sync trigger

Edge trigger

Edge trigger is the traditional and most often used type. It identifies a trigger condition by looking for the slope (rising or falling) and voltage level (trigger level) on the source you select. When the trigger edge crosses a predefined threshold, the oscilloscope begins to sample and acquire data from the signal. By acquiring data from the input signal, the oscilloscope can reconstruct the waveform and display it on the screen.

Prescaled trigger

Prescaled trigger extends direct triggering to signals up to 10 GHz. In this mode, there is no control over the trigger level or slope. The input circuitry includes a low-jitter high-speed 1:32 frequency divider. The divided signal is applied to the existing trigger circuitry. The trigger input is AC-coupled to the divider. The input threshold of the divider is set for maximum sensitivity and bandwidth, and it will operate correctly on a sine wave input from 1 GHz to 10 GHz. Square wave triggers, or other sharp-edged transitions, will function down to DC.

Clock recovery trigger

This optional type is needed in cases where direct or prescaled trigger signals are not available. The clock recovery trigger derives a timing reference directly from the NRZ waveform to be measured. The clock recovery trigger covers the most popular electrical lines used today from 12 Mb/s to 2.7 Gb/s bit rates.

Pattern Sync trigger

Pattern Sync trigger is the ability of the PicoScope 9000A to internally generate and lock onto a pattern trigger. The pattern trigger is derived from the supplied clock by automatically detecting data rate, pattern length, and trigger divide ratio. Pattern Sync trigger enables the Eye Line mode to walk through each bit of the data pattern, to average eye diagrams and to view specific bit trajectories.

External trigger inputs

Three external trigger inputs (one optional) are placed on the front panel:

- **DIRECT TRIGGER INPUT SMA female.** This input is used for edge triggering. PicoScope 9000 provides a 0 to 1 GHz direct trigger bandwidth.
- **PRESCALE TRIGGER INPUT SMA female.** This input is used for prescaled triggering. PicoScope 9000 provides 1 GHz to 10 GHz trigger bandwidth.
- **CLOCK RECOVERY TRIGGER INPUT SMA female.** This input is used for clock recovery triggering. PicoScope 9000 provides triggering on 12 Mb/s to 2.7 Gb/s bit rates.



When using a given trigger source, you should disconnect any other trigger source from the front panel to ensure specified performance.

Triggering process

Oscilloscopes respond to trigger signals in different ways, depending on their architecture. The PicoScope 9000 uses digital sampling oscilloscope technology to acquire and display wide-bandwidth waveforms. This type of instrument employs a triggering scheme referred to as equivalent time sampling. The trigger circuit and sampler circuits operate in parallel. The sampler samples the input signal at a specific rate. The trigger circuit operates independently of the sampler circuit, and a trigger event does not have to occur at the same time as a sample point. Because the instrument knows when the trigger event happened in relation to the sampled data, it knows where to place the sampled data on the display.

The triggering scheme is based on the following characteristics:

- An external trigger signal is required. The instrument does not have the ability to synchronize directly to the signal being measured.
- The instrument must be armed and an input channel must be turned on in order to respond to a trigger. Typically the instrument will be armed if it is placed in the Run mode. The instrument also becomes armed if it is in Single acquisition mode. The single acquisition mode occurs after the instrument is placed into Stop mode. Click the Stop/Single button repeatedly to toggle the instrument modes between stop and single acquisition.
- A significant time delay occurs between the time the instrument responds to a trigger and when the instrument is armed and able to respond to another trigger. This delay is called the rearm or setup and hold time, and is on the order of 5 μ s. Therefore, many trigger events can occur and are not responded to by the instrument while the rearming process takes place.
- A displayed waveform consists of several sampled points. A trigger event (edge) is required for each sampled point. For example, if the number of points making up a waveform trace is 512, then the instrument would have to respond to at least 512 trigger edges.
- A minimum time delay occurs between the time a trigger is received and when the data is actually sampled. This delay is on the order of 40 ns. Therefore, the signal at the trigger point (time 0) is usually not seen unless the data is delayed (through cable lengths or delay lines) relative to the trigger signal. The delay between the trigger event and the sample point can be longer than 40 ns. You can change the amount of delay in the [Time Base](#) ⁸⁹⁰ menu. Upon the next trigger event, a sample point is acquired at a small time increment in addition to the initial delay of 40 ns. Each additional trigger event yields sample points delayed by sequentially greater amounts of time. Therefore, after many triggers, the input waveform is reconstructed on the display screen.

The types of signals that can be viewed with these triggering requirements are divided into the following categories:

- Signals that are repetitive. The displayed waveforms are constructed from samples taken over multiple repetitions of the waveform. A trigger signal synchronous with the data is needed to control the timing of the sampling process.
- Signals that are not repetitive but are synchronous with a trigger signal. The primary example of a non-repetitive signal is the measurement of digital data streams or eye-diagrams with the oscilloscope triggered by a synchronous clock signal.

5.19.1 Source



The source provides the signal that the trigger system monitors. The Source function displays a list of the available trigger sources. There are four sources that the PicoScope 9000 can use for a trigger:

- External Direct
- External Prescaler
- Internal Clock
- Clock Recovery (PicoScope 9211A/9221A/9231A).

External Direct

Connect an external trigger source to the DIRECT trigger input (SMA female). The External Direct trigger source is an edge trigger. Use this source when the trigger signal is within the DC to 1 GHz frequency range.



The DIRECT trigger input female connector is a DC-coupled input with 50-ohm input impedance.

CAUTION!

To avoid damage to the DIRECT trigger input of the scope, make sure you do not exceed the maximum rated input voltage ± 2 V (DC + peak AC).

Using resistive divider probes you can increase the input impedance up to 5 kilohms, and using an active probe you can increase the input impedance up to 10 megohms.

External Prescaler

Connect an external trigger source to the PRESCALE trigger input SMA female. The External Prescaler trigger source is a prescaled trigger. Use it when the trigger signal has a frequency between 1 GHz and 10 GHz.

Internal Clock

With the Internal Clock source you can trigger the instrument from the precise internal clock. The frequency of the internal clock can be changed by the INTERNAL RATE control. Use this source as a TDR clock rate.



Changing trigger sources while the instrument is running causes newly acquired data to overwrite existing waveforms that are on the display. However, if the instrument is stopped, changing the trigger sources does not change the display until the instrument starts running again.

Clock Recovery (9211A/9221A/9231A).

Connect an external trigger source to the CLOCK RECOVERY trigger input SMA female when the Clock Recovery trigger source is selected. Use this source when trigger signal is an NRZ data pattern with any data rate between 12.3 Mb/s and 2.7 Gb/s.

5.19.2 INTERNAL RATE



The INTERNAL RATE spin-box allows you to vary the repetition rate of the internal clock from 16 ns up to 2 ms. If fine mode is off, the repetition rate can be set to 16 ns, 24 ns, 32 ns, 40 ns, 80 ns, 160 ns or 200 ns, and then changed in a 1-2-5 sequence. When fine mode is on, you can change the repetition rate in 8 ns increments.

The INTERNAL RATE is used only when the [Internal Clock](#) source is selected.

5.19.3 Mode



The trigger modes control the behaviour of the instrument when not triggered. The Mode menu lets you select between Freerun and Triggered modes.

The Mode menu is active when the External Direct, External Prescaler or Clock Recovery sources are selected in the [Source](#)^[40] menu.

Freerun

With the Freerun mode, the trigger circuit is armed and the instrument waits for up to 400 μs for a trigger occur. If a trigger does not occur within 400 μs , the instrument triggers itself, and the data that is acquired with the trigger is displayed on the screen. Use the Freerun mode when you are unsure how to setup the trigger menu to trigger the instrument, or for DC trigger signals. This mode forces the instrument to trigger, giving you glimpses of the signal, which then allows you to set up the instrument to display the signal.

For waveforms whose period is greater than 400 μs the Freerun mode should not be used, because the scope's 400- μs timeout will always occur before your waveform trigger. For waveforms whose period is lower than 400 μs , the Freerun mode works similarly to the Triggered mode.

Use Freerun triggering when you are not using an external trigger and you want to view the waveform for amplitude information only. Freerun triggering allows the instrument to trigger as soon as the instrument is armed, and is asynchronous to the data. You can also use Freerun triggering to view a signal without any timing information. It is an easy way to examine the amplitude of a signal.

Triggered

In Triggered mode, the instrument displays data only after all of the trigger conditions are met. Triggered mode keeps the instrument from triggering and displaying data on the screen before a specific trigger event occurs. Use Triggered mode to update the display only when a trigger event occurs or for waveforms that have a fundamental period of less than 400 μs .

5.19.4 LEVEL



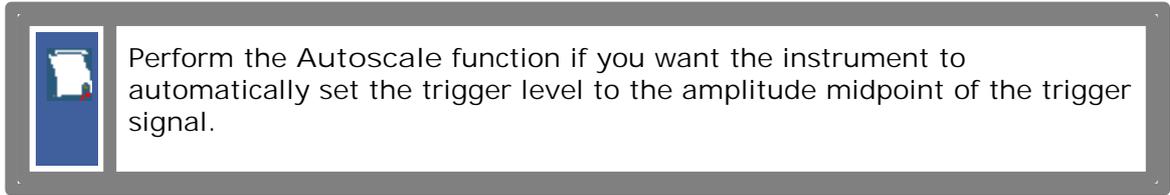
The LEVEL variable specifies the voltage threshold that a signal must cross in order for the instrument to trigger on that signal. When the input signal crosses this voltage level, the instrument triggers.

LEVEL is active only when External Direct is selected in the [Source](#)^[40] menu.

You can select the trigger level in one of three ways:

- By using the LEVEL spin box
- By using trigger level spin boxes in the [Permanent Controls](#)^[32] area.
- By using the [Pop-up Keypad](#)^[42] to quickly enter numeric data using the mouse.

When the External Direct trigger source is selected, you can adjust the trigger level value between -1 V and 1 V in 10 mV steps (coarse increment) or 1 mV steps (fine increment).



The trigger signal must be connected to the trigger input of the instrument. For example, if you are using the trigger input on the instrument front panel, the trigger signal must be connected to the front panel trigger input. Autoscale can then set the trigger level.

When direct (edge) trigger is in use, the trigger level setting also determines what the instrument uses as a reference to determine a high or low. A high is a voltage above the trigger level, and a low is a voltage below the trigger level.

The LEVEL value changes automatically if the attenuation factor is changed.

5.19.5 Slope

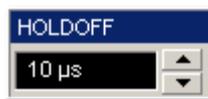


The Slope menu specifies whether the instrument triggers on either the positive or negative edge of the signal. The Slope menu is active when the External Direct source is selected in the [Source](#) ^[40] menu.

Positive. Triggers on an edge that transitions through and above the trigger level.

Negative. Triggers on an edge that transitions through and below the trigger level.

5.19.6 HOLDOFF

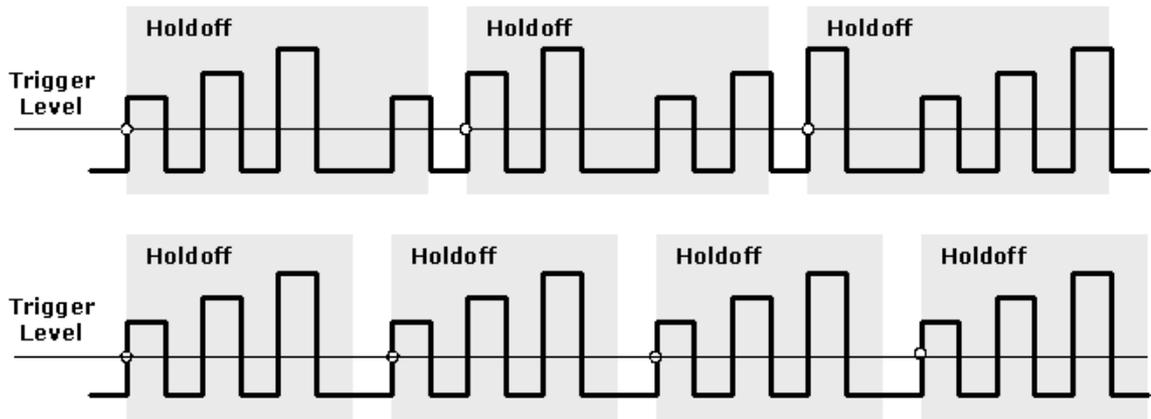


Trigger holdoff helps stabilize triggering. When you adjust the HOLDOFF control, the amount of time that the scope waits before re-arming the trigger circuitry also changes.

Before re-arming, the trigger circuitry cannot recognize when the next trigger conditions are satisfied and so cannot generate the next trigger event. When the instrument is triggering on undesired trigger events, you adjust holdoff to obtain stable triggering. For example, if you have a burst of pulses and want to trigger on the first pulse in the burst, you can set the holdoff time to be slightly longer than the burst width.

The HOLDOFF spin-box allows you to change the holdoff time from $5\text{ }\mu\text{s}$ to 1 s .

The HOLDOFF is active when the External Direct, External Prescaler or Clock Recovery sources are selected in the [Source](#) ^[40] menu.



5.19.7 Hysteresis



Trigger hysteresis helps to prevent false triggers from occurring on a falling edge due to noise when the rising edge is selected as the trigger edge (or on a rising edge when the falling edge is selected as the trigger edge).

The voltage through which the trigger signal must pass before the instrument is ready to accept another valid trigger is known as the arming voltage level. Hysteresis is the voltage difference between the arming level and the trigger threshold level.

The Hysteresis menu is active when the External Direct is selected in the [Source](#) menu.

The trigger hysteresis can be set to two modes:

- **Normal.** Hysteresis is enabled. The trigger hysteresis is set so that the instrument meets the trigger sensitivity specification. The instrument will trigger if a trigger signal crosses both the arming voltage level and the trigger threshold voltage level. Normal mode provides good trigger performance while minimizing false triggers.
- **High sensitivity.** The trigger hysteresis is turned off to allow best sensitivity to high-frequency signals. This mode should not be used for noisy lower-frequency signals that may mistigger without hysteresis, but can result in false triggers if there is significant noise on the trigger signal, or if the trigger signal is not monotonic in the region of the trigger threshold level. The High sensitivity hysteresis provides at least twice better sensitivity than the Normal hysteresis.

Normal Hysteresis

100 mV p-p DC to 100 MHz. Increasing linearly from 100 mV p-p at 100 MHz to 200 mV p-p at 1 GHz. Pulse Width: 500 ps @ 200 mV p-p

High Sensitivity Hysteresis, typical

50 mV p-p at 100 MHz. Increasing linearly from 50 mV p-p at 100 MHz to 100 mV p-p at 1 GHz.

5.19.8 Pattern Sync...



The Pattern Sync menu controls two functions:

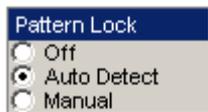
- Pattern Lock trigger, and
- Eye Line mode.

Pattern Lock is the ability of the PicoScope 9000A to internally generate and lock onto a pattern trigger. The pattern trigger is derived from the supplied clock by automatically detecting the following parameters:

- Data rate,
- Pattern length, and
- Trigger divide ratio.

The Pattern Sync functions are available with the PicoScope 9211A/9221A/9231A.

5.19.8.1 Pattern Lock



The PicoScope 9200A can internally generate a pattern trigger off the supplied clock. Any of three trigger sources can be used as a supplied clock.

The following table shows valid ranges for data rate and pattern length when using pattern lock.

External Direct Trigger	10 MHz to 1 GHz
External Prescaled Trigger	1 GHz to 8 GHz, up to 10 GHz typical.
Clock Recovery Trigger	12.3 GHz to 2.7 GHz

Off

When Pattern Lock is turned Off, the oscilloscope stops pattern trigger detection and triggers off the data rate instead.

Auto Detect

When Auto Detect is turned on, the oscilloscope automatically detects data rate, pattern length, and trigger divide ratio and generates the pattern trigger. To get correct pattern lock you should check the Pattern Length List. The pattern length you want to detect should be included in this list.

Manual

When Manual is turned on, the oscilloscope can manually detect data rate, pattern length, and trigger divide ratio and generates the pattern trigger. Use the PATTERN LENGTH control to detect the right pattern trigger when you do not have the information about data pattern length.

5.19.8.2 PATTERN LENGTH



Select Auto Detect from the Pattern Lock menu to have the pattern length automatically detected.

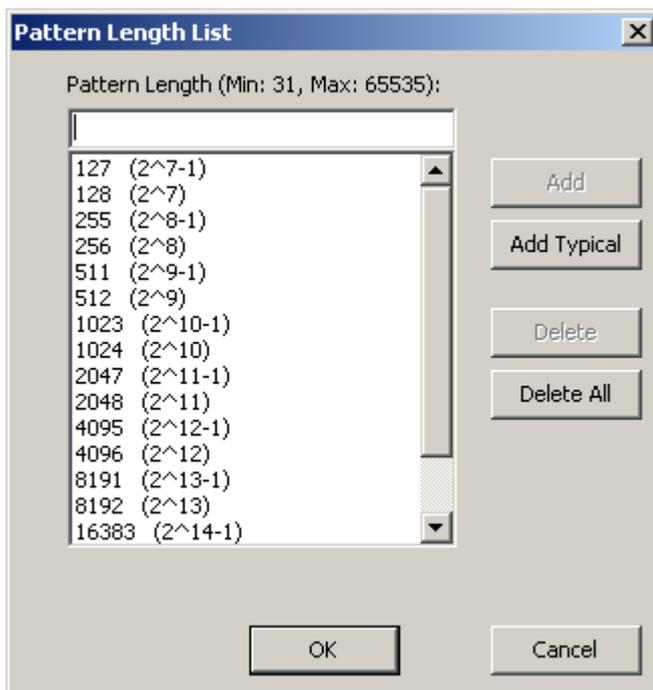
To manually enter the pattern length, click Manual in the Pattern Lock menu. Enter the length of the test pattern in bits, which can be any value between 31 and $2^{16}-1$. Use manual entry when you do not have any information about data pattern length.

5.19.8.3 Pattern Length List...



Click the Pattern Length List... to create a table with the list of pattern lengths. When Auto Detect is turned on, the oscilloscope automatically detects data rate, pattern length, and trigger divide ratio and generates the pattern trigger. Only pattern lengths included in the table will be used in the detection procedure.

You can modify the table to have typical or custom lengths, or you can create your own custom lengths.



5.19.8.4 Data Rate



Data Rate shows information about the detected data rate.

The PicoScope 9000A Series uses an internal frequency counter that constantly measures data rate value taking into account the trigger divide ratio. The precision of the counter is ± 50 ppm or better.

5.19.8.5 TRIGGER DIVIDER



Select Auto Detect from the Pattern Lock menu to have the trigger divide ratio automatically detected. You can also manually enter the trigger divide ratio.

The following table shows valid ranges for data rate and the trigger divide ratio when using pattern lock.

External Direct Trigger	<250 MHz: 1. 250 MHz to <500 MHz: 2. 500 MHz to <1 GHz: 4.
External Prescaled Trigger	1 GHz to <8 GHz: 32. 8 GHz to 10 GHz (typical): 64.
Clock Recovery Trigger	12.3 MHz to <1 GHz: 4. 1 GHz to <2 GHz: 8. 2 GHz to <2.7 GHz: 16.

5.19.8.6 Reset Pattern Lock



Click Reset Pattern Lock when you need to reset the pattern lock procedure.

5.19.8.7 START BIT



Set START BIT to specify the starting bit location for the scan.

When Auto Detect from the Pattern Lock menu is turned on, the START BIT value specifies an offset in data bits from the pattern trigger. Because the internally generated pattern trigger is synchronized to an unknown bit number in the data pattern, the START BIT does not specify an absolute bit in the data pattern.

Use this feature to step the triggering through each bit of a pattern when Eye Line mode is off. This setting is relative to an arbitrary reference pattern bit.

5.19.8.8 Eye Line



Eye Line mode is used to average eye diagrams and to view specific bit trajectories. The number of averages can be set from AVERAGE N in the Acquisition menu.

Eye Line mode uses the pattern lock feature to establish a pattern sync trigger and then to use that trigger to walk through each bit of the data pattern. For eye diagrams, this allows high and low values to be separated before being averaged together. Without Eye Line mode, averaging an eye diagram would result in highs from one bit being averaged with lows of another bit which results in an erroneous value between the two levels.

5.19.8.9 SCAN BITS



Set SCAN BITS to the number of bits or sub-frames you want to acquire.

5.19.8.10 Pattern Sync Trigger/Eye Line Setup Guide

Pattern Sync Trigger

1. Connect the equipment and get a picture of an eye diagram (see Figure 1).

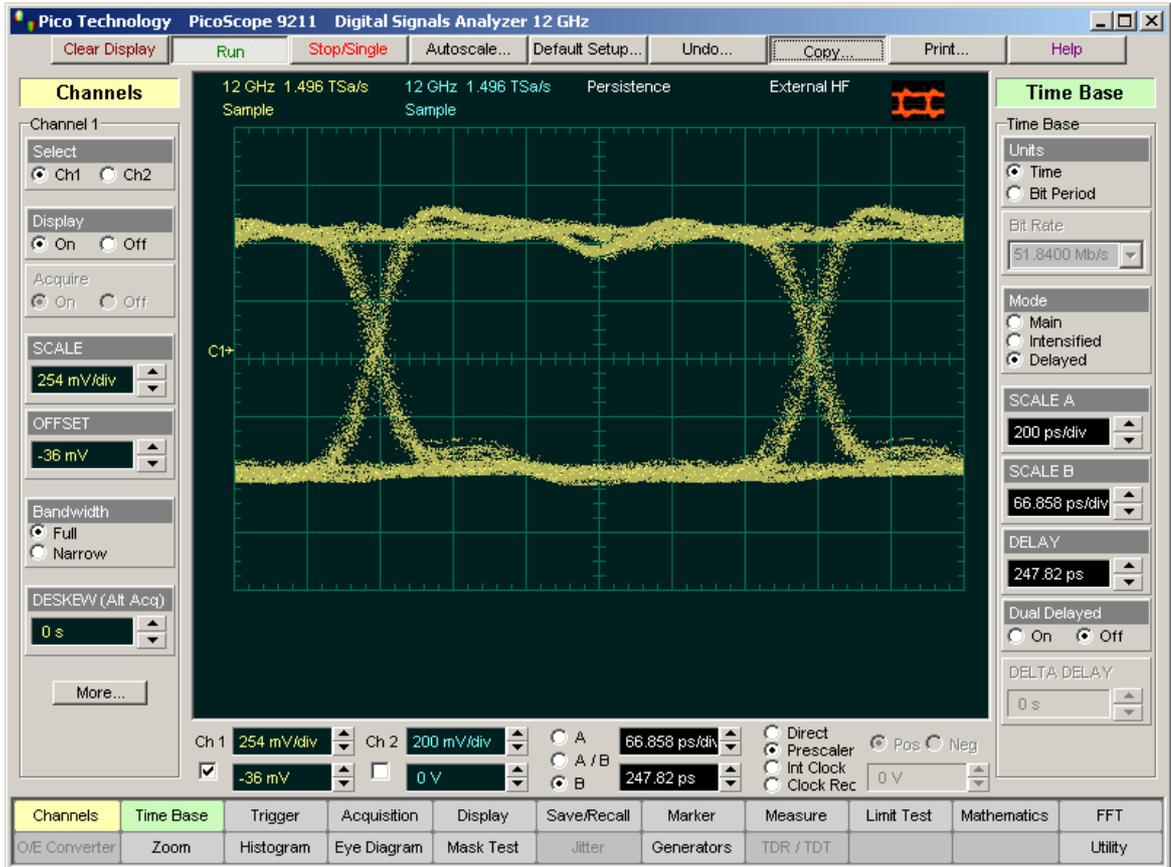


Figure 1

2. Click Trigger/More.../Pattern Sync.
3. Click Pattern Length List.. and make sure your pattern length is present in the table.
4. Click Auto Detect from the Pattern Lock menu. You should get a picture of the data pattern shown in Figure 2. Notice that data rate, pattern length and trigger divide ratio are automatically detected.



Figure 2

5. Click the A time base mode. Select the 1 ns/div Main Time Base scale.
 6. Enable START BIT to scan through a pattern (or part of a pattern).
- Eye Line mode
7. Click Acquisition/Multiple Average. Set AVERAGE N = 16.
 8. Click On from the Eye Line menu.
 9. Set SCAN BITS to 32. See Figure 3.
 10. Click Display/Infin Persistence.
 11. Click Autoscale. See Fig. 4 with an averaged eye diagram with specific bit trajectories.
 12. Go to the Eye Diagram menu to make the necessary measurements. See Figure 4.

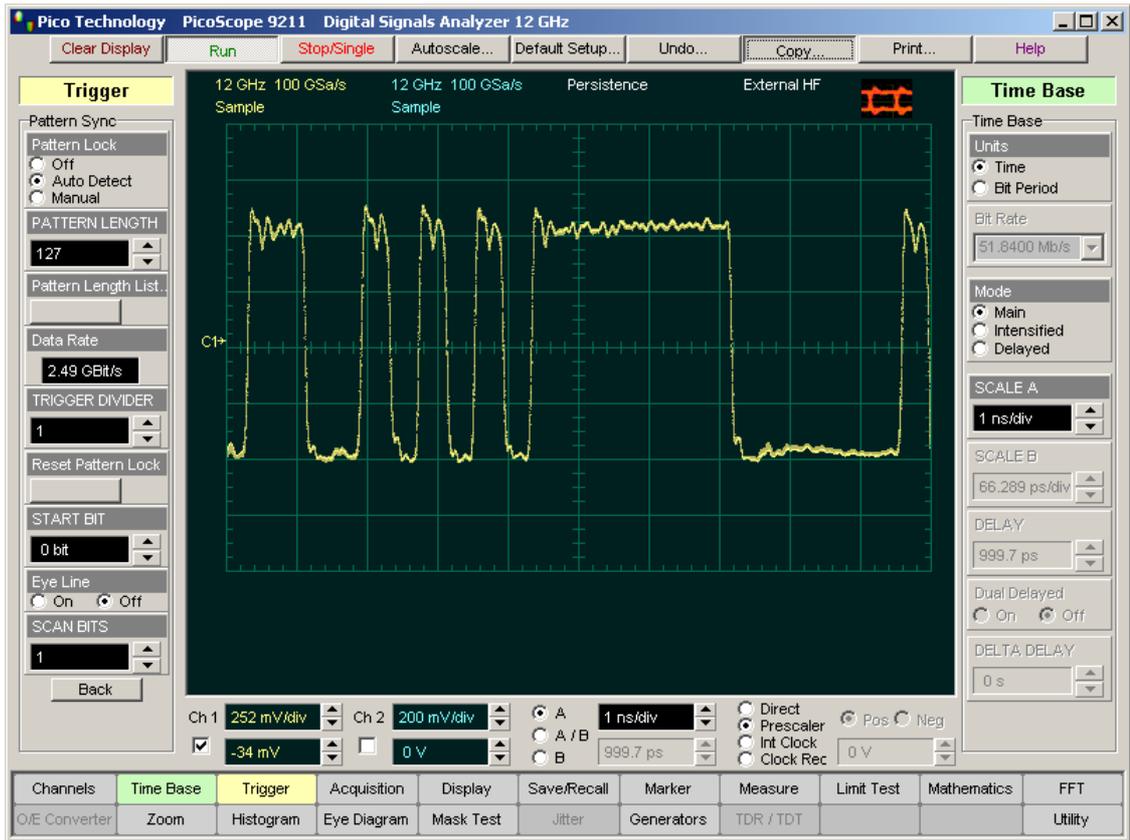


Figure 3

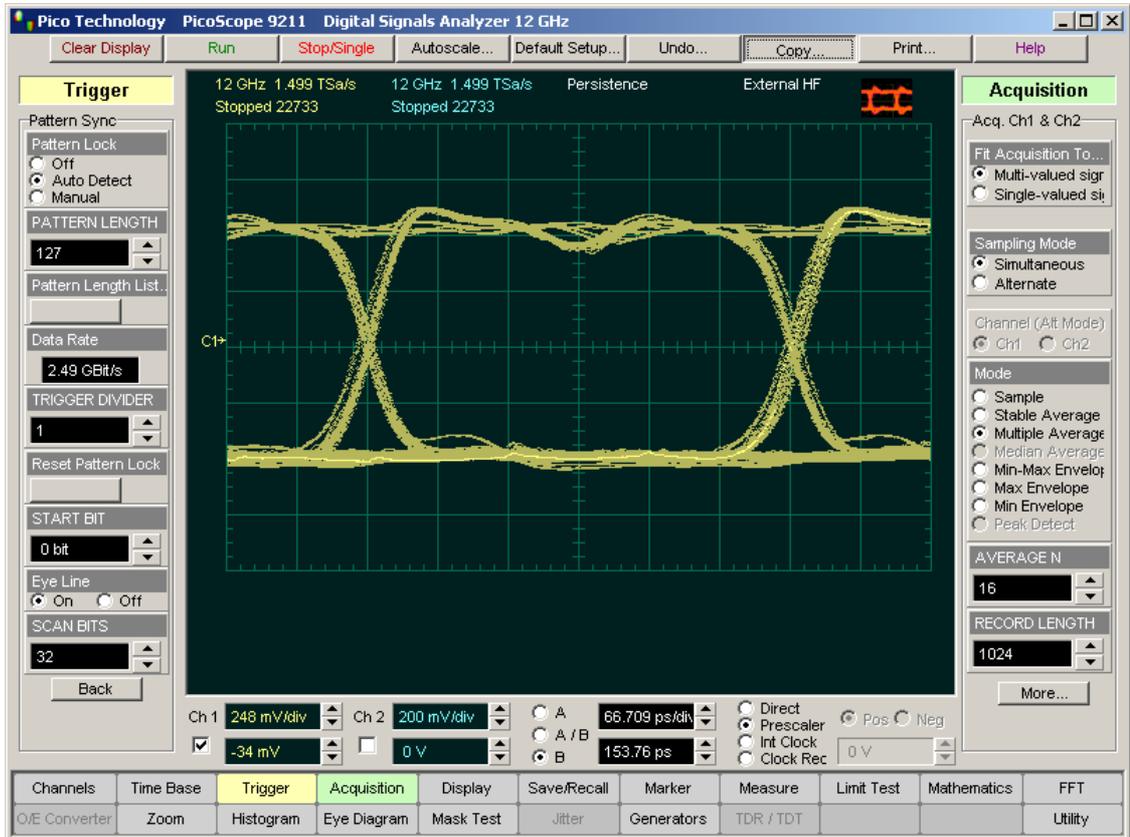
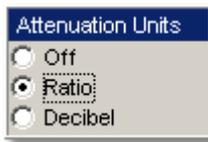


Figure 4

5.19.9 External Direct Scale

The External Direct Scale functions can be used when the trigger signal level changes due to the use of an amplifier, attenuator or a probe. The attenuation factor can be entered either as a ratio or decibel value.

5.19.10 Attenuation Units



You can enter the attenuation or gain characteristics of an external device when configuring a trigger channel for external scaling. The Attenuation Units function lets you select how you want the probe attenuation factor represented. There are options for either decibel or ratio. The formula for calculating decibels is:

$$20\log(V_{out}/V_{in}) \text{ or } 10\log(P_{out}/P_{in})$$

Decibel Versus Voltage Ratio:

dB	Voltage Ratio
3 dB	1.41
6 dB	2.00
10 dB	3.16
20 dB	10
40 dB	100
60 dB	1000
120 dB	1 000 000
-80 dB	0.0001



Changing the attenuation factor does not attenuate the trigger signal; it only changes the database for generating prompts on the display. If the trigger signal must be attenuated, use external attenuators.



Gain is implied when you enter negative decibel values or ratios of less than 1:1 in the ATTENUATION variable. The default attenuation value is 1:1.

5.19.11 ATTENUATION

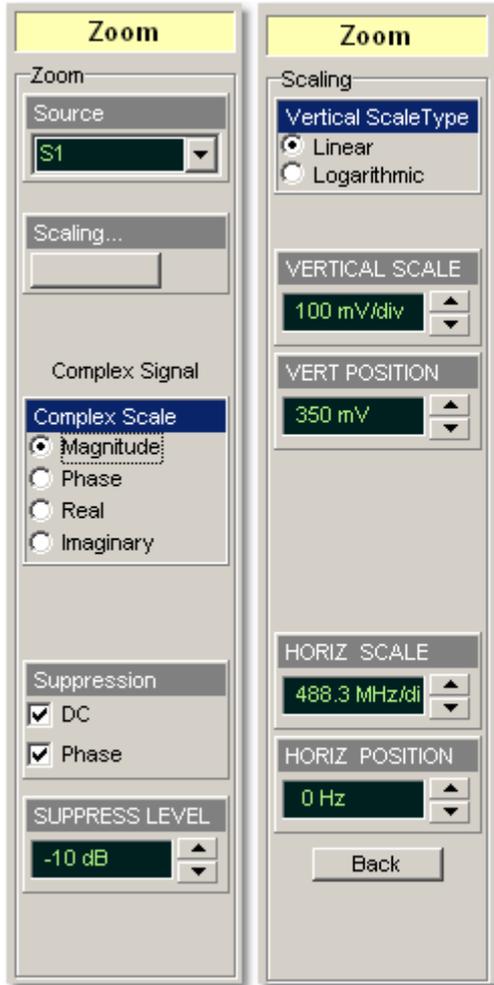


The ATTENUATION control lets you select an amplification or attenuation that matches the device connected to the trigger input of the instrument. When the attenuation is set correctly, the instrument maintains the trigger level if possible. For example, if you want to trigger the scope with a 0 to 5 V trigger source, you can attenuate the source with a 20 dB pad to bring the level within external trigger limits. The pad lowers the source level to 0 to 0.5 V, but you can use external scaling to compensate for the 20 dB pad. This allows you to view the trigger source voltage in the trigger level spin-box as though no attenuation were present. Because of this scaling feature, you can set the scope to trigger at the precise source level you want without calculating the drop across the pad.

The trigger level attenuation factor is used to establish a database for generating the LEVEL prompts on the display.

The attenuation factor is from 0.000,1:1 to 1,000,000:1 or from -80 dB to 120 dB.

5.20 Zoom Menu



In addition to channel scaling and a delayed timebase, the PicoScope 9000 includes graphical zoom capability for rescaling the vertical and horizontal components of waveforms simultaneously. You can use the Zoom menu to change the vertical and horizontal scales and positions for waveform memories, or waveform math functions and spectrums that are currently displayed. Also the instrument will convert your time domain waveform into a frequency domain spectrum using an FFT, similar to the way that an RF spectrum analyzer displays in different complex scales.

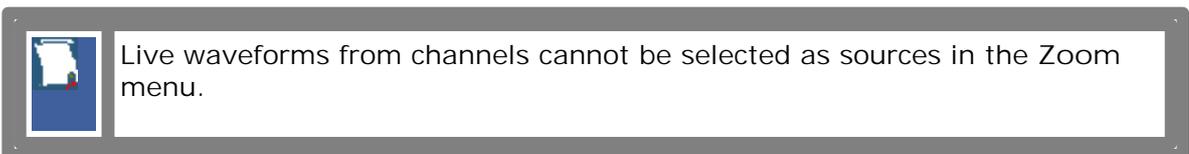
5.20.1 Source



The Source menu selects the source trace for displaying with different complex scales, and for vertical and horizontal scaling and positioning.

You may set the source to:

- Spectrums 1 and 2
- Functions 1 through 4
- Waveform memories 1 through 4



5.20.2 Scaling



Clicking the Scaling... button opens a second-level menu that let you control vertical and horizontal magnification and positioning without affecting the channels and timebase scaling controls.

5.20.2.1 Vertical Scale Type



The Vertical Scale Type menu allows you to set the scale of the vertical display. Vertical units can be either linear or logarithmic.

Linear. Sets the display to the current source value. Usually this is volts, but it may also be watts or amperes.

Logarithmic. Sets the display of the results to dB. Use [VERT POSITION](#)⁴¹⁶ to set what vertical position in the magnitude spectrum will be zero dB. The following equation applies:

$$dB = 20 \log_{10} \left(\frac{|X|}{X_{ref}} \right)$$

where: X is a complex data point in the spectrum, and X_{ref} is the reference value equal to 1 V.

5.20.2.2 VERTICAL SCALE



Magnitude

The VERTICAL SCALE function uses software expansion to set the vertical scaling of the selected waveform. It does not affect the hardware settings in the instrument, only the appearance of the waveform.

The scaling units are mV per division or dB per division. For example, if the vertical scale is set to 10 dB/div, and a peak is two divisions high, you know that the amplitude of the frequency peak is 20 dB. When scaling is set to 0 dBV, the display is in decibels relative to a 1 V peak sine wave (0 dBV) into 50 ohms.



Phase

The PHASE SCALE function uses vertical software expansion to set the phase characteristic of the spectrum. It does not affect the hardware settings in the instrument, only the appearance of the phase waveform. You can change phase scale from 4.5°/div to 90°/div.

5.20.2.3 VERT POSITION



The VERT POSITION controls use software to move the selected waveform vertically on the screen. Vertical position is the value at the centre of the graticule area. If you adjust the vertical position so that a peak is at the vertical centre of the graticule area, then you know that the peak magnitude is the vertical position value. For example, if the peak of the spike is at the vertical centre of the graticule area and the vertical position is -20 dBV, then you know that the peak magnitude is -20 dBV.

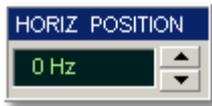
5.20.2.4 HORIZ SCALE



The HORIZ SCALE control allows you to zoom in a portion of the waveform record. Horizontal zooming can be entered in steps of 1-2-4-8. Changing the horizontal magnification of an FFT waveform using the HORIZ SCALE changes the appearance of the trace, but does not increase the horizontal (frequency) resolution.

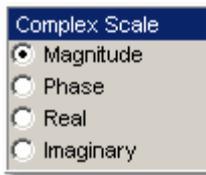
You can also change the frequency interval and frequency range by changing the record length and horizontal scale of the time-domain waveform. If the record length increases, frequency resolution improves. When the equivalent sample rate increases (due to a faster horizontal size setting), frequency interval and frequency range both increase, giving the FFT waveform a broader frequency range with less frequency resolution.

5.20.2.5 HORIZ POSITION



The HORIZ POSITION control allows you to move the horizontally expanded portion of the waveform record. The HORIZ POSITION variable uses software positioning.

5.20.3 Complex Scale

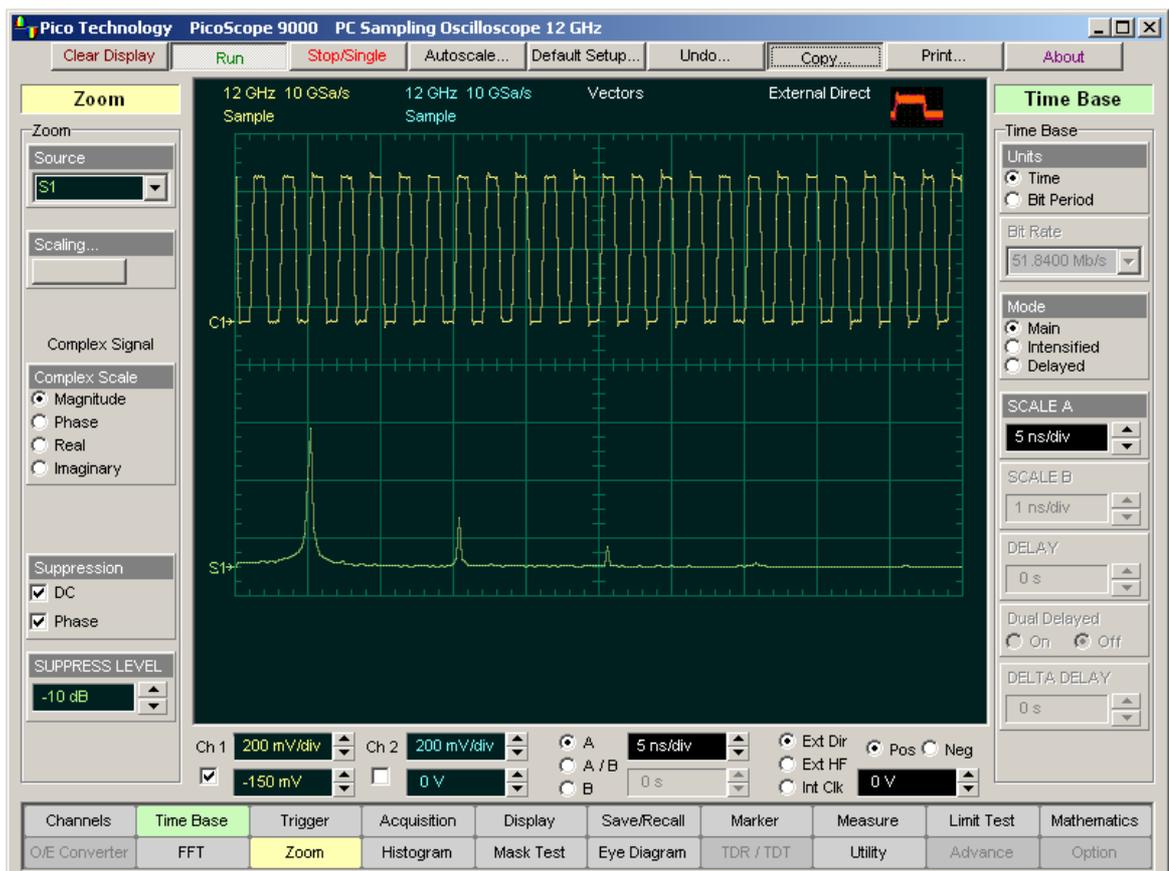


The Complex Scale menu selects the display format of a waveform that has a complex value. The options are:

- Magnitude
- Phase
- Real
- Imaginary

Magnitude

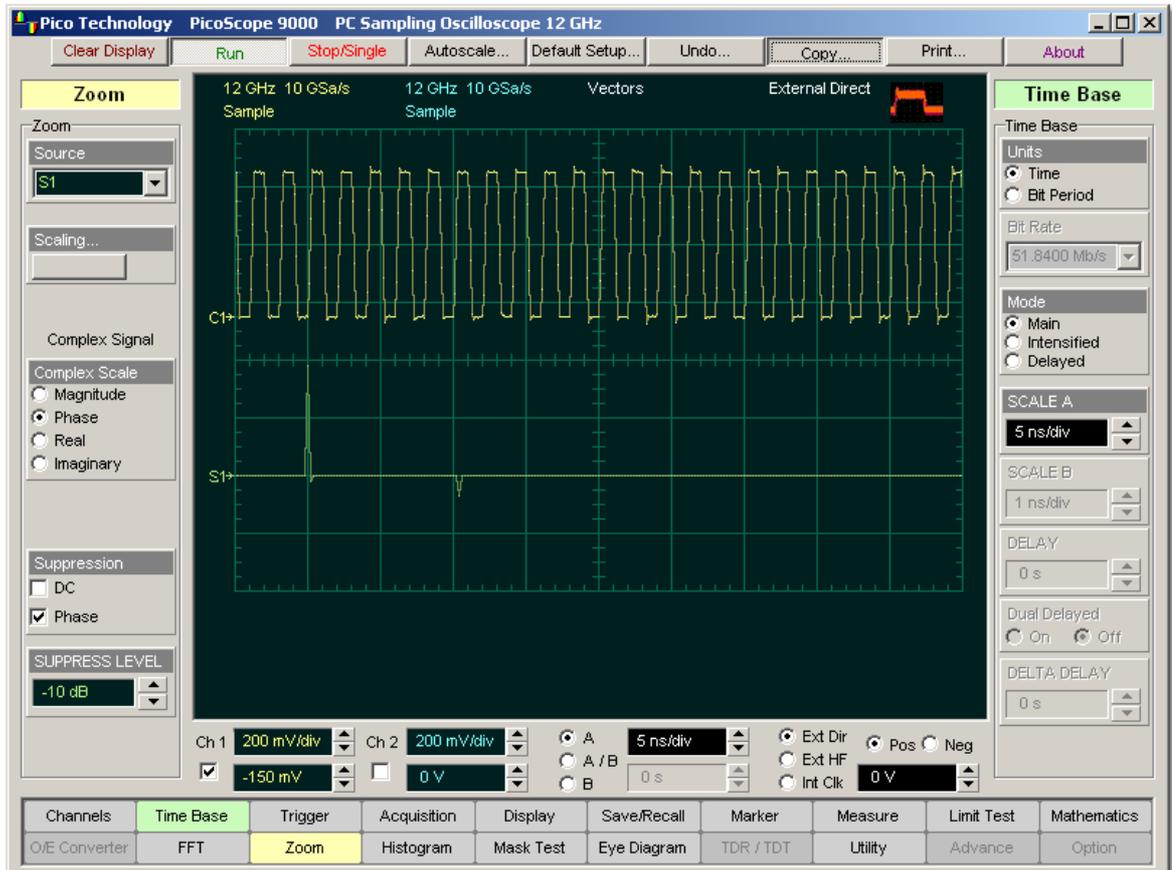
The peak signal amplitude is represented on a linear or logarithmic scale, in the same units as the input signal. You can choose to display data in dB or linear mode. You may display the real or imaginary parts of the spectral magnitude only. The VERT POSITION control gives complete control over the vertical position of the spectrum.



Spectrum Magnitude of 500-MHz pulse waveform

Phase

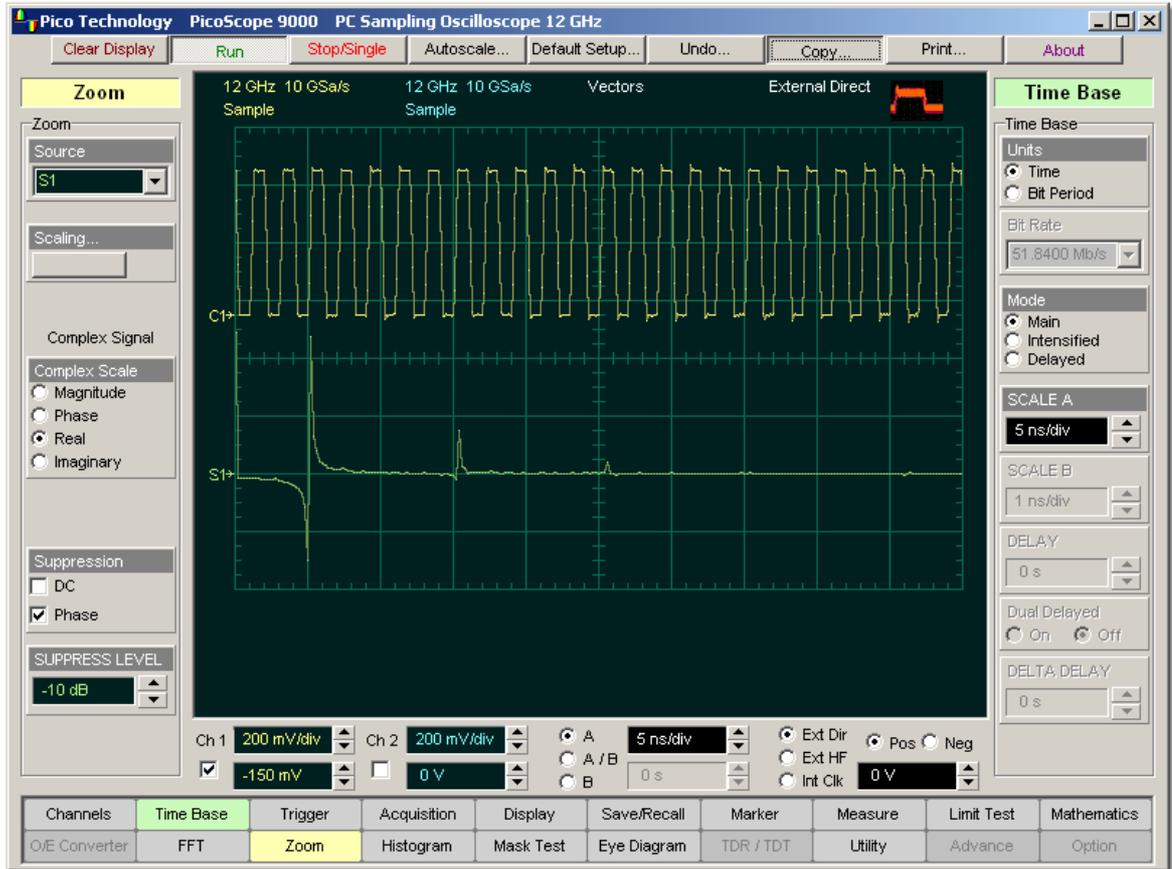
Phase is measured with respect to a cosine whose maximum occurs at the left-hand edge of the screen, at which point it is 0°. Similarly, a positive-going sine wave starting at the left-hand edge of the screen has a -90° phase. You can display phase data as a function of frequency in degrees. You can zero the noise phase for magnitudes below a threshold level.



Phase Spectrum of 500-MHz pulse waveform with deep suppression level

Real

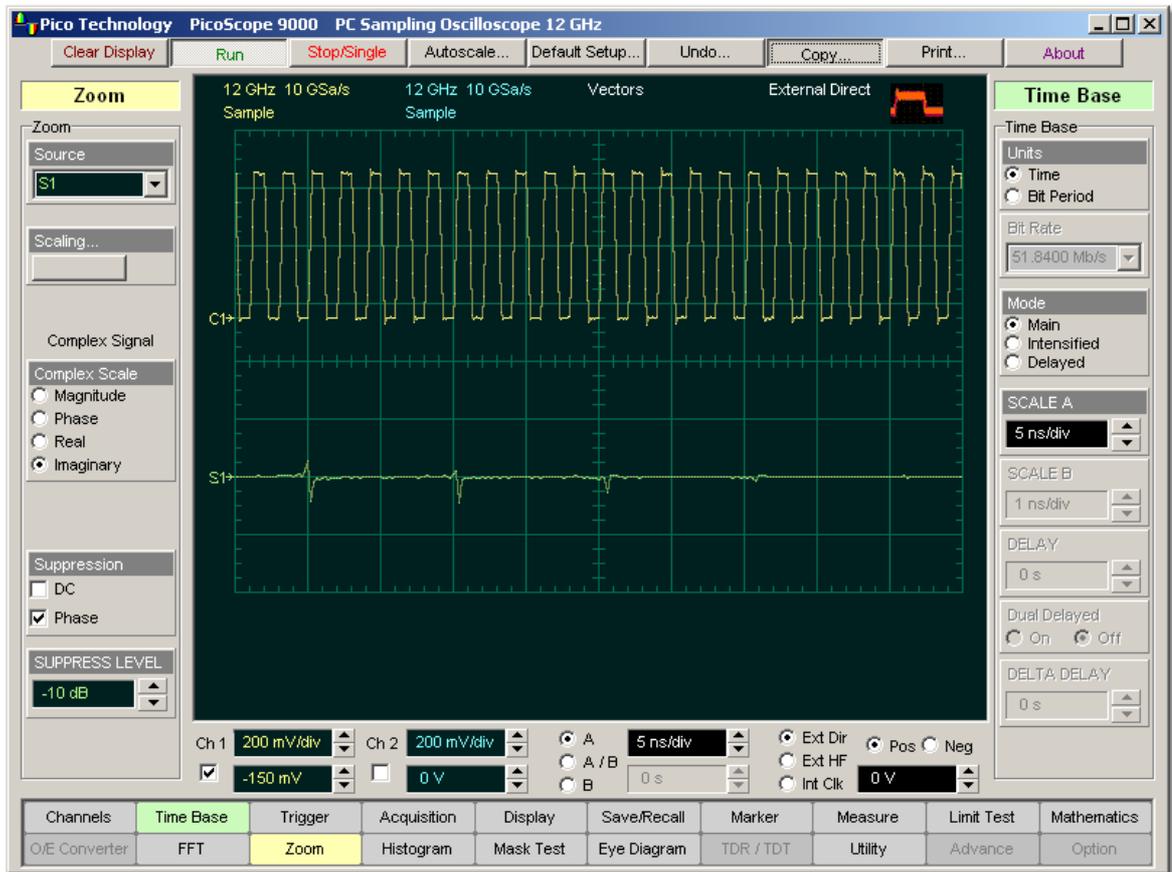
Displays the linear magnitude of the real part of the spectral magnitude only. This is useful if you process the spectrum off-line and transform it back into a time-domain trace. You could save the real spectrum into a waveform memory.



Real part of the spectrum for 500-MHz pulse waveform

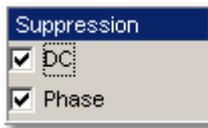
Imaginary

Displays the linear magnitude of the imaginary part of the spectral magnitude only. This is useful if you process the spectrum off-line and transform it back into a time-domain trace. You could save the imaginary spectrum into a waveform memory.



Imaginary part of the spectrum for 500-MHz pulse waveform

5.20.4 Suppression

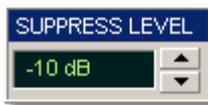


The Suppression mode allows you to reduce the DC components in your spectrum, and also to reduce the effect of noise in your phase FFT.

DC. Check the DC option to reduce the DC components in the FFT spectrum of the signal.

Phase. Your source waveform record may have a noise component with phase angles that randomly vary from - to + . This noise could make the phase display unusable. In such a case, use phase suppression to control the noise. Checking Phase reduces the effect of noise in your phase FFT.

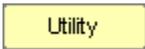
5.20.5 SUPPRESS LEVEL



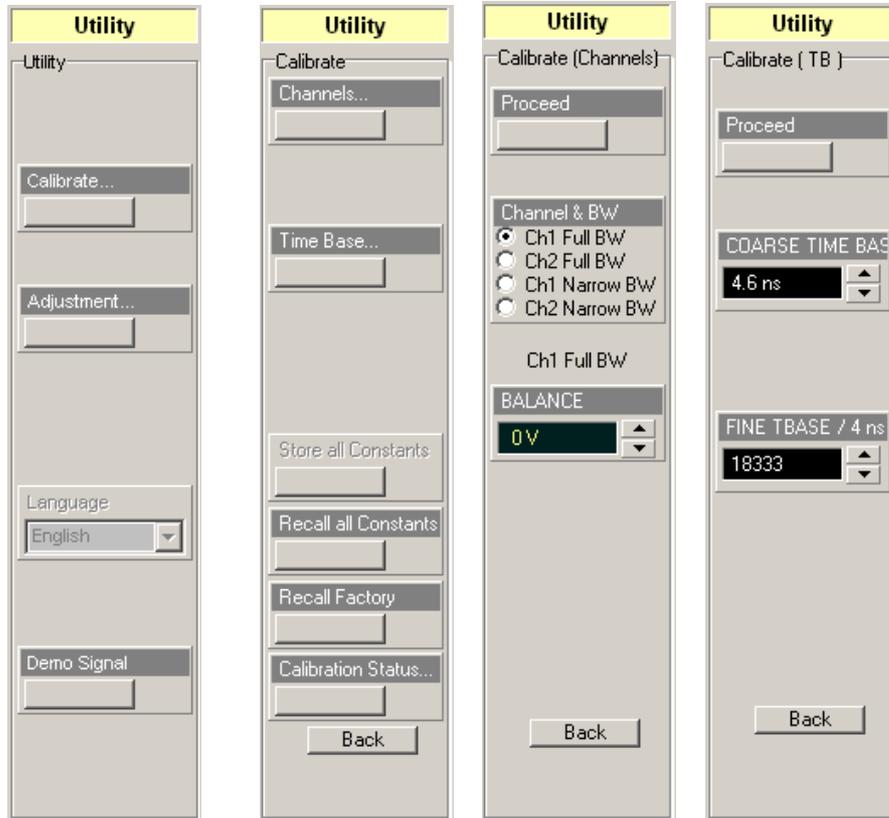
Your source waveform record may have a noise component with phase angles that randomly vary from - to + . This noise could make the phase display unusable. In such a case, use phase suppression to control the noise.

The SUPPRESS LEVEL control allows you to adjust the phase suppression level. You specify the phase suppression level in dB with respect to a peak having maximum amplitude among other peaks. If the magnitude of the frequency is greater than this threshold, then its phase angle will be displayed. FFT magnitudes below this level will have their phase set to zero.

5.21 Utility



The Utility menu provides a calibration menu, adjustment menu, language selection and demo signal menu.



Utility	Utility	Utility
Demo Signal Channel 1 Generator A	Amplitude Parameters OFFSET 0 V	Timing Parameters RANDOM JITTER 2 ps
Channel 2 Generator B	NOISE (RMS) 2 mV	PULSE WIDTH 1 ns
Generator <input checked="" type="radio"/> A <input type="radio"/> B <input type="radio"/> C <input type="radio"/> D	POS OVERSHOT 0 %	RISE TIME 100 ps
Waveform <input checked="" type="radio"/> Sinewave <input type="radio"/> Pulse <input type="radio"/> PRBS <input type="radio"/> TDR	NEG OVERSHOT 0 %	FALL TIME 100 ps
AMPLITUDE 500 mV	DROOP 0 %	PHASE 0 °
FREQUENCY 2.5 GHz	Mode <input checked="" type="radio"/> NRZ <input type="radio"/> RZ	DELTA PHASE 0 °
Amplitude...	PRBS Length 2 ⁿ <input checked="" type="radio"/> 5 <input type="radio"/> 7 <input type="radio"/> 11 <input type="radio"/> 15	Standard Frequency Custom Freq
Timing...	Length Function <input checked="" type="radio"/> 2 ⁿ - 1 <input type="radio"/> 2 ⁿ	Trigger <input checked="" type="radio"/> Clock <input type="radio"/> Pattern
Back	Back	Back

5.21.1 Calibrate...



Calibrate... opens channel and timebase calibration menus.

5.21.1.1 Channels...



Channels... opens the channels calibration menu.

5.21.1.1.1 Proceed



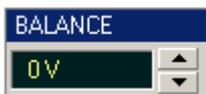
The Proceed command button performs channel calibration.

5.21.1.1.2 Channel & BW



Clicking a button in the Channel & BW menu shows the results of the channel calibration in the [BALANCE](#) ⁴²⁵ control.

5.21.1.1.3 BALANCE



The BALANCE control shows the results of the channel calibration for each of the options in the [Channel & BW](#) ⁴²⁵ menu.

5.21.1.2 Time Base...



The Time Base... button opens the timebase calibration menu.

5.21.1.2.1 Proceed



The Proceed command button performs timebase calibration.

5.21.1.2.2 COARSE TIME BASE



The COARSE TIME BASE control shows the result of the coarse timebase calibration that is a part of full timebase calibration.

5.21.1.2.3 FINE TIME BASE / 4 ns



The FINE TIME BASE control shows the results of the fine timebase calibration that is a part of full timebase calibration.

5.21.1.3 Store all Constants



The Store Constants command button stores all channels and timebase calibration constants.

5.21.1.4 Recall all Constants



The Recall all Constants command button recalls all stored channels and timebase calibration constants.

5.21.1.5 Recall Factory



The Recall Factory command button recalls factory-stored channels and timebase calibration constants.

5.21.2 Adjustment...



The Adjustment... button opens several menus used for the factory adjustment procedure. It is protected by a password.

5.21.3 Language

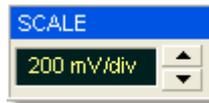


The Language control selects the language used in the PicoScope 9000A User's Guide. At the present time the available languages are English and Russian.

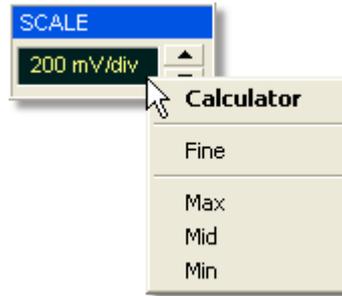
5.22 Pop-up keypad

The Pop-up keypad allows you to enter numeric values directly. You can use it with any numeric field in the PicoScope 9000 program: just right-click on the field and select Calculator. (You can also type variables directly into numeric fields: first type the number, then finish by typing a single letter - p,n,u,m,X,k,M,G,T. The meanings of these letters are explained below.)

1. Choose the numeric field that you wish to edit:



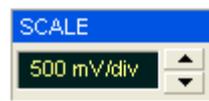
2. Right-click on the field to bring up the context menu:



3. Click the Calculator command to bring up the Pop-up keypad:



4. Enter the new value numerically by clicking the number keys, then click one of the multiplier buttons to complete the value. (The X button means a multiplier of 1.) Finally, click OK to update the numeric field:



Special Key Definitions



Min. Enter the minimum value of selected variable.



Mid. Enter the middle value of selected variable.



Max. Enter the maximum value of selected variable.



Fine. Enter the value of selected variable with fine resolution.



Coarse. Enter the value of selected variable with coarse resolution.



Numeric value keypad

Minus (-). Changes the sign of the mantissa. Changes the sign of the exponent after you have pressed the exponent key.



Dimension keypad

p (pico-suffix). Appends an exponent of 10^{-12} to the number you have entered.

n (nano-suffix). Appends an exponent of 10^{-9} to the number you have entered.

u (micro-suffix). Appends an exponent of 10^{-6} to the number you have entered.

m (milli-suffix). Appends an exponent of 10^{-3} to the number you have entered.

K (kilo-suffix). Appends an exponent of 10^3 to the number you have entered.

M (mega-suffix). Appends an exponent of 10^6 to the number you have entered.

G (giga-suffix). Appends an exponent of 10^9 to the number you have entered.

T (tera-suffix). Appends an exponent of 10^{12} to the number you have entered.



Clr (Clear). Clears any numbers you have entered.



Backspace. Use the backspace key to erase the character to the left of the insertion point.



Exp (Exponent). The number you enter after pressing this key is an exponent of 10.

6 Removal and Installation Procedures

This chapter describes the step-by-step disassembly procedures and lists the available replacement parts for the PicoScope 9000A Series of PC Sampling Oscilloscopes.

6.1 Dismantling Procedures

General Disassembly

This chapter provides the step-by-step guides on how to dismantle the oscilloscope and install the replacement assembly. To reassemble the oscilloscope, follow the instructions in reverse order.



The parts shown in the following figures are representative and may differ from what you have in your oscilloscope.

The removable assemblies

The removable assemblies include:

- Extruded metal enclosure
- Front and rear rubber bezel
- Front metal panel
- Rear metal panel
- SMA connector saver (attached to oscilloscope)
- Fan Assembly
- Acquisition Board

Mechanical Disassembly

Follow the instructions in this section for the instrument disassembly process.

Step 1: Pull the rubber bezels out to unscrew the metal enclosure.



Step 2: Unscrew SMA connector savers from both inputs of the channels, and also the nuts and washers from the trigger inputs. Use a 5/16" spanner (wrench).



The PicoScope 9201A has two trigger inputs, while the PicoScope 9211A/9221A/9231A have three trigger inputs.



Step 3: On the rear panel, unscrew the nuts and washers from the outputs (for PicoScope 9211A/9231A). Use a 5/16" spanner.

Step 4: Unscrew the four screws fixing the rear panel to the metal enclosure.



Step 5: Carefully separate the rear panel from the metal enclosure.



Step 6: Gently pull out the Acquisition Board halfway out of the metal enclosure.



Step 7: Disconnect the female connector of the Fan Assembly from the pin header located on the Acquisition Board.



Step 8: Pull out the Acquisition Board from the metal enclosure.



Step 9: To remove the cover from the sampler, unscrew the eight screws.



6.2 Replacement Parts

This section provides the information of the orderable replacement parts for the PicoScope 9000A Series of PC Sampling Oscilloscopes.

The parts available for replacement are listed in the table below with the reference part numbers and the respective part names. You can order the replacement parts from Pico Technology using the part number provided in the table, as follows:

1. Identify the Pico Technology part number of the required parts as shown in the replacement parts list.
2. Contact your nearest Pico Technology Sales Office or Service Center.
3. Provide the instrument's model number and serial number.

List of replacement parts

Part Number	Part Name
EN073-2	Extruded Enclosure
ELT-675	Front Panel for PicoScope 9201A
ELT-675-02	Front Panel for PicoScope 9211A
ELT-675-01	Front Panel for PicoScope 9221A/9231A
ELT-676	Rear Panel for PicoScope 9201A/9221A
ELT-676-01	Rear Panel for PicoScope 9211A/9231A
	Rubber Bezel

7 Glossary

7.1 A

AC (Alternating Current)

A signal in which the current and voltage vary in a repeating pattern over time.

AC Coupling

AC coupling removes the DC component of the waveform from the channel input or the trigger path. Only the AC portion of the waveform is displayed or used in the trigger path. You can use AC coupling to view an AC waveform with greater sensitivity or to trigger on an AC waveform that is riding on a DC waveform.

Accuracy

1. The closeness of the indicated value to the true value.
2. The percentage of error possible in transferring the signal through the vertical and horizontal channels.

Acquisition

Acquisition is the process of sampling an analog input waveform, digitising the samples and storing the samples in memory. The stored values represent the waveform record, which can be displayed as a waveform on the scope display, analysed, or transferred to a computer or a disk for further analysis. The trigger marks time in that process.

The [Acquisition](#)  control allows you to define the way the instrument acquires data from the input waveform. You can set up the instrument to continuously acquire data, or you can acquire data in single cycles. Acquisition control also allows you to enable waveform averaging, enveloping, or peak detecting and record length (points per waveform).

Acquisition Interval

The time duration of the waveform record divided by the record length. The oscilloscope displays one data point for every acquisition interval.

Acquisition System

The acquisition system is a combination of hardware and firmware that converts an analog input waveform into discrete digital values and assembles the waveform samples into a waveform record.

Acquisition Time

In a sample-and-hold or track-and-hold circuit, the time required after the sample or track command for the output to slew through a full-scale voltage change and settle to its final value within a specified error band.

AC RMS

The AC RMS is a modified RMS (root-mean-square) measurement. It removes the DC component of the waveform from the calculation of the RMS voltage.

ADC (Analog-to-Digital Converter)

The ADC is the part of the hardware acquisition system in a sampling oscilloscope that converts the analog input waveform into discrete digital values, which make up the waveform record. Several characteristics of the ADC such as sample rate, resolution, accuracy, and linearity directly relate to the oscilloscope's performance.

Alias

Nyquist's sampling theorem says that a signal must be sampled at a minimum rate equal to twice the input signal frequency for accurate representation. Signals sampled at a rate lower than this minimum (the Nyquist Rate) will show up as low-frequency signals due to insufficient sample points. Such a signal is called an alias. The phenomenon is called aliasing.

Alias frequency

A false lower-frequency component that appears in analog data that is reconstructed from original data digitized at an insufficiently high sampling rate.

Aliasing

An invalid low-frequency waveform (a false representation of a signal), or an aliased waveform, may be displayed by a digitising scope if a high frequency waveform is sampled at too low a sample rate. The waveform displayed on the oscilloscope may have a lower frequency than the actual input signal.

Aliasing is a condition that occurs when an oscilloscope digitizes at an effective sampling rate that is too slow to reproduce the input signal. A waveform is aliased when it is sampled at a frequency that is less than two times the highest frequency component of the waveform. For the best waveform fidelity, the sample rate should be at least four times the highest frequency component of the waveform.

Alternate Mode

A display mode of operation in which the oscilloscope completes tracing one channel before beginning to trace another channel.

Amplitude

1. The magnitude of a quantity or strength of a signal. In electronics, amplitude usually refers to either voltage or power.
2. Amplitude is the amplitude of the waveform.
3. Amplitude = Top - Base where Top is the most prevalent point above the waveform midpoint and Base is the most prevalent point below the waveform midpoint.

Analog-to-digital conversion

The process that changes an analog signal into a digital magnitude value.

AND

Logical designation or circuit function meaning that all inputs must be in the TRUE state for a TRUE output.

Annotations

Lines displayed on screen to indicate measurement reference levels and points that an automatic measurement is using to derive the measurement value.

Anti-alias filter

A filter that attenuates noise and high-frequency components of an analog signal prior to its conversion into a digital value.

Aperture Jitter

In a sample-and-hold or ADC, the jitter between the time of the sample (or convert) command pulse and the time the input signal is actually sampled. This jitter is usually due to thermal noise.

Aperture Uncertainty

In a sample-and-hold or ADC, the total uncertainty in the time of the sample (or convert) command pulse and the time the input signal is actually sampled, due to all causes including noise, signal amplitude-dependent delay variation (as in a flash ADC), temperature, etc. Often used interchangeably with "aperture jitter," but "aperture uncertainty" is the more inclusive term.

Area

Measurement of the waveform area taken over the entire waveform or the gated region. Expressed in volt-seconds. Area above ground is positive; area below ground is negative.

Attenuation

Attenuation is the difference in a signal's voltage, current, or power when it goes through a probe or other attenuation device. When using a standard 10:1 probe on a scope, the input waveform will be reduced, or attenuated, by a factor of 10 in voltage or 20 dB. Probe attenuation may be set in the CHANNELS menu.

Attenuation coefficient

The rate of optical power loss with respect to distance; measured in decibels per kilometer (dB/km) at a specific wavelength.

Auto

Auto (or Freerun) is a trigger mode in which the trigger circuit is armed, and the instrument then waits for up to 400 μ s for a trigger to occur. If a trigger does not occur within 400 μ s, the instrument triggers itself, and the data that is acquired with the trigger is displayed on the screen.

Automatic measurement

An automatic measurement of a parameter and its numeric readout that the instrument takes and updates directly from a channel, math, or reference waveform in real time, without operator intervention.

Autoprobe

Autoprobe is an interface that detects the some types of probe that are connected to a scope's input channels. Autoprobe automatically configures the vertical channel coupling and attenuation for the type of probe attached to the channel.

Autoscale

Autoscale (also Autoset) evaluates the input waveforms to a scope and adjusts the scope's controls to get a stable waveform display. Autoscale sets up front-panel controls based on the characteristics of the active waveform. In addition to turning on any channels that are sensed as active, trigger, horizontal, and vertical settings are adjusted automatically based on the input waveforms. A successful autoscale will set the volts/div, time/div, and trigger level to produce a coherent and stable waveform display.

Autostore

Autostore (see also [Infinite Persistence](#)^[45]) is a display mode in which acquired waveforms are displayed indefinitely.

Average (Acquisition mode)

In this mode, the oscilloscope acquires and displays a waveform that is the averaged result of several acquisitions. Averaging reduces the apparent noise. The oscilloscope acquires data as in the sample mode and then averages it according to a specified number of averages. You can use Averaging to eliminate random noise from a repetitive waveform.

Average Optical Power (AOP)

The time-averaged measurement of the optical power over a much longer time period than the bit rate of the signal.

Averaging

Mathematically smoothing the results of several measurements by adding them and dividing by the number of samples.

7.2 B

Balanced

A signal transmitted through a pair of wires, each having the same source impedance. Ground does not serve as a return path for the signal.

Balanced sampling gate

A type of sampling gate arranged so that strobe currents are balanced to minimise kick-out from the input connector of the sampler.

Bandwidth or BW

1. The bandwidth (BW) of the oscilloscope is the frequency range at which the channel-input circuits attenuate the waveform by 3 dB (70.7% of maximum). In modern specifications, bandwidth refers to the highest frequency signal the oscilloscope can acquire with no more than 3-dB (0.707) attenuation of the original (reference) signal. The PicoScope 9000 PC-Sampling Oscilloscope has a low-frequency response that extends to DC.
2. In normal use, the frequency range over which the gain of an amplifier or other circuit does not vary by more than 3 dB.
3. A range of frequencies over which a system works without degrading the original signal

Bandwidth (Full or Narrow)

When Narrow Bandwidth is enabled, the high-frequency noise of a waveform is reduced. When Narrow Bandwidth is enabled, it is easier to view on noisy waveforms.

Bandwidth Limit or BW Limit

The bandwidth limit is the instrument control that reduces the high frequency noise of a waveform by the use of a low-pass filter in the channel or trigger path of the instrument. Signals with high-frequency content may be distorted when the bandwidth is limited.

Base

Base is the statistically most prevalent voltage value below the waveform midpoint.

Base-line drift

Vertical movement of the entire trace under constant signal conditions and control settings.

BER

An acronym for Bit Error Ratio (or Rate). The principal measure of quality of a digital transmission system. BER is defined as:

$$BER = \text{Number of Errors} / \text{Total Number of Bits}$$

BER floor

A limiting of the bit-error-ratio in a digital system as a function of received power due to the presence of signal degradation mechanisms or noise.

Bin

Each frequency point represented in the frequency domain display of an FFT is called a bin.

Binning

A technique for combining points in a histogram to be compatible with the resolution of the display device.

Blind Time

In digital scopes, the blind time, or dead time, is the time from the end of one data acquisition to the beginning of the next acquisition. Better update rate in a scope means less dead time and less chance of missing a significant event.

Bit

One of the two numbers, 0 and 1, used to encode data. A bit is often represented by a high or low electrical voltage.

Bit error

An incorrect bit. Also known as a coding violation.

Bit Error Rate

Ratio of the number of bits of a message incorrectly received to the total number received.

Bitmap or .bmp

Bitmap, or .bmp, is a standard used for storing bit-mapped graphic files that can be imported into other Windows applications for documentation purposes.

Blind Time

See [Dead Time](#)^{44†}.

Blow-by

A display aberration caused by signal-induced current through the sampling-gate shunt capacitance. The nature of the aberration depends on the circuit time constants.

Bode plots

The amplitude and phase plots as a function of frequency are known as Bode plots. The logarithmic amplitude thus defined is measured in dB.

Brightness

The value associated with a pixel that represents a gray value between black and white.

7.3 C

CCD

Charge-Coupled Device. An integrated circuit that allows the transfer of a variable amount of charge through a series of cells; an analog shift register.

Channel

A path through an arrangement of components (modules and electrical or optical cabling or both) along which signals can be sent. Also an input used for signal acquisition. The PicoScope 9000 PC Sampling Oscilloscope has two input channels.

Channel Ground Reference Indicator

The indicator on the left side of the display that points to the position around which the waveform contracts or expands when vertical scale is changed. This position is ground when offset is set to 0 V; otherwise, it is ground plus offset.

Channel/probe deskew

A relative time delay for each channel. The ability to adjust deskew lets you align signals to compensate for the fact that signals may come in from cables of differing length.

Chop Mode

A display mode of operation in which small parts of each channel are traced so that more than one waveform can appear on the screen simultaneously.

Circuit Loading

The unintentional interaction of the probe and oscilloscope with the circuit being tested, distorting the signal.

Coherency

The optical power emitted from a laser diode after a specific current threshold is reached. Also known as Stimulated Emission.

Coherent display

A display where the time sequence of signal events is preserved. A coherent display may be produced by either random or sequential sampling.

Color-Grading (Waveform Persistence)

The color-graded persistence mode displays the sampled data points for an endless period of time. This persistence mode uses five color levels to represent the total number (density) of data counts acquired on a pixel (time and amplitude display coordinate) of the display graticule. Every time a display is acquired on a display coordinate, the counter for that coordinate is incremented. Each color used for the color grade mode represents a range of data counts. As the total count increases, the range of hits represented by each color also increases. If color grade is left on for a long time the waveform will become saturated with the color of highest hits.

You can use the color-graded persistence mode to display waveforms that use the instrument's measurement database. This database consists of all data samples displayed on the screen. The measurement database provides the data for the construction of histograms and the generation of mask tests.

Common Mode Range

The maximum range (usually voltage) within which differential inputs can operate without a loss of accuracy.

Common Mode Rejection Ratio

How well the common mode voltage is cancelled at different frequencies. 60 dB means that 1V of common mode voltage results in 1 mV at the oscilloscope input.

$$20 \times \log (1 \text{ V} / 1 \text{ mV}) = 60 \text{ dB}$$

Common Mode Signal (Noise)

The signal (usually noise) that appears equally and in phase on each of the differential signal conductors to ground.

Comparator

A circuit that compares two signals and changes a binary output when one signal exceeds the other.

Compensation

Compensation is an adjustment process that maximizes the bandwidth of a probe by precisely adjusting the capacitor in the probe such that the input capacitance of the scope is canceled. Probe compensation is typically accomplished by connecting the probe to a calibrator waveform built in the scope and performing a simple adjustment to the probe to make sure the displayed square wave is as square and flat-topped as possible.

Connect Dots

Connect dots is a display technique in which a straight line is drawn between two adjacent samples on the display (see [Vectors](#)^[47]).

Contrast Ratio

Contrast ratio is a measure of the RZ eye one level (at the eye window), to the one level found between eye diagram peaks.

Conversion time

The time required from the moment a channel is interrogated to the moment that accurate data is available. Usually associated with DACs and ADCs.

Convolution

The integration of the product of two functions in time. Convolution in the time domain is equivalent to multiplication in the frequency domain.

Correction

Correction is a TDR measurement technique that removes impedance discontinuities at the reference plane. Characteristic impedance measurements are more accurate after the discontinuities are removed. A waveform is derived in the correction process and represents the systematic errors of the input signal. This waveform is subtracted from the waveform of the device under test. The subtracted result is then put through a digital filter to yield the response waveform.

Countdown

The process of dividing an input frequency by n to produce a lower-frequency output. Countdown is usually used in sampling oscilloscopes to generate a lower-frequency trigger signal by responding to every n th signal transition. N is an integer divisor that may or may not be constant.

Counter

1. In software, a memory location used to store a count of certain occurrences.

2. In hardware, a circuit that counts events. See also event counter.

Coupling

The method of connecting two circuits together. Circuits connected with a wire are directly coupled; circuits connected through a capacitor or a transformer are indirectly (or AC, frequency filtering) coupled.

Crossing Percentage

Crossing percentage is a measure of the amplitude of eye diagram crossing points relative to the one level and zero levels.

Crossing Point

The point in time, in an NRZ eye diagram, where the rising edge of a waveform intersects with the falling edge.

Crosstalk

1. A phenomenon in which one or more signals interfere with another signal.

2. Unwanted coupling of a signal from one channel to another.

Cursors

Cursors are two sets of horizontal and vertical markers in the waveform display area used for making custom voltage and time measurements. See [Markers](#) ⁴⁵⁴.

7.4 D

DAC

Digital-to-analog converter.

Dark Calibration

Dark calibration (extinction ratio calibration) is a calibration that allows the instrument to identify internally generated offset (dark level) signals and remove them during the extinction ratio measurement calculations.

Data acquisition (DAQ)

Gathering information from sources such as sensors and transducers.

Data Dependent Jitter

Data-dependent jitter is pattern-related jitter caused by the combined effects of inter-symbol interference and duty cycle distortion.

DC (Direct Current)

A signal with a constant voltage and current.

DC Coupling

DC coupling passes both the AC and DC components of the waveform to the channel input or the trigger path. If a channel is DC-coupled, the DC component of the waveform can be quickly measured by noting the distance from the ground indicator.

DC Level Shift

A change in the nominal DC voltage level present in a circuit.

DC Offset

This term may imply that the shift is intentional, for example, adjustable by a control.

DC Overload

An overload signal of long duration compared to the normal input pulse width.

DC RMS

The DC RMS measurement is the typical method of making an rms (root-mean-square) voltage measurement.

Dead Time

In digital scopes, the dead time is the time from the end of one data acquisition to the rearm of the trigger circuitry for the next acquisition. Better update rate in a scope means less dead time and less chance of missing a significant event.

Decibel (dB)

A logarithmic measure of the ratio of two signal levels:

$$dB = 20 \log (\text{Voltage}_1 / \text{Voltage}_2) \text{ or } dB = 10 \log (\text{Power}_1 / \text{Power}_2)$$

Variants on the decibel (dB) used in spectrum-analysis and network-analysis measurements are:

dBmV	- absolute voltage level referred to 1 mV
dB μ V	- absolute voltage level referred to 1 μ V
dBm	- absolute power level referred to 1 mW
dBc	- level difference referred to a carrier level, c
dBc/Hz	- level difference referred to carrier level calculated for a measurement bandwidth of 1 Hz. (Spectrum and network analysis.)

Delay

Delay, or position, moves the waveform horizontally on the display. By adjusting the delay variable it is possible to view events that happen before (negative delay value) or after (positive delay value) the trigger point. Because the PicoScope 9000 is a sequential sampling oscilloscope, you can adjust the delay time only after (positive delay value) the trigger point.

Delay By Events Triggering

Delay by events triggering is a trigger mode in which the trigger circuitry arms on an edge from one of the channels, waits for a number of events on the selected channel, then triggers on an edge of the selected channel. Basically, the trigger criterion is two edge triggers separated by a selectable number of events.

Delay By Time Triggering

Delay by time triggering is a trigger mode in which the trigger circuitry arms on an edge of the selected channel, waits for a period of time, then triggers on an edge of the selected channel. Basically, the trigger criterion is two edge triggers separated by at least the selected period of time.

Delay measurement

A measurement of the time between the middle reference crossings of two different waveforms.

Delayed Sweep

Delayed sweep is a magnified portion of the main sweep. When delayed sweep is enabled, an expanded view of a selected portion of the waveform are displayed by the scope, allowing you to view and analyse the main sweep in more detail.

Delay measurement

A measurement of the time between the middle reference crossings of two different waveforms.

Delay time

The time between the trigger event and the acquisition of data. Also called Delta Time.

Delta (Δ)

Greek letter Δ (uppercase) used to represent a finite change in a variable.

Deterministic Jitter

Deterministic jitter is data-related jitter. It is the combined effects of the data-dependent jitter, periodic jitter and bounded uncorrelated jitter components that are present on a signal. Deterministic jitter is bounded, meaning that measured values do not increase with longer measurement times.

Differential Input

A circuit with two inputs that is sensitive to the algebraic difference between the two.

Differential Linearity

A term often inappropriately used to mean differential non-linearity.

Differential Output

A circuit with two outputs supplying one normal and one complementary level of output signal.

Differential Pulses

Two opposite-polarity pulses coincident in time.

Differential time domain reflectometry (TDR)

A technique for determining the impedance of coupled transmission lines in which complementary steps are applied to the two sides of the line to be tested, and the timing and the amplitude of the reflected signals are to be measured.

Differentiate (Signal Processing)

The capability of an oscilloscope to display a derivative math waveform. The derivative math waveform indicates the instantaneous rate of change of the waveform acquired. One use of derivative waveforms is the measurement of amplifier slew rate.

Digital Filtering

The manipulation of digital data to both enhance desirable and to remove undesirable aspects of the data.

Digital-to-analog conversion

The process that changes discrete values into a voltage or current.

Digitizing

The process of converting a continuous analog signal such as a waveform to a set of discrete numbers representing the amplitude of the signal at specific points in time. Digitising comprises two steps: sampling and quantization.

Display Update Rate

In digital scopes, the number of trigger events that the scope can capture and display is referred to as its update rate. Unlike an analog scope, digital scopes require time to move the sampled data to memory, display the acquired data, do any post-processing math (such as Amplitude or Frequency measurements), and re-arm the trigger circuitry for the next acquisition. Technology advances have greatly improved the update rate in digital scopes. Better update rate in a scope means less dead time and less chance of missing a significant event.

Display window

The time window represented within the horizontal limits of the graticule.

Dithering

Typically used when averaging signals (which have low noise content) to improve vertical resolution and decrease the effects of an ADC's non-linearities. The technique applies different offsets to each incoming waveform to ensure the signal is not always digitized by the same portion of the ADC. The offsets must be subtracted from the recorded signals before being included in the summed average.

Division

Measurement markings on the graticule of the oscilloscope.

Dragging

The act of changing your selection either by clicking (with the mouse) or touching (on a touchscreen) a point on the screen and pulling across the screen while holding down the button (mouse) or maintaining contact with your finger (touchscreen).

Duty Cycle

Duty cycle is the average duration that a waveform remains above the mid-amplitude point as a percentage of the waveform period.

Duty Cycle Distortion

Duty Cycle Distortion (DCD) is caused by a different duration of 1's and 0's. It is a measure of the time separation between the rising edge and falling edge at the 50% level of an NRZ eye diagram (middle threshold). The duty cycle distortion is then the difference in time between the intersecting edges. The duty cycle distortion can also be viewed as a percentage of the time difference relative to the full bit period or the time between adjacent crossing points.

Dynamic Range

1. Dynamic Range specifies the amplitude (size) of a signal that can be input into the scope at a particular vertical scale without overdriving the front end, resulting in an inaccurate acquisition of data.
2. The ratio of the largest to smallest signal that can be accurately processed by a module.

7.5 E

Earth Ground

A conductor that will dissipate large electrical currents into the Earth.

ECL

Emitter-coupled logic, an unsaturated logic performed by emitter-coupled transistors. Usually, ECL logic 1 = -1.6 V and logic 0 = -0.8 V.

Edge Triggering

Edge triggering is the traditional scope-triggering mode. A trigger event is defined as a transitioning edge of a specified polarity (slope) crossing a specified voltage threshold (level).

Effective Sample Rate

In the equivalent-time sampling mode, a waveform record is built up by sequential or random repetitive samples taken from multiple trigger events. This process allows samples in the waveform record to be spaced more closely together for repetitive waveforms. As a result, the waveforms appear to have been sampled at a much higher rate, sometimes referred to as an effective sample rate. The effective sample rate is calculated by the formula:

$$\text{Effective sample rate} = \text{Record length} / \text{Time length of the record}$$

This is the same as 1/(time between the sample points).

Electromagnetic compatibility (EMC)

The ability of electronic equipment to operate in an intended electromagnetic environment without degradation caused by interference; and to operate in its electromagnetic environment without creating interference with other equipment.

EMI

Electromagnetic interference caused by current or voltage induced into a signal conductor by an electromagnetic field.

Envelope

An acquisition mode in which the oscilloscope acquires and displays a waveform that shows the signal's highest and lowest points acquired over many acquisitions.

Equivalent Time

The time scale represented in the display of a sampling oscilloscope operating in the equivalent-time sampling mode.

Equivalent Time Sampling

A sampling mode in which the oscilloscope constructs a picture of a repetitive signal by capturing a little bit of information from each repetition. Thus, building the display takes longer than the time represented in the display.

In equivalent time sampling mode, a waveform record is built up by sequential or random repetitive samples taken from multiple trigger events. This process allows samples in the waveform record to be spaced more closely together for repetitive waveforms. As a result, the waveforms appear to have been sampled at a much higher rate, sometimes referred to as an effective sample rate.

In random equivalent-time sampling, an internal clock is used that runs asynchronously with respect to the input signal and the signal trigger. The oscilloscope takes samples continuously, independent of the trigger position, and displays them based on the time difference between the sample and the trigger. Although the samples are taken sequentially in time, they are random with respect to the trigger.

Error detection

Checking for errors in data transmission. A calculation is made on the data being sent and the results are sent along with it. The receiving station then performs the same calculation and compares its results with those sent. Each data signal conforms to specific rules of construction so that departures from this construction in the received signals can be detected. Any data detected as being in error is either deleted from the data delivered to the destination, with or without an indication that such deletion has taken place, or delivered to the destination together with an indication that it is in error.

Error rate

The ratio of the number of data units in error to the total number of data units.

Extinction Ratio

Extinction ratio is the ratio of the one level and the zero level of an eye diagram. This measurement is made in a section of the eye referred to as the eye window. Histograms are constructed using the sampled portions of the eye diagram within the eye window. One histogram is composed of data points from only the upper half of the eye diagram (one level). The second histogram is composed of data points from the lower half of the eye (zero level). The instrument analyses the histograms and determines the histogram means.

Extrema

The computation of a waveform envelope, by repeated comparison of successive waveforms, of all maximum points (roof) and all minimum points (floor). Whenever a given data point of the new waveform exceeds the corresponding maximum value in the roof record, it is used to replace the previous value. Whenever a given data point of the new waveform is smaller than the corresponding floor value, it is used to replace the previous value.

Eye Diagram or Pattern

Eye Diagrams are digital communication waveforms that consist of pseudo-random patterns of ones and zeros, which are best displayed as multivalued waveforms for analysis. Eye diagrams are multivalued waveforms because each point on the time axis has several voltage values associated with it. Single-valued waveforms, such as sine waves, square waves, and triangle waves, have a single voltage value associated with each point on the time axis. When analysing a digital communication waveform, single-valued displays are not very useful. By using infinite persistence feature, you can view eye diagrams.

Eye Height

Eye height is a measure of the vertical opening of an eye diagram.

Eye Opening Factor

Eye Opening Factor is a measure of the vertical opening of an RZ eye diagram. A noise contribution of 1 is subtracted from from the logic mean levels.

Eye Width

Eye width is a measure of the horizontal opening of an eye diagram.

Eye Window

The eye window provides the time boundaries within which signal parameters for eye diagrams are measured.

7.6 F

Fall Time

1. Fall time is the time interval on a falling edge of a waveform between an upper threshold (usually the 90% point) and a lower threshold (usually the 10% point).
2. Fall time is a measure of the mean one level to zero level transition time of the data of an eye diagram. The data crosses through the upper, middle, and lower thresholds, as well as through the NRZ eye crossing points.

False display

A sampling display that allows faulty or ambiguous interpretation usually caused by insufficient sample density or improper triggering (also known as [aliasing](#)^[434]).

Feedthrough

An unwanted signal that passes a closed gate or disabled input.

FFT (Fast Fourier Transform)

The Fast Fourier Transform is a mathematical algorithm that takes the sample points of a waveform in the time domain and computes the frequency components.

The FFT function enables the oscilloscope to transform a waveform from a display of its amplitude against time to one that plots the amplitudes of the various discrete frequencies the waveform contains. Some uses for the FFT capability are measuring harmonic content and distortion in systems, analysing vibration, testing the impulse response of filters, and identifying noise sources in digital logic circuits.

FFT Frequency Bins

A Fast Fourier Transform corresponds to analyzing the input signal with a bank of $n/2$ filters, all having the same shape and width, and centered at $n/2$ discrete frequencies. Each filter collects the signal energy that falls into the immediate neighborhood of its center frequency, and thus it can be said that there are $n/2$ "frequency bins". The distance Δf , in Hz, between the center frequencies of two neighboring bins is always $1/T$, where T is the duration of the time-domain record in seconds. The nominal width of bin is equal to Δf .

FFT Frequency Range

The range of frequencies computed and displayed in an FFT is 0 Hz to the Nyquist frequency.

FFT Frequency Resolution

In a narrow sense, the frequency resolution is equal to the bin width, Δf . That is, if the input signal changes its frequency by Δf , the corresponding spectrum peak will be displaced by Δf . For smaller changes of frequency, only the shape of the peak will change. However, the effective frequency resolution (i.e., the ability to resolve two signals whose frequencies are almost the same) is further limited by the use of window functions. The ENBW value of all windows other than the rectangular is greater than Δf (i.e., greater than the bin width).

FFT Number of Points

FFT is computed over the number of points (Transform Size) whose upper bound is the source number of points. FFT generates spectrums having $n/2$ output points.

FFT Phase

The time comparison in degrees or radians of a signal harmonic and the twiddle factor of the same frequency.

FFT Windows

The FFT window can be set to rectangular, Hamming, Nicolson, Hanning, flattop, or Blackman-Harris. A rectangular window is useful for transient signals. Use the Hanning window for frequency resolution and general-purpose use. Use the flattop window for making accurate amplitude measurements of frequency peaks.

Filter

An operation that selectively removes noise from a signal. Electronic filters include low-pass, band-pass, and high-pass types. Mathematical filters can operate on data to extract information and to enhance images.

Fine

Vernier, or fine control, allows a calibrated fine adjustment of a scaling factor such as the channel volts/div or the timebase time/div. For example, it is possible to set the V/div to 150 mV/div instead of the standard choices of 100, or 200 mV/div.

Freerun

Freerun is a trigger mode that will attempt to trigger the scope on the specified trigger conditions. If the trigger conditions are not met, a trigger will be forced, displaying the acquired data. This is a useful trigger mode to use if you are unsure about the exact trigger conditions, as it forces the scope to acquire and display a waveform, giving you a glimpse of the waveform. Caution should be used if the waveform is low-frequency as a free-running display may result even if the trigger conditions are valid. An alternative to the freerun trigger mode is the triggered, or normal, trigger mode, which requires that the trigger conditions be met before acquiring a waveform.

Frequency

The number of times a signal repeats in one second, measured in hertz (cycles per second). The frequency equals $1/\text{period}$.

Frequency Bins

The FFT algorithm takes a discrete source waveform, defined over N points, and computes N complex Fourier coefficients, which are interpreted as harmonic components of the input signal.

For a real source waveform (imaginary part equals 0), there are only $N/2$ independent harmonic components.

Frequency Domain

Signals displayed with frequency along the X-axis and magnitude along the Y-axis.

Frequency Range

The range of frequencies computed and displayed is 0 Hz (displayed at the left-hand edge of the screen) to the Nyquist frequency (at the rightmost edge of the trace).

Frequency Resolution

In a simple sense, the frequency resolution is equal to the bin width Δf . That is, if the input signal changes its frequency by Δf , the corresponding spectrum peak will be displaced by Δf . For smaller changes of frequency, only the shape of the peak will change. However, the effective frequency resolution (that is, the ability to resolve two signals whose frequencies are almost the same) is further limited by the use of window functions.

Frequency standard

A precise frequency generator such as a rubidium, cesium, or hydrogen maser whose output is used as a frequency.

Functions

Functions are mathematical operations (such as Add, Subtract, and Multiply) that can be performed on input waveforms, stored waveform memories, or even other functions. There are four functions, F1 to F4, which can be set up in the [Mathematics](#) menu. When the function is set up and turned on, a post-processing calculation is done and a new waveform is displayed.

7.7 G

Gated measurements

A feature that lets you limit automated measurements to a specified portion of the waveform. You define the area of interest using measurement gates.

GIF

GIF (Graphics Interchange Format) is a standard graphics format used to store bit-mapped graphic files that can be imported into other applications for documentation purposes.

Gigahertz (GHz)

1,000,000,000 hertz; a unit of frequency.

Glitch

A spike or short-time duration structural aberration on an otherwise smooth waveform that is normally characterized by more gradual amplitude changes. In digital electronics, where the circuit under test uses an internal clock, a glitch can be considered to be any pulse narrower than the clock width. Glitch is an intermittent error in a circuit.

Glitch

A spike or short-time duration structural aberration on an otherwise smooth waveform that is normally characterized by more gradual amplitude changes. In digital electronics, where the circuit under test uses an internal clock, a glitch can be considered to be any pulse narrower than the clock width.

GPIB (General Purpose Interface Bus)

GPIB (General Purpose Interface Bus), or IEEE 488 bus, is an interconnect bus and protocol that allows multiple test and measurement instruments to be linked together in a network under the control of a computer. GPIB transfers data and commands with eight parallel data lines and several control and handshake lines. Also called HP-IB.

Graphics Interchange format or .gif

Graphics interchange format or .gif is a standard graphics format used to store bit mapped graphic files that can be imported into other applications for documentation purposes. You can save the .gif file to the internal hard disk or an external memory device. It is a compressed, 256-color file format.

Graticule or Grid

The graticule, or grid, is the enclosed area where the waveform is displayed on a scope. Tick marks on the frame or axis of the graticule or horizontal and vertical lines within the graticule are a scaling aid for making visual measurements.

Gray Scale (Waveform Persistence)

The gray-scale waveform persistence mode displays the sampled data points for an endless period of time. This persistence mode uses one hue that varies in saturation and luminosity to represent the number (density) of data counts acquired on a pixel (time and amplitude display coordinate) of the display graticule. Every time a display is acquired on a display coordinate, the counter for that coordinate is incremented. Each level of saturation and luminosity used for the gray-scale mode represents a range of data counts. The peak density of data counts is represented by the by the brightest regions of the waveform. You can use the gray-scale persistence mode to display waveforms that use the instrument's measurement database. This database consists of all data samples displayed on the screen. The measurement database provides the data for the construction of histograms and the generation of mask tests.

Ground

1. A conducting connection by which an electric circuit or equipment is connected to the earth to establish and maintain a reference voltage level.
2. The voltage reference point in a circuit.

Ground Loop

A circuit with multiple low-impedance paths connected to the same ground potential. A ground loop acts as a shorted transformer turn, which induces circulating ground currents. These currents produce slight changes in the ground potentials within the circuit.

7.8 H

Harmonic distortion (HD)

A form of distortion in analog circuits that generates harmonics (signals whose frequencies are integer multiples of the input signal). It is calculated as the ratio of a single harmonic to the level of the original signal. Harmonic distortion is related to total harmonic distortion (THD), the ratio of the sum of multiple harmonics to the level of the original signal.

Hardcopy

The ability to save an oscilloscope display in an electronic format usable by a printer.

Hertz (Hz)

The unit of frequency. One hertz is equal to one cycle per second.

HF Reject

HF Reject removes the high-frequency portion of the triggering signal. Thus, only low-frequency components are passed on to the triggering system to start an acquisition. High-frequency rejection attenuates signals above tens of kHz.

HF Sync

Reduces the trigger rate by including a frequency divider in the trigger path, enabling the input trigger rate to exceed the maximum for repetitive signals.

High

The value used as the 100% level in amplitude measurements, such as Peak and Overshoot.

High-pass filter

A circuit that attenuates low-frequency components in an analog signal.

Histogram

A graphical statistical representation of data such that the data is divided into intervals or bins. The intervals or bins are then plotted on a bar chart where the height is proportional to the number of data points contained in each interval or bin. The distribution of acquired data is displayed within a user-definable window.

Holdoff by Events

Selects a minimum number of events between triggers. An event is generated when the trigger source meets its trigger conditions. A trigger is generated when the trigger condition is met after the selected number of events from the last trigger. The hold-off by events is initialized and started on each trigger.

Holdoff by Time

Holdoff time is the amount of time that the scope waits before rearming the trigger circuitry. By using different holdoff times, complex waveform triggering can be stabilised.

Horizontal Acquisition Window

A common time window or range that is applied to all channels in parallel to determine the segment of an incoming signal that becomes the waveform record. The trigger and horizontal controls determine the duration of this window and its placement in the incoming signal.

Horizontal bar cursors

The two horizontal bars that you position to measure the voltage parameters of a waveform. The oscilloscope displays the value of the cursors with respect to ground and the voltage value between the bars.

Horizontal Reference

1. The trigger point corresponds to the horizontal reference point when the horizontal position is set to zero. Reference represents the point from which the delay offset is calculated.
2. The point about which waveforms are expanded or contracted horizontally when horizontal scale adjustments are made. The horizontal reference point remains anchored as the rest of the waveform grows or shrinks around it.

Horizontal Scale

Horizontal scale is an instrument control that controls the X-axis or time per division of displayed waveforms. Referred to as sweep speed in some instruments

7.9

I

IEEE-488.2 (See [GPIB⁴⁴⁸](#))

Impulse

An electromagnetic pulse of short duration--shorter than one cycle at the highest frequency being considered.

Infinite Persistence

Infinite persistence is a display mode in which acquired waveforms are displayed indefinitely. In the usual display modes, waveforms are overwritten with each acquisition, but when infinite persistence is selected, old waveforms are not erased and sample points accumulate on the display like a storage scope. You can use infinite persistence to measure worst-case timing jitter on a waveform. Other applications include display of eye diagrams (telecommunications) or detection of metastable states in logic designs.

Initialization

A process of setting the instrument to a completely known, default condition.

Integral Linearity

A term often used inappropriately to mean integral non-linearity.

Integral Non-Linearity

Deviation of ADC response from an appropriate straight-line fit. The specification is sometimes defined as maximum deviation, expressed as a fraction of full scale. More recent ADCs have a specification expressed as a percent of reading plus a constant.

Integrate

The capability of an oscilloscope to display an integral math waveform. The integral math waveform is computed from the acquired waveform. One use of integral waveforms is for measuring power and energy.

Interleaved Clocking

Supplying clock pulses of equal frequency to parallel circuits or instruments in order to increase the system sample rate. An example is the use of two transient recorders with inputs in parallel but complementary clocks to allow operation at twice the maximum rate of a single unit.

Internal clock

A trigger source that is synchronized to the internal clock, with a selectable repetition rate. It is most often used with TDR to synchronize the generation of TDR step pulses with subsequent acquisition.

Interpolation (Signal Processing)

Generally speaking, a "connect-the-dots" processing technique to estimate what a fast waveform looks like based on only a few sampled points. More specifically, Interpolation refers to the way the oscilloscope calculates values for record points when the oscilloscope cannot acquire all the points for a complete record with a single trigger event. That condition occurs when the oscilloscope is limited to real-time sampling and the timebase is set to a value that exceeds the effective sample rate of the oscilloscope. The oscilloscope can have two interpolation options: linear or $\sin(x)/x$ interpolation.

Linear interpolation calculates record points in a straight-line fit between the actual values acquired. $\sin(x)/x$ computes record points in a curve fit between the actual values acquired. It assumes all the interpolated points fall in their appropriate point in time on that curve.

Integrate

The capability of an oscilloscope to display an integral math waveform. The integral math waveform is computed from the acquired waveform.

Interval Trigger

Selects an interval between two edges of the same slope. The trigger can be generated on the second edge if it occurs within the selected interval or after the selected interval. The timing for the interval is initialized and restarted whenever the selected edge occurs.

7.10 J

Jitter

Jitter is any frequency- or phase-related spurious variation of a waveform from its ideal. It consists of short-term fluctuations in the output of a circuit or instrument that are independent of the input. It appears on a waveform edge before or after the trigger point as a wide, smeared edge.

1. Jitter is the measure of the time variances of the rising and falling edges of an eye diagram as these edges affect the crossing points of the eye.
2. Jitter is a measure of the time variances of the rising or falling edges of a pulse waveform at the middle threshold.

JPEG or .jpg

The JPEG file format, or .jpg, is a graphics file format that can be imported into other applications for documentation purposes. It can be greatly compressed, but because this compression is lossy, it can result in reduced image quality. This format is a good choice where file size is a more important factor than image quality.

7.11 K

Kick-out

A signal, usually unwanted, that comes from the internal circuitry and exits through an input connector.

Kilohertz (kHz)

1000 hertz; a unit of frequency.

7.12 L

Leakage

In the power spectrum of a sine wave with an integral number of periods in the (rectangular) time window (that is, where the source frequency equals one of the bin frequencies), the spectrum contains a sharp component whose value accurately reflects the source waveform's amplitude. For intermediate input frequencies this spectral component has a lower and broader peak.

The broadening of the base of the peak, stretching out into many neighboring bins, is termed *leakage*. It is due to the relatively high side lobes of the filter associated with each frequency bin.

The filter side lobes and the resulting leakage are reduced when one of the available window functions is applied. The best reduction is provided by the Blackman–Harris and Flattop windows. However, this reduction is offset by a broadening of the main lobe of the filter.

LF

Low Frequency.

LF Rejection

LF Rejection removes the low-frequency portion of the signal. Thus, only high-frequency components are passed on to the channel or triggering system for acquisition. Low-frequency rejection attenuates signals below the tens of kHz.

Limit Test

Comparison of an input signal or math waveform to a template waveform. When performing a limit test, the oscilloscope looks for waveforms that fall outside the limits defined by the template waveform. The oscilloscope can be programmed to generate a hardcopy, beep, or stop and wait for input from an operator when it finds a waveform that exceeds the template limits.

Linear Interpolation

Linear interpolation is another term for 'join the dots'. A straight line is drawn between two adjacent data points.

Linearity

The closeness of a device's response to a straight line.

Lissajous figure

A special case of an X-Y plot in which the waveforms applied to both axes are sinusoidal functions. For a stable display the waveforms must be related harmonics. Lissajous figures are useful for determining phase and harmonic relationships.

The X-Y plot can be selected in the [DISPLAY](#) ^[55] menu.

Live Waveforms

Waveforms that can update as the acquisition system acquires data. Channel waveforms are live waveforms; reference waveforms are not. Math waveforms are live if they contain live waveforms.

Logical 1

A signal level indicating the TRUE state; corresponds to the unit being set (i.e., if interrogated, the answer is yes).

Logical 0

A signal level indicating the FALSE state; corresponds to the unit NOT being set (i.e., if interrogated, the answer is no).

Logic Triggering

Logic triggering allows you to qualify the trigger event further than the standard edge trigger mode.

Long-Term Stability

Stability over a long time, such as several days or months.

Loop gain

The product of sampling efficiency, forward gain, and feedback attenuation in a sampling loop. Loop gain in a calibrated system is normally unity (1), but can go to values more or less than unity.

Low

The value used as the 0% level in amplitude measurements, such as Peak and Overshoot.

Low-pass filter

A circuit that attenuates the high-frequency components in an analog signal.

Luminance

The brightness or intensity of a color.

Luminosity

The relative brightness of a color. A 100% luminosity is the maximum color brightness. A 0% luminosity is pure black.

7.13 M

Main Sweep

When main sweep is enabled, all input channels will be displayed along a single common timebase. If delayed sweep is enabled, then the display shows an expanded view of a selected portion of the main sweep.

Margin Measurements

A feature that lets you limit automated measurements to a specified portion of the waveform. You define the area of interest using the vertical cursors.

Markers

On-screen markers that you can align with a waveform to take accurate measurements. Markers are two sets of horizontal, vertical, or waveform markers in the waveform display area used for making custom voltage and time measurements. Markers, or Cursors, can be placed anywhere on the displayed waveform and the scope will display the numerical position of the markers and the difference between the markers with units in volts and time for the time-domain display or dB and Hz for FFT functions.

Mask

A form of waveshape limit test that defines a maximum deviation equal to a uniform tolerance on each measured point in a waveform. A mask template consists of numbered, shaded regions on the instrument display screen. The input waveform must remain within these regions in order to comply with industry standards. The waveforms that intrude into these regions are mask violations.

Mask Test

A test process used to verify that waveforms generated by a test device conform to industry standards.

Mathematics

The mathematics functions are mathematical operations (such as Add, Subtract, Multiply, and Integrate) that can be performed on input waveforms, stored waveform memories, or even other functions. There are four functions, F1 to F4, which can be set up in the [MATHEMATICS](#) ^[239] menu. When the function is set up and turned on, a post-processing calculation is done and the resulting waveform is displayed.

Math Waveform

A waveform defined by a combination of one or more operands (channel waveforms, reference waveforms, and automatic measurement scalars). Math waveforms may also contain math operators and functions.

Maximum

Amplitude (voltage) measurement of the maximum amplitude. Typically the most positive peak voltage.

Maximum Input Voltage

The maximum voltage that can be applied to an input channel without damaging the input circuitry.

Mean

Amplitude (voltage) measurement of the arithmetic mean over the entire waveform.

Measurement statistics

The accumulation of a history of individual measurement readouts, showing the mean and standard deviation of a selected number of samples.

Measurement updating

The process of automatically adjusting the measurement parameters to reflect changes in the waveform targeted by an automatic measurement.

Median

The data value of a waveform above and below which there are equal numbers of data points.

Megahertz (MHz)

1,000,000 hertz; a unit of frequency.

Megasamples per second (MS/s)

A sampling rate unit equal to one million samples per second.

Memory

Four Memories in an oscilloscope used to store waveforms or settings. You can use that waveform data later for processing. The oscilloscope saves the data even when the oscilloscope is turned off or unplugged.

Memory Depth

The number of waveform samples stored in the waveform memory. The greater the memory depth, the greater the amount of sampled data that is available for analysis or measurements. This is referred to as Record Length by some oscilloscope manufacturers.

Microsecond

A unit of time equivalent to 0.000 001 seconds.

Millisecond (ms)

A unit of time equivalent to 0.001 seconds.

Minimum

Amplitude (voltage) measurement of the minimum amplitude. Typically the most negative peak voltage.

Monochrome

An image represented by a single color. Often, a monochrome image is presented as white on a black background.

Monotonic

A function with a derivative that does not change sign.

Multiple-Valued Waveform

A method of representing a signal in which every horizontal acquisition point can have associated with it multiple amplitude values. An eye diagram is an example of a multiple-valued waveform. In contrast, a single-valued waveform is displayed by measuring and displaying one and only one amplitude value for each horizontal acquisition point.

Multiplexer (MUX)

A set of semiconductor or electromechanical switches arranged to direct one of many inputs to a single output.

7.14 N

NAND

An AND circuit, except with a complementary (negative true) output.

Nanosecond (ns)

A unit of time equivalent to 0.000 000 001 seconds.

Negative duty cycle

A timing measurement representing the ratio of the negative pulse width to the signal period expressed as a percentage.

Negative overshoot measurement

Amplitude (voltage) measurement.

Negative width

A timing measurement of the distance (time) between two amplitude points (the falling-edge middle reference point (default 50%) and the rising-edge middle reference point (default 50%) on a negative pulse.

Noise

An unwanted voltage or current in an electrical circuit.

Noise distortion

The nonlinear behavior that circuits or devices exhibit when driven with a broadband noise signal.

Noise floor

1. The level below which no information can be obtained from a signal. A signal that occurs below a noise floor is permanently lost.
2. The minimum discernible signal that can be detected by a receiver.

Noise Reject

Noise Reject is a trigger conditioning setting that makes the trigger circuitry less sensitive to noise. You can use noise reject when triggering on noisy waveforms minimize the possibility of false triggering. Basically, noise reject increases the trigger hysteresis band so that noise on a waveform will not generate a trigger.

NOR

An OR circuit, except with a complementary (negative true) output.

Normal Trigger Mode

A mode in which the oscilloscope does not acquire a waveform record unless a valid trigger event occurs. It waits for a valid trigger event before acquiring waveform data. Normal trigger mode, or triggered, requires that the trigger conditions be met before the acquisition process terminates. If the trigger conditions are not met, new input data cannot be displayed. The normal or triggered mode is the desired mode of triggering when you know the trigger conditions and want a stable trigger. An alternative to the normal or triggered mode is the auto trigger mode, which will force a trigger after a period of time if trigger conditions are not met.

NRZ

(Non-return to zero) A type of signal coding that ensures that, in any one bit period, the signal is turned on for the entire duration of a logical one pulse and turned off (or nearly off) for the entire duration of a logical zero pulse.

Number of Points

The FFT is computed over the number of points (Transform Size) whose upper bounds are the source number of points, and by the maximum number of points selected in the menu. The FFT generates spectrums of $N/2$ output points.

Nyquist Frequency

The Nyquist frequency is equal to one half of the effective sampling frequency (after decimation): $f \times N/2$.

Nyquist point

The minimum sampling frequency as defined by the Nyquist Sampling Theorem, which requires that a signal be sampled at a minimum rate equal to twice the input signal frequency for faithful reproduction. Sampling below this frequency will lead to aliasing.

7.15 O

Offset

Offset moves the waveform vertically up or down on the Y-axis of the display. It is similar to the vertical position control on analog scopes. Offset is precisely calibrated on a digital scope. The offset voltage is the voltage at the center of the graticule area.

Offset null

An adjustment to remove any unwanted DC offset that may be present in the sampler. Effectively zeroes the sampler so that an input signal with zero volts of amplitude delivers a zero volt output.

OMA (Optical Modulation Amplitude)

The difference between the average power levels of the logic 1 level, High, and the logic 0 level, Low, of the optical pulse signal. The levels are the Means of the logical levels sampled within an Aperture of the logical 1 and 0 regions of the pulse. The logical 1 and 0 time intervals are marked by the crossings of a reference level determined as the Average Optical Power (AOP) of the signal.

One Level

One Level is a measure of the mean value of the logical 1 of an eye diagram.

OR

A logic circuit having the property that if at least one input is true, the output is true.

Oscilloscope

An instrument used to make voltage changes visible over time. The word oscilloscope comes from "oscillate," since oscilloscopes are often used to measure oscillating voltages.

Overshoot

Overshoot is a distortion that follows a waveform edge transition. This distortion occurs after the edge crosses through the waveform threshold levels,, and can occur on either the rising or falling edge.

Overshoot, Negative

A time-domain parameter in waveform measurements, equal to the base value of a waveform minus the minimum sample value, expressed as a percentage of the amplitude.

Overshoot, Positive

A time-domain parameter in waveform measurements, equal to the maximum sample value minus the top value, expressed as a percentage of the amplitude. The top value is the most probable state determined from a statistical distribution of data point values in the waveform.

7.16 P

Pass/Fail Testing

Post-acquisition testing of a waveform against a reference mask or of waveform parameters against reference values.

Pattern Dependency

Pattern dependency is the behavior of a waveform as it is influenced by the preceding data pattern. For example, a logic level one that follows a logic level zero may have a different amplitude than a logic level one that follows a previously generated logic level one.

Pattern Triggering

Pattern triggering qualifies the trigger event by having the scope search for a pattern using the selected channel inputs. You can define the pattern as a combination of highs, lows, or don't care levels. Input channel voltages above the selected voltage level are highs while voltages below the selected voltage level are lows.

Peak-to-Peak

Amplitude (voltage) measurement of the absolute difference between the maximum and minimum amplitude.

Peak Detect

Peak detect is an acquisition mode that runs the sampler at a very high equivalent rate, even though the timebase setting would dictate a slower sampling rate. The oversampled data is processed so that a maximum and minimum pair is stored for each time bucket for display. Using this mode will ensure that very fast extremes of a waveform, such as glitches, will be captured and displayed.

Period

1. The amount of time it takes a wave to complete one cycle. Period equals 1/frequency.

2. A full period is the time measured between the first and third 50% crossing points (medial points) of a cyclic waveform.

Periodic Jitter

Periodic Jitter is one component of Deterministic Jitter. Periodic Jitter is predictable and not data-related and often has Sinusoidal Jitter (SJ) as a component.

Persistence

Persistence is a display mode in which old waveform data is left on the display for a specified period of time. You can select persistence settings of variable, or infinite. There are different persistence modes available in the instrument: Variable, Infinite, Gray-Scaled and Color-Graded.

Phase

A timing measurement between two waveforms of the amount one leads or lags the other in time. Phase is expressed in degrees, where 360° comprise one complete cycle of one of the waveforms. Waveforms measured should be of the same frequency or one waveform should be a harmonic of the other.

Pixel

1. The fundamental picture element in a digital image.
2. The coordinate unit used to define the horizontal location of a pixel in an image. ("Pixel" is an acronym for "picture element.")

Pigtail

A fiber-optic cable that has a connector installed on one end.

Pop-up menu

A menu that displays when you right click an application element, such as a channel or its icon, a measurement or other readout. Usually provides quick access to settings related to the object clicked.

Position

Position moves the waveform horizontally on the display. Real-time digitizing scopes allow you to view events that happened before the trigger event. A negative position value is time before the trigger event, and a positive position value is time after the trigger event. Some scopes refer to position as delay.

In some scopes, position also refers to a control that moves the waveform vertically on the Y-axis of the display. In this series of scopes, however, vertical movement is controlled by the offset in the [Channel](#) ^[45] menu.

Positive Duty Cycle

A timing measurement of the ratio of the positive pulse width to the signal period, expressed as a percentage.

Positive Overshoot

Amplitude (voltage) measurement.

Positive Width

A timing measurement of the distance (time) between two amplitude points? the rising-edge middle reference point (default 50%) and the falling-edge middle reference point (default 50%)? on a positive pulse.

Posttrigger

The specified portion of the waveform record that contains data acquired after the trigger event.

PRBS (Pseudo Random Binary Sequence)

A repetitive digital signal pattern that is close enough to a random signal for testing purposes.

Preshoot

Preshoot is a distortion that precedes a waveform edge transition. This distortion occurs after the edge crosses through the waveform threshold levels, and can occur on either the rising or falling edge.

Pretrigger

The specified portion of the waveform record that contains data acquired before the trigger event.

Pre-trigger Sampling

A design concept used in transient recording in which a predetermined number of samples taken before a stop trigger are preserved.

Probe

An oscilloscope input device, usually having a pointed metal tip for making electrical contact with a circuit element and a flexible cable for transmitting the signal to the oscilloscope.

Probe compensation

Adjustment that improves low-frequency response of a probe.

Pulse

A common waveform shape that has a fast rising edge, a width, and a fast falling edge.

Pulse Trigger

Selects a pulse width, either maximum or minimum. The trigger is generated on the selected edge when the pulse width is either greater than or less than the selected width. The timing for the width is initialized and restarted on the edge opposite to the edge selected.

Pulse Width

Determines the duration between the Pulse Start (the 50% magnitude transition point, on the leading edge) and the Pulse Stop (medial point on the trailing edge) of a pulse waveform.

7.17 Q

Q-factor

Q-factor is a figure of merit for an eye diagram indicating the vertical eye opening relative to the noise at both the high and low logic levels.

Quantizing

The process of converting an analog input that has been sampled, such as a voltage, to a digital value.

Quantizing error

The inherent uncertainty in digitizing an analog value that is caused by the finite resolution of the conversion process. Increasing the resolution of an ADC reduces the uncertainty.

7.18 R

RAM

A memory in which each data address can either be written into or read from at any time.

Random Jitter

Random Jitter is jitter that is unpredictable and not data-related. Random jitter is unbounded, meaning that measured values increase with longer measurement times.

Random Repetitive Sampling

One method of Equivalent Time Sampling. Acting upon stable, repetitive signals, it represents the process of storing different full sampling sweeps in a DSO or digitizer system, where each sweep is slightly offset from the other to achieve a higher effective sampling rate than the single-shot rate. A major advantage of this technique is "pretrigger viewing".

Range

The maximum and minimum allowable full-scale signal (input or output) that yields a specified performance level.

Real Time Sampling

A sampling mode in which the oscilloscope collects as many samples as it can as the signal occurs. In real-time sampling mode, all the data points that make up a waveform come from a single trigger event unless you have enabled averaging. The real-time sampling mode is typically used on events that occur either once or infrequently - to capture single-shot or transient events.

Recall Setup or Load Setup

Recall Setup is a quick and easy way to reconfigure the scope to a previous configuration. The scope's configuration, or setup, includes timebase scale (s/div), position, vertical scale (V/div), offset, trigger source and level, as well as all the other settings.

Reconstruction

Reconstruction, sometimes called interpolation, fills in information between acquired sample points using digital signal processing techniques. 'Join the dots' involves a simple linear interpolation, while reconstruction usually refers to more advanced techniques such as sin x filters that will increase the resolution, accuracy and repeatability of time-interval measurements.

Record Length

Record length is the number of waveform samples stored in the waveform memory. The greater the memory depth, the greater the amount of sampled data that is available for analysis or measurements. Increasing the memory depth decreases the display update rate. This is called Memory Depth in this scope.

Recovered Clock

The process of extracting a clock signal from electrical digital communications signals. The resulting trigger signal is made available to the instrument. The recovered clock has a lower jitter modulation bandwidth than trigger from data signal.

Reference memory

Memory in an instrument used to store waveforms or settings. You can use that waveform data later for processing. The instrument saves the data even when the instrument is turned off or unplugged.

Reference waveforms

Waveforms that are static, not live (see live waveforms). Reference waveforms are channel or math waveforms that you save to references or to files in the instrument's file system. Once saved, they do not update.

Reflection Coefficient (Rho)

In time-domain reflectometry, the ratio of peak amplitude of a reflection to the incident step amplitude. The observed reflection coefficient may depend upon system rise time, losses in the transmission medium, and the nature of the discontinuity that produced the reflection.

Repetitive Sampling

Repetitive sampling is another term that is used to refer to equivalent time sampling. In the repetitive or equivalent-time sampling mode, a waveform record is built up by taken from multiple trigger events. This process allows samples in the waveform record to be spaced more closely together for repetitive waveforms. As a result, the waveforms appear to have been sampled at a much higher rate, sometimes referred to as the effective sampling rate.

The equivalent time sampling mode increases the effective bandwidth of the scope for repetitive waveforms that have a stable trigger. It can also be used with multi-valued waveforms such as eye diagrams.

Resolution

The minimum measurable increment, such as one bit level of an ADC. Time resolution is determined by the sampler bandwidth and ADC sampling rate, which on a DSO is plus or minus one sampling interval.

Responsivity

The ratio of an optical detector's electrical output to its optical input, often as a function of optical wavelength.

Rise Time

1. Rise time is a measure of the transition time of a waveform as the rising edge passes through the lower (usually the 10% point), middle (usually the 50% point), and upper threshold (usually the 90% point) or logic levels.
2. Rise time is a measure of the mean transition time of the data on the upward slope of an eye diagram. The data crosses through the following thresholds: the lower, middle, and upper thresholds, as well as through the crossing points of NRZ eyes.

RMS

RMS is the root-mean-square (rms) of the voltage values of a waveform. The RMS value of an AC voltage equals the DC voltage that would cause the same heating in a resistive load.

Roll or Scan Mode

Roll or scan mode is a display mode available on some scopes that emulates a strip chart recorder, showing a continuously drawn waveform at slow sweep speeds. Waveforms can be displayed at slow sweeps but will be displayed only when the acquisition period has a full record, not point by point. The trigger activity light on the front panel will assist in showing the acquisition process.

ROM

Read-only memory is any type of memory that cannot be readily rewritten. The information is stored permanently and used repeatedly. Usually randomly accessible.

Runt Pulse

A runt pulse is a pulse in a waveform that is lower in amplitude than the other pulses in the waveform.

RZ

(Return to zero) A type of signal coding that ensures, in any one bit period, that the signal is turned on for the first half of a logical one pulse and turned off (or nearly off) for the second half of the logical one pulse. As with NRZ coding, the signal is turned off (or nearly off) for the entire duration of a logical zero pulse.

7.19 S

Sample

The oscilloscope creates a record point by saving the first sample during each acquisition interval. Sample mode is the default acquisition mode.

Sample and hold (S/H)

A circuit that acquires an analog voltage and stores it temporarily in a capacitor. This circuit is also referred to as a sample-and-hold amplifier (SHA).

Sample interval

The time interval between successive samples in a timebase. For real-time digitizers, the sample interval is the reciprocal of the sampling rate. For equivalent-time digitizers, the time interval between successive samples represents equivalent time, not real time.

Sample Point

An item of raw data from an ADC used to calculate a waveform point.

Sampling Rate

Sampling rate is the rate at which the acquisition system samples a waveform. In real-time mode, all samples in a given waveform record are taken from one trigger event and are evenly spaced in time at a distance of $1/(\text{sample rate})$. In equivalent-time mode, a waveform record is built up from multiple trigger events. This process allows samples in the waveform record to be spaced more closely together for repetitive waveforms. As a result, the waveforms appear to have been sampled at a much higher rate, sometimes referred to as an effective sample rate.

Sampling

The process of capturing an analog input, such as a voltage, at a discrete point in time and holding it constant so that it can be quantized for further processing or display. Two general methods of sampling are: real-time sampling and equivalent-time sampling.

Sampling efficiency

The percentage of signal voltage transferred across the sampling gate when the gates conduct.

Sampling Frequency

The clock rate at which samples are taken during the process of digitizing an analog signal in a DSO or digitizer.

Sampling gate

An electronic switch that briefly conducts a command to collect and store the instantaneous value of a signal (sometimes called sampling bridge).

Sampling loop

The circuits that provide the main signal path through the input sampling gate, amplifiers, forward gain attenuator, memory gate, memory, feedback attenuator, and back to the sampling gate (also called feedback loop).

Sampling Oscilloscope

An oscilloscope using sampling along with the means for building a coherent display of the samples taken.

Saturation

The saturation of a color is the purity of the color or the absence of white. A 100% saturated color has no white component. A 0% saturated color is pure white.

Save Setup

The scope's configuration, or setup, includes the timebase scale (s/div), position, vertical scale (V/div), offset, trigger source and level, as well as all the other settings.

Using setups makes it quick and easy to reconfigure the scope to a previous configuration.

Scale (Vertical or Horizontal)

Vertical scale is an instrument control that controls the Y-axis or volts (or other unit) per division for the selected channel. This control allows you to adjust the sensitivity of the instrument. Horizontal scale is an instrument control that controls the X-axis or time per division of displayed waveforms. Horizontal scale is referred to as sweep speed in some instruments.

Scan Mode

See [Roll or Scan mode](#)⁴⁶³

Screen

The surface of the CRT or LCD upon which the visible pattern is produced - the display area.

Screen Update Rate

The number of times per second that the screen information is renewed. The quicker the rate, the better the feel of the DSO controls.

Sequential sampling

A sampling process where samples are taken at successively later times relative to the trigger recognition point.

Sensitivity

1. The minimum signal input capable of causing an output signal with the desired characteristics.
2. The ratio of the magnitude of the instrument response to the input magnitude (e.g., a voltage ADC has a sensitivity that is usually measured in counts/mV). Often, sensitivity is referred to the input and is therefore stated as the inverse.

Sequential equivalent-time sampling

A type of equivalent-time sampling in which one sample is taken per acquisition, with each sample skewed incrementally with respect to an external trigger event. This instrument acquires using sequential equivalent time sampling.

Settling Time

Settling time is the time it takes for a waveform to settle to within some user defined \pm percentage of its steady state value following a rising or falling edge.

Shot Noise

Noise caused by current fluctuations, due to the discrete nature of charge carriers and random emission of charged particles from an emitter. Many refer to shot noise loosely, when speaking of the mean square shot noise current (amperes) rather than a noise power (watts).

Signal Generator

A test device for injecting a signal into a circuit input; the circuit's output is then read by an oscilloscope.

Signal Processing

With respect to oscilloscopes, this refers to functions that are performed by signal processing hardware or software. For example, signal measurements (rise time, overshoot, period, etc.), FFTs, Integration and Differentiation functions are signal processing functions.

Sine Wave

A common curved wave shape that is mathematically defined (by the value of the sin function).

Single Shot

A signal measured by an oscilloscope that only occurs once (also called a transient event).

Signal-to-Noise ratio (SNR)

Signal-to-noise is a ratio of the signal difference between one level and zero level relative to the noise present at both levels. The ratio of total signal to noise expressed in decibels (dB). The larger the number, the better. SNR is calculated by:

$$SNR = 20 \log (Signal_{RMS} / Noise_{RMS})$$

A related unit is the signal-to-noise-and-distortion ratio (SINAD), the ratio of the input signal to the sum of noise and harmonics:

$$SINAD = 20 \log (Signal_{RMS} / (Noise + Harmonics)_{RMS})$$

Significant Instant

A significant instant is any convenient, easily identifiable point on a signal (for example, a point on either the rising or falling edge of a pulse).

Simultaneous sample and hold

A data-acquisition technique in which several sample-and-hold circuits sample several different analog channels simultaneously.

Sine Wave

A common curved wave shape that is mathematically defined (by the value of the sin function).

Single

In single trigger mode, the scope triggers once when the trigger conditions are met. Once the acquisition process is complete, the scope will display the acquired waveform and stop the acquisition process.

Single Shot

A signal, measured by an oscilloscope, that only occurs once (also called a transient event).

Single-Valued Waveform

A method of representing a signal in which every horizontal acquisition point has associated with it one and only one amplitude value. In contrast, an eye diagram is displayed by measuring and displaying multiple amplitude values for each horizontal acquisition point.

Skew

Skew changes the horizontal position of a waveform on the display independent of any other waveforms on the display. Skew is typically used for overlaying waveforms, or eliminating timing differences caused by different cable and probe lengths. The timebase position control moves all of the waveforms on the display at the same time, whereas skew moves individual waveforms.

Slewing

The causing of successive samples to be taken at different times than the trigger recognition point.

Slope

On a graph or an oscilloscope screen, the ratio of a vertical distance to a horizontal distance. A positive slope increases from left to right, while a negative slope decreases from left to right.

Smoothing

A process that reduces displayed noise by reducing the gain of the sampling loop. By oversampling the input signal, the sampling loop can maintain an apparent unity gain while reducing noise.

SNR

Signal-to-Noise Ratio (SNR) is the ratio of the magnitude of the signal to that of the noise.

Source

The source (input channel, math function, waveform memory, spectrum, or constant) used when performing tasks such as measurements, math, or mask tests.

Square

The process of multiplying a value by itself.

Square Wave

A common wave shape consisting of repeating square pulses.

Standard Deviation

Standard deviation is the measure of the dispersion or spread of the statistical average of all results for a particular measurement. Standard deviation is represented by the Greek letter sigma (σ). In a Gaussian distribution, two sigma, or within ± 1 of the mean, is where 68.3 percent of the data points reside. Six sigma, or within ± 3 of the mean, is where 99.7 percent of the data points reside.

State Triggering

State triggering is an edge-qualified pattern trigger. A trigger event occurs if a specified pattern is present when an edge occurs on the designated clock waveform.

State Qualified

State-Qualified triggering generates a trigger when the trigger source meets its conditions during the selected pattern. A pattern is defined as a logical AND combination of trigger states. A trigger state is either high or low; high when a trigger source is greater than the trigger level, and low if it is less than the trigger level.

Stimulated Emission

The optical power emitted from a laser diode after a specific current threshold is reached. Also known as Coherency.

Stop/Single

In the Stop/Single mode, the scope triggers once when the trigger conditions are met. Once the acquisition process is complete, the scope will display the acquired waveform and stop the acquisition process. You can begin another acquisition by pressing the front-panel Run button.

Stop Trigger

A pulse that is used to stop a transient recording or similar sequence.

Strobe

A short duration pulse that operates the sampling gate.

Strobe kick-out

A fraction of the strobe signal coming out of the input connector.

Summed, or Summation, Averaging

The repeated addition, with equal weight, of successive waveforms divided by the total number of waveforms acquired.

Sweep

One horizontal pass of an oscilloscope's trace from left to right across the screen.

Sweep Cycle Time

The time required for making a complete sweep and preparing for the next sweep. It can be measured as the time from the start of one sweep to the start of the next sweep.

Sweep Speed

The rate at which the sweep moves across the display. The sweep speed is expressed in units of time per division, for example, 1 ns/div.

7.20 T

Test Template

A general form of waveshape limit test, which defines an arbitrary limit (or non-uniform tolerance) on each measured point in a waveform.

Text Verbose

An ASCII text file format that uses alphanumeric characters to represent the voltage values of a waveform. This format includes header information about the waveform and when it was acquired. The text file formats are a convenient method for transferring waveforms to other computer applications.

Threshold

The voltage or current level at which a circuit will respond to a signal at its input. Also referred to as trigger level.

Throughput

Throughput is the rate at which the scope can acquire, display, and make measurements on a waveform. The faster the throughput of a scope, the more waveforms per second that it can process. Faster throughput in a scope means less dead time and less chance of missing a significant event

TIFF or .tif

TIFF, or .tif, is a high-quality graphics file format that can be imported into other applications for documentation purposes. Widely supported across platforms (PC, Mac, UNIX), its better quality makes it a format of choice for master copies, but results in larger file sizes.

Time Base

Oscilloscope circuitry that controls the timing of the sweep. The timebase is set by the Time/div variable.

Time Base Accuracy

The closeness of the indicated time value to the true value.

Time Base Range

The range of values to which the horizontal deflection factor can be set.

Time domain

Signals displayed with time on the X-axis and amplitude on the Y-axis. Instruments that display signals in this format are called time-domain instruments.

Time domain

Signals displayed with time on the X-axis and amplitude on the Y-axis. Instruments that display signals in this format are called time-domain instruments.

Time Domain Network Analysis (TDNA)

TDNA includes both time-domain reflectometry (TDR) and time-domain transmission (TDT) measurements. Imperfect connectors, cabling, and even the response of the instrument itself can introduce errors into TDR/TDT measurements. Understanding the effects of these errors, and more importantly, how to remove them, will result in more accurate and useful measurements.

Time Domain Reflectometry (TDR)

The technique of sending a pulse or step signal into a transmission line and analyzing any reflections produced. TDR gives an intuitive measurement of any discontinuities in a circuit. It measures the location, electrical length, nature of circuit (resistive, capacitive, inductive), and amount of reflection from discontinuities.

Time Domain Transmission (TDT)

TDT is a measurement technique that measures both attenuation and propagation delay of your device under test. TDT requires that you connect an electrical channel to the output of your device under test. The instrument sends a fast step signal into your device. The output from the device is then sent into the electrical channel and back into the instrument.

Time@Maximum

Time@Maximum is a measure of the time of the first occurrence of the first data sample with the maximum signal level.

Time@Minimum

Time@Minimum is a measure of the time at which the first data sample with the minimum signal level first occurs.

Time Qualified

Time-Qualified triggering generates a trigger when the trigger source meets its trigger condition after entering or exiting the pattern. The trigger can occur even if the pattern disappears before the trigger meets its trigger conditions.

Tolerance Mask

A form of waveshape limit test that defines a maximum deviation equal to a uniform tolerance on each measured point in a waveform.

Top

Top is the statistically most prevalent voltage value above the waveform midpoint.

Total harmonic distortion (THD)

See [Harmonic Distortion](#)⁴⁴⁹

Total Jitter

Jitter is the measure of the time variances of the rising and falling edges of an eye diagram as these edges affect the crossing points of the eye. Total Jitter represents the combined effects of all components of jitter: Deterministic Jitter and Random Jitter.

Trace

The visible shapes drawn on the screen of an oscilloscope.

Transient

A signal, measured by an oscilloscope, that only occurs once (also called a single-shot event).

Trend

Plot of a parameter value or other characteristic of a measurement over a period of time.

Trigger

1. The circuit that initiates a horizontal sweep on an oscilloscope and determines the beginning point of the waveform.
2. The signal that tells the DSO to start capturing data.

Trigger Coupling

Describes the circuitry used to connect the trigger source to the trigger circuit. Several types of coupling are available: HF Reject, LF Reject, Noise Reject, AC, and DC. The different types of coupling provide improved triggering performance depending on the characteristics of the trigger source.

Triggered

The triggered, or normal, trigger mode requires that trigger conditions be met before the acquisition process terminates. If the trigger conditions are not met, the scope will not display any input waveforms. The normal or triggered mode is the desired mode of triggering when you want a stable trigger and know the trigger conditions. An alternative to the normal or triggered mode is the freerun (or auto) trigger mode, which will force a trigger after a period of time if trigger conditions are not met.

Trigger Event

A trigger event is the change, in the trigger source waveform, that meets your trigger condition and tells the acquisition system where the sampled data point corresponding to the trigger point is stored in the channel memory. The time at which the trigger event occurs is the time reference for the waveform and is, by definition, 0 seconds.

Trigger Holdoff

A control that inhibits the trigger circuit from looking for a trigger level for some specified time after the end of the waveform.

Trigger Hysteresis

Trigger Hysteresis is the difference between the arming voltage and the trigger level voltage. This defines the minimum peak-to-peak waveform voltage, which can cause a trigger. The waveform must cross both the arming level voltage and the trigger level voltage to generate a trigger event. Trigger Hysteresis helps to prevent false triggers from occurring on a falling edge due to noise when the rising edge is selected as the trigger edge (or on a rising edge when the falling edge is selected as the trigger edge).

Trigger kick-out

A signal from a trigger circuit that comes out of the trigger input connector.

Trigger Level

The voltage level that a trigger source signal must reach before the trigger circuit initiates a sweep.

Trigger pick-off

A circuit used to extract a portion of the input signal to trigger the timebase.

Trigger recognition

The process of responding to a suitable triggering signal.

Trigger recognition point

The time when trigger recognition occurs. Also, the point on a displayed waveform representing the instant of trigger recognition.

Trigger Source

The signal source used to trigger the scope. Usually one of the input channels or a dedicated input.

TTL (Transistor-Transistor Logic)

A class of logic circuitry with signal levels defined as follows: logical 0 = 0 to 0.8 V and logical 1 = 2.0 to 5.0 V.

7.21 U

Update Rate

Display Update Rate. In digital scopes, the number of trigger events that the scope can capture and display is referred to as its update rate. Unlike analog scopes, digital scopes require time to move the sampled data to memory, display the acquired data, do any post-processing math (such as Amplitude or Frequency measurements), and rearm the trigger circuitry for the next acquisition. Technology advances have greatly improved the update rate in digital scopes. Better update rate in a scope means less dead time and less chance of missing a significant event.

Uptime

The number of hours the instrument has been powered on.

7.22 V

Variable Persistence

The ability to set time parameters for the displaying of acquired data is a valuable analysis tool. Setting the time to a minimum allows you to view rapidly changing signals when you want immediate display feedback. Setting the time to infinite allows you to observe worst-case jitter of a signal, as the acquired waveforms are never erased – similar to a storage scope. Setting the persistence time to intermediate values allows you to observe long-term changes or trends.

Vectors

Vectors, or 'connect the dots', is a display technique in which a straight line is drawn between two adjacent samples on the display. It is a display feature and has no effect on the waveform data stored in the channel memory. This method is also called linear interpolation.

Vernier

Vernier, or fine control, allows a calibrated fine adjustment of a scaling factor such as the channel volts/div or the timebase time/div. For example, it is possible to set the mV/div to 150 mV/div instead of the standard choices of 100, or 200 mV/div by entering the desired value using the numeric keypad for the mV/div scale factor.

Vertical bar markers

You position the two vertical bars to measure a time parameter of a waveform record. The oscilloscope displays the value of the markers with respect to the trigger and the time difference between the bars.

Vertical Accuracy

The closeness of the indicated signal voltage to the true value.

Vertical Resolution

The number bits of bits used to digitize the input signal. A 14-bit digitizer can resolve a signal into 16,384 levels.

Vertical Sensitivity

The range of values to which the vertical deflection factor can be set.

Volt

The unit of electric potential difference.

Voltage

The difference in electric potential expressed in volts, between two points.

7.23 W**Waveform**

A graphic representation of a voltage varying over time.

Waveform database

A collection of sequentially acquired waveforms.

Waveform interval

The time interval between record points as displayed.

Waveform markers

The marker mode that presents two cursors that you position to measure both the time and amplitude parameters of a waveform record. The instrument displays the times of both cursors with respect to the trigger and the time difference between the cursors. The instrument also displays the amplitude values of both cursors with respect to the waveform ground and between the cursors.

Waveform Memory

A waveform memory is a convenient, non-volatile, waveform storage area. It contains a single waveform record along with the vertical and horizontal scaling factors for that waveform.

Waveform Point

A digital value that represents the voltage of a signal at a specific point in time. Waveform points are calculated from sample points and stored in memory.

Waveform Record

The collection of acquired data in a waveform.

Waveform types

Waveform types of the source to be measured can be Pulse, NRZ, and RZ. Each waveform type has a measurement category (Amplitude, Timing, or Area) that can be selected.

Window

In general, the period of time acquired in a waveform is called a "window". In instruments with dual timebase architecture, a window refers to the magnified section of a lower resolution (main) waveform. The window waveform is acquired with a smaller equivalent time sample interval than the main waveform.

Window Functions

Used to modify the spectrum of a truncated waveform prior to Fourier analysis.

Alternately, window functions determine the selectivity (filter shape) in a Fourier transform spectrum analyzer.

Windows OS

The underlying operating system on which this instrument runs.

7.24 X

XY Display Mode

XY is a display mode that converts the scope from a volts versus time display to a volts versus volts display of two input channels, functions, or waveform memories. The XY display plots the voltage values of two inputs, with one input's voltage values displayed horizontally and the second input's voltage values plotted vertically. This is a useful display mode for evaluating phase relations between two waveforms.

XY format

A display format that compares the voltage level of two waveform records point by point. It is useful for studying phase relationships between two waveforms.

7.25 Y

YT format

The conventional oscilloscope display format. It shows the voltage of a waveform record (on the vertical axis) as it varies over time (on the horizontal axis).

7.26 Z

Z-axis

Another name for the brightness of the trace at a given location.

Zero Level

Zero Level is a measure of the mean value of the logical 0 of an eye diagram.

Zero phase reference point

The point in the time-domain record to which the phase values of the FFT are referenced.

Zoom

Zoom allows you to analyse your waveform in more detail by expanding the waveform display either horizontally



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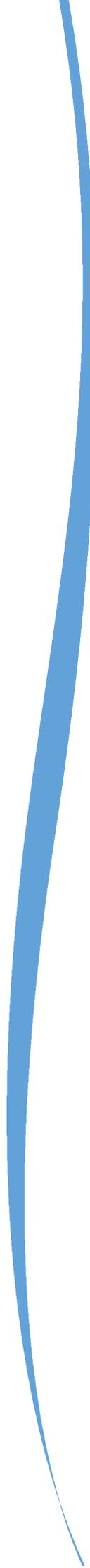
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